

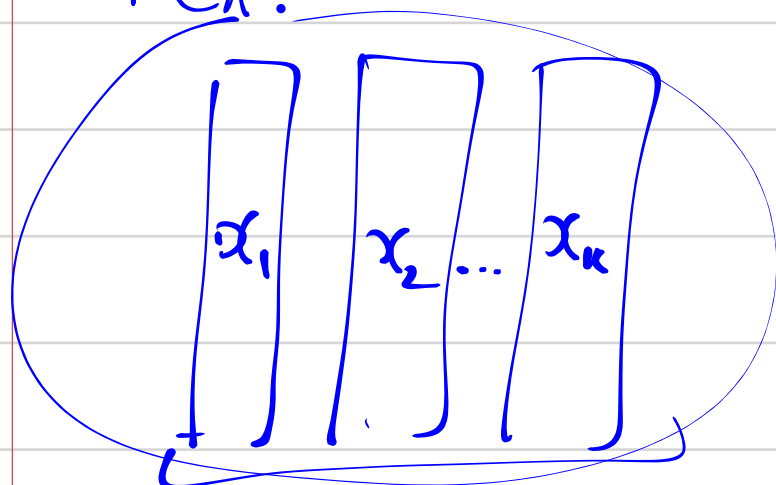
PCA + SVD

Principal Component Analysis.

4 views

- ① \rightarrow max var \leftarrow most popular
- ② \rightarrow min dist
- ③ \rightarrow max R^2 \leftarrow most intuitive
- ④ \rightarrow linear algebra view

PCA.

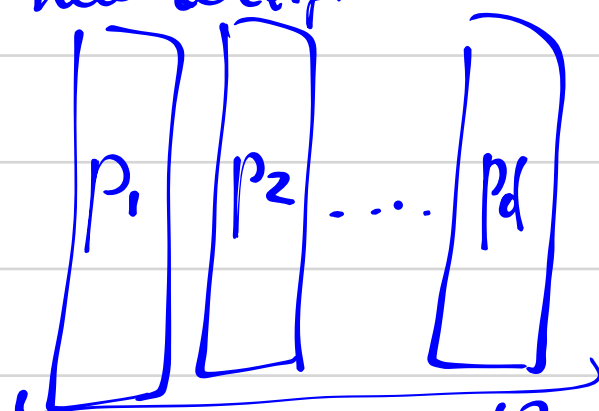


$X [n \times k]$

n -obs.
 k -predictors.

goal?

new artificial variables.



$P [n \times d]$

n -obs.
 d -number of
new vars.
 $d \leq k$

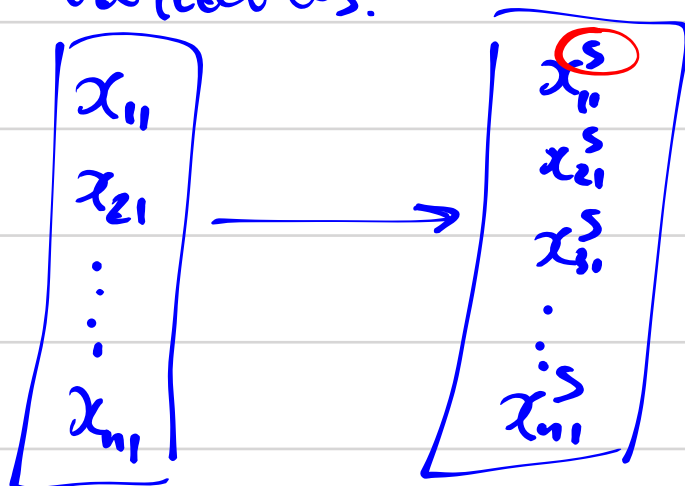
Informal

new variables should preserve as much info from original var-s as possible.

formal approach.

Idea 1

Remove units of meas-t of original variables.



$$se(x_j) = \sqrt{\frac{\sum_i (x_{ij} - \bar{x}_j)^2}{n-1}}$$

$$x_{ij}^s = \frac{x_{ij} - \bar{x}_j}{se(x_j)}$$

i -obs. no
 j -var. no

from now on we assume that
original variables are already
centered the ^{standard} superscript "s"

$\sum_{i=1}^n x_{ij} = 0$ $se(x_j) = 1$

$x_j = \begin{bmatrix} \vdots \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$

$X \xrightarrow{\text{create}} P$
 $[n \times k] \quad [n \times d]$
 $d \leq k$

max-var approach to PCA.

every new variable is a linear comb. n
of original **[stand]** variables.

