

Ένωση Πληροφορικών Ελλάδας

Νέες τεχνολογίες και ρομποτική
στην Έρευνα και Διάσωση

Χάρης Γεωργίου (MSc, PhD)

Ένωση Πληροφορικών Ελλάδας

Στόχοι:

- Πρώτος “καθολικός” φορέας εκπροσώπησης πτυχιούχων Πληροφορικής.
- Αρμόδιος φορέας εκπροσώπησης επαγγελματιών Πληροφορικής.
- Αρμόδιος επιστημονικός “συμβουλευτικός” φορέας για το Δημόσιο.
- Αρωγός της Εθνικής Ψηφιακής Στρατηγικής & Παιδείας της χώρας.



Τομείς παρέμβασης

Ποιοι είναι οι κύριοι τομείς παρεμβάσεων της ΕΠΕ;

- ① Εθνική Ψηφιακή Στρατηγική & Οικονομία
- ② Εργασιακά (ΤΠΕ), Δημόσιος & ιδιωτικός τομέας
- ③ Παιδεία (Α', Β', Γ')
- ④ Έρευνα & Τεχνολογία
- ⑤ Έργα & υπηρεσίες ΤΠΕ
- ⑥ Ασφάλεια συστημάτων & δεδομένων
- ⑦ Ανοικτά συστήματα & πρότυπα
- ⑧ Χρήση ΕΛ/ΛΑΚ
- ⑨ Πνευματικά δικαιώματα
- ⑩ Κώδικας Δεοντολογίας (ΤΠΕ)
- ⑪ Κοινωνική μέριμνα (ICT4D)





Harris Georgiou (MSc, PhD) – <https://github.com/xgeorgio/info>

- R&D: Associate post-doc researcher and lecturer with the University Athens (NKUA) and University of Piraeus (UniPi)
- Consultant in Medical Imaging, Machine Learning, Data Analytics, Signal Processing, Process Optimization, Dynamic Systems, Complexity & Emergent A.I., Game Theory
- HRTA member since 2009, LEAR / scientific advisor
- HRTA field operator (USAR, scuba diver)
- Wilderness first aid, paediatric (child/infant)
- Humanitarian aid & disaster relief in Ghana, Lesvos, Piraeus
- Support of unaccomp. minors, teacher in community schools
- Streetwork training, psychological first aid & victim support
- 2+ books, 160+ scientific papers/articles (and 5 marathons)

Επισκόπηση – Πηγές

- Περιεχόμενα:
 - Τεχνολογίες USAR επόμενης γενιάς (UAV, COP, AR, remote sensing, ...)
 - “Detection of victims with UAVs during wide area Search and Rescue operations” (SSRR’22)
 - “Emergency response in recent urban/suburban disaster events in Attica: Technology gaps, limitations and lessons learned” (ISCRAM’21)
 - Future trends / “Moving forward”
- Πηγές:
 - EU H2020 projects (SCENT, FASTER, CURSOR, INGENIOUS, INTREPID)
 - INSARAG Guidelines for USAR Operations (2020)

Hellenic Rescue Team of Attica – H.R.T.A

- Independent NGO, participate in field-specific & first-aid training, about 800 members in Attica
- Certified experts in various topics & environments (wilderness, urban, river, scuba, ...)
- Active since 2000, part of the Greek Civil Protection's general plan when needed, as well as internationally in large events in close collaboration with other H.R.T branches in Greece
- Respond in emergency/disaster events, medical first-responders in the scene, SAR missions, humanitarian aid & relief in disaster zones
- Provide training and medical/safety coverage, specialized or general-purpose, to the public



LAND SAR: Wilderness, non-urban
(mountain, canyon/river, forest)



WATER SAR: Surface, underwater, shore
(sea, large river, lake)



URBAN SAR: emergency response, disaster relief
(earthquake, flood, fire, large-scale accidents)



Hellenic Rescue Team of Attica – H.R.T.A

- Participating in EU-funded R&D projects since 2016
- Primary role as domain expert (SAR), technology demonstration, field testing, dissemination in domain
- Already hosting large-scale field events in HRTA Training Center at Afidnes (Attica) since 2019
- Related large-scale missions in Attica disaster events, in flash floods (Mandra, 2017) and rapid wildfires (Mati, 2018), for SAR, missing persons, humanitarian aid

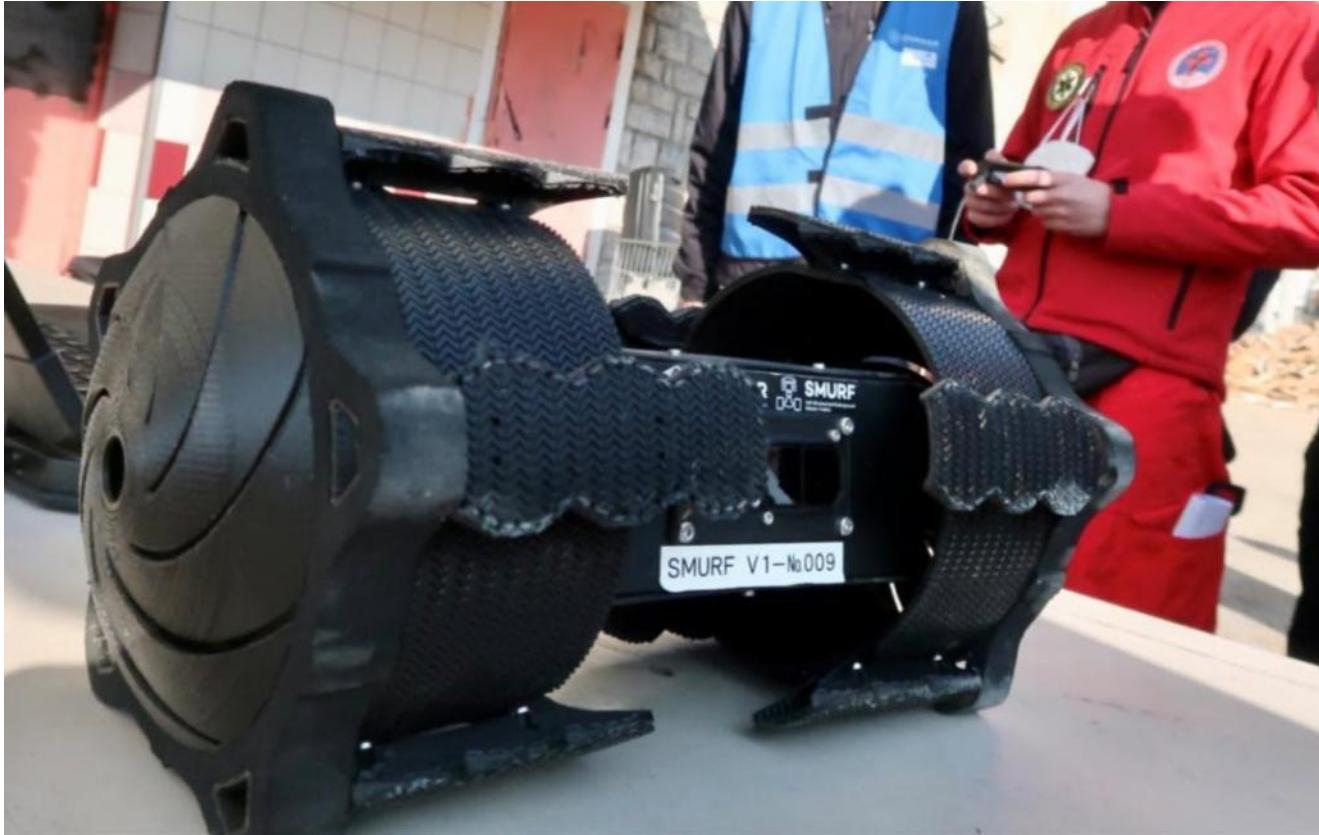


Intelligent Toolkit for Reconnaissance and assessment in Perilous Incidents

These projects have received funding from the European Union's Horizon 2020 research and innovation programme under grant agreements n688930, n833507, n.832790 and n.833435, n883345



