Commuter Tracking Sensor Network

Weekly Report - October 19th, 2014

Team Members:

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Other Collaborators:

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Project Website:

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Updated Milestone Chart

| Milestone | Team Member in Charge | Modified Completion Date | Original Completion Date | Comments |
|---|--------------------------------|--------------------------------|--------------------------------|--|
| 1. Contact Monroe County Discuss deployment options for sensor nodes. | Jared | 10/28/2014 | 10/27/2014 | Not a priority until we complete more of the technical requirments. |
| 2. Networking Architecture Configuration and Testing | | 10/13/2014 | 6/15/2014 | |
| 2.1 Configure XBees for DigiMesh and have them communicating in close proximity | Seth, Jared | 10/16/2014 | 6/1/2014 | Done for now. Some additional configuration changes might need to be updated as more testing is done. |
| 2.2 Range Test | Seth, Jared | 10/25/2014 | 6/9/2014 | Waiting for the XBees to be interfaced with the Pi so this can be done easily. |
| 2.3 Small-scale trail deployment | Seth, Jared | 10/25/2014 | 6/15/2014 | Dependent on 2.1 and 2.2 |
| 3. Windbelt power module design | | 10/2/2014 | 6/18/2014 | |
| 3.1 Breadboard prototyping | Alex, Jared | 10/25/2014 | 6/1/2014 | BQ25504 appears to be working on the breadboard for the Windbelt configuration determined during transient simulation. Tuning to get levels that are more on par with what the simulation predicted. QFN to DIP converters for the secondary |

| | | | | boost converter and buck converter have been ordered. |
|---|----------------|------------|-----------|---|
| 3.2 PCB design | Alex | 10/25/2014 | 6/10/2014 | Prior to continuing with PCB design, breadboard prototyping should be completed. |
| 3.3 Ship design for stamping | Alex | 10/25/2014 | 6/18/2014 | 3.2 Must be completed first |
| 3.4 Spice Transient Analysis | Alex, Jared | 10/20/2014 | 9/22/2014 | COMPLETE Transient analysis is complete for both the buck and secondary boost converter. Levels are attainable for both the 6-10V unregulated (Pixy) and 3-3.3V regulated (XBee) ranges. |
| 4. Windbelt power module construction and testing | | 10/22/2014 | 6/30/2014 | |
| 4.1 Solder on components | Alex | 11/14/2014 | 6/29/2014 | These got pushed back since they require a 2 week shipment turnaround time. 3.3 Must be completed first. |
| 4.2 Continuity tests | Alex | 11/14/2014 | 6/30/2014 | These got pushed back since they require a 2 week shipment turnaournd time. Can be done at same time as 4.1 |
| 5. Server/Gateway setup | Seth | 10/10/2014 | 7/1/2014 | The server is a Raspberry Pi located at ctsn.student.rit.edu. |
| 5.1 Install software (Django, Apache, etc.) | Seth | 6/21/2014 | 6/17/2014 | COMPLETE Apache, Django, MariaDB are installed and ready to go. |
| 5.2 Interface XBee with Pi | Seth | 10/22/2014 | 7/1/2014 | In progress. Right now, raw packets are able to be sent between the XBees, but these packets must be parsed so the message can be received. This was unforseen, and therefore the day was pushed back |

| 5.3 Install and configure fail2ban | Seth | 9/1/2014 | 6/21/2014 | COMPLETE |
|---|-----------------------------|------------|-----------|---|
| 6. Server/Gateway testing | | 10/12/2014 | 7/1/2014 | COMPLETE |
| 6.1 Disable root login test | Seth | 6/21/2014 | 6/16/2014 | COMPLETE Done automatically when Raspbian was updated |
| 6.2 Set the SSH port to a non-standard port test | Seth | 6/21/2014 | 6/17/2014 | COMPLETE SSH Port is set to 1315, not the default port of 22 |
| 6.3 Disable password login test - must log in with SSH key | | 9/5/2014 | 6/21/2014 | COMPLETE SSH Keys are required to login to the server via SSH |
| 6.4 White Hat Hacker Test | Seth | 10/12/2014 | 6/21/2014 | COMPLETE. They could not access the server via ssh, get a root shell, or access the database directly. Jared (security major) will be providing a formal report of the pen test results. We will be able to fortify security based on the results |
| 6.5 Ping disabled test | Seth, Security Majors | 10/31/2014 | 6/21/2014 | DEFERRED While the server is on the RIT campus, this is completed since outsiders can not ping rit.edu If the server moves of campus for whatever reason, this will need to be revisited |
| 7. Sensor hardware testing and integration | | 10/31/2014 | 7/11/2014 | |
| 7.1 Begin playing with Pixy Cam in USB tethered mode | Jared, Alex, Seth | 7/11/2014 | 5/1/2014 | COMPLETE We've all experimented and interfaced with the PixyCam now, and familiarized ourselves with its basic operation. |
| 7.2 Interface Pixy Cam with an XBee | Jared, Alex | 10/31/2014 | 6/22/2014 | Antennas are in. Dependent on 2.2 |

