# Types and Programming Language Project Report\*

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# Introduction

In current Internet environment, users tend to share more personal data online. This phenomenon makes it increasingly important for applications to protect confidentiality. For existing approaches to achieve privacy control, programmers are forced to ensure compliance by their own efforts, even when both the application and the policies may be evolving rapidly. This can cause considerable burdens to application developers.

This academic paper, called A Language for Automatically Enforcing Privacy Policies.<sup>1</sup>, proposes a new programming model that makes the system responsible for automatically producing outputs consistent with programmer-specified policies. This automation makes it easier for programmers to enforce policies specifying how each sensitive value should be displayed in a given context, therefore solves the problem mentioned above. Furthermore, they have implemented this programming model in a new functional constraint language named **Jeeves**.

We carried out our course project based on this paper. More specifically, we first read and comprehended this paper, including the language design, the semantics, the evaluation and typing rules, the partial property proof and the implementation details as we did in our class. Then we proved the progress and preservation parts which is left out in the paper by ourselves. Finally, we successfully run the implementation codes provided by the authors and wrote our own use cases to understand the implementation details.

# 1 Language Design

#### 1.1 Jeeves

Jeeves allows the programmer to specify policies explicitly and upon data creation rather than implicitly across the code base. The Jeeves system trusts the programmer to correctly specify policies describing high- and low-confidentiality views of sensitive values and to correctly provide context values characterizing output channels. Figure 1 shows the jeeves syntax, which looks like a high-level language since it's based on and translated from  $\lambda_{\rm J}$  described in next subsection.

Several key words in this syntax tell what Jeeves wants to do and what it is capable of doing.

• Level provides variables the means of abstraction to specify policies incrementally and independently of the sensitive value declaration. Level variables can be constrained directly (by explicitly passing around a level variable) or indirectly (by constraining another level variable when there is a dependency).

<sup>\*</sup>done at June 5th, 2016

 $<sup>^{1}</sup>$ http://www.cs.cmu.edu/ jyang2/papers/popl088-yang.pdf

- Policies, introduced through policy expressions, provide declarative rules describing when to set a level variable to top or bottom.
- Context construct relieves the programmer of the burden of structuring code to propagate values from the output context to the policies. Statements such as print that release information to the viewer require a context parameter.

```
 \begin{array}{lll} Level & ::= & \perp \mid \top \\ Exp & ::= & v \mid Exp_1 \; (op) \; Exp_2 \\ & \mid \; \mathbf{if} \; Exp_1 \; \mathbf{then} \; Exp_t \; \mathbf{else} \; Exp_f \\ & \mid \; Exp_1 \; Exp_2 \\ & \mid \; \langle Exp_{\perp} \mid Exp_{\top} \rangle \left( \ell \right) \\ & \mid \; \mathbf{level} \; \ell \; \mathbf{in} \; Exp \\ & \mid \; \mathbf{policy} \; \ell : \; Exp_p \; \mathbf{then} \; Level \; \mathbf{in} \; Exp \\ Stmt \; ::= & \quad \mathbf{let} \; x : \tau \; = \; Exp \\ & \mid \; \mathbf{print} \; \{Exp_c\} \; Exp \end{array}
```

Figure 1: Jeeves syntax

#### 1.2 Lambda J

One interesting thing is the authors don't formally implement Jeeves from the scratch. Instead, they introduce  $\lambda_J$ , a simple constraint functional language based on the  $\lambda$ -calculus, and then they show how to translate Jeeves from  $\lambda_J$ . Here we describe the  $\lambda_J$  language show in Figure 2.

Basically, The  $\lambda_J$  language extends the  $\lambda$ -calculus with logical variables. Expressions (e) include the standard  $\lambda$  expressions extended with the **defer** construct for introducing logic variables, the **assert** construct for introducing constraints, and the **concretize** construct for producing concrete values consistent with the constraints.  $\lambda_J$  evaluation produces irreducible values (v), which are either concrete (c) or symbolic  $(\sigma)$ . Concrete values are what one would expect from  $\lambda$ -calculus, while symbolic values are values that cannot be reduced further due to the presence of logic variables. Symbolic values also include the **context** construct which allows constraints to refer to a value supplied at concretization time. The context variable is an implicit parameter provided in the **concretize** expression. In the semantics we model the behavior of the context variable as a symbolic value that is constrained during evaluation of concretize.  $\lambda_J$  contains a **let** rec construct that handles recursive functions in the standard way using **fix**.

