# Display controller component

REV A

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### 1 Overview

#### IN THIS CHAPTER

- ▶ Features
- Memory requirements
- ▶ Resource requirements
- ▶ Performance

The display controller module is used to drive a single graphics LCD screen up to 800 \* 600 pixels incorporating a managed double buffer.

### 1.1 Features

- Non-blocking SDRAM management.
- Real time servicing of the LCD.
- ► Touch interactive display
- Image memory manager to simplify handling of images.
- No real time constraints on the application.

### 1.2 Memory requirements

Resource	Usage	
Stack	6198 bytes	
Program	11306 bytes	

# 1.3 Resource requirements

Resource	Usage
Channels	3
Timers	0
Clocks	0
Threads	1



# 1.4 Performance

The achievable effective bandwidth varies according to the available xCORE MIPS. The maximum pixel clock supported is 25MHz.



# 2 Hardware requirements

IN THIS CHAPTER

- ▶ Recommended hardware
- Demonstration applications

#### 2.1 Recommended hardware

#### 2.1.1 sliceKIT

This module may be evaluated using the sliceKIT modular development platform, available from digikey. Required board SKUs are:

- XP-SKC-L2 (SliceKIT L2 Core Board)
- ► XA-SK-SCR480 plus XA-SK-XTAG2 (sliceKIT xTAG adaptor)

### 2.2 Demonstration applications

### 2.2.1 Display controller application

- ▶ Package: sw\_display\_controller
- ► Application: app\_display\_controller

This combination demo employs the module\_lcd along with the module\_sdram, module\_touch\_controller\_lib, module\_i2c\_master and the module\_display\_controller framebuffer framework component to implement a 480x272 display controller.

Required board SKUs for this demo are:

- ► XP-SKC-L16 (sliceKIT L16 Core Board) plus XA-SK-XTAG2 (sliceKIT xTAG adaptor)
- XA-SK-SDRAM
- ➤ XA-SK-SCR480 (which includes a 480x272 color touch screen)



### 3 API

#### IN THIS CHAPTER

- ► Configuration defines
- ▶ API
  - component: sc\_sdram\_burst which handles the SDRAM
  - component: sc\_lcd which handles the LCD

The below section details the APIs in the application. For details about the LCD and SDRAM APIs please refer to the respective repositories.

### 3.1 Configuration defines

The module\_display\_controller can be configured via the header display\_controller\_conf.h. The module requires nothing to be additionally defined however any of the defines can be overridden by adding the header display\_controller\_conf.h to the application project and adding the define that needs overridding. The possible defines are:

#### **DISPLAY CONTROLLER MAX IMAGES**

This defines the storage space allocated to the display controller for it to store image metadata. When an image is registered with the display controller its dimensions and location in SDRAM address space are stored in a table. The define specifies how many entries are allowed in that table. Note, there is no overflow checking by default.

#### **DISPLAY CONTROLLER VERBOSE**

This define switches on the error checking for memory overflows and causes verbose error warnings to be emitted in the event of an error.

#### 3.2 API

- display\_controller\_client.xc
- display\_controller\_internal.h
- display\_controller.xc
- ▶ display\_controller.h
- ▶ transitions.h
- ▶ transitions.xc

The display controller handles the double buffering of the image data to the LCD as a real time service and manages the I/O to the SDRAM as a non-real time service.

The display controller API is as follows:

void display\_controller(chanend c\_client, chanend c\_lcd, chanend c\_sdram)



Function to manage the LCd c\_server and SDRAM server whilst maintaining image buffers.

This function has the following parameters:

c\_client The channel from the display\_controller to the client application.

c\_lcd The channel from the display\_controller to the LCd c\_server.

c\_sdram The channel from the display\_controller to the SDRAM server.

The function reads a line of pixel data from the SDRAM.

This function has the following parameters:

c\_server The channel from the client application to the display\_controller.

line The image line number to be read.

image\_no The image number whose line is to be read.

buffer[] The buffer which is to be filled with the read data.

