信息科学与技术学院 SCHOOL OF INFORMATION SCIENCE&TECHNOLOGY





计算机视觉

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Lp相似度

```
def LpS(X, Y, p = 2.0 ):
    x = np.float64(X.reshape(-1))
    y = np.float64(Y.reshape(-1))
    n = len(x)
    return 1.0-np.linalg.norm(x-y,p)/255.0/n**(1.0/p)
```

差相似度

```
def diffS(X, Y):
    x = np.float64(X.reshape(-1))
    y = np.float64(Y.reshape(-1))
    n = len(x)
    return 1.0-np.abs(np.sum(x-y))/255.0/n
```



余弦相似度

```
def cosin(X, Y):
    r""" Calculate cosin Similarity for X and Y
    Args:
        X (np.float64): images
        Y (np.float64): images
    Returns:
        np.float64: cosin results.
    .....
    vector_a = np.float64(X.reshape(-1))
    vector b = np.float64(Y.reshape(-1))
    num = np.dot(vector_a , vector_b)
    denom = np.linalg.norm(vector_a) * np.linalg.norm(vector_b)
    sim = num / denom
    return sim
```



谷本(Tanimoto)相似度

```
def Tanimoto(X, Y):
    vector_a = np.float64(X.reshape(-1))
    vector_b = np.float64(Y.reshape(-1))
    num = np.dot(vector_a , vector_b)
    denom = np.dot(vector_a , vector_a)+np.dot(vector_b , vector_b)-num
    sim = num / denom
    return sim
```



皮尔逊(Pearson)相似度

```
def correlationN(X, Y):
    x = np.float64(X.reshape(-1))
    y = np.float64(Y.reshape(-1))
    return np.corrcoef(x,y)[0,1]
```



结构相似度(SSIM)

```
def ssim(X, Y, data_range=255.0, K=(0.01, 0.03)):
    r""" Calculate ssim index for X and Y
   Args:
       X (np.float64): images
       Y (np.float64): images
       data_range (float or int, optional): value range of input images. (usually 1.0 or 255)
    Returns:
       np.float64: ssim results.
   K1, K2 = K
   # batch, width = X.shape
   C1 = (K1 * data range) ** 2
   C2 = (K2 * data range) ** 2
   mu1 = np.mean(X)
   mu2 = np.mean(Y)
   mu1_sq = mu1**2
   mu2 sq = mu2**2
   mu12 = mu1 * mu2
   sigma1_sq = np.mean((X - mu1_sq)**2)
   sigma2_sq = np.mean((Y - mu2_sq)**2)
   sigma12 = np.mean((X - mu1 sq)*(Y - mu2 sq))
   cs_ = (2 * sigma12 + C2) / (sigma1_sq + sigma2_sq + C2) # set alpha=beta=gamma=1
    ssim = ((2 * mu12 + C1) / (mu1 sq + mu2 sq + C1)) * cs
    return ssim
```

平均结构相似度(MSSIM)

```
def Mssim(img1, img2):
   # img1=cv2.cvtColor(img1, cv2.COLOR BGR2GRAY)
   # img2=cv2.cvtColor(img2, cv2.COLOR BGR2GRAY)
   C1 = (0.01 * 255)**2
   C2 = (0.03 * 255)**2
   img1 = img1.astype(np.float64)
   img2 = img2.astype(np.float64)
   hws=5#half win size
   sigma=0.3*hws#(0.3*(hws-1)+0.8)
   kernel = cv2.getGaussianKernel(hws*2+1, sigma)
   window = np.outer(kernel, kernel.transpose())
   mu1 = cv2.filter2D(img1, -1, window)[hws:-hws, hws:-hws] # valid
   mu2 = cv2.filter2D(img2, -1, window)[hws:-hws, hws:-hws]
   mu1 sq = mu1**2
   mu2 sq = mu2**2
   mu1 mu2 = mu1 * mu2
   sigma1 sq = cv2.filter2D(img1**2, -1, window)[hws:-hws, hws:-hws] - mu1 sq
   sigma2 sq = cv2.filter2D(img2**2, -1, window)[hws:-hws, hws:-hws] - mu2 sq
   sigma12 = cv2.filter2D(img1 * img2, -1, window)[hws:-hws, hws:-hws] - mu1_mu2
   ssim map = ((2 * mu1 mu2 + C1) * (2 * sigma12 + C2)) / ((mu1 sq + mu2 sq + C1) *
   (sigma1 sq + sigma2 sq + C2))
   return ssim map.mean()
```



峰值信噪比(PSNR)

```
def psnr(X, Y):
   x = np.float64(X.reshape(-1))
    y = np.float64(Y.reshape(-1))
    mse = np.mean((x/255 - y/255) ** 2)
    if mse < 1.0e-10:
        return 100
    return 10 * math.log10(1.0**2/mse)
```



获取直方图、显示结果

```
def GrayHist(img):
    grayHist = np.zeros(256,dtype=np.uint64)
    for v in range(256):
        grayHist[v] = np.sum(img==v)
    return grayHist
def showHistResult(hist1,hist2):
    plt.plot(hist1, color = 'b')
    plt.plot(hist2, color = 'r')
    plt.xlim(0,256)
    plt.ylim(0,max(np.amax(hist1),np.amax(hist2)))
    plt.xticks([])
    plt.show()
```



Lp相似度 for 直方图

```
def LpS(X, Y, p = 2.0 ):
    x = np.float64(X.reshape(-1))
    y = np.float64(Y.reshape(-1))
    n = len(x)
    x = x/np.sum(x)
    y = y/np.sum(y)
    return 1.0-np.linalg.norm(x-y,p)/2**(1.0/p)
```



SIFT特征匹配

◆ 参考

https://blog.csdn.net/wu_zhiyuan/article/details/ /126028766

https://www.freesion.com/article/7751388844/



◆ 接下来的时间: 上机实验并完成实验报告

- 一、实验内容。
- 【1】选 2-3 组图片,使用基于模版的像素匹配定位图片,用 3-5 种相似性度量,需要输出定位时的相似度。
- 【2】选 1-2 组图片,使用基于模版的直方图匹配定位图片,用 3-5 种相似性度量,需要输出定位时的相似度。。
- 【3】选 1-2 组图片,用 SIFT 或者其他特征匹配方法定位图片,可尝试输出基于特征点的匹配程度(距离或相似度)。。