Current technologies / Under development: UxV



Credits: CURSOR project

Current technologies / Under development: COP

CHARGE COP Search and Rescue - Crisis Search and Rescue Center

System Users Operational Resources Windows Preferences Help

engage ASTRIAL

Pending Events

Type	Information	Resources
[23] Oct 20, 2021 16:44 Crisis (L) Natural Disaster Tsunami (L) 123	[1111] [345FDSTFA09] [0GD0677A90M]	
[25] Dec 1, 2021 14:39 Crisis (L) Natural Disaster Earthquake (L) 112	[Light team 1] [EMTA 1] [Agapitos Giannis] [Heavy team]	

Land Incident Details [25]

ID: 25 Date: Dec 1, 2021 Time: 2:39:00 PM

Organization Name: Search and Rescue Organization Legal Name: Search and Rescue Department: Search and Rescue

Type: Crisis (L) Location: Longitude: 23.855333 Latitude: 38.167687 Caller: 112

Status: IN PROGRESS
CLOSED
CANCELED
AWAITING DISPATCHER
WITHOUT RESOURCE
PARTIAL CONTROL
FULL CONTROL
AWAITING RESOURCE

Classification:

Severity: Extreme Certainty: POSSIBLE

Response type: Evacuate Response Urgency: Immediate

Confirmation status: PENDING

of injured persons: 0 # of deaths: 0 Is SAR involved: Has diseases: Description:

Assign Resources

TOTAL (150) NOTIFIED (150) ARRIVED (0) DEPARTED (0) CANCELLED (0)

Active All

Call...	Type	Sector	Worksite	Identity...	Compos...	Status	Op. Mode	Notified	Arrival	Departure	Canceled
1	Sector F...	Sector F...	Worksite...	• 85105481...	SMURF01	Alarmed	DEPLOYED	14:48			
2	Sector F...	Sector F...	Worksite...	• 18185011...	GPHS-01	Alarmed	DEPLOYED	14:48			
3	Sector F...	Sector F...	Worksite...	• 73423434...	SMURF02	Alarmed	DEPLOYED	14:48			
4	Sector F...	Sector F...	Worksite...	• 64523	SNR-02	Alarmed	DEPLOYED	14:48			
5	•	Sector F...	Worksite...	• 4123	AXE	Alarmed		14:48			
6	•	Sector F...	Worksite...	• 53141233	SNR-01	Alarmed	DEPLOYED	14:48			
7	•	Sector F...	Worksite...	• SU-1112	GPRO-01	Alarmed	DEPLOYED	14:48			
8	•	Sector F...	Worksite...	• SX-U1309	TD-01	Alarmed	DEPLOYED	14:48			
9	•	•	•	•	•	•	•	•	•	•	•