A novel feature of  $\lambda_J$  is that logic variables are also associated with a default value that serves as a default assumption: this is the assigned value for the logic variable unless it is inconsistent with the constraints. The purpose of default values is to provide some determinism when logic variables are underconstrained.

#### 2 Semantics

Here is the semantics...

```
n \mid b \mid \lambda x : \tau . e \mid record \ x \overline{:} v
           | error | ()
              x \mid \mathbf{contex} \ \tau
\sigma ::=
           \mid c_1 (op) \sigma_2 \mid \sigma_1 (op) c_2 \mid
           \mid \sigma_1 (op) \sigma_2 \mid
           | if \sigma then v_t else v_f
v ::= c \mid \sigma
             v \mid e_1 \ (op) \ e_2
e ::=
           | if e_1 then e_t else e_f | e_1 e_2
           | let x : \tau = e_1 in e_2
           | let rec f: \tau = e_1 in e_2
             defer x : \tau\{e\} defaut v_d
              assert e
              concretize e with v_c
```

Figure 2:  $\lambda_{\rm J}$  syntax

# 3 Properties

**Lemma 1.** (ConcreteFunction). if v is a value of type  $\tau_1 \to \tau_2$ , then  $v = \lambda x : \tau_1.e$ , where e has type  $\tau_2$ .

*Proof.* According to the  $\lambda_{\rm J}$  syntax, we can get Lemma 1 immediately.

**Theorem 1.** (Progress). Suppose e is a closed, well-typed expression. Then e is either a value v or there is some e' such that  $\vdash \langle \Sigma, \Delta, e \rangle \to \langle \Sigma', \Delta', e' \rangle$ .

*Proof.* According to the dynamic demantics 3 and static semantics 5 of  $\lambda_{\rm J}$ , we will proof that any  $\lambda_{\rm J}$  program holds the *progress* property by structral induction over the syntax of  $\lambda_{\rm J}$ . According to Figure 2, there are nine kinds of expressions including the value expression v. Next we discuss each of them respectively.

