Project3

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A) Xichen Li: I worked on project-3 all independently.

Consider a 1-D problem with potential energy:

$$U(x) = \begin{cases} \infty & for \quad x < 0 \\ \infty & for \quad x > L \\ 0 & for \quad 0 < x < L \end{cases}$$

The eigenfunction corresponding to quantum number n is, $\psi_n = A_n sin(\frac{n\pi}{L}x)$, where A_n is the normalization constant. Find the expectation value of the position operator for an electron in the state:

• (i)
$$\psi_2$$

• (ii) $(\frac{3}{\sqrt{2}}\psi_1 - \frac{3}{\sqrt{2}}\psi_2 + 4\psi_3)/5$ at $t = 0$

• (iii) Recalculate (ii) by including the time dependent part of the wave function. Derive an expression. Plot this as a function of time.

• (iv) By using the mass of the particle is $9.1*10^{-31}kg$ and the length of the box is 3nm, plot the expectation value of position as a function of time.

Answer

• (i) At t=0, the expectation of the position is:

$$\langle x \rangle = \int_0^L A_2 \sin(\frac{2\pi}{L}x) x A_2 \sin(\frac{2\pi}{L}x) dx$$

Where $A_n = \sqrt{\frac{2}{L}}$. And this integraal can be calculated using trigonometruc identity:

$$\langle x \rangle = \frac{2}{L} \int_0^L \frac{x}{2} dx + \frac{2}{L} \int_0^L \frac{-x}{2} cos(\frac{4\pi x}{L}) dx$$

The second term is equal to zero and $\langle x \rangle = \frac{L}{2}$

. (ii) At t=0, the expectation of the position is:

$$< x >= \int_0^L A_n (\frac{3}{5\sqrt{2}} sin(\frac{\pi}{L}x) - \frac{3}{5\sqrt{2}} sin(\frac{2\pi}{L}x) + \frac{4}{5} sin(\frac{3\pi}{L}x)) x A_n (\frac{3}{5\sqrt{2}} sin(\frac{\pi}{L}x) - \frac{3}{5\sqrt{2}} sin(\frac{2\pi}{L}x) + \frac{4}{5} sin(\frac{3\pi}{L}x)) dx$$

$$< x >= \frac{2}{L} \int_0^L x [\frac{9}{50} sin^2 (\frac{\pi}{L}x) + \frac{9}{50} sin^2 (\frac{2\pi}{L}x) + \frac{16}{25} sin^2 (\frac{3\pi}{L}x) - \frac{18}{50} sin(\frac{\pi}{L}x) sin(\frac{2\pi}{L}x) + \frac{24}{25\sqrt{2}} sin(\frac{\pi}{L}x) sin(\frac{3\pi}{L}x)$$

$$- \frac{24}{25\sqrt{2}} sin(\frac{2\pi}{L}x) sin(\frac{3\pi}{L}x)] dx$$

$$< x >= \frac{L}{2} \frac{9}{50} + \frac{L}{2} \frac{9}{50} + \frac{L}{2} \frac{16}{25} + a + 0 + b \approx 0.697L$$

. (iii) Include the time dependent part, the expression becomes:

$$< x > = \int_{0}^{L} A_{n} (e^{\frac{iE_{1}t}{\hbar}} \frac{3}{5\sqrt{2}} sin(\frac{\pi}{L}x) - e^{\frac{iE_{2}t}{\hbar}} \frac{3}{5\sqrt{2}} sin(\frac{2\pi}{L}x) + e^{\frac{iE_{3}t}{\hbar}} \frac{4}{5} sin(\frac{3\pi}{L}x)) x A_{n} (e^{\frac{-iE_{1}t}{\hbar}} \frac{3}{5\sqrt{2}} sin(\frac{\pi}{L}x) - e^{\frac{-iE_{2}t}{\hbar}} \frac{3}{5\sqrt{2}} sin(\frac{2\pi}{L}x) + e^{\frac{-iE_{3}t}{\hbar}} \frac{4}{5} sin(\frac{3\pi}{L}x)) dx$$

Where $E_n = \frac{\hbar^2}{2m} (\frac{n\pi}{L})^2$ As we can see from the expression which include some additional cosine term for each interference between the three eigenfunctions. Use the code below to calculate the expression of < x > as a function of time. A normalized mass and charge and \hbar are used in the code below for part (iii).

```
In [113]: import numpy as np
          #import numpy.pi as pi
          %matplotlib notebook
          import matplotlib.pyplot as plt
          import scipy.integrate as spi
          eta = 1
          m = 1
          q = 1
          L=100
          T0=50e3
          dt=100
In [114]: #t = np.linspace(0,T0,num=N)
          #t=0
          E1=eta**2/(2*m)*(np.pi/L)**2
          E2=eta**2/(2*m)*(2*np.pi/L)**2
          E3=eta**2/(2*m)*(3*np.pi/L)**2
          An=np.sqrt(2/L)
          x0 = 0
          x1 = L
```