Available Assets

Vehicle Personnel Equipment Aircraft

Crisis Search and Rescue Center

Identity: SX-U1309 Description: Transport drone UAV

3D Map 2D Map

27.00 Meters

SatWays Ltd. All Rights Reserved

38.16782 N 23.85542 E Alt: 259.73 Meter ASL

Credits: CURSOR project

Current technologies / Under development: ARV



Credits: FASTER project

What is needed: Remote Sensing



Credits: FASTER project

What is needed: Quick & Safe Access



What is needed: Team localization & hazard mapping



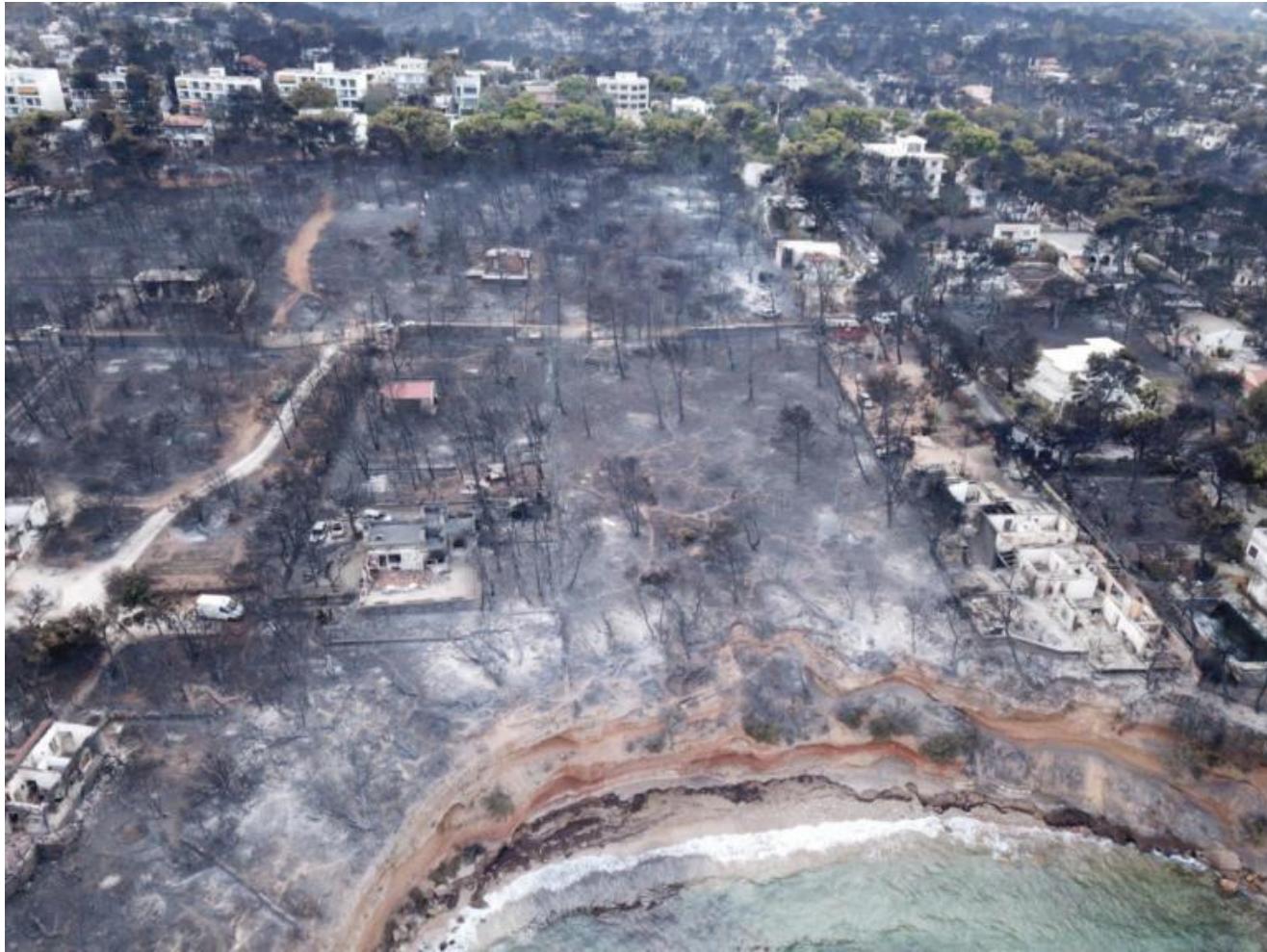
Mati, 2018



Mati, 2018

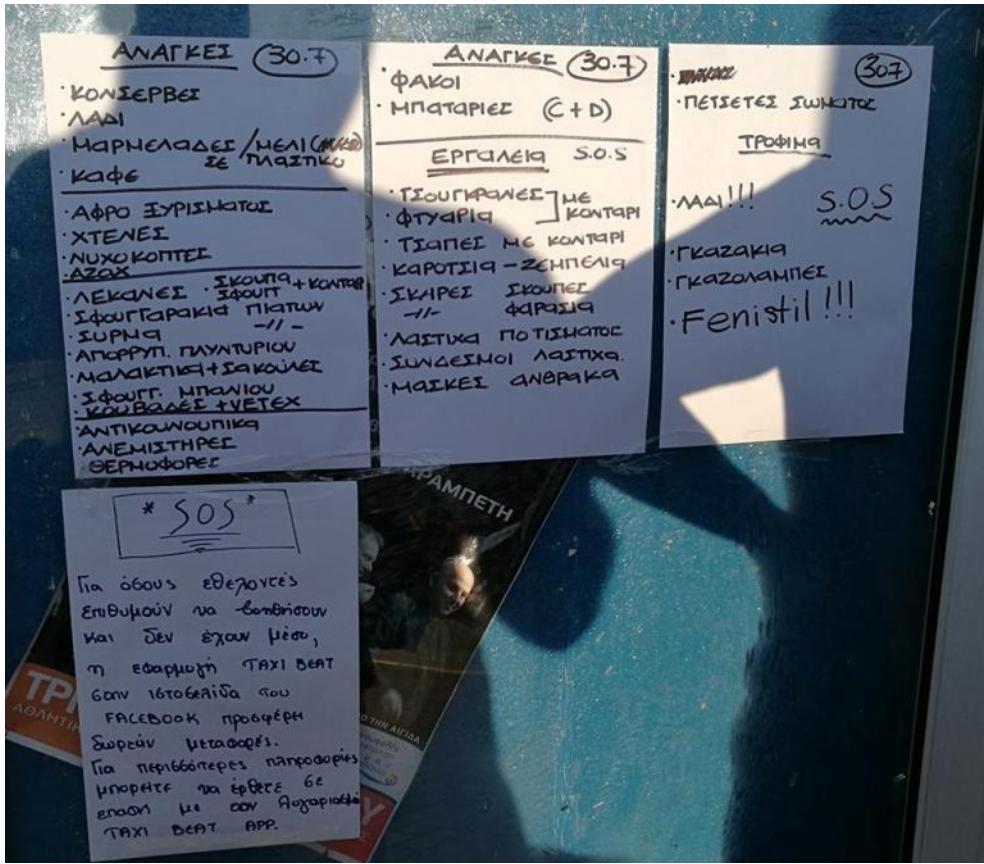


Mandra, 2017



Mati, 2018

What is needed: Last-mile gap & self-organization



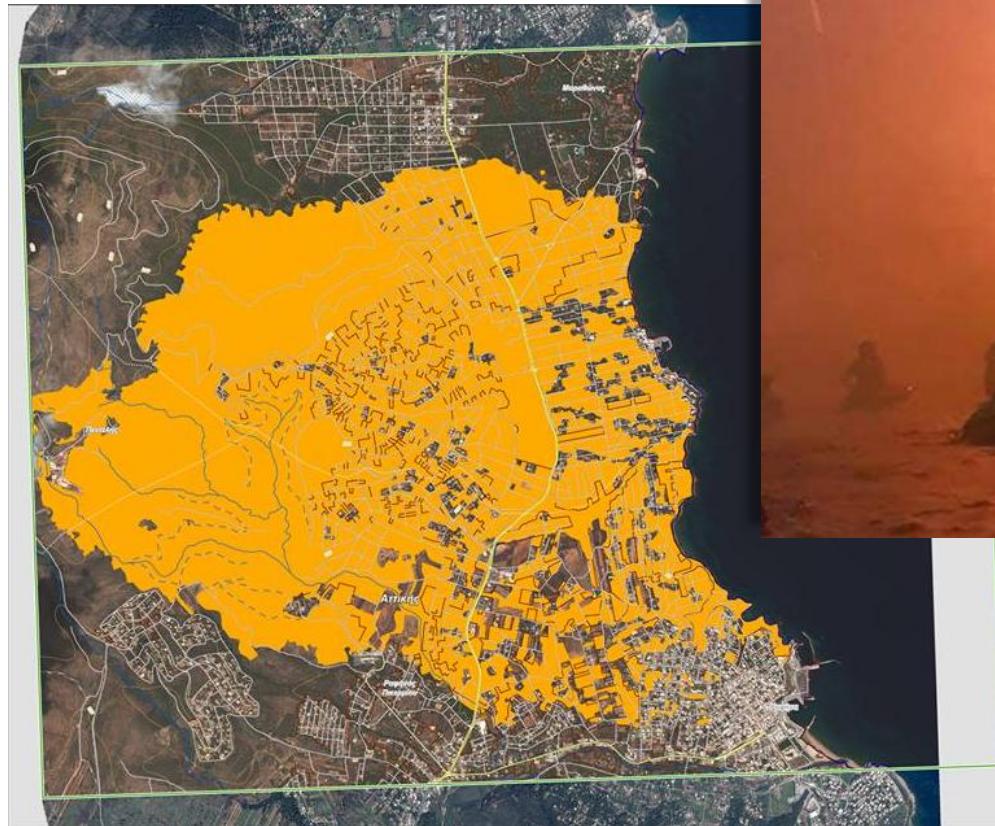
Mati, 2018

Future trends: Live event monitoring (floods)



*Mandra flash flood overview, western Attica,
Greece (Nov. 2017)*

Future trends: Live event monitoring (fires)



Mati wildfire overview, eastern Attica, Greece (Jul. 2018)

Detection of victims with UAVs during wide area Search and Rescue operations

Harris V. Georgiou, *Hellenic Rescue Team of Attica (HRTA, Greece)*

Friedrich Steinhäusler, *International Security Competence Centre (ISCC, Austria)*

SSRR 2022 Special Session Paper 74



CURSOR DRONE FLEET

Current configuration of the CURSOR drone fleet:

- ✓ Mothership drone (MD)
- ✓ 3D modelling drone swarm (MOD)
- ✓ Heavy-load transport drone (TD)
- ✓ Advanced situational awareness drone (ASAD)

Main responsibilities and mission:

- ✓ Wide-area search and worksite monitoring 24/7
- ✓ Worksite 3D mapping for mission planning
- ✓ Aerial transportation platform (e.g. for SMURFs)
- ✓ Aerial communication relay, illumination, audio alerting



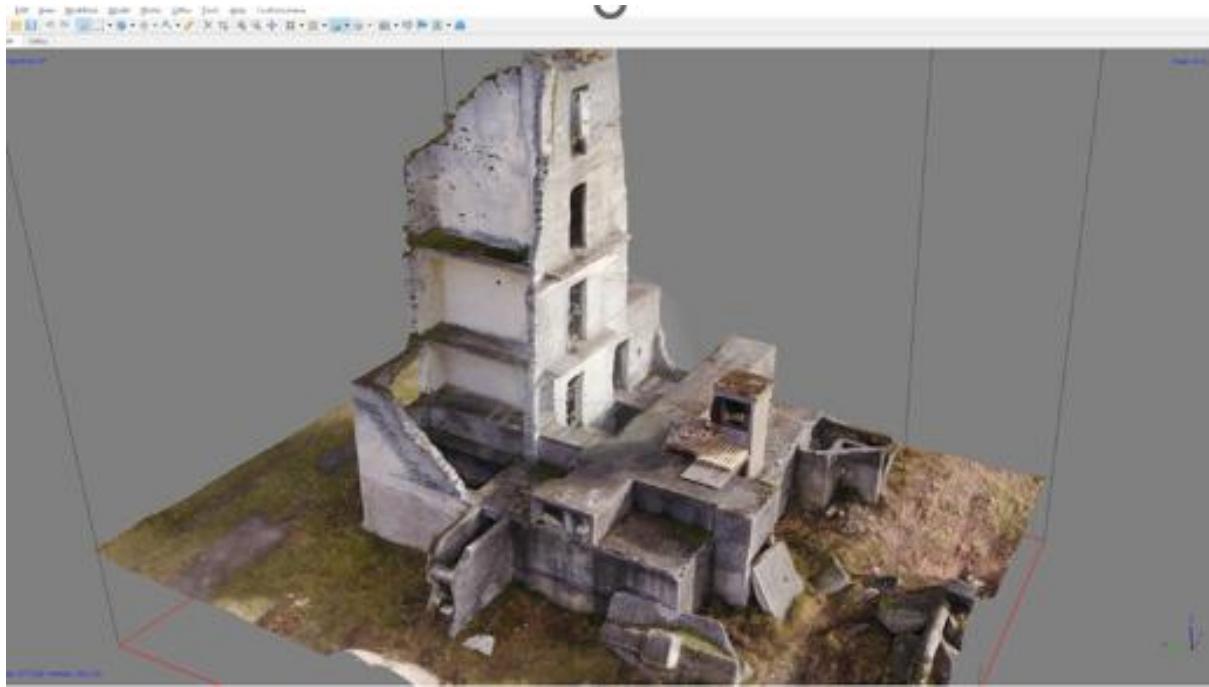
Mothership Drone:

Non-stop situational awareness;
Communication between crisis management and first responders;
Spot light illumination of site

