Xu Chen December 3, 2014

1 Multivariariate Partial Derivative

Let f be a function of x_1 and x_2 . Pick a fixed vector $z = [z_1, z_2]^T$. For this two-variable function, the first-order Taylor expansion (around the point z) is

$$f(x) \approx f(z) + \frac{\partial f}{\partial x_1}\Big|_{x=z} (x_1 - z_1) + \frac{\partial f}{\partial x_2}\Big|_{x=z} (x_2 - z_2) \quad \forall x \in \mathbf{R}^2 \text{ close to } z$$

$$= f(z) + \left[\frac{\partial f}{\partial x_1} \quad \frac{\partial f}{\partial x_2} \right]_{x=z} \left[\begin{array}{c} x_1 - z_1 \\ x_2 - z_2 \end{array} \right]$$

$$= f(z) + \nabla f(x)\Big|_{x=z}^T (x - z)$$

$$(1)$$

The term

$$\nabla f(x) = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{bmatrix}$$

is called the gradient of f(x), a generalization of df(x)/dx in the single-variable calculus. It is a 2 by 1 column vector if f(x) is a mapping from \mathbb{R}^2 and \mathbb{R} . For instance, if $f(x_1, x_2) = x_1 + 2x_2$, then

$$\nabla f(x) = \left[\begin{array}{c} 1 \\ 2 \end{array} \right]$$

Note: by convention, the gradient of a $\mathbf{R}^{\mathbf{n}} \to \mathbf{R}$ mapping $f(x_1, x_2, \dots, x_n)$ is defined as a column vector:

$$\nabla f(x) = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix}$$

as it defines a vector/direction in a vector space. A corresponding definition is the derivative

$$Df(x) = \begin{bmatrix} \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \dots & \frac{\partial f}{\partial n} \end{bmatrix}$$

which is a row vector and

$$\nabla f(x) = \left[Df(x) \right]^T$$

We can generalize the above result. For instance, if $f_1(x, u) = f_1(x_1, x_2, u_1, u_2)$ then the Taylor approximation around the point (\bar{x}, \bar{u}) is

$$f_{1}(x,u) \approx f_{1}(\bar{x},\bar{u}) + \left[\frac{\partial f_{1}(x,u)}{\partial x_{1}}, \frac{\partial f_{1}(x,u)}{\partial x_{2}}\right] \begin{vmatrix} x = \bar{x} \\ x_{2} - \bar{x}_{2} \end{vmatrix}$$

$$+ \left[\frac{\partial f_{1}(x,u)}{\partial u_{1}}, \frac{\partial f_{1}(x,u)}{\partial u_{2}}\right] \begin{vmatrix} x = \bar{x} \\ u = \bar{u} \end{vmatrix}$$

$$= f_{1}(\bar{x},\bar{u}) + \nabla_{x}^{T}f_{1}(x,u) \begin{vmatrix} x = \bar{x} \\ u = \bar{u} \end{vmatrix}$$

$$= f_{2}(\bar{x},\bar{u}) + \nabla_{x}^{T}f_{1}(x,u) \begin{vmatrix} x = \bar{x} \\ u = \bar{u} \end{vmatrix}$$

$$= f_{3}(\bar{x},\bar{u}) + \nabla_{x}^{T}f_{2}(x,u) \begin{vmatrix} x = \bar{x} \\ u = \bar{u} \end{vmatrix}$$

$$= f_{3}(\bar{x},\bar{u}) + \nabla_{x}^{T}f_{3}(x,u) \begin{vmatrix} x = \bar{x} \\ u = \bar{u} \end{vmatrix}$$

Xu Chen December 3, 2014

OD 11 1	O 1.	1
Table L	C-radient	examples

$\nabla f(x)$	$D\nabla f\left(x\right)$	
$\frac{x}{\ x\ _2}$		
2x		
$3 x _2x$	$ 3 x _2 + 3\frac{x^Tx}{ x _2}$	
y		
y		
$\frac{x}{(\ln 10) x ^2}$		
$A^{T}(Ax-b)$		
	$ \begin{array}{c c} \nabla f(x) \\ \hline $	