$\begin{bmatrix} \vdots \\ p_1 \\ \vdots \end{bmatrix} = v_{11} \cdot \begin{bmatrix} \vdots \\ x_1 \\ \vdots \end{bmatrix} + v_{21} \cdot \begin{bmatrix} \vdots \\ x_2 \\ \vdots \end{bmatrix} + \dots + v_{k1} \cdot \begin{bmatrix} \vdots \\ x_k \\ \vdots \end{bmatrix}$

intuit

exam1 exam2

$\begin{bmatrix} 5 \\ 6 \\ 1 \\ 2 \\ 3 \end{bmatrix}$ $\begin{bmatrix} 2 \\ 2 \\ 2 \\ 2 \\ 2 \end{bmatrix}$

↑ ↑

some info no info

formally

$p_1 = X \cdot v_1$ $X [n \times k]$
 $v_1 [k \times 1]$

max sample variance (p_1)
 v_1
 subject to $\|v_1\| = 1$

$v_{11}^2 + v_{21}^2 + v_{31}^2 + \dots + v_{k1}^2 = 1$

As x_1, x_2, \dots, x_k are (already) centered
 and $p_1 = ?x_1 + ?x_2 + \dots + ?x_k$ p_1 is also centered
 $(\bar{p}_1 = 0)$

Step 1.

$$\max_{\|v_1\|=1} \|p_1\|^2$$

$$p_1 = X \cdot v_1$$

$$\max \|p_1\| \leftrightarrow \max x(p_1)$$
$$\max \text{share}(p_1)$$

first principal component!

Step 2

create

p_2

$$\max_{v_2} \|p_2\|^2$$

s.t.

$$\|v_2\|=1$$

and

$$p_2 = X \cdot v_2$$

$$v_2 \perp v_1$$

Step 3

create

p_3

$$\max_{v_3} \|p_3\|^2$$

s.t.

$$\|v_3\|=1$$

and

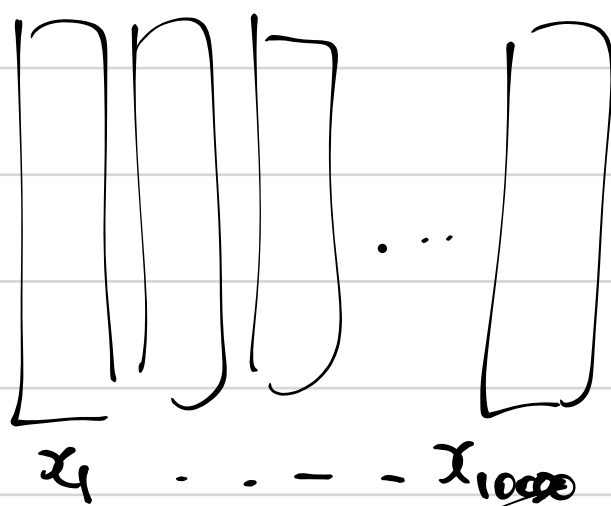
$$v_3 \perp v_1, v_2$$

$$p_3 = X \cdot v_3$$

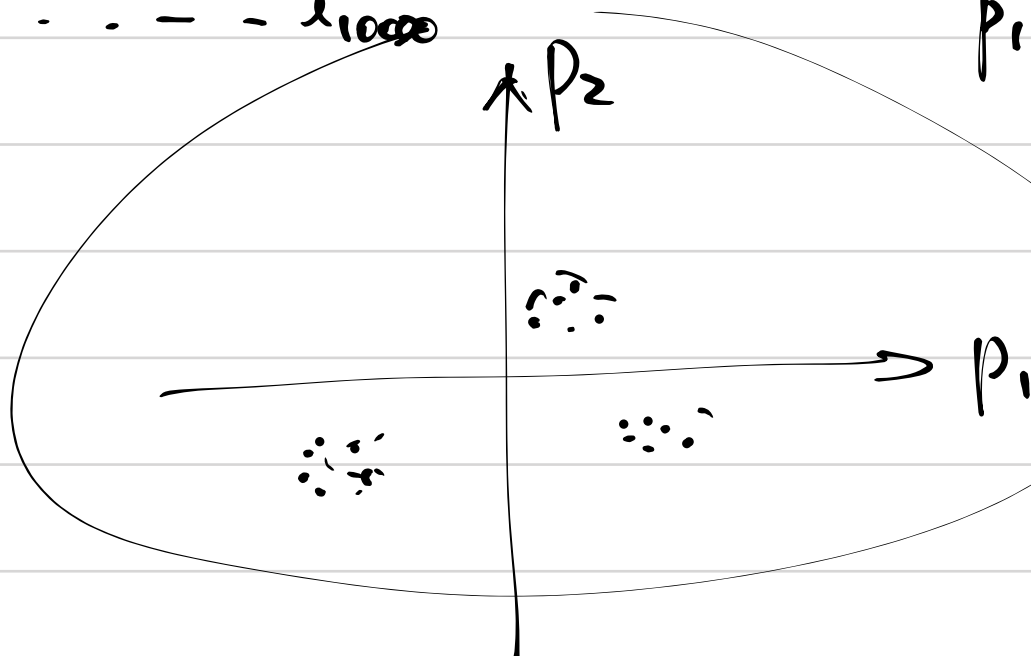
.....