- ✓ Drone tethered with cable for:
 - Electric power transmission from mobile electric generators to drone
 - Signal transmission from drone to base station on the ground
- ✓ Drone can stay in the air 24/7*
- ✓ LED flood lights
- ✓ Special megaphone (125 dB)
- ✓ WiFi contact point

Modelling Swarm Drones:

Creation of orthophoto and 3D model of disaster area with 5 pre-programmed drones



3-D model



Transport Drone:

Transporting & unloading SMURFs;
Video of unloading site

Sensor Platform:

- ✓ Remotely controlled heavy-load transport mechanism (electric winch + laser-guided distance sensor)
- ✓ Payload release under remote radio-control

Advanced Situational Awareness Drone

Sensor platform:

- ✓ HD video camera
- ✓ Thermal camera
- ✓ LED lights



CURSOR DRONE SENSORS

Depending on the drone type, the following sensors are installed on the standardized drone platform:

- ✓ HD video-camera
- ✓ 30x optical zoom video-camera
- ✓ Thermal-camera
- ✓ Radio-controlled winch for lowering and lifting payload (maximum payload: 5 kg)
- ✓ Radio-controlled, laser-guided release mechanism for SMURFs
- ✓ Aerodynamically shaped megaphone
- ✓ LED flood light
- ✓ WiFi access point
- ✓ Parachute for emergency landing of drone (optional)

CURSOR DRONE FLEET – Results

Advantages:

- ✓ Wide range of COTS flying platforms available
- ✓ Low purchasing cost for UAV as compared to aircraft
- ✓ Low operational costs (negligible cost of fuel, service and maintenance)
- ✓ UAV availability at short notice in a crisis
- ✓ Small-sized, lightweight, portable deployment package
- ✓ Take-off and landing at user-selected locations (designated LZ)
- ✓ UAV equipped with a wide range of sensors and instruments
- ✓ Safe, remote operation in an uncontaminated / hazardous area
- ✓ Easy field training of FRs as UAV operators
- ✓ Estimated average cost reduction for purchase and operation
- ✓ Estimated average time to start SAR missions: 10 min

Hellenic Rescue Team of Attica – H.R.T.A.

“Emergency response in recent urban/suburban disaster events in Attica:
Technology gaps, limitations and lessons learned”



Related paper:

17th ISCRAM Conference, Track 14: Technologies for First Responders (ISCRAM 2021), 23-26 May 2021 @ Blacksburg, VA, USA.

(Best Practitioners Paper / Murray Turoff Award)

H. Georgiou, A. Vlachopoulos, A. Tzeletopoulou (Sept. 2020)



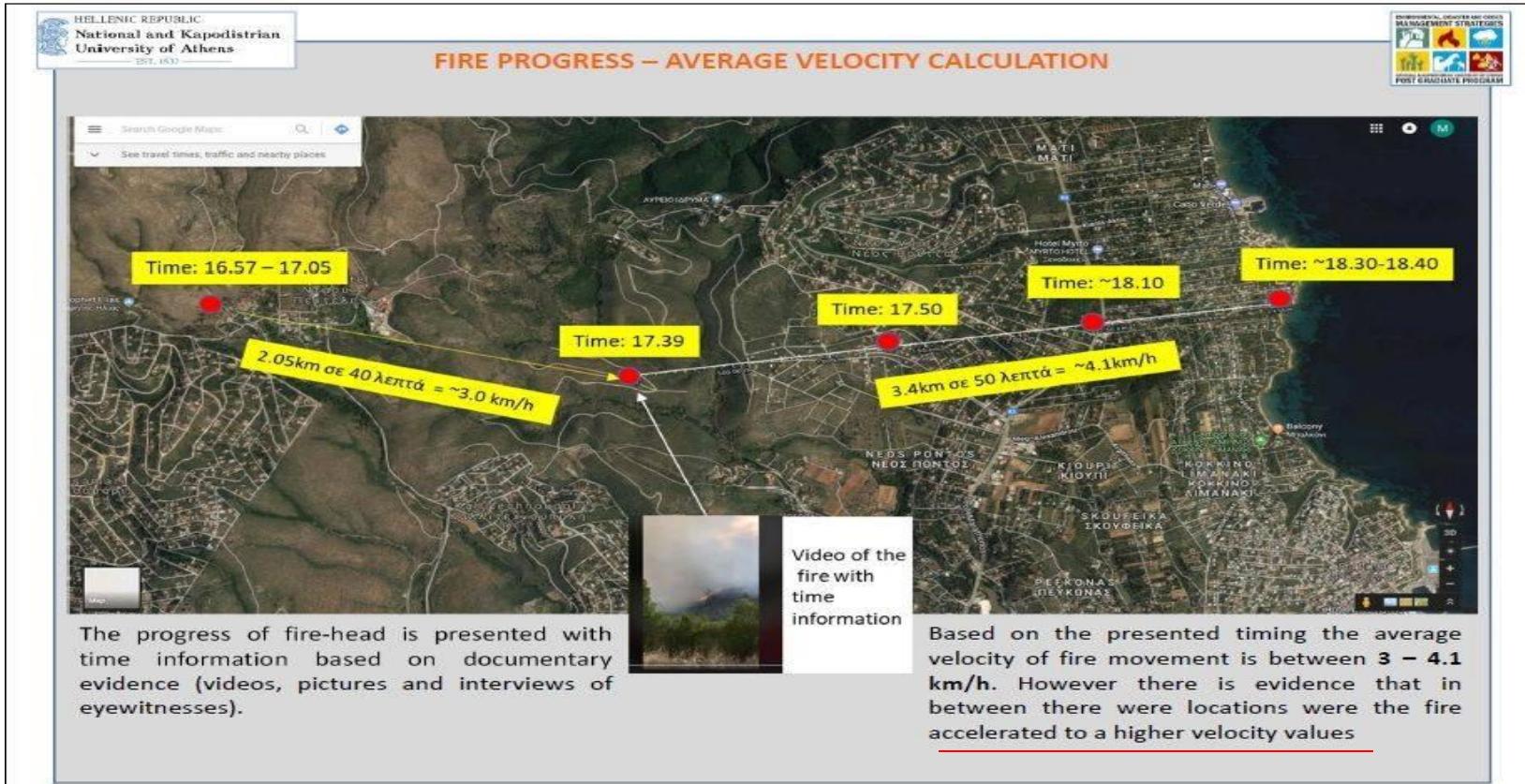
Hellenic Rescue Team of Attica – H.R.T.A.

- Mandra, Attica (Nov/2017):
 - Flash flood event in western Attica
 - Associated to local wildfires a few months before
 - 23 dead, major urban damages
- Mati, Attica (Jul/2018):
 - Wildfire crossing into urban/mixed area
 - Unique local weather conditions (downhill winds)
 - 102 dead, several people in ICUs (burn treatment)

H.R.T.A. at Mati, Attica (Jul/2018)



H.R.T.A. at Mati, Attica (Jul/2018)



Source: E. Lekkas, P. Carydis, K. Lagouvardos, et.al. (2018). The July 2018 Attica (Central Greece) Wildfires – Scientific report (v1.3).
Newsletter of Environmental, Disaster and Crisis Management Strategies, Issue 8.

H.R.T.A. at Mati, Attica (Jul/2018)



Hellenic Rescue Team of Attica – H.R.T.A.

Operational assessment:

- ❖ **Reliable, multi-aspect communications** and continuous flow of information between field teams and C&C is imperative.
- ❖ A **rapid deployment “scout” team** into the hotzone very early on provides invaluable information for preparing the main teams.
- ❖ Central organization and guidance from the authorities is expected, but must not be a prerequisite – **decentralized and autonomous deployment plans** should always be available.
- ❖ **Prepare for the unexpected** – no way to have 100% knowledge of access routes, severity of the situation, number of casualties, evacuation options (Mati: by sea, via small shallow-hull boats)
- ❖ **Multi-aspect SAR** may be required (Mati: urban, coastal, sea).
- ❖ Other important factors in multi-day operations in the disaster area: (+) **volunteers**, (-) **journalists/cameras**.
- ❖ **PFA debriefing** is necessary, more sessions may be required for team members involved in specific events or scenes.

Hellenic Rescue Team of Attica – H.R.T.A.