- For the value expression v, according to the definition we can conclude that it holds the property immediately.
- For the expression  $e_1$  (op)  $e_2$ , according to the hyposthesis, we know that subexpression  $e_1$  and  $e_2$  are both closed and well-typed expressions. Thus if  $e_1$  is not a value, according to E-OP1, there must be a expression  $e'_1$  such that  $e_1 \to e'_1$ . Therefore the expression  $e_1$  (op)  $e_2$  can be reduced to  $e'_1$  (op)  $e_2$ , and the same as if the  $e_1$  is already a value but  $e_2$  is not according to E-OP2. While if both  $e_1$ and  $e_2$  are values, we know that  $e_1$  (op)  $e_2$  is a value as well. Let  $c = e_1$  (op)  $e_2$ , according to E-OP,  $\vdash \langle \Sigma, \Delta, e_1 \ (op) \ e_2 \rangle \to \langle \Sigma', \Delta', c \rangle$ . Hence, we can conclude that expression  $e_1$  (op)  $e_2$  holds the progress property.
- For the expression if  $e_1$  then  $e_t$  else  $e_f$ , the conditional expression  $e_1$  is a either a **concrete** expression or a **symbolic** expression. If expression  $e_1$  is **concrete** and not a value, according to E-COND, there must be an expression  $e'_1$  such

```
\mathscr{G} \vdash \langle \Sigma, \Delta, e \rangle \rightarrow \left\langle \Sigma', \Delta', e' \right\rangle
                                                                  \frac{\mathscr{G} \vdash \langle \Sigma, \Delta, e_1 \rangle \rightarrow \left\langle \Sigma', \Delta', e_1' \right\rangle}{\mathscr{G} \vdash \langle \Sigma, \Delta, e_1 \ e_2 \rangle \rightarrow \left\langle \Sigma', \Delta', e_1' \ e_2 \right\rangle} \quad \text{E-APP1} \quad \frac{\mathscr{G} \vdash \left\langle \Sigma, \Delta, e_2 \right\rangle \rightarrow \left\langle \Sigma', \Delta', e_2' \right\rangle}{\mathscr{G} \vdash \left\langle \Sigma, \Delta, v \ e_2 \right\rangle \rightarrow \left\langle \Sigma', \Delta', v \ e_2 \right\rangle}
                                                                                                                                                                                                                                                                                                                                                                                                        E-APP2
                                                                                                                                                                        E-APPLAMBDA \frac{c' = c_1 \ (op) \ c_2}{\mathscr{G} \vdash \langle \Sigma, \Delta, c_1 \ (op) \ c_2 \rangle \rightarrow \langle \Sigma', \Delta', c' \rangle}
                                                                                                                                                                                                                                                                                                                                                                                                                 E-OP
                    \overline{\mathscr{G} \vdash \langle \Sigma, \Delta, \lambda x. e \ \upsilon \rangle \rightarrow \langle \Sigma', \Delta', e[x \mapsto \upsilon] \rangle}
\frac{\mathscr{G} \vdash \langle \Sigma, \Delta, e_1 \rangle \rightarrow \left\langle \Sigma', \Delta', e_1' \right\rangle}{\mathscr{G} \vdash \langle \Sigma, \Delta, e_1 \ (op) \ e_2 \rangle \rightarrow \left\langle \Sigma', \Delta', e_1' \ (op) \ e_2 \right\rangle}
                                                                                                                                                                                   E-OP1 \frac{\mathscr{G} \vdash \langle \Sigma, \Delta, e_2 \rangle \rightarrow \left\langle \Sigma', \Delta', e_2' \right\rangle}{\mathscr{G} \vdash \left\langle \Sigma, \Delta, \upsilon \right. \left(op\right) \left. e_2 \right\rangle \rightarrow \left\langle \Sigma', \Delta', \upsilon \right. \left(op\right) \left. e_2' \right\rangle}
                                                                                                                                                                                                                                                                                                                                                                                                                E-OP2
                                                                                                       \frac{\mathscr{G} \vdash \langle \Sigma, \Delta, e_c \rangle \rightarrow \langle \Sigma', \Delta', e_c' \rangle}{\mathscr{G} \vdash \left\langle \Sigma, \Delta, \text{if } e_c \text{ then } e_t \text{ else } e_f \right\rangle \rightarrow \left\langle \Sigma', \Delta', \text{if } e_c' \text{ then } e_t \text{ else } e_f \right\rangle}
                                                                                                                                                                                                                                                                                                                                                                                                       E-COND
                                                                                                                                                        \frac{\mathscr{G} \vdash \langle \Sigma, \Delta, e_t \rangle \rightarrow \langle \Sigma', \Delta', e_t' \rangle}{\mathscr{G} \vdash \left\langle \Sigma, \Delta, \text{if true then } e_t \text{ else } e_f \right\rangle \rightarrow \left\langle \Sigma', \Delta', e_t' \right\rangle}
                                                                                                                                                                                                                                                                                                                                                                           E-CONDTRUE
                                                                                                                                               \frac{\mathscr{G} \vdash \left\langle \Sigma, \Delta, e_f \right\rangle \rightarrow \left\langle \Sigma', \Delta', e_f' \right\rangle}{\mathscr{G} \vdash \left\langle \Sigma, \Delta, \text{if false then } e_t \text{ else } e_f \right\rangle \rightarrow \left\langle \Sigma', \Delta', e_f' \right\rangle}
                                                                                                                                                                                                                                                                                                                                                                         E-CONDFALSE
