MIT AI2 Camp 204

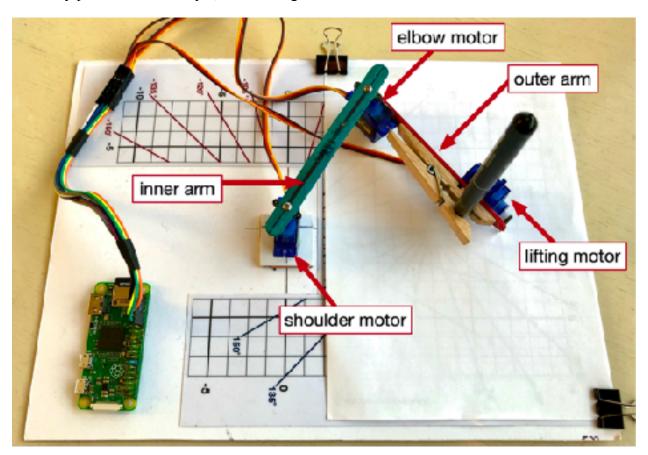
Final Project — Components and materials

You'll need:

- ♦ a Raspberry Pi
- three servo motors
- ◆ sticks or stiff card to make two arms, each about 10cm long (Walmart)
- ♦ jumper wires and GPIO pin header to connect the Pi to the servos
- ♦ a clothes peg (Walmart)
- ◆ a board or sheet of card, about A4 size
- ◆ strong adhesive(Super Glue) or a hot glue gun (HomeDeport/Lowes)

1.2. Assembly

The image below shows the basic construction of the BrachioGraph plotter and the names of some key parts. In this example, the drawing sheet is A5 size.



Dorhea 5 Pcs SG90 Micro Servo Motor



Roll over image to soom in

- 100% REW is and high quality. Staff Tensor (4.8Y). 17.5xx An (1 bysical).
 Operating veltage: ECV= 54; Femperature range: -50 to +60; Dead band width:
- $^{\circ}$ Mini serve SCSO is they and lightweight with high output power.

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\$16,70

- 96/90 serve more compatible with the project like Robert word Robert band/ control the serve with potentiometer/ multi serve control.
- + Title SGBOthas X wire interfaces in which the connections should be made as