Technology gaps / limitations:

- ❖ Fixed-line, cellular networks down for hours during the events.
- ❖ In some cases, even R/F comms were difficult for various reasons.
- ❖ **Text messaging via Internet** seems to be mostly reliable.
- ❖ Open technologies & platforms heavily used by the field teams, e.g. Google Maps and hourly weather forecasts.
- ❖ Photographic material need to be sent to **forensic experts** to verify findings (bone fragments), while teams were still in the field.
- ❖ Very difficult to do exact orientation, mapping, search plans for the field teams when the level of damages has changed the entire area.
- ❖ Very difficult to perform house-by-house search when the disaster area is extensive or/and when **access is denied** or too dangerous.
- ❖ Simple improvised solutions, like **paper notes** outside destroyed houses ("we are ok"), are also invaluable in terms of safety & time.

Hellenic Rescue Team of Attica – H.R.T.A.

Future prospects / focus points:

- ❖ **Safety:** The field teams need to have minimal exposure to hazards in terms of time and area. Remote sensing, rich information flows, as well as personal biometrics are very valuable assets.
- ❖ **Communications:** Reliable links between team members and between teams and C&C are imperative in the field.
- ❖ **Situational awareness:** The C&C needs to have real-time perception of the field and needs to push it to the deployed teams.
- ❖ **Logistics & preparedness:** Every asset needs to be easily maintainable, ready to be deployed, easy to incorporate in current operational plans and field equipment (especially when carried).
- ❖ **Missing persons / victim identification:** In large-scale disaster events with a large number of “unknowns” (missing/victims), swift identification or at least registry is important (very limited now).
- ❖ **Last-mile information gap:** Affected population inside the disaster area usually does not have access to vital information.

Search and Rescue operations in urban environment: Lessons from disaster events in Attica

Spyros Chrysanthopoulos

Hellenic Rescue Team of Attica (HRTA) *

President of AC board

Giannis Chaidemenos

Hellenic Rescue Team of Attica (HRTA)

Chief of USAR Operations sector

Theofanis Kapetanakis

Hellenic Rescue Team of Attica (HRTA)

Chief of Operations

Stelios Vernardos

Hellenic Rescue Team of Attica (HRTA)

Deputy Chief of USAR Operations sector

Harris Georgiou†

Hellenic Rescue Team of Attica (HRTA) †

R&Dadvisor, LEAR

v1.0.0

March 26 , 2020

ABSTRACT

Emergency response operations in large-scale urban/suburban disaster events is often addressed by the standard protocols and international guidelines for collapsed buildings, heavy debris, etc (INSARAG). However, a wide range of First Responder (FR) operations need to address various other contexts, work environments and hazards. In this paper, two real disaster events are explored as use cases for such urban/suburban FR operations, namely a flash flood and a wildfire, both in Attica, Greece (2017-2018). Based on our team's experience from these mobilizations and active participation in both these events as FR actor in the field, we present the challenges, the complexity of such multi-aspect disaster events, the limitations of emergency response, the technology gaps of the FR teams, as well as the lessons learned during these deployments. Finally, we make some notes on future prospects and possible advancements in tools and technologies that would greatly enhance the operational safety and readiness of the FR teams in such events.

Keywords

First Responders, Search and Rescue, Flash Flood, Urban Wildfire, Urban Operations.

INTRODUCTION

Today's emergency response operations need to address a very wide range of missions, from localized accidents with very few victims to large-scale disaster events with hundreds of known and unknown victims. The context of such operations also ranges widely in terms of working environment (open/closed spaces), hazards, weather conditions, time constraints, medical emergencies, evacuation routes, etc. It is imperative that the First Responder (FR) teams and the Communication & Coordination Center (C3) have the necessary resources to operate with safety,

*This work was partially supported by the projects *FASTER* (<https://www.faster-project.eu/>), *CURSOR* (<https://cordis.europa.eu/project/id/832790>) and *INGENIOUS* (<https://ingenious-first-responders.eu>), which have received funding from the European Union's Horizon 2020 (H2020) programme under grant agreements No:83507, No:802790 and No:83435, respectively.

†Corresponding author - mailto:harris@georgiou.info

<http://www.eoathens.gr/>



(a)



(b)

Figure 1. Mandra areas affected by the flood (source: Copernicus).

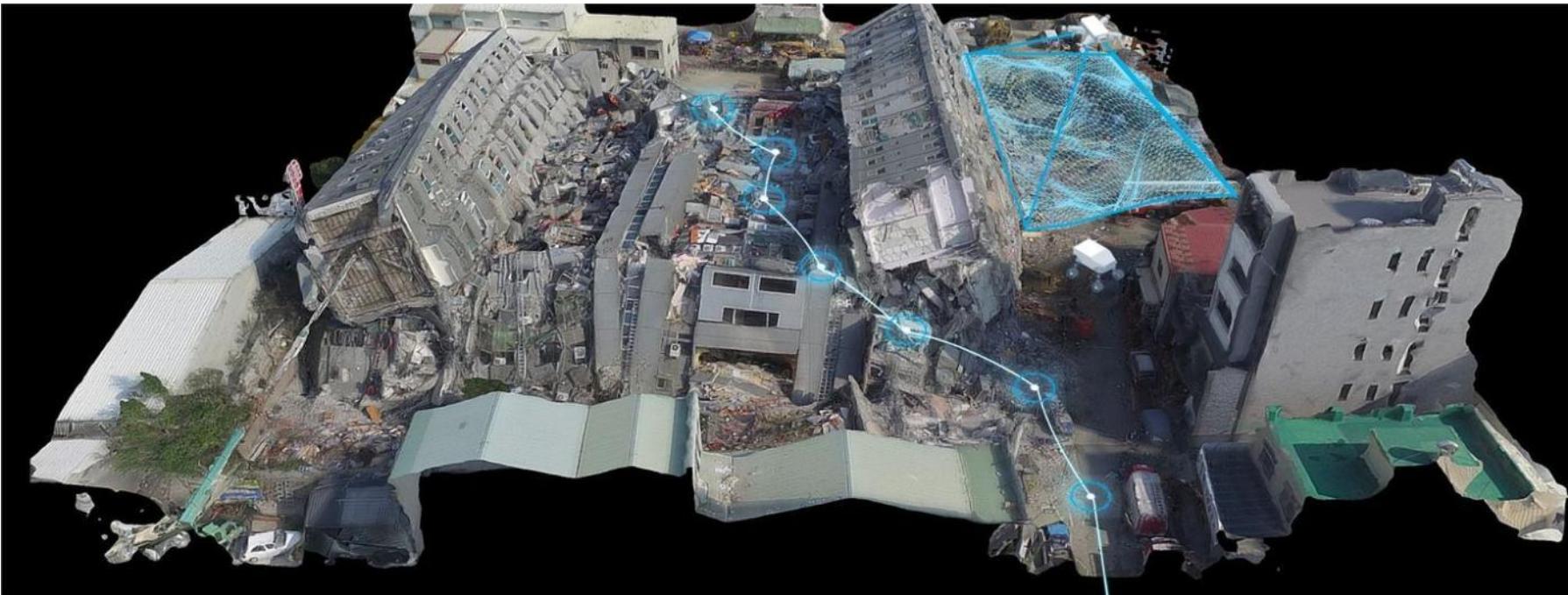


(a)



(b)

