$$\Phi_{\theta,\xi}(z)_{t} = \mathcal{F}_{d}^{-1} \left( \mathcal{F}_{1}^{-1}(B)_{t} \mathcal{F}_{d}(z_{0}) \right) + \mathcal{F}_{d+1}^{-1} \left( B \mathcal{F}_{d+1} \left( \mathbf{1}_{\geq 0} H_{\theta,\xi}(z_{0}) \right) \right)_{t}$$
**Fixed Point Solver**:  $z = \Phi_{\theta,\xi}(z)$ 

Lift  $L_{ heta}: \mathbb{R}^{d_u} 
ightarrow \mathbb{R}^{d_h}$ 

t = 0

**ODE Solver**: 
$$z_t = \mathcal{F}_d^{-1}(v_t)$$

$$v_t = v_0 + \int_0^t Av_s + \mathcal{F}_d(H_{\theta,\xi}(\mathcal{F}_d^{-1}(v_s))), \quad v_0 = \mathcal{F}_d(z_0)$$

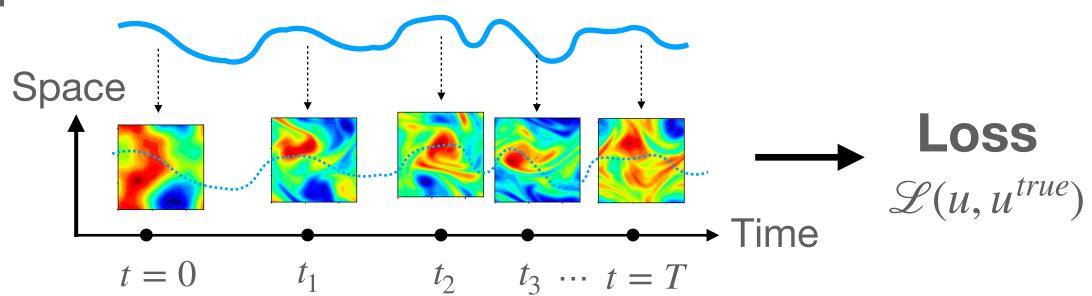
Readout  $\Pi_{\theta}: \mathbb{R}^{d_h} 
ightarrow \mathbb{R}^{d_u}$ 

$$\left(u_0: \mathscr{D} \to \mathbb{R}^{d_u}, \quad \xi: [0,T] \to L^2(\mathscr{D}, \mathbb{R}^{d_{\xi}})\right)$$

## Space Time

 $\cdots t = T$ 

**Solution Operator** 



 $u:[0,T]\to L^2(\mathcal{D},\mathbb{R}^{d_u})$  Physical Space