

Autocorrelation

Remedies:

1) Specification:

True: $y_t = \alpha + \beta X_t + \underbrace{\gamma z_t + \epsilon_t}$

Est: $y_t = \alpha + \beta X_t + u_t$

$$u_t = \gamma z_t + \epsilon_t$$

if z_t - AR process
↓
Autocorr.
of errors

else
↓
NOT

2) AR(1) transform (Special GLS)

Cohran - Ocutt procedure

$$y_t = \beta_1 + \beta_2 X_t + u_t \quad | \cdot L \cdot p$$

$$\text{Assumption: } u_t = \rho u_{t-1} + \varepsilon_t$$

$$y_t = \beta_1 + \beta_2 X_t + \rho u_{t-1} + \varepsilon_t$$

$$\rho y_{t-1} = \beta_1 \cdot \rho + \beta_2 \cdot \rho X_{t-1} + \rho u_{t-1}$$

$$y_t - \rho y_{t-1} = \beta_1 (1 - \rho) + \beta_2 (X_t - \rho X_{t-1}) + \varepsilon_t$$

$$y_t^* = \beta_1^* + \beta_2 X_t^* + \varepsilon_t$$

$$\text{s.t. : } \hat{\rho} \begin{matrix} \nearrow \\ \searrow \end{matrix} \begin{matrix} \hat{u}_t = \rho \hat{u}_{t+1} + v_t \\ DW \rightarrow 2(1 - \rho) \end{matrix}$$

$$\hat{\rho} = 1 - \frac{DW}{2}$$

Prais - Winsten correction

for 1st observation

$$y_t^* = \beta_1 + \beta_2 X_t^* + \varepsilon_t$$

$$y_1 = \beta_1 + \beta_2 X_1 + u_1 \quad | \cdot \sqrt{1 - \rho^2}$$

$$\sigma_u^2 = \text{Var}(\rho u_{t-1} + \varepsilon_t) = \rho^2 \sigma_u^2 + \sigma_\varepsilon^2 + 2\rho \text{Cov}(u_{t-1}, \varepsilon_t)$$

$$\sigma_u^2 = \frac{\sigma_\varepsilon^2}{1 - \rho^2} \quad (1 - \rho^2) \sigma_u^2 = \sigma_\varepsilon^2 \Rightarrow$$

3) MA(1) Transform:

$$\hat{\beta} = (X' \Omega^{-1} X)^{-1} X' \Omega^{-1} y \leftarrow \text{GLS}$$

$$\Omega = \begin{pmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix} \sigma_\varepsilon^2$$

$$\text{if } \Omega = \hat{\Omega} \Rightarrow \text{FGLS}$$

$$\hat{\beta} \xrightarrow{\text{OLS}} \beta = (X'X)^{-1} X'y \Rightarrow \text{OLS}$$

$$\Omega = \begin{pmatrix} x_1 & & 0 \\ & \ddots & \\ 0 & & x_n \end{pmatrix} \sigma_\varepsilon^2$$

$$\Downarrow$$

WLS

AR(1) in error term $\varepsilon_t = \rho \varepsilon_{t-1} + u_t$

$$\Omega = \frac{\sigma_\varepsilon^2}{1 - \rho^2} \begin{pmatrix} 1 & \rho & \dots & \rho^{n-1} \\ \rho & 1 & \ddots & \\ \vdots & \ddots & \ddots & \rho \\ \rho^{n-1} & \dots & \rho & 1 \end{pmatrix} \text{Cov}(\varepsilon_t, \varepsilon_{t-k})$$

$$= \frac{\sigma_\varepsilon^2}{1 - \rho^2}$$

MA(1)

$$\varepsilon_t = u_t + \rho u_{t-1}$$

$$\Omega = \sigma_{\varepsilon}^2 \begin{pmatrix} 1 & \rho & 0 & \dots & 0 \\ \rho & 1 & \rho & \dots & 0 \\ 0 & \rho & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & \rho & 1 \end{pmatrix}$$

$$\text{Var}(\varepsilon_t) = (1 + \rho^2) \sigma_{\varepsilon}^2$$

4) Adding lag of y_t

$$y_t = \beta_1 + \beta_2 x_t + \beta_3 \cdot y_{t-1} + u_t$$

$\rho u_{t-1} + \varepsilon_t$

Common Factor Test:

From CO transform:

$$y_t = \rho y_{t-1} + \beta_1 (1 - \rho) + \beta_2 (x_t - \rho \cdot x_{t-1}) + \varepsilon_t$$

$$y_t = \overset{\lambda_1}{\beta_1 (1 - \rho)} + \overset{\lambda_2}{\beta_2 x_t} - \overset{\lambda_3}{\rho \beta_2 \cdot x_{t-1}} + \overset{\lambda_4}{\rho y_{t-1}} + \varepsilon_t$$

↳ ARDL(1, 1) with restrictions:

$$\lambda_3 = -\lambda_2 \cdot \lambda_4$$

(non-linear restriction)

$$\Rightarrow n \cdot \log \frac{RSS_R}{RSS_u} \sim \chi^2_1$$

5) ARDL(p, q)