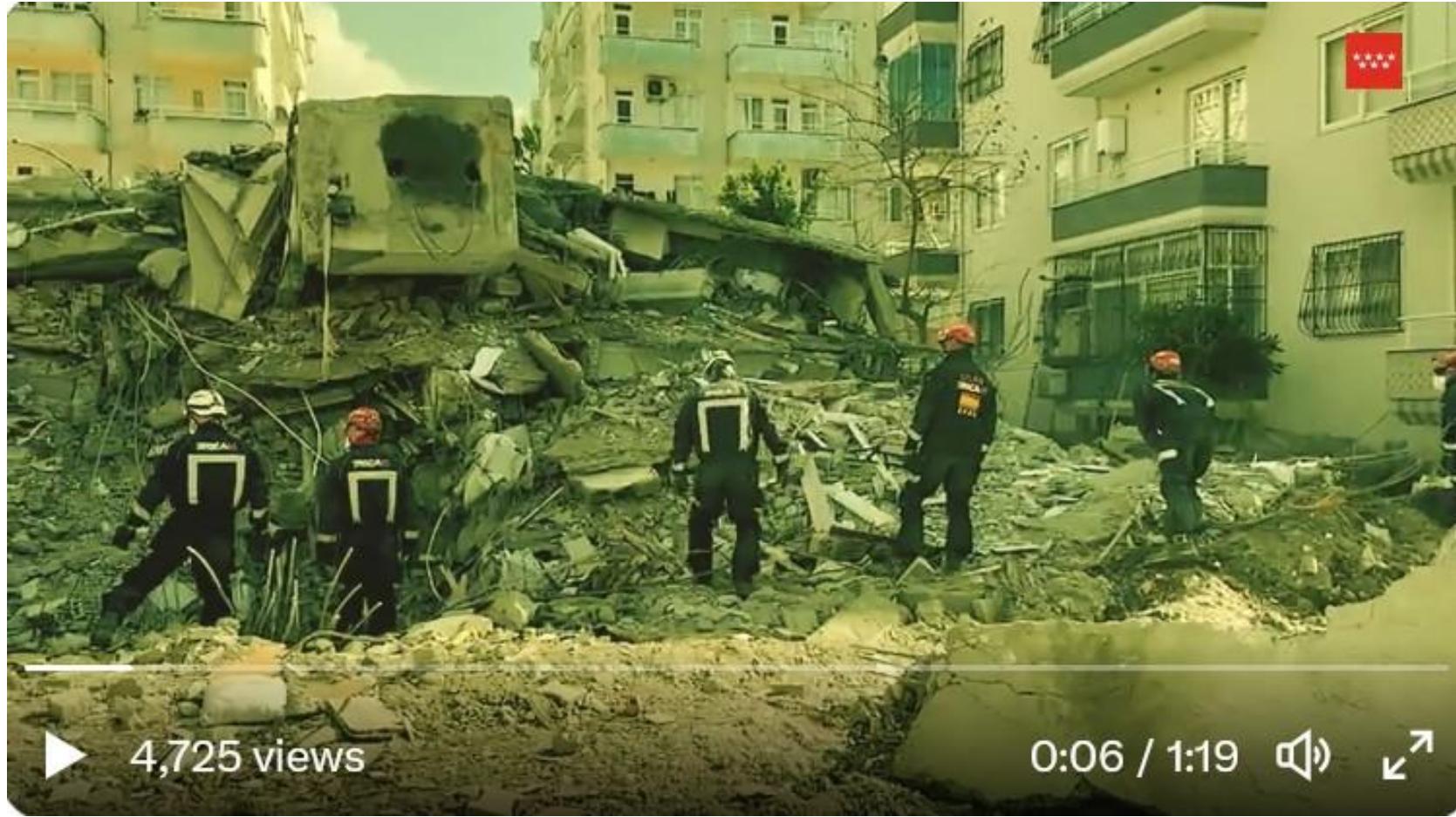
Figure 2. Mandra center (a) during and (b) after the flood (source: local media)



Credits: INTREPID project



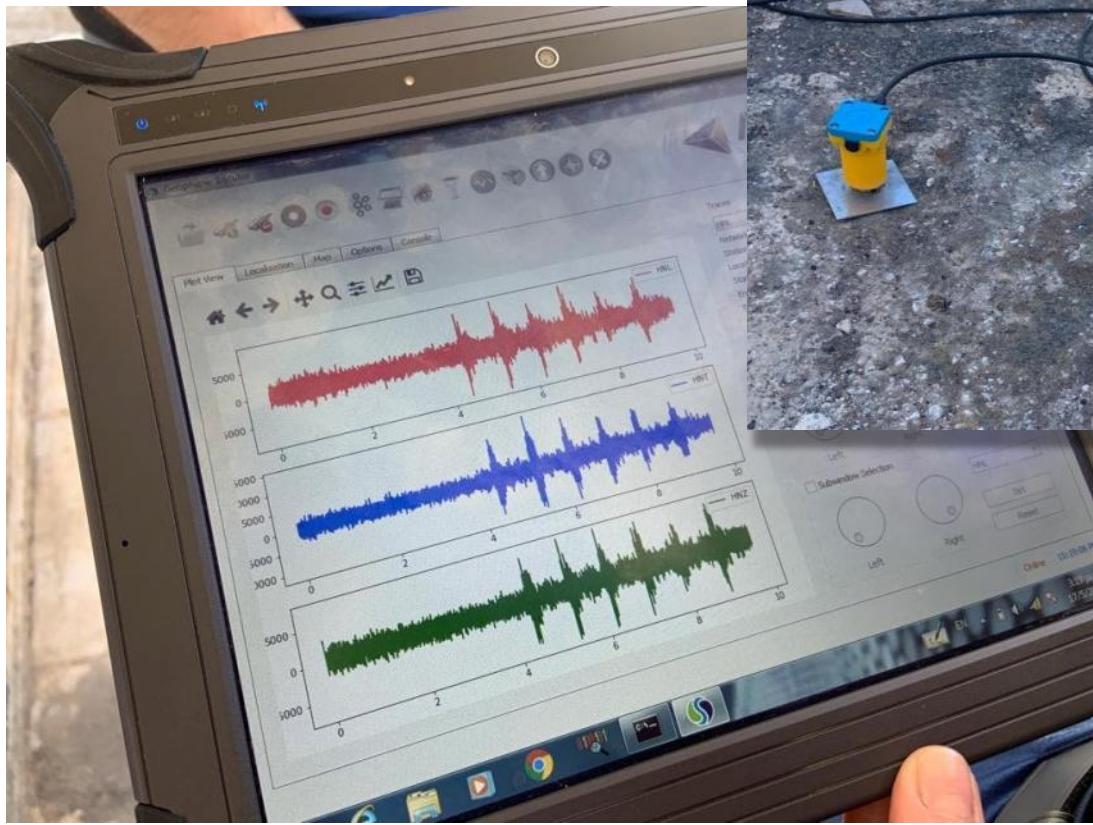
Credits: FASTER project (Madrid, Apr.2022)



