

# Types and Programming Language Project Report\*

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## Introduction

Here is the introduction...

## 1 Language Design

### 1.1 Jeeves

Here we describe Jeeves syntax in Figure 1. Totally, it contains three types

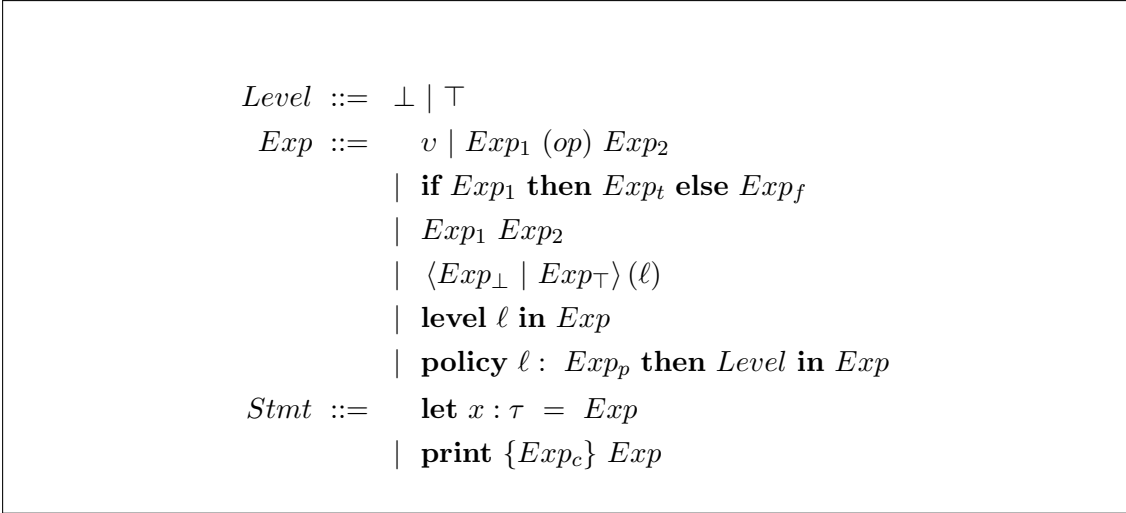

$$\begin{aligned} Level &::= \perp \mid \top \\ Exp &::= v \mid Exp_1 (op) Exp_2 \\ &\quad \mid \text{if } Exp_1 \text{ then } Exp_t \text{ else } Exp_f \\ &\quad \mid Exp_1 Exp_2 \\ &\quad \mid \langle Exp_\perp \mid Exp_\top \rangle (\ell) \\ &\quad \mid \text{level } \ell \text{ in } Exp \\ &\quad \mid \text{policy } \ell : Exp_p \text{ then } Level \text{ in } Exp \\ Stmt &::= \text{let } x : \tau = Exp \\ &\quad \mid \text{print } \{Exp_c\} Exp \end{aligned}$$

Figure 1: Jeeves syntax

### 1.2 Lambda J

Here we describe the  $\lambda_J$  language shown in Figure 2.

## 2 Semantics

Here is the semantics...

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\*done at June 5th, 2016

$$\begin{aligned}
c &::= n \mid b \mid \lambda x : \tau. e \mid \text{record } x \bar{v} \\
&\quad \mid \text{error} \mid () \\
\sigma &::= x \mid \text{context } \tau \\
&\quad \mid c_1 (op) \sigma_2 \mid \sigma_1 (op) c_2 \\
&\quad \mid \sigma_1 (op) \sigma_2 \\
&\quad \mid \text{if } \sigma \text{ then } v_t \text{ else } v_f \\
v &::= c \mid \sigma \\
e &::= v \mid e_1 (op) e_2 \\
&\quad \mid \text{if } e_1 \text{ then } e_t \text{ else } e_f \mid e_1 e_2 \\
&\quad \mid \text{let } x : \tau = e_1 \text{ in } e_2 \\
&\quad \mid \text{let rec } f : \tau = e_1 \text{ in } e_2 \\
&\quad \mid \text{defer } x : \tau\{e\} \text{ default } v_d \\
&\quad \mid \text{assert } e \\
&\quad \mid \text{concretize } e \text{ with } v_c
\end{aligned}$$

