Gradient Descent

Logistic Regression Revisited Given a 2×2 grid where each cell aij can take on one of two colors c1 and c2, find a function that can identify the following diagonal pattern:



That is, find f such that

$$f\left(\begin{bmatrix} a_{00} & a_{01} \\ a_{10} & a_{11} \end{bmatrix}\right) = \begin{cases} \checkmark \text{ if } \begin{vmatrix} a_{00} & a_{01} \\ a_{10} & a_{11} \end{vmatrix} = \begin{vmatrix} c_{1} & c_{2} \\ c_{2} & c_{1} \end{vmatrix} = \begin{vmatrix} a_{00} & c_{11} \\ c_{21} & c_{22} \end{vmatrix}$$

We can define: \checkmark = 1 and X = 0

We can assign weights to each cell

$$\begin{bmatrix} w_1 & w_2 \\ w_3 & w_4 \end{bmatrix} \otimes \begin{bmatrix} a_{00} & a_{01} \\ a_{10} & a_{11} \end{bmatrix} = w_1 a_{00} + w_2 a_{01} + w_3 a_{10}$$

Equivalently we can decide to move the value b to the left of the equation in order for the weighted sum to reveal a diagonal pattern at 0: w1 a00 + w2 a01 + w3 a10 + w4 a11 + b = 0 if diagonal pattern found We could then find a function σ to apply to the result of this sum in order to make predictions $\{0, 1\}$:

$$\sigma(w_1 a_{00} + w_2 a_{01} + w_3 a_{10} + w_4 a_{11} + b) = 1$$
 if $w_1 a_{00} + w_2 a_{01} + w_3 a_{10} + w_4 a_{11} + b = 0$ else 0

Suppose we relax our definition of diagonal by having a continuum of colors [c1, c2]. This means there will be a continuum of values for our weighted sum to take when a diagonal pattern is found:

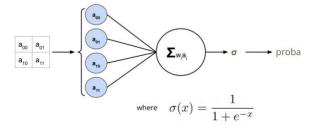
$$w_1 a_{00} + w_2 a_{01} + w_3 a_{10} + w_4 a_{11} + b > 0$$
 if diagonal

We would like our function to adapt to this vagueness of specification / definition by reflecting an uncertainty in prediction (i.e. predicting probabilities of being diagonal)

$$\sigma(w_1a_{00} + w_2a_{01} + w_3a_{10} + w_4a_{11} + b) > 0.5$$
 then diagonal

When σ is the logistic (also called sigmoid) function, this is Logistic Regression. So for each cell we're looking to learn a weight wi that makes σ larger for diagonal patterns. The bias term b lets us account for systemic dimming or brightening of cells (i.e. when the data is not normalized).

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$



Recall that logistic regression is looking for weights and a bias that maximizes the probability of having seen the data we saw:

$$\max \prod_{i=1}^{n} P(y_i = 1 | x_i)$$

$$= \min -\frac{1}{n} \sum_{i=1}^{n} \left[y_i \log(\sigma(-w^T x_i + b)) + (1 - y_i) \log(1 - \sigma(-w^T x_i + b)) \right]$$

$$= \min \operatorname{Cost}(w, b)$$

Gradient Descent (intuition):

There is no closed form solution to finding the extrema of this cost function. We can however use an iterative process by which we increment w and b gradually toward some minimum (most likely local). Goal: find a sequence of wi 's (and b's) that converge toward a minimum.

Intuitively the best nudge should be in the direction of the largest rate of change (steepness) of the function. Rate of change -> think derivatives

$$\nabla f(x) = f'(x)$$

Intuitively, the rate of change of a multi-dimensional function should be a combination of the rate change in each dimension. For a 3-dimensional function, the rate of change would be:

$$\nabla f(x, y, z) = \frac{\partial f}{\partial x}\vec{i} + \frac{\partial f}{\partial y}\vec{j} + \frac{\partial f}{\partial z}\vec{k}$$

$$f(x) = 3x^2 - 2y$$

Without even computing derivatives we can see that changes in x create more positive change in f than changes in y.

 $\nabla f = 6xi - 2j$ This is the gradient of f and can be evaluated at any point (x, y) in the space.

However, the gradient expresses the instantaneous rate of change. At p, ∇f p is the steepest but the highest value of f will depend on how many units we step in that direction. If we step too many units away, the instantaneous change in f is no longer representative of what values f will take.