                                                                                  \frac{\mathscr{G} \vdash \langle \Sigma, \Delta, e_t \rangle \rightarrow \langle \Sigma', \Delta', e_t' \rangle}{\mathscr{G} \vdash \left\langle \Sigma, \Delta, \mathbf{if} \ \sigma \ \mathbf{then} \ e_t \ \mathbf{else} \ e_f \right\rangle \rightarrow \left\langle \Sigma', \Delta', \mathbf{if} \ \sigma \ \mathbf{then} \ e_t' \ \mathbf{else} \ e_f \right\rangle}
                                                                                                                                                                                                                                                                                                                                                                           E-CONDSYMT
                                                                                  \frac{\mathscr{G} \vdash \left\langle \Sigma, \Delta, e_f \right\rangle \rightarrow \left\langle \Sigma', \Delta', e_f' \right\rangle}{\mathscr{G} \vdash \left\langle \Sigma, \Delta, \text{if } \sigma \text{ then } v_t \text{ else } e_f' \right\rangle \rightarrow \left\langle \Sigma', \Delta', \text{if } \sigma \text{ then } v_t \text{ else } e_f' \right\rangle}
                                                                                                                                                                                                                                                                                                                                                                           E-CONDSYMF
         \frac{\mathscr{G} \vdash \langle \Sigma, \Delta, e \rangle \rightarrow \langle \Sigma', \Delta', e' \rangle}{\mathscr{G} \vdash \langle \Sigma, \Delta, \mathbf{defer} \ x : \tau\{e\} \ \mathbf{default} \ v_d \rangle \rightarrow \langle \Sigma', \Delta', \mathbf{defer} \ x : \tau\{e'\} \ \mathbf{default} \ v_d \rangle}
                                                                                                                                                                                                                                                                                                                             E-DEFERCONSTRAINT
                                                   \frac{fresh\ x'}{\mathscr{G}\vdash \langle \Sigma, \Delta, \mathbf{defer}\ x:\tau\{e\}\ \mathbf{default}\ v_d\rangle \rightarrow \langle \Sigma\cup \{\mathscr{G}\Rightarrow v_c[x\mapsto x']\}, \Delta\cup \{\mathscr{G}\Rightarrow x'=v_d\}, x'\rangle}
                                                                                                                                                                                                                                                                                                                                                                                                 E-DEFER
                                                                                                                                               \frac{\mathscr{G} \vdash \langle \Sigma, \Delta, e \rangle {\rightarrow} \langle \Sigma', \Delta', e' \rangle}{\mathscr{G} \vdash \langle \Sigma, \Delta, \mathbf{assert} \ e \rangle {\rightarrow} \langle \Sigma', \Delta', \mathbf{assert} \ e' \rangle}
                                                                                                                                                                                                                                                                                                                            E-ASSERTCONSTRAINT
                                                                                                                                                                                                                                                                                                                                                                                              E-ASSERT
                                                                                                                                                                                                               \mathscr{G} \vdash \langle \Sigma, \Delta, \mathbf{assert} \ v \rangle \rightarrow \langle \Sigma \cup \{\mathscr{G} \Rightarrow v\}, \Delta, () \rangle
                                            \frac{\mathscr{G} \vdash \langle \Sigma, \Delta, e \rangle \rightarrow \langle \Sigma', \Delta', e' \rangle}{\mathscr{G} \vdash \langle \Sigma, \Delta, \mathbf{concretize} \ e \ \mathbf{with} \ \upsilon_c \rangle \rightarrow \langle \Sigma', \Delta', \mathbf{concretize} \ e' \ \mathbf{with} \ \upsilon_c \rangle}
                                                                                                                                                                                                                                                                                                                                               E-CONCRETIZEEXP
                                                                                                          \frac{\text{MODLE}(\Delta, \Sigma \cup \{\mathscr{G} \cap \mathbf{context} = v_c\}) = \mathscr{M} \quad c = \mathscr{M}[[v_{\nu}]]}{\mathscr{G} \vdash \langle \Sigma, \Delta, \mathbf{concretize} \ v_{\nu} \ \mathbf{with} \ v_c \rangle \rightarrow \langle \Sigma, \Delta, c \rangle}
                                                                                                                                                                                                                                                                                                                                                 E-CONCRETIZESAT
                                                                                                                    MODLE(\Delta,\Sigma \cup \{\mathscr{G} \cap \mathbf{context} = v_c\}) = UNSAT
                                                                                                                                                                                                                                                                                                                                    E-CONCRETIZEUNSAT
                                                                                                          \mathscr{G} \vdash \langle \Sigma, \Delta, \mathbf{concretize} \ \upsilon_{\nu} \ \mathbf{with} \ \upsilon_{c} \rangle \rightarrow \langle \Sigma, \Delta, \mathbf{error} \rangle
```

