

Commuter Tracking Sensor Network

Weekly Report - September 7th, 2014

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Project Website:

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Updated Milestone Chart

Milestone	Team Member in Charge	Modified Completion Date	Original Completion Date	Comments
5.1 Install software (Django, Apache, etc.)	Seth	6/21/2014	6/17/2014	COMPLETE Apache, Django, MariaDB are installed and ready to go.
6.1 Disable root login test	Seth	6/21/2014	6/16/2014	COMPLETE Done automatically when Raspbian was updated
6.2 Set the SSH port to a non-standard port test	Seth	6/21/2014	6/17/2014	COMPLETE SSH Port is set to 1315, not the default port of 22
7.1 Begin playing with Pixy Cam in USB tethered mode	Jared, Alex, Seth	7/11/2014	5/1/2014	COMPLETE We've all experimented and interfaced with the PixyCam now, and familiarized ourselves with its basic operation.
5.3 Install and configure fail2ban	Seth	9/1/2014	6/21/2014	COMPLETE
3.1 Breadboard prototyping	Alex	9/5/2014	6/1/2014	Started with half-wave rectifier circuit, and building up to the power amplification and conditioning circuit.
6.3 Disable password login test - must log in with SSH key	Alex, Jared, Seth	9/5/2014	6/21/2014	Not done yet. Jared still needs to generate keys.
6.5 Ping disabled test	Seth, Security Majors	9/5/2014	6/21/2014	DEFERRED While the server is on the RIT campus, this is completed since outsiders can not ping rit.edu. If the server moves off campus for whatever reason, this will need to be revisited
12.1 Create status webpage,	Seth	9/5/2014	9/5/2014	COMPLETE Status webpage that

hosted somewhere else				pings the gateway is functional. Its current hosted on one of Seth's pis, located at http://people.rit.edu/~srh7240/ctsn_status
10.1 Code Review for Pixy Software	Alex, Seth, Jared	9/8/2014	9/8/2014	COMPLETE Code review was completed. Information was documented regarding each file's contents.
10.2 Compile GCC version of Pixy software and note differences	Seth	9/8/2014	9/8/2014	DEFERRED According to the pixy cam developers, GCC version is not ready to use yet. That's fine though, we can use Keil instead, when the licensing update in the department is rolled out.
3.2 PCB design	Alex	9/12/2014	6/10/2014	Boost converter library for Eagle complete schematic development underway. Nick Conn has agreed to be a point of contact for us if we have difficulty. We have many other sources to make this work.
6.4 White Hat Hacker Test	Seth	9/18/2014	6/21/2014	Waiting for keys to be generated. Seth will talk with some people this week to see if anyone is willing to attempt to hack the server.
8.1 Use CAD tools to design sensor enclosure	Jared	9/19/2014	7/1/2014	Everything that is not dependent on the size of the custom PCB is complete. Awaiting dimensions to continue.
10.3 Train camera for identifying walkers, bikers, and horses	Seth	9/19/2014	8/1/2014	BLOCKED Currently blocked due to licensing issues. Keil license renewed, and awaiting system wide update in the department to continue development.
11. Database Creation		9/23/2014	9/14/2014	
11.1 Create mysql or mariadb database so data from trail can be saved to it	Jared	9/23/2014	9/5/2014	MariaDB is installed on the server, and is ready to go

12.3 Link to database	Jared, Alex	9/23/2014	9/21/2014	Database library is readily available and easily linkable through Django framework.
8.2 Use 3D printer to print the enclosures	Jared	9/26/2014	7/15/2014	
12. Website Creation		9/26/2014	9/28/2014	
12.2 Create front end	Jared, Alex	9/26/2014	9/14/2014	Stub Django project is installed on the server and ready to be modified.
16.2 Activate website	Team	9/29/2014	11/9/2014	
13. Website Testing (See Gantt Chart)	Team	9/30/2014	10/4/2014	
10. Sensor Software - Identify targets		10/1/2014	9/1/2014	
10.4 Train camera to figure out what direction the target is going	Seth	10/1/2014	9/1/2014	
3. Windbelt power module design		10/2/2014	6/18/2014	
3.3 Ship design for stamping	Alex	10/2/2014	6/18/2014	
4.1 Solder on components	Alex	10/3/2014	6/29/2014	
4. Windbelt power module construction and testing		10/6/2014	6/30/2014	
4.2 Continuity tests	Alex	10/6/2014	6/30/2014	
5. Server/Gateway setup	Seth	10/6/2014	7/1/2014	The server is a Raspberry Pi located at ctsn.student.rit.edu.