Figure 2:  $\lambda_J$  syntax

### 3 Properties

**Lemma 1.** (ConcreteFunction). *if  $v$  is a value of type  $\tau_1 \rightarrow \tau_2$ , then  $v = \lambda x : \tau_1. e$ , where  $e$  has type  $\tau_2$ .*

*Proof.* According to the  $\lambda_J$  syntax, we can get Lemma 1 immediately.  $\square$

**Theorem 1.** (Progress). *Suppose  $e$  is a closed, well-typed expression. Then  $e$  is either a value  $v$  or there is some  $e'$  such that  $\vdash \langle \Sigma, \Delta, e \rangle \rightarrow \langle \Sigma', \Delta', e' \rangle$ .*

*Proof.* According to the dynamic demantics 3 and static semantics 5 of  $\lambda_J$ , we will proof that any  $\lambda_J$  program holds the *progress* property by structral induction over the syntax of  $\lambda_J$ . According to Figure 2, there are nine kinds of expressions including the value expression  $v$ . Next we discuss each of them respectively.

- For the value expression  $v$ , according to the definition we can conclude that it holds the property immediately.
- For the expression  $e_1 (op) e_2$ , according to the hyposthesis, we know that sub-expression  $e_1$  and  $e_2$  are both closed and well-typed expressions. Thus if  $e_1$  is not a value, according to E-OP1, there must be a expression  $e'_1$  such that  $e_1 \rightarrow e'_1$ . Therefore the expression  $e_1 (op) e_2$  can be reduced to  $e'_1 (op) e_2$ , and the same as if the  $e_1$  is already a value but  $e_2$  is not according to E-OP2. While if both  $e_1$  and  $e_2$  are values, we know that  $e_1 (op) e_2$  is a value as well. Let  $c = e_1 (op) e_2$ , according to E-OP,  $\vdash \langle \Sigma, \Delta, e_1 (op) e_2 \rangle \rightarrow \langle \Sigma', \Delta', c \rangle$ . Hence, we can conclude that expression  $e_1 (op) e_2$  holds the *progress* property.
- For the expression **if**  $e_1$  **then**  $e_t$  **else**  $e_f$ , the conditional expression  $e_1$  is a either a **concrete** expression or a **symbolic** expression. If expression  $e_1$  is **concrete** and not a value, according to E-COND, there must be an expression  $e'_1$  such