The function reads a line of pixel data from the SDRAM.

This function has the following parameters:

c\_server The channel from the client application to the display\_controller.

line The image line number to be read.

image\_no The image number whose line is to be read.

buffer A pointer to the buffer which is to be filled with the read data.



The function writes a line of pixel data to the registered image in SDRAM.

This function has the following parameters:

c\_server The channel from the client application to the display\_controller.

line The image line number to be written.

image\_no The image number whose line is to be written.

buffer[] The buffer which is to be written to the image.

The function writes a line of pixel data to the registered image in SDRAM.

This function has the following parameters:

c\_server The channel from the client application to the display\_controller.

line The image line number to be written.

image\_no The image number whose line is to be written.

buffer A pointer to the buffer which is to be written to the image.

The function writes a partial line of pixel data to the registered image in SDRAM.

This function has the following parameters:

c\_server The channel from the client application to the display\_controller.

line The image line number to be written.

image\_no The image number whose line is to be written.

buffer[] The buffer which is to be written to the image.

line\_offset The offset in pixels to begin the write of the image line from.



word\_count The number of words to write to the image line.

buffer\_offset

The offset from the begining of the buffer to write from in words.

The function writes a partial line of pixel data to the registered image in SDRAM.

This function has the following parameters:

c\_server The channel from the client application to the display\_controller.

line The image line number to be written.

image\_no The image number whose line is to be written.

buffer A pointer to the buffer which is to be written to the image.

line\_offset The offset in pixels to begin the write of the image line from.

word\_count The number of words to write to the image line.

buffer\_offset

The offset from the begining of the buffer to write from in words.

Registers an image with the display controller.

Returns an image handle to refer to the image from then on.

This function has the following parameters:

server The channel from the client application to the display\_controller.

img\_width\_words

The width of the image in words.

img\_height\_lines

The height of the image in lines(pixels).



Makes the display controller wait until the current SDRAM service has completed.

This function has the following parameters:

server The channel from the client application to the display\_controller.

buffer The buffer which is to be written to the image.

Makes the display controller wait until the current SDRAM service has completed.

This function has the following parameters:

c\_server The channel from the client application to the display\_controller.

buffer A pointer to the buffer which is to be written to the image.

Commits the image to the display controller to be displayed on the LCD screen when the current image is completly displayed.

The display controller contains a single next image number buffer meaning that if the buffer is empty (the previously committed image is already on the LCD screen) then the command will return immediatly. If the buffer is full then this function will block until the current image is on the LCD screen and the buffer is ready for a new entry. This behaviour ensures that frame commits will not overwrite.

This function has the following parameters:

c\_server The channel from the client application to the display\_controller.

image\_no The image handle of the image to be displayed as per the described behaviour.

Commits the image to the display controller to be displayed on the LCD screen and initialises the display controller.

This must only be called once at the begining of the display controllers use.

This function has the following parameters:



server The channel from the client application to the display\_controller.

image\_no The image handle of the image to be displayed as per the described

behaviour.

The transition API is as follows:

Transition effect: A -> B as a wipe, i.e.

B wipes to A from the right.

This function has the following parameters:

c\_server The channel from the client application to the display\_controller.

frame\_buffer

An array of the frame buffer image handles.

image\_from The image handle of the image to transition from.

image\_to The image handle of the image to transition to.

frames The number of frame to take over the course of the transisiton.

cur\_fb\_index

The initial index of the current frame in the frame\_buffer .

This function returns:

The final index of the current frame in the frame\_buffer.

Transition effect: A -> B as a slide, i.e.

B slides over A from the right.

This function has the following parameters:

c\_server The channel from the client application to the display\_controller.



frame\_buffer

An array of the frame buffer image handles.

image\_from The image handle of the image to transition from.

image\_to The image handle of the image to transition to.

frames The number of frame to take over the course of the transisiton.

cur\_fb\_index

The initial index of the current frame in the frame buffer.

This function returns:

The final index of the current frame in the frame\_buffer .

Transition effect: A -> B as a roll, i.e.

