

# Offshore wind-turbine structures: a review

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This paper reviews various issues related to wind-power generation, one of the more popular forms of renewable energy, including attractions and challenges of electric power generation through onshore and offshore resources. Significant increases in wind-turbine dimensions, rated power-generation capacity and size of wind farm developments over the past two decades are projected to continue. Offshore wind-power generation presents many engineering challenges including: limited guidelines available for analysis and design of foundation/support structures; inadequate logistics for construction/fabrication; and comparatively expensive operation and maintenance costs, which combined result in current levelised cost of energy approximately double that for onshore wind-power generation. Different offshore foundation options are discussed in terms of general layout, loading characteristics and related fundamental natural frequency. Outlooks for some new approaches/developments and areas for further research are identified that may go towards reducing the levelised cost of energy for wind-power generation more in line with that from other energy resources, thereby enhancing the attractiveness of this industry for potential investors.

## Notation

$A$	scalar
$EI$	bending stiffness
$f_{\text{nat}}$	first natural frequency
$f_{\text{wind}}$	probability density function
$k$	shape factor quantifying width of wind-speed distribution
$L$	strut length
$M$	turbine mass
$\bar{U}_{10}$	wind speed at 10 m elevation above mean sea level or typically at hub height for OWTs
$\bar{U}_z$	mean wind speed at elevation $z$ above mean sea level
1P	first excitation frequency
3P	blade passing frequency for three-bladed turbine
$\alpha$	scalar
$\mu$	strut mass per unit length
$\nu$	Weibull random variable

## 1. Introduction

Wind-power turbines harness the kinetic energy of the wind, providing the motive force to rotate turbine blades and develop, by way of a drive shaft, the mechanical power to

generate electricity. Wind turbines are categorised by axis of rotation of the main rotor shaft (either horizontal or vertical axis) and whether they are located onshore or offshore (Tong, 2010). For modern commercial wind turbines, the main rotor shaft is horizontally aligned. Rated power-generation capacity is mainly dependent on rotor diameter and wind speed (IRENA, 2012); for example, if wind speed increases two-fold, its energy content increases eight-fold. Two key speed terms are 'cut-in speed', at which the wind turbine begins to produce power, and 'cut-out speed' at which the turbine must be shut down to protect the rotor and drive-train machinery from possible damage (Sørensen *et al.*, 2009; Tong, 2010).

Between 2000 and 2011, global wind-power capacity approximately doubled every 3 years, with an estimated total power generation of 238 GW achieved by the end of 2011; China, the USA and Germany are the top industry players (GWEC, 2011). Although the market is still dominated by onshore, with significant onshore wind resources yet to be explored, the offshore wind market is growing rapidly. Global total installed capacity for offshore of 3.12 GW was generated by the end of

2010, with 1.16 GW added in 2010 alone – a 59.4% increase on the previous year (WWEA, 2011). Total offshore wind-power capacity in Europe reached 2.90 GW by the end of 2010, with 0.88 GW added in 2010; again this represents a significant increase of 43.6% on the previous year. This occurred at the same time as onshore new-capacity additions declined by 13% (WWEA, 2011).

The size of offshore wind farms is also increasing, with 2010 data indicating that the average size of an offshore wind farm in terms of power output was 155 MW – more than double the average wind farm size of 72 MW for 2009 (EWEA, 2011). Preliminary data for 2011 suggest that offshore wind-power capacity in Europe increased by 0.86 GW (EWEA, 2012), with the offshore market likely to be driven by mainly the UK and Germany, although France and Sweden also have significant projects imminent. Collectively the European Union (EU) has plans to generate approximately 40 GW from offshore wind by 2020 (EWEA, 2009). In its 2008 communication on offshore wind energy, the European Commission anticipated offshore wind can and must make a substantial contribution to meeting the EU's energy policy objectives through a very significant increase – in the order of 30 to 40 times by 2020 and 100 times by 2030 – in installed capacity compared to today (ECN, 2011a).

Interest in offshore wind power is also increasing in other regions of the world, with, for example, China, the USA and South Korea planning to generate 6.0 and 3.0, 2.5 GW, respectively, by 2020. Building on this, China and the USA have ambitious plans to generate 65 and 54 GW, respectively, from offshore wind by 2030 (AWEA, 2012; Musial and Bonnie, 2010).