Given a "smooth" function f for which there exists no closed form solution for finding its maximum, we can find a local maximum through the following steps:

- 1. Define a step size α (tuning parameter)
- 2. Initialize p to be random
- 3. $p_{new} = \alpha \nabla f_p + p$
- 4. p \square p_{new}
- 5. Repeat 3 & 4 until p \sim p_{new}

Notes about α :

- \bullet If α is too large, GD may overshoot the maximum, take a long time to or never be able to converge
- If α is too small, GD may take too long to converge

We need to compute $\nabla Cost(w, b)$:

$$\nabla \operatorname{Cost}(w, b) = \left[\frac{\partial}{\partial w} \operatorname{Cost}, \frac{\partial}{\partial b} \operatorname{Cost}\right]$$
$$\frac{\partial}{\partial w} \operatorname{Cost} = \frac{1}{n} \sum_{i=1}^{n} x_i (y_i - \sigma(-w^T x_i + b))$$
$$\frac{\partial}{\partial b} \operatorname{Cost} = \frac{1}{n} \sum_{i=1}^{n} \sigma(-w^T x_i + b) - y_i$$

- 1. Start with random w and b: $w = [0\ 0\ 0\ 0]^T$, b = 0 Note: $\sigma(0) = 0.5$
- 2. Compute the Cost(w, b) Cost($[0\ 0\ 0\ 0]T$, $[0\ 0\ 0]T$, $[0\ 0\ 0]$ = -1 log($[0\ 0\ 0]$) = -log(0.5)
- 3. Compute the gradient ∇ Cost at (w, b)

$$\frac{\partial}{\partial w} \text{Cost} = \frac{1}{1} \sum_{i=1}^{1} \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix} (1 - \sigma(0)) = \begin{bmatrix} 0 \\ 1/2 \\ 1/2 \\ 0 \end{bmatrix}$$

- 4. Adjust w & b by taking α steps in the direction of $-\nabla Cost_{(w,b)}$
- 5. Compute the updated Cost

$$\operatorname{Cost}(\begin{bmatrix} 0 \\ -\alpha/2 \\ -\alpha/2 \\ 0 \end{bmatrix}, \frac{\alpha}{2}) = -\log(\sigma(\alpha + \frac{1}{2}))$$

Recall the Cost is computed for the entire dataset. This has some limitations:

- 1. It's expensive to run
- 2. The result we get depends only on the initial starting point

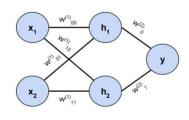
Note:

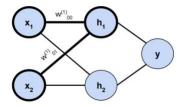
The magnitude of ∇f_p depends on p. A p gets closer to the min / max, the size of ∇f_p decreases. This also means that points p that contain more "information" have larger gradients. So the order with which this process is exposed to examples matters.

Neural Networks:

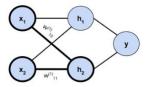
We need to define:

- 1. How input flows through the network to get the output (forward propagation)
- 2. How the weights and biases gets updated (Backpropagation)

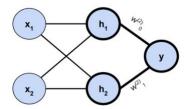




$$h_1 = \sigma(w^{(1)}_{00} x_1 + w^{(1)}_{01} x_2 + b^{(1)}_1)$$



$$h_2 = \sigma (w^{(1)}_{10} x_1 + w^{(1)}_{11} x_2 + b^{(1)}_2)$$



$$y = \sigma(w^{(2)}_0 h_1 + w^{(2)}_1 h_2 + b^{(2)}_1)$$

Using matrix notation:

$$\begin{bmatrix} h_1 \\ h_2 \end{bmatrix} = \sigma \left(\begin{bmatrix} w_{00}^{(1)} & w_{01}^{(1)} \\ w_{10}^{(1)} & w_{11}^{(1)} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} b_1^{(1)} \\ b_2^{(1)} \end{bmatrix} \right)$$
$$y = \sigma \left(\begin{bmatrix} w_{00}^{(2)} \\ w_{01}^{(2)} \end{bmatrix}^T \begin{bmatrix} h_1 \\ h_2 \end{bmatrix} + b^{(2)} \right)$$

If we don't, we just end up with normal logistic regression on x_1 and x_2 .

$$\begin{aligned} h_1 &= w^{(1)}_{00} x_1 + w^{(1)}_{01} x_2 + b^{(1)}_{1} \\ h_2 &= w^{(1)}_{10} x_1 + w^{(1)}_{11} x_2 + b^{(1)}_{2} \end{aligned}$$