What is the main use?

10000 vars.



PCA



⊕ visualize complex data

⊕ use forecasting algo -> that fail with too many variables

ℓ_X
 $n=3$
 $k=2$

$1/\sqrt{3}$	$1/3$
$1/\sqrt{3}$	$-2/3$
$-2/\sqrt{3}$	$1/\sqrt{3}$

unscaled

$$x_1 = \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}$$

$\bar{x}_1 = 0$

$$s(x_1) = \sqrt{\frac{1^2 + 1^2 + (-2)^2}{3-1}} = \sqrt{\frac{6}{2}} = \sqrt{3}$$

scaled orig. variables

find p_1 ?

$$p_1 = v_{11} \cdot \underbrace{\begin{pmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ -2/\sqrt{3} \end{pmatrix}}_{x_1} + v_{21} \cdot \underbrace{\begin{pmatrix} 1/\sqrt{3} \\ -2/\sqrt{3} \\ 1/\sqrt{3} \end{pmatrix}}_{x_2}$$

max $s^2(p_1)$
 v_1

max $\|p_1\|^2$
 $\|v_1\|=1$

$$\|p_1\|^2 = p_1^T \cdot p_1 = (v_{11} \cdot \underbrace{x_1^T} + v_{21} \cdot \underbrace{x_2^T}) \cdot (v_{11} \cdot \underbrace{x_1} + v_{21} \cdot \underbrace{x_2}) =$$

$$= v_{11}^2 \cdot \underbrace{x_1^T \cdot x_1}_{\|x_1\|^2} + v_{21}^2 \cdot \underbrace{x_2^T \cdot x_2}_{\|x_2\|^2} + 2v_{11}v_{21} \cdot \underbrace{x_1^T \cdot x_2}_{\|x_1\| \|x_2\| \cos \theta} =$$

$$x_1^T x_1 = \begin{pmatrix} 1/\sqrt{3} & 1/\sqrt{3} & -2/\sqrt{3} \end{pmatrix} \cdot \begin{pmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ -2/\sqrt{3} \end{pmatrix} = \frac{1}{3} + \frac{1}{3} + \frac{4}{3} = 2$$

$$x_1^T x_2 = \begin{pmatrix} 1/\sqrt{3} & 1/\sqrt{3} & -2/\sqrt{3} \end{pmatrix} \cdot \begin{pmatrix} 1/\sqrt{3} \\ -2/\sqrt{3} \\ 1/\sqrt{3} \end{pmatrix} = \frac{1}{3} - \frac{2}{3} - \frac{2}{3} = -1$$

$$\|p_1\|^2 = 2 \cdot v_{11}^2 + 2v_{21}^2 = 2 \cdot v_{11} \cdot v_{21} \rightarrow \max_{\|v_1\|=1}$$

? trick?

divide by v_{11}^2

$$\|v_1\|=1$$

$$v_{11}^2 + v_{21}^2 = 1$$

$$\|p\|^2 = 2 \cdot v_{11}^2 + 2 v_{21}^2 = 2 \cdot v_{11} \cdot v_{21} =$$

$$v_{11}^2 + v_{21}^2 = 1$$

$$= \underbrace{(v_{11}^2 + v_{21}^2)}_1 \cdot \left(2 - 2 \frac{v_{11} \cdot v_{21}}{v_{11}^2 + v_{21}^2} \right) =$$

$$= 2 - 2 \cdot \frac{v_{21}/v_{11}}{1 + \frac{v_{21}^2}{v_{11}^2}} =$$

$$\cdot / v_{11}^2$$

$$\frac{v_{21}}{v_{11}} = t$$

$$h(t) = 2 - 2 \frac{t}{1+t^2} \rightarrow \max_t$$

$$\max_t \frac{t}{1+t^2}$$

$$\left(\frac{t}{1+t^2} \right)' = \frac{1(1+t^2) - 2t \cdot t}{(1+t^2)^2} =$$

$$= \frac{1+t^2-2t^2}{(1+t^2)^2} = 0.$$

....

$$t=1$$

$$t=-1$$

opt.

$$t^* = -1$$

$$\frac{v_{21}}{v_{11}} = -1$$

$$v_{11}^2 + v_{21}^2 = 1$$

two optima:

$$\begin{cases} v_{11} = \frac{1}{\sqrt{2}} \\ v_{21} = -\frac{1}{\sqrt{2}} \end{cases}$$

$$\begin{cases} v_{11} = -\frac{1}{\sqrt{2}} \\ v_{21} = \frac{1}{\sqrt{2}} \end{cases}$$

$$p_1 = \frac{1}{\sqrt{2}} \cdot x_1 - \frac{1}{\sqrt{2}} \cdot x_2$$

$$\text{or } p_1 = -\frac{1}{\sqrt{2}} x_1 + \frac{1}{\sqrt{2}} x_2$$

geometry behind the first approach.