$\boxed{\mathcal{G} \vdash \langle \Sigma, \Delta, e \rangle \rightarrow \langle \Sigma', \Delta', e' \rangle}$	
$\frac{\mathcal{G} \vdash \langle \Sigma, \Delta, e_1 \rangle \rightarrow \langle \Sigma', \Delta', e'_1 \rangle}{\mathcal{G} \vdash \langle \Sigma, \Delta, e_1 \ e_2 \rangle \rightarrow \langle \Sigma', \Delta', e'_1 \ e'_2 \rangle}$	E-APP1
$\frac{\mathcal{G} \vdash \langle \Sigma, \Delta, e_2 \rangle \rightarrow \langle \Sigma', \Delta', e'_2 \rangle}{\mathcal{G} \vdash \langle \Sigma, \Delta, v \ e_2 \rangle \rightarrow \langle \Sigma', \Delta', v \ e'_2 \rangle}$	E-APP2
$\frac{\mathcal{G} \vdash \langle \Sigma, \Delta, \lambda x. e \ v \rangle \rightarrow \langle \Sigma', \Delta', e[x \mapsto v] \rangle}{\mathcal{G} \vdash \langle \Sigma, \Delta, c_1 \ (op) \ c_2 \rangle \rightarrow \langle \Sigma', \Delta', c'_1 \ c'_2 \rangle}$	E-APPLAMBDA
$\frac{c' = c_1 \ (op) \ c_2}{\mathcal{G} \vdash \langle \Sigma, \Delta, c_1 \ (op) \ c_2 \rangle \rightarrow \langle \Sigma', \Delta', c' \rangle}$	E-OP
$\frac{\mathcal{G} \vdash \langle \Sigma, \Delta, e_1 \rangle \rightarrow \langle \Sigma', \Delta', e'_1 \rangle}{\mathcal{G} \vdash \langle \Sigma, \Delta, e_1 \ (op) \ e_2 \rangle \rightarrow \langle \Sigma', \Delta', e'_1 \ (op) \ e'_2 \rangle}$	E-OP1
$\frac{\mathcal{G} \vdash \langle \Sigma, \Delta, e_2 \rangle \rightarrow \langle \Sigma', \Delta', e'_2 \rangle}{\mathcal{G} \vdash \langle \Sigma, \Delta, v \ (op) \ e_2 \rangle \rightarrow \langle \Sigma', \Delta', v \ (op) \ e'_2 \rangle}$	E-OP2
$\frac{\mathcal{G} \vdash \langle \Sigma, \Delta, e_c \rangle \rightarrow \langle \Sigma', \Delta', e'_c \rangle}{\mathcal{G} \vdash \langle \Sigma, \Delta, \text{if } e_c \text{ then } e_t \text{ else } e_f \rangle \rightarrow \langle \Sigma', \Delta', \text{if } e'_c \text{ then } e_t \text{ else } e_f \rangle}$	E-COND
$\frac{\mathcal{G} \vdash \langle \Sigma, \Delta, e_t \rangle \rightarrow \langle \Sigma', \Delta', e'_t \rangle}{\mathcal{G} \vdash \langle \Sigma, \Delta, \text{if true then } e_t \text{ else } e_f \rangle \rightarrow \langle \Sigma', \Delta', e'_t \rangle}$	E-CONDTRUE
$\frac{\mathcal{G} \vdash \langle \Sigma, \Delta, e_f \rangle \rightarrow \langle \Sigma', \Delta', e'_f \rangle}{\mathcal{G} \vdash \langle \Sigma, \Delta, \text{if false then } e_t \text{ else } e_f \rangle \rightarrow \langle \Sigma', \Delta', e'_f \rangle}$	E-CONDFALSE