Figure 3: Dynamic semantics for  $\lambda_{\rm J}$ .

```
\delta ::= \mathbf{concretize} \mid \mathbf{sym} determinism tag
\beta ::= \mathbf{int}_c \mid \mathbf{bool}_c \mid \mathbf{unit} \mid \mathbf{int} \mid \mathbf{bool} base type
\tau ::= \beta \mid \tau_1 \xrightarrow{nr} \tau_2 \mid \tau_1 \to \tau_2 type
```

Figure 4:  $\lambda_{\rm J}$  types

```
\tau_1 <: \tau_2
                                                                                                                                                                                                                                                                                                                                        S-BOOL
                                                                                                                                         S-REFLEXIVE
                                                                                                                                                                                                                                                 S-INT
                                                                                                                                                                                                                                                                                   \overline{\mathrm{bool}_c <: \mathrm{bool}}
                                                                                                                                                                                                         \overline{\mathbf{int}_c <: \mathbf{int}}
                                                                                                             \overline{\tau < : \tau}
                                                                                                                                                                                                                                                                                  \frac{\tau_1' <: \tau_1 \quad \tau_2 <: \tau_2'}{\tau_1 \rightarrow \tau_2 <: \tau_1' \rightarrow \tau_2'}
                                                                                                                                                                                                                               S-RECFUN
                                                                                                                                                                                                                                                                                                                                              S-FUN
                                                                                                                                                            \overline{\tau_1} \xrightarrow{nr} \tau_2 < : \tau_1 \rightarrow \tau_2
                                                                                                                                                                        rep \tau
                                                                                                                                                                                                                   OK-SUBTYPE
                                                                                                                                                                                                                                                                                                               OK-BASETYPE
                                                                                                                                                                                                                     \frac{\mathbf{rep}\ (\tau_1 \overset{nr}{\rightarrow} \tau')\ \mathbf{rep}\ \tau_2}{\mathbf{rep}\ (\tau_1 \overset{nr}{\rightarrow} \tau') \overset{nr}{\rightarrow} \tau_2}
                                                                             \frac{\mathbf{rep} \ \tau_2}{\mathbf{rep} \ \beta_1 \to \tau_2}
                                                                                                                                OK-BASEFUNCTION
                                                                                                                                                                                                                                                                                                    OK-HOFUNCTION
                                                                                                                                                                                                         \frac{\mathbf{rep}\ \tau_1{\rightarrow}\tau_2\ \mathbf{rep}\ \tau_1'{\rightarrow}\tau_2'}{\mathbf{rep}\ (\tau_1{\rightarrow}\tau_2){\rightarrow}(\tau_1'{\rightarrow}\tau_2')}
                                        rep \tau_1 \rightarrow \tau_2
                                                                                                                                                                                                                                                                                               OK-RECFUNCTION
                                                                                                  OK-RECFUNCTIONBASE
                                rep (\tau_1 \rightarrow \tau_2) \rightarrow \beta
                                                                                                                                                         \Gamma; \gamma \vdash e : \langle \tau, \delta \rangle
                       \tfrac{x \in \Gamma}{\Gamma; \gamma \vdash x : \Gamma(x)}
                                                                         T-VAR
                                                                                                                                                           T-INT
                                                                                                                                                                                                                                                                                                                                          T-UNIT
                                                                                                                                                                                                                                               T-BOOL
                                                                                                                                                                                                                                                                                        \overline{\Gamma;\gamma\vdash():\mathbf{unit}}