B rolls on from the right and A rolls off to the right.

This function has the following parameters:

c\_server The channel from the client application to the display\_controller.

frame\_buffer

An array of the frame buffer image handles.

image\_from The image handle of the image to transition from.

image\_to The image handle of the image to transition to.

frames The number of frame to take over the course of the transisiton.

cur\_fb\_index

The initial index of the current frame in the frame\_buffer .

This function returns:

The final index of the current frame in the frame\_buffer .



unsigned frames, unsigned cur\_fb\_index)

Transition effect: A -> B as a dither, i.e.

B is revealed in 2 pixel chunks until A is gone.

This function has the following parameters:

c\_server The channel from the client application to the display\_controller.

frame buffer

An array of the frame buffer image handles.

image\_from The image handle of the image to transition from.

image\_to The image handle of the image to transition to.

frames The number of frame to take over the course of the transisiton.

cur\_fb\_index

The initial index of the current frame in the frame\_buffer .

This function returns:

The final index of the current frame in the frame\_buffer .

Transition effect: A -> B as a fade, i.e.

A fades away as B fades in.

This function has the following parameters:

c\_server The channel from the client application to the display\_controller.

frame\_buffer

An array of the frame buffer image handles.

image\_from The image handle of the image to transition from.

image\_to The image handle of the image to transition to.

frames The number of frame to take over the course of the transisiton.



cur\_fb\_index

The initial index of the current frame in the frame\_buffer .

This function returns:

The final index of the current frame in the frame\_buffer .

The transitions use the display controller API.



# 4 Programming guide

#### IN THIS CHAPTER

- ► Shared memory interface
- ▶ Source code structure
- Executing the project
- ▶ Software requirements

# 4.1 Shared memory interface

The display controller uses a shared memory interface to move the large amount of data around from tile to tile efficiently. This means that the display\_controller, sdram\_server and lcd\_server must be one the same tile.

### 4.2 Source code structure

	Project	File	Description
	module_display_controller	display_controller.h	Header file containing the APIs for the display controller component.
		display_controller.xc	File containing the implementation of the display controller component.
		display_controller_client.xc	File containing the implementation of the display controller client functions.
		display_controller_internal.h	Header file containing the user configurable defines for the display controller component.
		transitions.h	Header file containing the APIs for the display controller transitions.
Figure 1: Project structure		transitions.xc	File containing the implementation of the display controller transitions.



### 4.3 Executing the project

The module by itself cannot be built or executed separately - it must be linked in to an application. Once the module is linked to the application, the application can be built and tested for driving a LCD screen.

- 1. module\_display\_controller
- 2. module\_lcd
- 3. module\_sdram
- 1. module\_touch\_controller\_lib or module\_touch\_controller\_server
- module\_i2c\_master

should be added to the list of MODULES.

### 4.4 Software requirements

The module is built on xTIMEcomposer version 12.0 The module can be used in version 12.0 or any higher version of xTIMEcomposer.



# 5 Example applications

IN THIS CHAPTER

- ▶ app\_display\_controller\_demo
- ► Application notes

This tutorial describes a demo application that uses the display controller module. §2.1 describes the required hardware setup to run the demos.

### 5.1 app\_display\_controller\_demo

This application demonstrates how the lcd\_module is used to write image data to the LCD screen whilst imposing no real time constraints on the application. The purpose of this demonstration is to show how data is passed to the display\_controller. This application also demonstrates an interactive display using touch\_controller\_lib module.

### 5.2 Application notes

### 5.2.1 Getting started

- 1. Plug the XA-SK-LCD Slice Card into the 'TRIANGLE' slot of the sliceKIT Core Board
- 2. Plug the XA-SK-SDRAM Slice Card into the 'STAR' slot of the sliceKIT Core Board
- 3. Open app\_display\_controller\_demo.xc and build the project.
- 4. Run the program ensuring that it is run from the project directory where the TGA images are.

The output produced should look like a series of images transitioning on the LCD when the screen is touched.





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