| | T | | | |
|--|-------------------------|------------|-----------|---|
| 7.3 Integrate with existing power | Jared, | | | Will be done upon completion of 3.1 |
| module | Alex | 10/31/2014 | 7/11/2014 | |
| 8. Sensor | | | | |
| Enclosure Design / | | | | |
| Testing | | 10/31/2014 | 8/7/2014 | |
| 8.1 Use CAD tools to design sensor enclosure | Jared | 10/24/2014 | 7/1/2014 | This is no longer blocked. This process can continue taking into account the largest board size available through the evaluation version of EAGLE. |
| 8.2 Use 3D printer to | | | | 8.1 Must be done first |
| print the enclosures | Jared | 10/29/2014 | 7/15/2014 | |
| 8.3 Test (See Gantt Chart) | Jared | 10/31/2014 | 8/7/2014 | Dependent on 8.2 |
| 9. Windbelt Testing (See Gantt Chart) | Alex | 11/5/2014 | 5/27/2014 | Once BQ25504 device is working as predicted in simulation, it will be connected to the windbelt and tested outdoors. The same will be done for the secondary boost and buck converters. |
| 10. Sensor Software - Identify targets | | 10/24/2014 | 9/1/2014 | |
| 10.1 Code Review for Pixy Software | Alex, Seth, Jared | 9/8/2014 | 9/8/2014 | COMPLETE Code review was completed. Information was documented regarding each file's contents. |
| 10.2 Compile GCC version of Pixy software and note differences | | | 9/8/2014 | No longer a requirement. Keil will work just fine. |
| 10.3 Train camera for identifying walkers, bikers, and horses | Jared | 10/31/2014 | 8/1/2014 | Jared has been playing with various algorithms on his computer at home with a webcam. The code location in the Pixy cam firmware |

| | | | | where to inject the algorithm has been located. |
|--|---------------|------------|-----------|---|
| 10.4 Train camera to figure out what direction the target is going | Jared | 10/31/2014 | 9/1/2014 | 10.3 and 10.4 are not dependent on one another. These two tasks should be completed in parallel. |
| 11. Database | | | | |
| Creation | | 9/23/2014 | 9/14/2014 | |
| 11.1 Create mysql or mariadb database so data from trail can be saved to it | Seth | 10/31/2014 | 9/5/2014 | The rest of this can be completed in parallel with the CV algorihms. Need to know what data needs to be saved to the database resultant of the CV algorithms. |
| 12. Website Creation | | 9/26/2014 | 9/28/2014 | Front end is complete, but there may need to be some work done on the backend down-the-road when nodes need to send data to the database |
| 12.1 Create status webpage, hosted somewhere else | Seth | 9/5/2014 | 9/5/2014 | COMPLETE Status webpage that pings the gateway is functional. Its currently hosted on one of Seth's pis, located at http://people.rit.edu/~srh7240/ctsn_status. |
| 12.2 Create web front end | Seth, Alex | 10/31/2014 | 9/14/2014 | Front end is COMPLETE. Data results from the CV algorithms mus be identified and linked to the database to render on the webpage. |
| 12.3 Link website to database | Seth | 10/31/2014 | 9/21/2014 | Done for now. There will need to be some work done once the nodes need to save data to the database. |
| 13. Website Testing (See Gantt Chart) | Team | 10/12/2014 | 10/4/2014 | COMPLETE. Jared (security major) will be providing a formal report of the pen test results. We will be able to |

| | | | | fortify security based on the results |
|--|---------------|------------|------------|---|
| 14. Target Data Communication | | 10/28/2014 | 10/5/2014 | |
| 14.1 Sensors communicate target data with each other | Seth, Alex | | 10/4/2014 | Dependent on 7.2 |
| 14.2 Sensors can communicate and write target data to database | Seth | 11/7/2014 | 10/5/2014 | Dependent on 7.2 |
| 15. Computer Vision Testing (See Gantt Chart) | | 11/1/2014 | 10/28/2014 | Dependent on 10.3 and 10.4 |
| 16. Deployment | | 11/17/2014 | 11/9/2014 | |
| 16.1 Deploy nodes on trail | Team | 11/17/2014 | 11/5/2014 | |
| 16.2 Activate website | Team | 9/27/2014 | 11/9/2014 | Complete. Website is located at http://ctsn.student.rit.edu:1415 (login required) |
| 17.Integration Testing | | 11/13/2014 | | |
| 17.1 Advanced II integration testing with focus on single node in controlled environment | Team | 11/5/2014 | | |
| 17.2 Advanced II integration testing with focus on single node in an outdoor environment | Team | 11/10/2014 | | |
| 17.3 Advanced II testing with focus on operation in outdoor | Team | 11/13/2014 | | |

| environment for | | |
|-----------------|--|--|
| multiple nodes | | |

Current Milestones

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Status

Difficulties

The boost converter is giving higher than expected values at the VBAT pin. The theory is that ground levels are unbalanced across the chip. Further research has shown that one of the ground pins actually should be taking signal ground as opposed to general ground. Making this change should allow us to see behavior comparable to that in the simulations.

Surprises

The XBees are a bit more difficult to work with than originally thought. In order to use them, the characters that are sent over uart need to be in a packet from. Our code not only needs to put messages into this form, but also needs to parse the packets to get the actual message. Things get more difficult since the Pi's Uart only receives 8 characters at a time. Luckily, code has been written for the parsing. It acts like a state machine. Now the code just needs to be plugged into what already exists.

For a bit, the XBee was not able to send or receive characters over Uart when connected to the Pi, but an XBee with almost the same configuration was able to when connected via USB to a computer. The problem was the XBee's ground and the Pi's ground were completely different, by about 300 mV. After connecting the two grounds, everything finally worked.

Successes

We were able to get the XBees communicating with each other over a small range in lab. However, as mentioned, parsing of the sent packets needs to be done, which has been started, but is not complete yet.

The boost converter soldering went well. There are no shorts across the chip.

Gantt Chart