                                                                                                             \overline{\Gamma; \gamma \vdash n : \mathbf{int}_c}
                                                                                                                                                                                              \Gamma; \gamma \vdash b : \mathbf{bool}_c
                                                                                                                                                                                                            \frac{\Gamma; \gamma \vdash e_1 : \tau_1 \quad \Gamma; \gamma \vdash e_2 : \tau_2 \quad \tau_1, \tau_2 < : \tau \quad \mathbf{rep} \ \tau}{\Gamma; \gamma \vdash e_1 \ (op) \ e_2 : \tau}
                                                                             \frac{\mathbf{rep} \ \tau}{\Gamma; \gamma \vdash \mathbf{context} \ \tau : \tau}
                                                                                                                                                  T-CONTEXT
                                                                                                                                       \frac{\Gamma; \gamma \vdash e : \mathbf{bool}_c \quad \Gamma; \gamma \vdash e_t : \tau_1 \quad \Gamma; \gamma \vdash e_f : \tau_2 \quad \tau_1, \tau_2 <: \tau \quad \mathbf{rep} \ \tau}{\Gamma; \gamma \vdash \mathbf{if} \ e \ \mathbf{then} \ e_t \ \mathbf{else} \ e_f : \tau}
                                                                                                                                                                                                                                                                                                                                 T-CONDC
                                                                                                \underline{\Gamma;} \gamma \vdash e{:}\mathbf{bool} \quad \Gamma; \mathbf{sym} \vdash e_t{:}\beta_1 \quad \Gamma; \mathbf{sym} \vdash e_f{:}\beta_2 \quad \beta_1, \beta_2 < :\beta_c \quad \mathbf{rep} \ \beta_c
                                                                                                                                                                                                                                                                                                                       T-CONDSYM
                                                                                                                                                       \Gamma; \gamma \vdash \mathbf{if} \ e \ \mathbf{then} \ e_t \ \mathbf{else} \ e_f : \beta_c
                                                                                                                                                             \frac{\Gamma; \gamma \vdash e_1 : \tau_1 \xrightarrow{nr} \tau_2 \quad \Gamma, x : \tau_d; \gamma \vdash e_2 : \tau_1' \quad \tau_1' < : \tau_1 \quad \mathbf{rep} \ \tau_1 \quad \mathbf{rep} \ \tau_2}{\Gamma; \gamma \vdash (e_1 \ e_2) : \tau_2} \quad \text{T-APP}
\frac{\Gamma,\!x\!:\!\tau_d;\!\gamma\vdash\!e\!:\!\tau'}{\Gamma;\!\gamma\vdash\!(\lambda x\!:\!\tau_d.e)\!:\!\tau_d\!\to\!\tau'}
                                                                                                      T-LAMBDA
                                                                                               \frac{\Gamma, f: \tau_1 \rightarrow \tau_2; \gamma \vdash e_1: \tau_1 \rightarrow \tau_2 \quad \Gamma, f: \tau_1 \overset{nr}{\rightarrow} \tau_2; \gamma \vdash e_2: \tau_2 \quad \mathbf{rep} \ \tau \quad \mathbf{rep} \ \tau_2}{\Gamma; \gamma \vdash \mathbf{let} \ \mathbf{rec} \ f: \tau_1 \overset{nr}{\rightarrow} \tau_2 = e_1 \ \mathbf{in} \ e_2: \tau_2}
                                                                                                                                                                                                                                                                                                               T-APPLETREC
                                                                          \frac{\gamma{=}\mathbf{concrete} \quad \Gamma;\!\gamma{\vdash}e_1{:}\tau_1{\to}\tau_2 \quad \Gamma;\!\gamma{\vdash}e_2{:}\tau_1' \quad \tau_1'{<:}\tau_1 \quad \mathbf{rep} \ \tau_1 \quad \mathbf{rep} \ \tau_2}{\Gamma;\!\gamma{\vdash}(e_1\ e_2){:}\tau_2}
                                                                                                                                                                                                                                                                                                              T-APPCURREC
                                                                          \frac{\Gamma{,}x{:}\beta{;}\gamma{\vdash}e_c{:}\mathbf{bool}\quad \Gamma{;}\gamma{\vdash}v{:}\beta}{\Gamma{;}\gamma{\vdash}(\mathbf{defer}x{:}\beta\{e_c\}\ \mathbf{default}\ v){:}\beta}
                                                                                                                                                                                                                                                 \frac{\Gamma; \gamma \vdash e_c \text{:bool}}{\Gamma; \gamma \vdash (\mathbf{assert} \ e_c) \text{:unit}}
                                                                                                                                                                                                  T-DEFER
                                                                                                                                                                                                                                                                                                                                T-ASSERT
                                                                                                                                                                                       \Gamma; \gamma \vdash e_1 : \beta \quad \Gamma; \gamma \vdash^c e_1 : \beta' \quad \Gamma; \gamma \vdash v : \beta'
                                                                                                                                                                                                                                                                                                            T-CONCRETIZE
                                                                                                                                                                                       \Gamma; \gamma \vdash (\mathbf{concretize} \ e_1 \ \mathbf{with} \ v) : \beta_c
```