A significant hurdle for the offshore market, however, is the high initial capital investment costs of the project, which is related to: inadequate and (or) potentially unreliable design guidelines for offshore wind-turbine (OWT) installations, especially foundation structures; more stringent requirements for durable construction materials to withstand the harsh marine environment; high-tech equipment requirements for on-site operation and also shortage of trained manpower (Musial and Bonnie, 2010). In addition, the next generation of OWTs will be installed at greater distances offshore and hence in greater water depths (see Section 4). Compared with onshore, attractions of offshore wind-power generation generally include: longer life-span of OWTs on account of less fluctuation of wind speed; availability of ample free space for installation; consistently higher wind speeds and generally reduced adverse environmental effects (Damien and Mo, 2002).

This review paper considers the following aspects of the wind industry

- trends in geometric size and rated power-generation capacity of onshore and offshore wind turbines
- cost analyses
- different foundation options available, including features of exemplary structures, with particular focus on OWT structures
- challenges and attractions of wind-power generation.

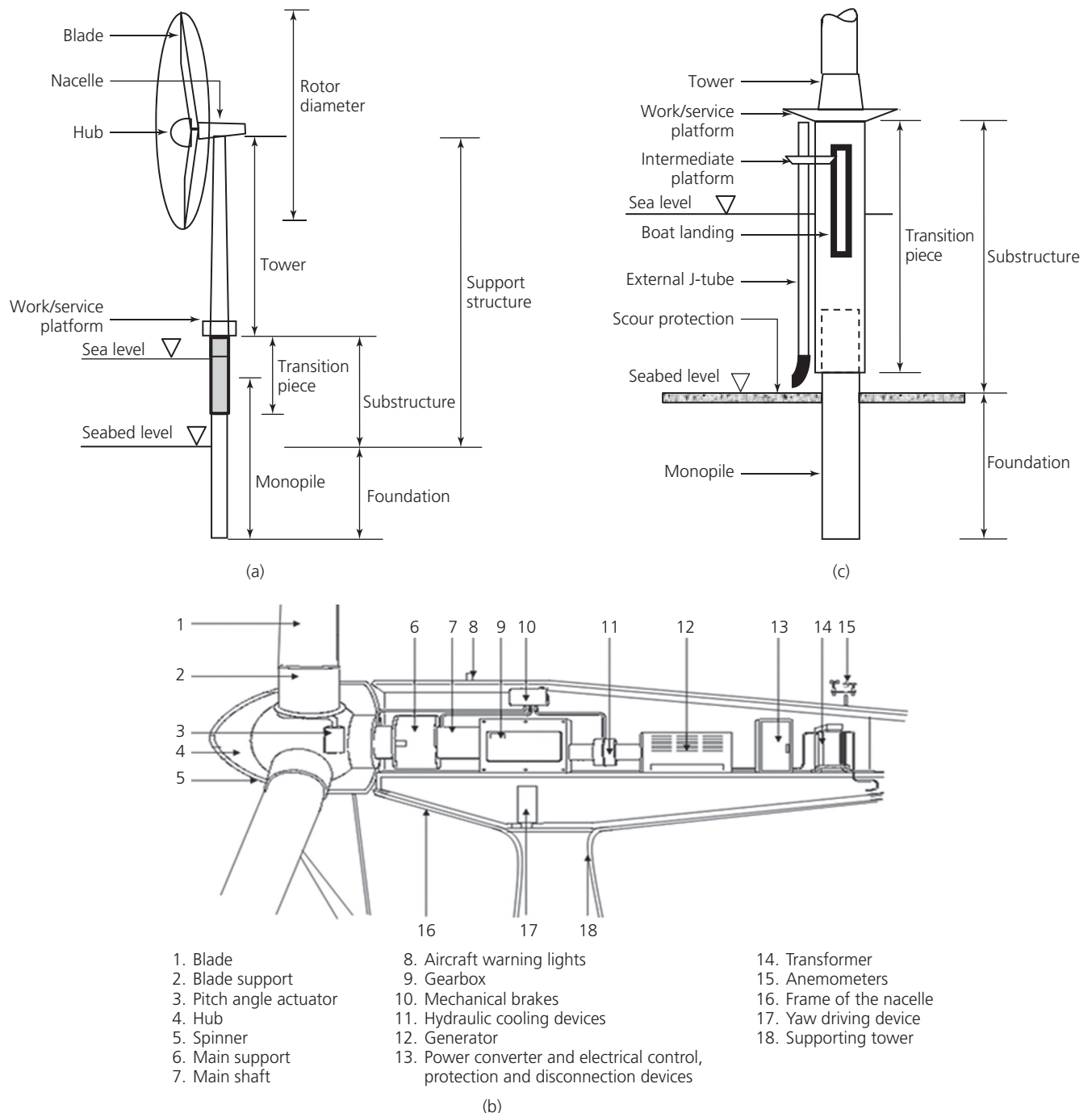
Recommendations for future research and practice are also proposed to make offshore wind energy comparable with other sources of renewable energy.