Then

$$y = \sigma(w^{(2)}_{0} h_{1} + w^{(2)}_{1} h_{2} + b^{(2)}_{1})$$

$$= \sigma(w^{(2)}_{0} (w^{(1)}_{00} x_{1} + w^{(1)}_{01} x_{2} + b^{(1)}_{1}) + w^{(2)}_{1} (w^{(1)}_{10} x_{1} + w^{(1)}_{11} x_{2} + b^{(1)}_{2}) + b^{(2)}_{1})$$

$$= \sigma(w_{1} x_{1} + w_{2} x_{2} + b_{2})$$

Neural Networks - BackPropagation Using the chain rule:

$$\frac{\partial C}{\partial W^{(2)}} = \frac{\partial C}{\partial u^{(2)}} \frac{\partial u^{(2)}}{\partial W^{(2)}} \quad \text{where} \quad u^{(2)} = W^{(2)}h + b^{(2)}$$

$$= \frac{\partial C}{\partial u^{(2)}} \cdot h = \frac{1}{n} \sum_{i=1}^{n} h(y_i - \sigma(u^{(2)}))$$

$$\downarrow h = \sigma(W^{(1)} \times + b^{(1)})$$

$$\frac{\partial C}{\partial b^{(2)}} = \frac{\partial C}{\partial u^{(2)}} \frac{\partial u^{(2)}}{\partial b^{(2)}} = \frac{1}{n} \sum_{i=1}^{n} y_i - \sigma(u^{(2)})$$

So we can update W(2) and b(2) as follows:

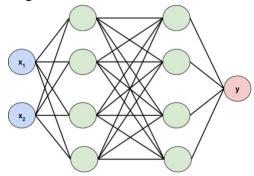
$$\begin{bmatrix} W_{new}^{(2)} \\ b_{new}^{(2)} \end{bmatrix} = -\alpha \begin{bmatrix} \frac{\partial C}{\partial W^{(2)}} \\ \frac{\partial C}{\partial b^{(2)}} \end{bmatrix} + \begin{bmatrix} W^{(2)} \\ b^{(2)} \end{bmatrix}$$

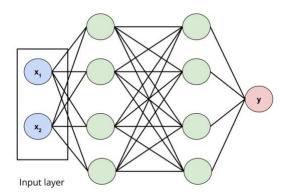
Important Note:

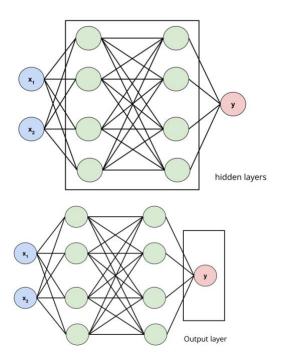
Important Note:

$$\begin{split} \frac{\partial C}{\partial W^{(1)}} &= \frac{\partial C}{\partial h} \cdot \frac{\partial h}{\partial W^{(1)}} = \frac{\partial C}{\partial h} \cdot \frac{\partial h}{\partial u^{(1)}} \cdot \frac{\partial u^{(1)}}{\partial W^{(1)}} \quad \text{where} \quad u^{(1)} = w^{(1)}x + b^{(1)} \\ &= \frac{\partial C}{\partial u^{(2)}} \cdot \frac{\partial u^{(2)}}{\partial h} \cdot \frac{\partial h}{\partial u^{(1)}} \cdot \frac{\partial u^{(1)}}{\partial W^{(1)}} = \frac{\partial C}{\partial u^{(2)}} \cdot W^{(2)} \cdot \sigma'(u^{(1)}) \cdot x \\ &\stackrel{\text{Depends on both data and weights Initializing all weights to zero then is not a good idea} \end{split}$$

In general:







Neural Networks Can do both Classification and Regression

Neural Networks - Tuning Parameters

- 1. Step size α
- 2. Number of BackPropagation iterations
- 3. Batch Size
- 4. Number of hidden layers
- 5. Size of each hidden layer
- 6. Activation function used in each layer
- 7. Cost function
- 8. Regularization (to avoid overfitting)

Neural Networks - Convolutional Neural Networks

Creating such a filter allows us to:

- 1. Reduce the number of weights
- 2. Capture features all over the image

The process of applying a filter (or kernel) is called a convolution

Recurrent Neural Networks

Handling sequences of input.

Intuition: What a word is / might be in a sentence is easier to figure out if you know the words around it.

Applications:

- 1. Predicting the next word
- 2. Translation

- 3. Speech Recognition4. Video Tagging