Figure 5: Static semantics for  $\lambda_{\rm J}$  describing simple type-checking and enforce restriction on scope of nondeterminism and recursion. Recall that  $\beta$  refers to base (non-function) types.

that  $\vdash \langle \Sigma, \Delta, \mathbf{if} \ e_1 \ \mathbf{then} \ e_t \ \mathbf{else} \ e_f \rangle \rightarrow \langle \Sigma', \Delta', \mathbf{if} \ e_1' \ \mathbf{then} \ e_t \ \mathbf{else} \ e_f \rangle$ . Similarly, if expression  $e_1$  is a **conceret** value, it must be **true** or **false**. According to E-CONDTRUE and E-CONDFALSE, **if**  $e_1$  **then**  $e_t$  **else**  $e_f$  can be reduced as well. On the other hand, if the expression  $e_1$  is **symbolic**, according to E-CONDSYMT and E-CONDSYMF, it holds the *progress* property.

- For the expression  $e_1$   $e_2$ , if the sub-expression  $e_1$  or  $e_2$  is not a value, similar as the expression  $e_1$  (op)  $e_2$ , according to E-APP1 and E-APP2, it can be at least reduce one step and evetually both  $e_1$  and  $e_2$  are values. Then according to the previous **Concrete Function Lemma**,  $e_1$   $e_2$  must be the form as  $\lambda x : e.v$ , according to E-APPLAMBDA, it holds the property immediately.
- For the expression **defer**  $x : \tau\{e\}$  **default**  $v_d$ , if sub-expression e is not a value, by the induction hypothesis, there must be an expression e' such that  $\vdash \langle \Sigma, \Delta, e \rangle \rightarrow \langle \Sigma', \Delta', e' \rangle$ , then by E-DEFERCONSTRAINT, the expression can be perform a reduction  $\vdash \langle \Sigma, \Delta, \mathbf{defer} \ x : \tau\{e\}$  **default**  $v_d \rangle \rightarrow \langle \Sigma', \Delta', \mathbf{defer} \ x : \tau\{e'\}$  **default**  $v_d \rangle$
- For the expression **assert** e,
- For the expression concretize e with  $v_c$ ,
- For the expression let  $x : \tau = e_1$  in  $e_2$  and let  $\operatorname{rec} f : \tau = e_1$  in  $e_2$ , expressions  $e_1$  and  $e_2$  are composed by one ore more above expressions. Thus, it holds the property accordingly.

**Theorem 2.** (Preservision). If  $\Gamma \vdash e : \tau \delta$  and  $e \to e'$ , then  $\Gamma \vdash e' : \tau \delta$ .

Proof. we can ...

### 4 Evaluation

Here is the example area.

```
data Exp = E_BOOL Bool | E_NAT Int
                | E_STR String | E_CONST String
                               | E_CONTEXT
                | E_VAR Var
                | E_LAMBDA Var Exp | E_THUNK Exp
                | E_OP Op Exp Exp | E_UOP UOp Exp
                | E_IF Exp Exp Exp | E_APP Exp Exp
                | E_DEFER Var Exp | E_ASSERT Exp Exp
                | E_LET Var Exp Exp
                | E_RECORD [(FieldName, Exp)]
                | E_FIELD Exp FieldName
                deriving (Ord, Eq)
data Op = OP_PLUS | OP_MINUS
                | OP_LESS | OP_GREATER
                | OP_EQ | OP_AND | OP_OR | OP_IMPLY
                deriving (Ord, Eq)
data UOp = OP_NOT
                    deriving (Ord, Eq)
data FieldName = FIELD_NAME String deriving(Ord, Eq)
data Var = VAR String deriving (Ord, Eq)
```

```
let name =
    level a in
    policy a: !(context = alice) then bottom in < "Anonymous" | "Alice" >(a)

let msg = "Author is " + name

print {alice} msg
print {bob} msg
-----
```

### 5 Conclusion

Here is the conclusion section...

# References

- [1] J. Yang, K. Yessenov, and A. Solar-Lezama. A language for automatically enforcing privacy policies. In Proceedings of the 39th annual ACM SIGPLAN-SIGACT symposium on Principles of programming languages (POPL '12). ACM, New York, NY, USA, 85-96.
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