$\frac{\mathcal{G} \vdash \langle \Sigma, \Delta, e_t \rangle \rightarrow \langle \Sigma', \Delta', e'_t \rangle}{\mathcal{G} \vdash \langle \Sigma, \Delta, \text{if } \sigma \text{ then } e_t \text{ else } e_f \rangle \rightarrow \langle \Sigma', \Delta', \text{if } \sigma \text{ then } e'_t \text{ else } e_f \rangle}$	E-CONDSYMT
$\frac{\mathcal{G} \vdash \langle \Sigma, \Delta, e_f \rangle \rightarrow \langle \Sigma', \Delta', e'_f \rangle}{\mathcal{G} \vdash \langle \Sigma, \Delta, \text{if } \sigma \text{ then } v_t \text{ else } e_f \rangle \rightarrow \langle \Sigma', \Delta', \text{if } \sigma \text{ then } v_t \text{ else } e'_f \rangle}$	E-CONDSYMF
$\frac{\mathcal{G} \vdash \langle \Sigma, \Delta, e \rangle \rightarrow \langle \Sigma', \Delta', e' \rangle}{\mathcal{G} \vdash \langle \Sigma, \Delta, \text{defer } x: \tau \{e\} \text{ default } v_d \rangle \rightarrow \langle \Sigma', \Delta', \text{defer } x: \tau \{e'\} \text{ default } v_d \rangle}$	E-DEFERCONSTRAINT
$\frac{\text{fresh } x'}{\mathcal{G} \vdash \langle \Sigma, \Delta, \text{defer } x: \tau \{e\} \text{ default } v_d \rangle \rightarrow \langle \Sigma \cup \{\mathcal{G} \Rightarrow v_c[x \mapsto x']\}, \Delta \cup \{\mathcal{G} \Rightarrow x' = v_d\}, x' \rangle}$	E-DEFER
$\frac{\mathcal{G} \vdash \langle \Sigma, \Delta, e \rangle \rightarrow \langle \Sigma', \Delta', e' \rangle}{\mathcal{G} \vdash \langle \Sigma, \Delta, \text{assert } e \rangle \rightarrow \langle \Sigma', \Delta', \text{assert } e' \rangle}$	E-ASSERTCONSTRAINT
$\frac{\mathcal{G} \vdash \langle \Sigma, \Delta, \text{assert } v \rangle \rightarrow \langle \Sigma \cup \{\mathcal{G} \Rightarrow v\}, \Delta, () \rangle}{\mathcal{G} \vdash \langle \Sigma, \Delta, \text{assert } v \rangle \rightarrow \langle \Sigma \cup \{\mathcal{G} \Rightarrow v\}, \Delta, () \rangle}$	E-ASSERT
$\frac{\mathcal{G} \vdash \langle \Sigma, \Delta, e \rangle \rightarrow \langle \Sigma', \Delta', e' \rangle}{\mathcal{G} \vdash \langle \Sigma, \Delta, \text{concretize } e \text{ with } v_c \rangle \rightarrow \langle \Sigma', \Delta', \text{concretize } e' \text{ with } v_c \rangle}$	E-CONCRETIZEEXP
$\frac{\text{MODLE}(\Delta, \Sigma \cup \{\mathcal{G} \cap \text{context} = v_c\}) = \mathcal{M} \quad c = \mathcal{M}[[v_\nu]]}{\mathcal{G} \vdash \langle \Sigma, \Delta, \text{concretize } v_\nu \text{ with } v_c \rangle \rightarrow \langle \Sigma, \Delta, c \rangle}$	E-CONCRETIZESAT
$\frac{\text{MODLE}(\Delta, \Sigma \cup \{\mathcal{G} \cap \text{context} = v_c\}) = \text{UNSAT}}{\mathcal{G} \vdash \langle \Sigma, \Delta, \text{concretize } v_\nu \text{ with } v_c \rangle \rightarrow \langle \Sigma, \Delta, \text{error} \rangle}$	E-CONCRETIZEUNSAT

Figure 3: Dynamic semantics for  $\lambda_J$ .

$\delta ::=$	<b>concretize</b>   <b>sym</b>	determinism tag
$\beta ::=$	<b>int</b> <sub>c</sub>   <b>bool</b> <sub>c</sub>   <b>unit</b>   <b>int</b>   <b>bool</b>	base type
$\tau ::=$	$\beta$   $\tau_1 \xrightarrow{nr} \tau_2$   $\tau_1 \rightarrow \tau_2$	type

Figure 4:  $\lambda_J$  types

$\boxed{\tau_1 <: \tau_2}$	
$\overline{\tau <: \tau}$	S-REFLEXIVE
$\overline{\text{int}_c <: \text{int}}$	S-INT
$\overline{\text{bool}_c <: \text{bool}}$	S-BOOL
$\frac{}{\tau_1 \xrightarrow{nr} \tau_2 <: \tau_1 \rightarrow \tau_2}$	S-RECFUN
$\frac{\tau'_1 <: \tau_1 \quad \tau_2 <: \tau'_2}{\tau_1 \rightarrow \tau_2 <: \tau'_1 \rightarrow \tau'_2}$	S-FUN
$\boxed{\text{rep } \tau}$	
$\frac{\text{rep } \tau \quad \tau' <: \tau}{\text{rep } \tau}$	OK-SUBTYPE
$\overline{\text{rep } \beta}$	OK-BASETYPE
$\frac{\text{rep } \tau_2}{\text{rep } \beta_1 \rightarrow \tau_2}$	OK-BASEFUNCTION
$\frac{\text{rep } (\tau_1 \xrightarrow{nr} \tau') \quad \text{rep } \tau_2}{\text{rep } (\tau_1 \xrightarrow{nr} \tau') \xrightarrow{nr} \tau_2}$	OK-HOFUNCTION
$\frac{\text{rep } \tau_1 \rightarrow \tau_2}{\text{rep } (\tau_1 \rightarrow \tau_2) \rightarrow \beta}$	OK-RECFUNCTIONBASE
$\frac{\text{rep } \tau_1 \rightarrow \tau_2 \quad \text{rep } \tau'_1 \rightarrow \tau'_2}{\text{rep } (\tau_1 \rightarrow \tau_2) \rightarrow (\tau'_1 \rightarrow \tau'_2)}$	OK-RECFUNCTION
$\boxed{\Gamma; \gamma \vdash e : \langle \tau, \delta \rangle}$	
$\frac{x \in \Gamma}{\Gamma; \gamma \vdash x : \Gamma(x)}$	T-VAR
$\overline{\Gamma; \gamma \vdash n : \text{int}_c}$	T-INT
$\overline{\Gamma; \gamma \vdash b : \text{bool}_c}$	T-BOOL
$\overline{\Gamma; \gamma \vdash () : \text{unit}}$	T-UNIT
$\frac{\text{rep } \tau}{\Gamma; \gamma \vdash \text{context } \tau : \tau}$	T-CONTEXT
$\frac{\Gamma; \gamma \vdash e_1 : \tau_1 \quad \Gamma; \gamma \vdash e_2 : \tau_2 \quad \tau_1, \tau_2 <: \tau \quad \text{rep } \tau}{\Gamma; \gamma \vdash e_1 (op) e_2 : \tau}$	T-OP
$\frac{\Gamma; \gamma \vdash e : \text{bool}_c \quad \Gamma; \gamma \vdash e_t : \tau_1 \quad \Gamma; \gamma \vdash e_f : \tau_2 \quad \tau_1, \tau_2 <: \tau \quad \text{rep } \tau}{\Gamma; \gamma \vdash \text{if } e \text{ then } e_t \text{ else } e_f : \tau}$	T-CONDC
$\frac{\Gamma; \gamma \vdash e : \text{bool} \quad \Gamma; \text{sym} \vdash e_t : \beta_1 \quad \Gamma; \text{sym} \vdash e_f : \beta_2 \quad \beta_1, \beta_2 <: \beta_c \quad \text{rep } \beta_c}{\Gamma; \gamma \vdash \text{if } e \text{ then } e_t \text{ else } e_f : \beta_c}$	T-CONDSYM
$\frac{\Gamma, x : \tau_d; \gamma \vdash e : \tau' \quad \text{rep } \tau_d \quad \text{rep } \tau'}{\Gamma; \gamma \vdash (\lambda x : \tau_d. e) : \tau_d \rightarrow \tau'}$	T-LAMBDA
$\frac{\Gamma; \gamma \vdash e_1 : \tau_1 \xrightarrow{nr} \tau_2 \quad \Gamma, x : \tau_d; \gamma \vdash e_2 : \tau'_1 \quad \tau'_1 <: \tau_1 \quad \text{rep } \tau_1 \quad \text{rep } \tau_2}{\Gamma; \gamma \vdash (e_1 e_2) : \tau_2}$	T-APP
$\frac{\Gamma, f : \tau_1 \rightarrow \tau_2; \gamma \vdash e_1 : \tau_1 \rightarrow \tau_2 \quad \Gamma, f : \tau_1 \xrightarrow{nr} \tau_2; \gamma \vdash e_2 : \tau_2 \quad \text{rep } \tau \quad \text{rep } \tau_2}{\Gamma; \gamma \vdash \text{let rec } f : \tau_1 \xrightarrow{nr} \tau_2 = e_1 \text{ in } e_2 : \tau_2}$	T-APPLETREC
$\frac{\gamma = \text{concrete} \quad \Gamma; \gamma \vdash e_1 : \tau_1 \rightarrow \tau_2 \quad \Gamma; \gamma \vdash e_2 : \tau'_1 \quad \tau'_1 <: \tau_1 \quad \text{rep } \tau_1 \quad \text{rep } \tau_2}{\Gamma; \gamma \vdash (e_1 e_2) : \tau_2}$	T-APPCURREC
$\frac{\Gamma, x : \beta; \gamma \vdash e_c : \text{bool} \quad \Gamma; \gamma \vdash v : \beta}{\Gamma; \gamma \vdash (\text{defer } x : \beta \{ e_c \} \text{ default } v) : \beta}$	T-DEFER
$\frac{\Gamma; \gamma \vdash e_c : \text{bool}}{\Gamma; \gamma \vdash (\text{assert } e_c) : \text{unit}}$	T-ASSERT
$\frac{\Gamma; \gamma \vdash e_1 : \beta \quad \Gamma; \gamma \vdash e_1 : \beta' \quad \Gamma; \gamma \vdash v : \beta'}{\Gamma; \gamma \vdash (\text{concretize } e_1 \text{ with } v) : \beta_c}$	T-CONCRETIZE

Figure 5: Static semantics for  $\lambda_J$  describing simple type-checking and enforce restriction on scope of nondeterminism and recursion. Recall that  $\beta$  refers to base (non-function) types.

that  $\vdash \langle \Sigma, \Delta, \text{if } e_1 \text{ then } e_t \text{ else } e_f \rangle \rightarrow \langle \Sigma', \Delta', \text{if } e'_1 \text{ then } e_t \text{ else } e_f \rangle$ . Similarly, if expression  $e_1$  is a **concret** value, it must be **true** or **false**. According to E-CONDTRUE and E-CONDFALSE,  $\text{if } e_1 \text{ then } e_t \text{ else } e_f$  can be reduced as well. On the other hand, if the expression  $e_1$  is **symbolic**, according to E-CONDSYMT and E-CONDSYMF, it holds the *progress* property.

- For the expression  $e_1 \ e_2$ , if the sub-expression  $e_1$  or  $e_2$  is not a value, similar as the expression  $e_1 \ (op) \ e_2$ , according to E-APP1 and E-APP2, it can be at least reduce one step and eventually both  $e_1$  and  $e_2$  are values. Then according to the previous **Concrete Function Lemma**,  $e_1 \ e_2$  must be the form as  $\lambda x : e.v$ , according to E-APPLAMBDA, it holds the property immediately.
- For the expression **defer**  $x : \tau\{e\}$  **default**  $v_d$ , if sub-expression  $e$  is not a value, by the induction hypothesis, there must be an expression  $e'$  such that  $\vdash \langle \Sigma, \Delta, e \rangle \rightarrow \langle \Sigma', \Delta', e' \rangle$ , then by E-DEFERCONSTRAINT, the expression can be perform a reduction  $\vdash \langle \Sigma, \Delta, \text{defer } x : \tau\{e\} \text{ default } v_d \rangle \rightarrow \langle \Sigma', \Delta', \text{defer } x : \tau\{e'\} \text{ default } v_d \rangle$
- For the expression **assert**  $e$ ,
- For the expression **concretize**  $e$  **with**  $v_c$ ,
- For the expression **let**  $x : \tau = e_1$  **in**  $e_2$  and **let rec**  $f : \tau = e_1$  **in**  $e_2$ , expressions  $e_1$  and  $e_2$  are composed by one or more above expressions. Thus, it holds the property accordingly.

□

**Theorem 2.** (Preservision). *If  $\Gamma \vdash e : \tau\delta$  and  $e \rightarrow e'$ , then  $\Gamma \vdash e' : \tau\delta$ .*

*Proof.* we can ...

□

## 4 Evaluation

Here is the example area.

```
data Exp = E_BOOL Bool | E_NAT Int
         | E_STR String | E_CONST String
         | E_VAR Var | E_CONTEXT
         | E_LAMBDA Var Exp | E_THUNK Exp
         | E_OP Op Exp Exp | E_UOP UOp Exp
         | E_IF Exp Exp Exp | E_APP Exp Exp
         | E_DEFER Var Exp | E_ASSERT Exp Exp
         | E_LET Var Exp Exp
         | E_RECORD [(FieldName, Exp)]
         | E_FIELD Exp FieldName
         deriving (Ord, Eq)

data Op = OP_PLUS | OP_MINUS
         | OP_LESS | OP_GREATER
         | OP_EQ | OP_AND | OP_OR | OP_IMPLY
         deriving (Ord, Eq)

data UOp = OP_NOT deriving (Ord, Eq)

data FieldName = FIELD_NAME String deriving (Ord, Eq)
data Var = VAR String deriving (Ord, Eq)
```

```

-----
let name =
  level a in
    policy a: !(context = alice) then bottom in < "Anonymous" | "Alice" >(a)

let msg = "Author is " + name

print {alice} msg
print {bob} msg
-----

```

## 5 Conclusion

Here is the conclusion section...

## References

- [1] J. Yang, K. Yessenov, and A. Solar-Lezama. A language for automatically enforcing privacy policies. In Proceedings of the 39th annual ACM SIGPLAN-SIGACT symposium on Principles of programming languages (POPL '12). ACM, New York, NY, USA, 85-96.
- [2] B. Pierce. Types and Programming Languages, *MIT Press*, 2002.