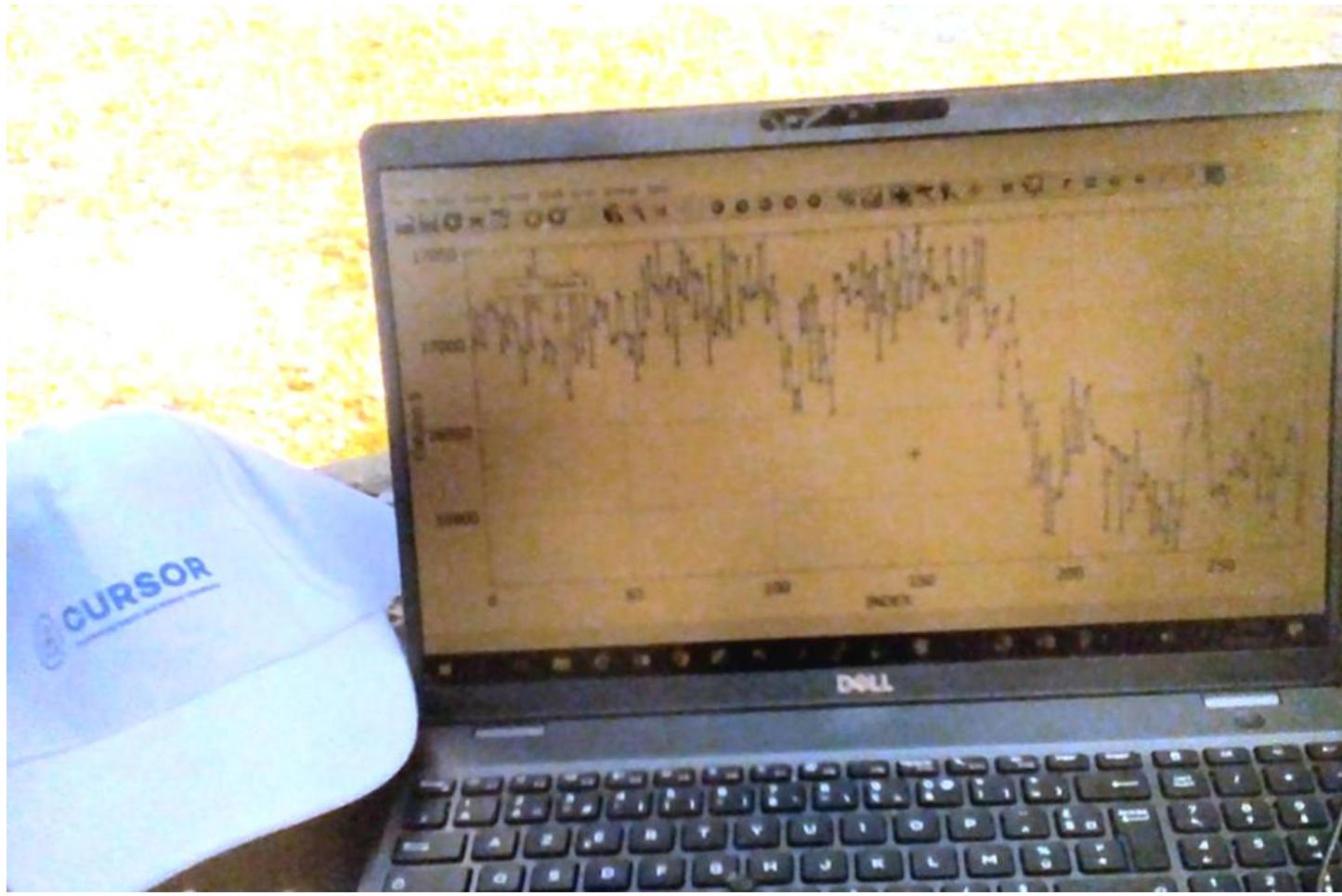
Hatay (Turkey), Feb.2023



Adiyaman (Turkey), Feb.2023



Credits: CURSOR project



Future trends: Access routes assessment

1044

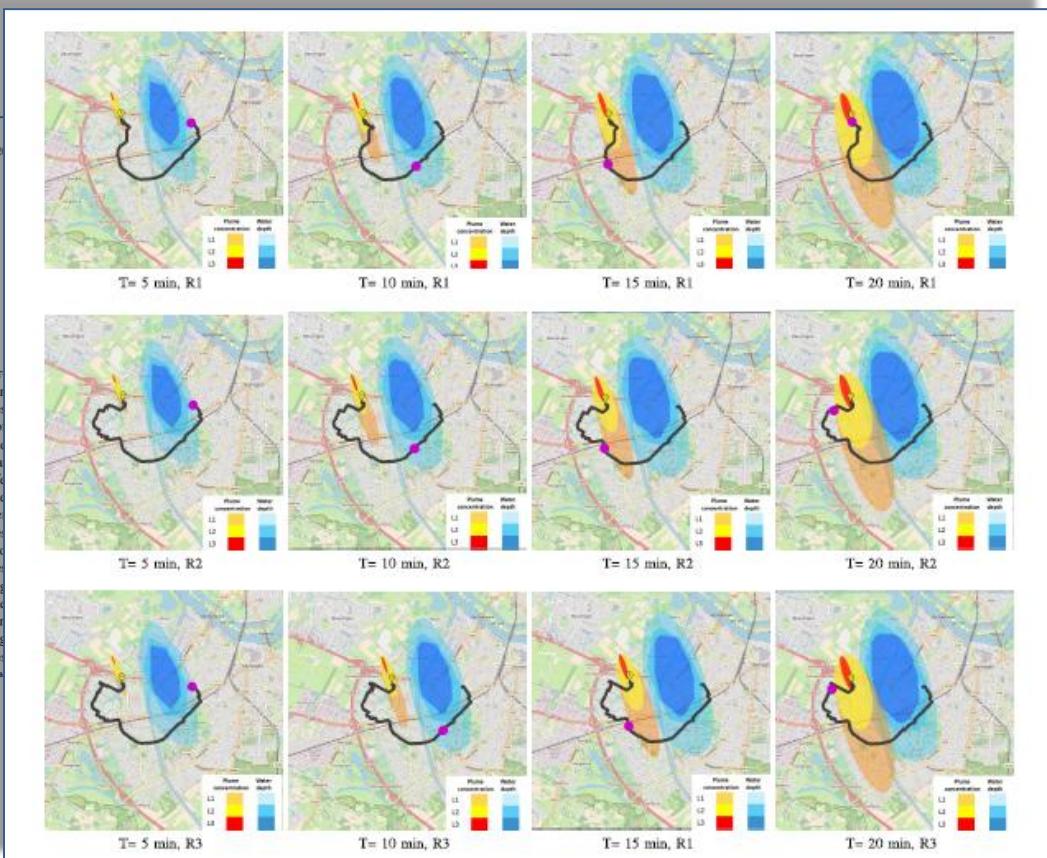
IEEE TRANSACTIONS ON INTELLIGENT TRANSPORTATION SYSTEMS, VOL. 21, NO. 3, MARCH 2020

Safe Route Determination for First Responders in the Presence of Moving Obstacles

Zhiyong Wang[✉] and Sisi Zlatanova[✉]

Abstract—Determining safe and fast routes for first responders is an important issue in a disaster response. Especially when different types of disasters (e.g., toxic plumes, fires, and floods) occur and affect transportation networks simultaneously, special routing strategies (e.g., detour) would be needed to ensure the safety for responders. On the other hand, after disasters happen, a quick response time is required, and the responders should move as fast as possible and even go through certain obstacles to reach the disaster sites to deliver emergency services. In this paper, we study path planning through moving obstacles, taking into account the influence of obstacles on the status of road networks and the speed of rescue vehicles. A set of algorithms is proposed to deal with not only geometries but also the properties of moving obstacles to support route generation. Based on the Dijkstra algorithm, a new routing algorithm is designed and developed, which aims at minimizing the risk while constraining the travel time of routes. We validate our approach with a set of experiments on some navigation cases. The experimental results show the promise of the algorithm in the generation of feasible and safe routes for first responders to pass through moving obstacles.

for disaster situations, they rely only on the real-time information of roads and do not consider the predicted information of obstacles (e.g., position, shape, and properties of obstacles in the near future), which could undermine the feasibility of their route plans and even endanger rescuers when they move through certain types of obstacles. Therefore, there is a great necessity for new approaches to provide responders with safe routes that guide them in the road networks considering the moving obstacles. Another issue is that the response time after disasters happen is critical. For example, in many countries (e.g., the Netherlands and Australia), the responders have to reach incident sites within a time limit after emergencies occur [7]. Although in some cases conversely avoiding moving obstacles would ensure the safety of responders, they lose their time needed for their rescue missions. As responders can have some protective equipment that prevents them from being harmed by hazards, they can pass through some obstacles within certain risk levels to facilitate the disaster response.



Future trends: Body part detection & assessment

Data-Driven Skin Detection in Cluttered Search and Rescue Environments

Yogeshwar Singh Dadwhal[✉], Student Member, IEEE, Satish Kumar, Member, IEEE,
and H. K. Sardana[✉], Member, IEEE

Abstract—Locating human victims in cluttered urban search and rescue (USAR) environments is still a challenge. In this paper, we present an approach to generate *skin objectness* windows to assist human rescuers. We introduce the term *skin objectness* to denote the task of extracting windows in the scene with a high probability of skin presence for locating victims. Unlike naïve skin segmentation approaches, the presented algorithm accounts for both color and spatial information to extract regions of interest and at the same time, rejects the background clutter. We use temporal information of the video sequence to make the skin objectness windows more reliable. To selectively boost skin regions, the RGB skin pixels are transformed to Gabor space to generate a transformation matrix. The matrix is used to generate skin. Further, the Bayesian inference and temporal cues from previous frame are used to refine the skin objectness windows. It has real-time applications in image retrieval, action classification, etc. The proposed method demonstrates quantitative and qualitative results on a disaster dataset.

Index Terms—Distinctiveness, Gabor filters, color image analysis, skin detection, temporal processing.

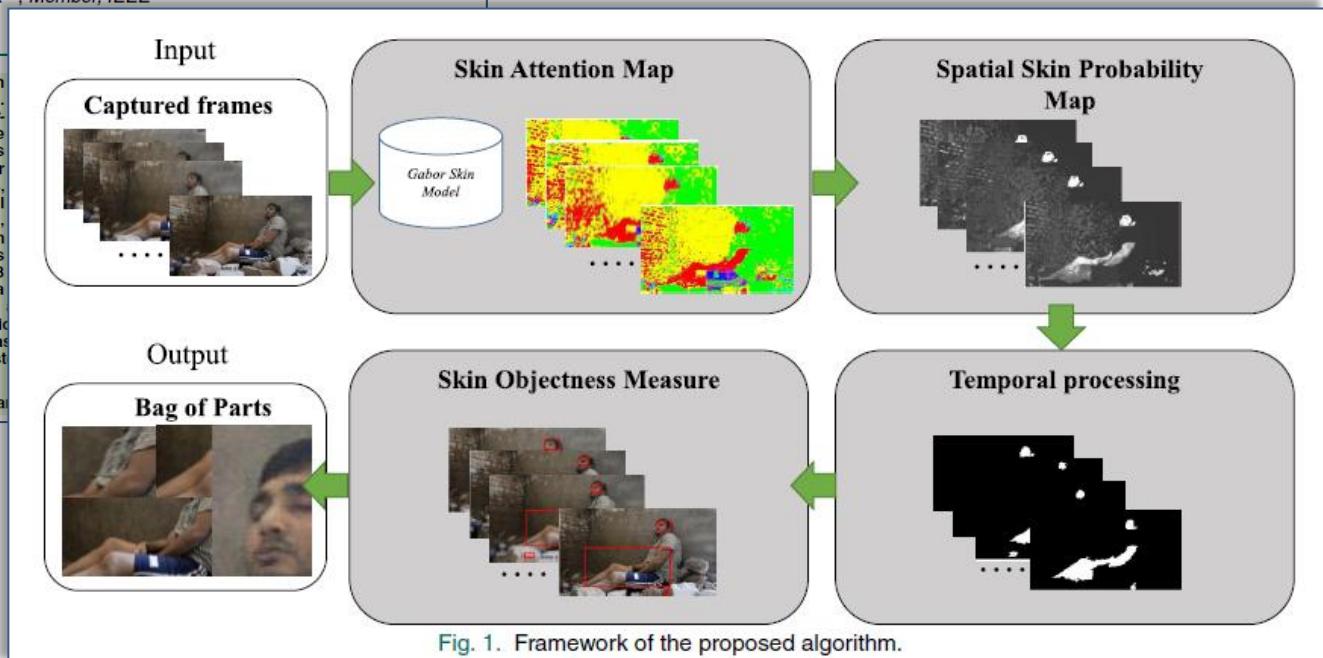


Fig. 1. Framework of the proposed algorithm.

Last thoughts: Small steps, simple lessons



PROACTIVE EU @PROACTIVE_EU · 3h

Testimony by **#CSAB** member Luca Rotondi from **@EmergenzaSordi** on the valuable contribution of deaf volunteers in our **#CBRNe** exercise. Their participation exposed communication challenges. This experience helps grow the knowledge on the needs of deaf persons during a **#CBRN** incident.

...



Moving forward

- First Responder safety enhancement
- Situational awareness, hazards, area mapping
- Rapid-deployment scout team
- Adapt & solve – e.g. USAR evacuation via sea
- Live forecasting of local weather conditions
- Accurate localization inside disaster area
- Missing/found persons registry & tracking
- Open standards & interoperability for tools
- Forensic tools in the field for non-experts
- Underwater voice/data communications
- Simple tools may be vital (maps, translate, ...)
- “Prepare for the unexpected”



Σύνοψη

- Περιεχόμενα:
 - Τεχνολογίες USAR επόμενης γενιάς (UAV, COP, AR, remote sensing, ...)
 - “Detection of victims with UAVs during wide area Search and Rescue operations” (SSRR’22)
 - “Emergency response in recent urban/suburban disaster events in Attica: Technology gaps, limitations and lessons learned” (ISCRAM’21)
 - Future trends / “Moving forward”
- Πηγές:
 - EU H2020 projects (SCENT, FASTER, CURSOR, INGENIOUS, INTREPID)
 - INSARAG Guidelines for USAR Operations (2020)

```

MOVE 1 TO DATA-C(N-T).
ADD 1 TO N-CHANGED.
GO TO LOOP-SCAN.

SELECT-CLZ.
ADD DATA-X(N-T) TO SUM2-X.
ADD DATA-Y(N-T) TO SUM2-Y.
ADD 1 TO N-CLZ.
IF DATA-C(N-T) EQUAL 2 GO TO LOOP-SCAN.
MOVE 2 TO DATA-C(N-T).
ADD 1 TO N-CHANGED.


```

LOOP-SCAN.

ADD 1 TO N-T.

GO

```

91      id : Integer := 0; -- target ID (counter)
92      det : Integer := 0; -- detection slots in sequence
93      pwr : Integer := 0; -- rel. power of detection
94      pwr0 : Integer := delimit; -- rel. power baseline (adapt
95      disp : Boolean := False; -- target reporting (flag)
96
97      begin
98          -- process the FOV slots --
99          for p in 1..(seekerData'Length)-1 loop
100              -- rel. power is current detection 'step'
101              pwr := abs(seekerData(p+1)-seekerData(p));
102              if pwr >= delimit then
103                  -- detection valid, continue analysis
104                  if pwr > pwr0*delimit then
105                      -- strong new 'step' from baseline (new target)
106                      pwr0 := pwr; -- update the baseline
107
108                      det := id;
109                      id := id + 1;
110
111                      -- check if
112                      if (det = id) then
113                          id := id + 1;
114                          disp := True;
115                          pwr0 := pwr;
116                          disp := False;
117

```

Fortran



apnea
coding

*how it works:
Cold War SOSUS - realistic*

STDIN
Input for the program (Optional)

Output:

```
x86_64-linux-gnu-gcc-9 -c HelloWorld.adb
HelloWorld.adb:1:01: compilation unit expected
x86_64-linux-gnu-gnatmake-9: "HelloWorld.adb" com
```

- Error-correction codes (comms)
- Optimization algorithms
- Optimal-path algorithms
- GZteam repository (ERC)
- ...

YouTube:

@ApneaCoding



<https://www.youtube.com/@apneacoding>

Github:

@xgeorgio



<https://github.com/xgeorgio>

Αναφορές

- F. Steinhausler, H. Georgiou (2022). “Detection of victims with UAVs during wide area Search and Rescue operations”, IEEE Intl. Symposium on Safety, Security and Rescue Robotics (SSRR 2022), 8-10/11/2022 @ Seville.
- S. Chrysanthopoulos, T. Kapetanakis, G. Chaidemenos, S. Vernardos, H. Georgiou, C. Rossi (2020). “Emergency response in recent urban/suburban disaster events in Attica: Technology gaps, limitations and lessons learned”, 17th ISCRAM Conference, Track 14: Technologies for First Responders (ISCRAM 2020), 24-27 May 2020 @ Blacksburg, VA, USA [Best Paper / Murray Turoff Award] ISSN:978-1-949373-27-88, s/n:2289, pp. 984-989.
- “First responder Advanced technologies for Safe and efficient Emergency Response”. FASTER Project (GA-833507), EU Horizon H2020, CORDIS, E.C. – <https://www.faster-project.eu>
- “The First Responder (FR) of the Future: a Next Generation Integrated Toolkit (NGIT) for Collaborative Response, increasing protection and augmenting operational capacity”. INGENIOUS Project (GA-833435), EU Horizon H2020, CORDIS, E.C. – <https://ingenious-first-responders.eu>
- “Coordinated Use of miniaturized Robotic equipment and advanced Sensors for search and rescue Operations”. CURSOR Project (GA-832790), H2020, E.C. – <https://cursor-project.eu>
- “Intelligent Toolkit for Reconnaissance and assessment in Perilous Incidents”. INTREPID Project (GA-883345), EU Horizon H2020, CORDIS, E.C. – <https://intrepid-project.eu>
- “Smart Toolbox for Engaging Citizens into a People-Centric Observation Web”. SCENT project (GA-688930), H2020, E.C. – <https://scent-project.eu>
- INSARAG Guidelines for USAR Operations (2020) – <https://www.insarag.org/methodology/insarag-guidelines/>

Ερωτήσεις



Χάρης Γεωργίου (MSc,PhD)
<https://www.linkedin.com/in/xgeorgio/>
https://twitter.com/xgeorgio_gr