5.2 Interface XBee with Pi	Seth	10/6/2014	7/1/2014	The XBee did not arrive on time, so this slipped.
6. Server/Gateway testing		10/6/2014	7/1/2014	
2.1 Configure XBees for DigiMesh and have them communicating in close proximity	Seth, Jared	10/7/2014	6/1/2014	
8. Sensor Enclosure Design / Testing		10/8/2014	8/7/2014	
8.3 Test (See Gantt Chart)	Jared	10/8/2014	8/7/2014	
2.2 Range Test	Seth, Jared	10/9/2014	6/9/2014	
2. Networking Architecture Configuration and Testing		10/13/2014	6/15/2014	The XBees did not come in on time, so this had to be pushed back. All Raspberry Pis have software on them so they can use uart to communicate with the XBees when needed for testing purposes.
2.3 Small-scale trail deployment	Seth, Jared	10/13/2014	6/15/2014	
15. Computer Vision Testing (See Gantt Chart)	Alex, Seth	10/13/2014	10/28/2014	
14.1 Sensors communicate target data with each other	Seth	10/14/2014	10/4/2014	
7.2 Interface Pixy Cam with an XBee	Jared	10/22/2014	6/22/2014	
1. Contact Monroe County	Jared	10/28/2014	10/27/2014	Not a priority until we complete more of the technical requirements.

Discuss deployment options for sensor nodes.				
14. Target Data Communication		10/28/2014	10/5/2014	
14.2 Sensors can communicate and write target data to database	Seth	10/28/2014	10/5/2014	
9. Windbelt Testing (See Gantt Chart)	Alex	10/29/2014	5/27/2014	Frame and coil assemblies are complete for the 3rd Windbelt prototype. One coil is complete. Waiting for epoxy to cure completely before beginning second winding. Plan to test with one n=1000 coil to see how much AC voltage is generated prior to connecting a second coil in series. With the specifications being used, the windbelt should provide 3.3 VAC.
7. Sensor hardware testing and integration		10/31/2014	7/11/2014	
7.3 Integrate with existing power module	Jared, Alex	10/31/2014	7/11/2014	Will be done upon completion of the power module.
17.1 Advanced II integration testing with focus on single node in controlled environment	Team	11/5/2014		
17.2 Advanced II integration testing with focus on single node in an outdoor environment	Team	11/10/2014		

17.Integration Testing		11/13/2014		
17.3 Advanced II testing with focus on operation in outdoor environment for multiple nodes	Team	11/13/2014		
16. Deployment		11/17/2014	11/9/2014	
16.1 Deploy nodes on trail	Team	11/17/2014	11/5/2014	

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Status

Difficulties

Inductor coil assembly is a bit touchy, as epoxy between the plexiglass and ferrite core is taking extended periods to cure, despite the advertised bonding strength and drying time. The assembly was left to dry after being wound for the second time, since the plexiglass would come loose from the core during the winding process. Several applications of epoxy were attempted, since the first would not hold as the wire expanded around the core, and the previous applications had to be removed prior to repeated attempts. A vice was used to stabilize the assembly while it was drying, which had significantly better results than placing them under heavy objects.

From the software side of things, getting the compiler to work for the Pixy Cam has been bumpy. ARMCC, which is included with the Keil IDE in the CE department, will work, but there were licensing problems on the computers. In the meantime, there was an attempt to use GCC instead of ARMCC, however, GCC is not ready to be used on the Pixy cam according to the developers. Everything compiles fine, but the generated .hex file can not be flashed to the camera as of yet without error occurring. Once the Keil license is settled in the department, development on the Pixy cam can continue.

Surprises

Loctite epoxy does not cure to maximum psi as fast as advertised. It also smells like a sewer.

rit.edu is not pingable. This means that our router does not need to disable pinging, as RIT handles that for us.

Successes

AutoCad design is going smoothly. Awaiting PCB dimensions to continue.

Windbelt prototype construction is going fairly smoothly. The fourth prototype version increases the number of windings the coil by about 500. Two coils are placed in series, with $n=1000$ windings each. This design is proven to generate 3.3 VAC, which will be sufficient for the boost converter to power on. The windbelt frame is made out of 1" board, and design can be found at the following site: [Windbelt Prototype Drawings](#).

The status webpage the pings the CTSN server is up and running. It is located on one of Seth's Pis off campus. It can be reachable at http://people.rit.edu/~srh7240/ctsn_status. It is updated every minute. It shows "Ok" if the server is working fine.

Open Questions & Problems

The only problem we have right now is waiting for the Keil license in the department to be sorted out so development on the Pixy Cam can continue.

Gantt Chart