 $integrand = lambda \ x : An*(3/(5*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(np.pi/L*x)-3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(2*np.sqrt(2))*np.sqrt(2)*np.sqr$

 $4/(5)*np.\exp(1j*E3*t/eta)*np.\sin(3*np.pi/L*x))*x*An*(3/(5*np.sqrt(2))*np.\exp(-1j*E1*t/eta)*np.\sin(np.pi/L*x) \\ -3/(5*np.sqrt(2))*np.\exp(-1j*E2*t/eta)*np.\sin(2*np.pi/L*x)+4/(5)*np.exp(-1j*E3*t/eta)*np.sin(3*np.pi/L*x))$

69.69014298960704

print(x_avg[0])

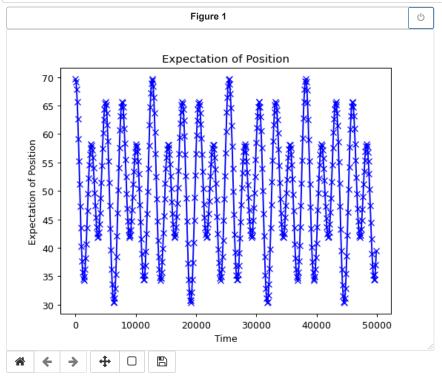
tr=np.arange(0,T0,dt)
for t in tr:

x_avg=x_avg+[result]

result, error = spi.quad(integrand, x0, x1)

x_avg=[]

```
In [115]: plt.figure()
    plt.plot(tr, x_avg, color='b', ls='-', marker='x')
    plt.title('Expectation of Position')
    plt.xlabel('Time')
    plt.ylabel('Expectation of Position')
```



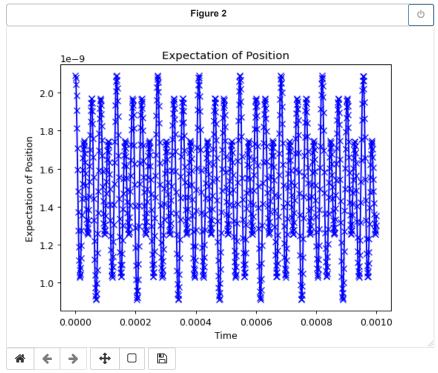
Out[115]: Text(0, 0.5, 'Expectation of Position')

• (iv) By using the mass of the particle is $9.1 * 10^{-31} kg$ and the length of the box is 3nm, plot the expectation value of position as a function of time.

```
In [116]: eta = 6.63e-34/2/np.pi #Reduced Plank constant in eV.s
                                 m = 9.11e-31 #Assuming the particle mass is equal to a free electron
                                 q = 1.6e-19
                                 L=3e-9
                                  T0=1e-3
                                 dt=1e-6
                                  #t = np.linspace(0,T0,num=N)
                                  #t=0
                                 E1=eta**2/(2*m)*(np.pi/L)**2
                                 E2=eta**2/(2*m)*(2*np.pi/L)**2
                                 E3=eta**2/(2*m)*(3*np.pi/L)**2
                                 An=np.sqrt(2/L)
                                 x0 = 0
                                 x1 = L
                                 x_avg=[]
                                 tr=np.arange(0,T0,dt)
                                  for t in tr:
                                                integrand = lambda \ x : An*(3/(5*np.sqrt(2))*np.exp(1j*E1*t/eta)*np.sin(np.pi/L*x)-3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.pi/L*x)+3/(5*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.exp(1j*E2*t/eta)*np.sin(2*np.sqrt(2))*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqrt(2)*np.sqr
                                                             4/(5)*np.exp(1j*E3*t/eta)*np.sin(3*np.pi/L*x))*x*An*(3/(5*np.sqrt(2))*np.exp(-1j*E1*t/eta)*np.sin(np.pi/L*x)
                                                             -3/(5*np.sqrt(2))*np.exp(-1j*E2*t/eta)*np.sin(2*np.pi/L*x)+4/(5)*np.exp(-1j*E3*t/eta)*np.sin(3*np.pi/L*x))
                                               result, error = spi.quad(integrand, x0, x1)
                                                x_avg=x_avg+[result]
                                  print(x_avg[0])
```

2.090704289688212e-09

```
In [117]: plt.figure()
    plt.plot(tr, x_avg, color='b', ls='-', marker='x')
    plt.title('Expectation of Position')
    plt.xlabel('Time')
    plt.ylabel('Expectation of Position')
```



Out[117]: Text(0, 0.5, 'Expectation of Position')

In []: