

$$\Phi_{\theta,\xi}(z)_t = \mathcal{F}_d^{-1} \left(\mathcal{F}_1^{-1}(B)_t \mathcal{F}_d(z_0) \right) + \mathcal{F}_{d+1}^{-1} \left(B \mathcal{F}_{d+1} \left(\mathbf{1}_{\geq 0} H_{\theta,\xi}(z_\cdot) \right) \right)_t$$

Fixed Point Solver : $z = \Phi_{\theta,\xi}(z)$

$$\left(z_0 : \mathcal{D} \rightarrow \mathbb{R}^{d_h}, \quad \xi : [0, T] \rightarrow L^2(\mathcal{D}, \mathbb{R}^{d_\xi}) \right) \longrightarrow z : [0, T] \rightarrow L^2(\mathcal{D}, \mathbb{R}^{d_h}) \quad \textbf{Latent Space}$$

ODE Solver : $z_t = \mathcal{F}_d^{-1}(v_t)$

$$v_t = v_0 + \int_0^t A v_s + \mathcal{F}_d(H_{\theta,\xi}(\mathcal{F}_d^{-1}(v_s))), \quad v_0 = \mathcal{F}_d(z_0)$$

Lift $L_\theta : \mathbb{R}^{d_u} \rightarrow \mathbb{R}^{d_h}$

Readout $\Pi_\theta : \mathbb{R}^{d_h} \rightarrow \mathbb{R}^{d_u}$

$$\left(u_0 : \mathcal{D} \rightarrow \mathbb{R}^{d_u}, \quad \xi : [0, T] \rightarrow L^2(\mathcal{D}, \mathbb{R}^{d_\xi}) \right) \xrightarrow{\textbf{Solution Operator}} u : [0, T] \rightarrow L^2(\mathcal{D}, \mathbb{R}^{d_u}) \quad \textbf{Physical Space}$$