If we have another similar function

$$f_{2}(x,u) \approx f_{2}(\bar{x},\bar{u}) + \left[\frac{\partial f_{2}(x,u)}{\partial x_{1}}, \frac{\partial f_{2}(x,u)}{\partial x_{2}}\right] \begin{vmatrix} x = \bar{x} \\ u = \bar{u} \end{vmatrix}$$

$$+ \left[\frac{\partial f_{2}(x,u)}{\partial u_{1}}, \frac{\partial f_{2}(x,u)}{\partial u_{2}}\right] \begin{vmatrix} x = \bar{x} \\ u = \bar{u} \end{vmatrix}$$

$$= f_{2}(\bar{x},\bar{u}) + \nabla_{x}^{T} f_{2}(x,u) \begin{vmatrix} x = \bar{x} \\ u = \bar{u} \end{vmatrix}$$

$$= f_{2}(\bar{x},\bar{u}) + \nabla_{x}^{T} f_{2}(x,u) \begin{vmatrix} x = \bar{x} \\ u = \bar{u} \end{vmatrix}$$

$$= \bar{u}$$

$$= \bar{u}$$

$$= \bar{u}$$

$$= \bar{u}$$

Then for the ${f R}^2 imes {f R}^2 o {f R}^2$ function

$$f(x,u) = \left[\begin{array}{c} f_1(x,u) \\ f_2(x,u) \end{array} \right]$$

we have

$$f\left(x,u\right) \approx \begin{bmatrix} f_{1}\left(\bar{x},\bar{u}\right) \\ f_{2}\left(\bar{x},\bar{u}\right) \end{bmatrix} + \underbrace{\begin{bmatrix} \frac{\partial f_{1}}{\partial x_{1}} & \frac{\partial f_{1}}{\partial x_{2}} \\ \frac{\partial f_{2}}{\partial x_{1}} & \frac{\partial f_{2}}{\partial x_{2}} \end{bmatrix}}_{\nabla_{x}^{T}f\left(x,u\right)} \begin{bmatrix} x_{1} - \bar{x}_{1} \\ x_{2} - \bar{x}_{2} \end{bmatrix} + \underbrace{\begin{bmatrix} \frac{\partial f_{1}}{\partial u_{1}} & \frac{\partial f_{1}}{\partial u_{2}} \\ \frac{\partial f_{2}}{\partial u_{1}} & \frac{\partial f_{2}}{\partial u_{2}} \end{bmatrix}}_{\nabla_{u}^{T}f\left(x,u\right)} \begin{bmatrix} u_{1} - \bar{u}_{1} \\ u_{2} - \bar{u}_{2} \end{bmatrix}$$

$$= \underbrace{\begin{bmatrix} x_{1} - \bar{x}_{1} \\ x_{2} - \bar{x}_{2} \end{bmatrix}}_{\Phi} + \underbrace{\begin{bmatrix} \frac{\partial f_{1}}{\partial u_{1}} & \frac{\partial f_{1}}{\partial u_{2}} \\ \frac{\partial f_{2}}{\partial u_{1}} & \frac{\partial f_{2}}{\partial u_{2}} \end{bmatrix}}_{V_{u}^{T}f\left(x,u\right)} \begin{bmatrix} u_{1} - \bar{u}_{1} \\ u_{2} - \bar{u}_{2} \end{bmatrix}$$

$$= \underbrace{\begin{bmatrix} u_{1} - \bar{u}_{1} \\ u_{2} - \bar{u}_{2} \end{bmatrix}}_{\Phi}$$

$$= \underbrace{f\left(\bar{x},\bar{u}\right) + A\left(x - \bar{x}\right) + B\left(u - \bar{u}\right)}_{\Phi}$$

From here we learnt how to compute the derivative and gradient of a multi-input multi-output function:

$$D_x \left[\begin{array}{c} f_1 \\ f_2 \end{array} \right] = \left[\begin{array}{cc} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{array} \right], \ \nabla_x \left[\begin{array}{c} f_1 \\ f_2 \end{array} \right] = \left[\begin{array}{cc} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_2}{\partial x_1} \\ \frac{\partial f_1}{\partial x_2} & \frac{\partial f_2}{\partial x_2} \end{array} \right]$$

Similar to single-variable calculus, we can use the chain rule to compute multi-variable derivatives:

$$Dg(f(x)) = D_a g(f(x)) Df(x)$$

Hence

$$\nabla g(f(x)) = \nabla f(x) \nabla_{q} g(f(x))$$

The gradient of some common functions are listed in the following table.

Xu Chen December 3, 2014

Exercise: Prove the results in Table 1. Assume compatible dimensions. Show that

$$\nabla_{X}Tr\left(XY\right)=Y^{T}$$

where Tr(XY) denotes the trace of the matrix XY. Hint:

$$\frac{\partial Tr\left(XY\right)}{\partial X_{ij}}=Y_{ji}$$