## 2. Trends in geometric size and rated power capacity of offshore wind turbines

Figure 1(a) shows the main components of an OWT system, including a typical monopile foundation, the substructure, transition piece, tower, rotor blades and nacelle (hub). Modern OWTs are installed with either pitch-regulated blades or variable rotational speed systems in order to allow optimisation of power production over a wide range of prevailing wind speeds. The rotational speed of the main rotor shaft is typically between 10 and 20 rpm (Alderlieste, 2010; Malhotra, 2011). The nacelle (Figure 1(b)) contains key electromechanical components of the wind turbine, including the gearbox and generator. Operational details of these components have been reported by Maria (2009) and Tong (2010). The gearbox may cause efficiency losses for the wind turbine and is a particular source of noise. Recent developments in the design of permanent magnet generators have made it possible to construct some types of wind turbines without the requirement for a gearbox. In this case, the rotor is connected directly to a low-speed multi-pole generator that rotates at the same speed, termed a direct-drive unit. Removing the gearbox removes one of the key components requiring more maintenance and that is prone to failure. This simplification of the mechanical part allows reductions in size and mass of the nacelle (Treehugger, 2011).

The substructure connects the transition piece or tower to the foundation at seabed level. In Figure 1(a), a monopile is shown as the foundation system, although other foundation types, discussed later in the paper, may also be used. Together the tower, substructure/support structure and foundation maintain the turbine in its correct operational position. The transition piece provides a means of correcting for any vertical misalignment of the foundation that may have occurred during its installation. In some cases, the foundation can extend to above the water surface, thereby also serving as a substructure by connecting directly to the transition piece or tower.

Figure 2 shows the steady increase in rotor diameter and rated power capacity (RPC) of wind turbines installed over the past



**Figure 1.** Major components of OWT system: (a) wind-turbine system; (b) electromechanical parts adapted from ABB (2012); (c) details of monopile and transition piece

three decades. In particular, between 1990 and 2010, the RPC increased from typically 0.5 to 7.5 MW and rotor diameter from approximately 40 to 150 m (EWEA, 2011b). Offshore wind turbines having 250 m rotor diameters and with  $RPC \geq 20$  MW are currently in the research and development

phase (EWEA, 2011b). Table 1 presents correlations determined from data of more than 150 modern, utility-scale wind turbines which can be used to approximate the size and mass of different OWT components, considering RPC as a key driving input.

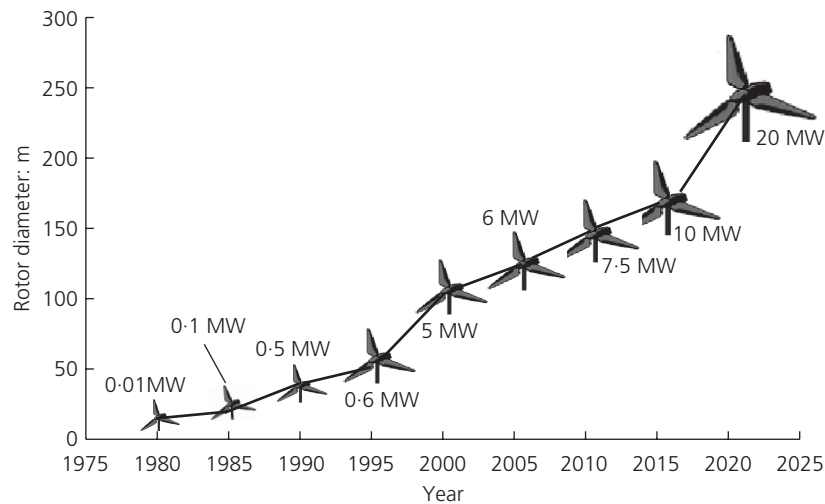


Figure 2. Increase in rotor diameter and RPC of wind turbines

### 3. Cost analysis of wind-power generation

Approximately 70–75% of the total cost of offshore wind-power production is related to initial capital investment costs, including that of the turbine, foundation, electrical equipment and grid connection (Kooijman *et al.*, 2001; Søren *et al.*, 2009). The ‘levelised cost of energy’ (LCOE) is the primary measure for quantifying and comparing underlying economics of power projects (Fischer, 2011). For wind-power systems, LCOE represents the sum of all costs, including capital cost, operation and maintenance costs, and also expected annual energy production (Cambell, 2008; Søren *et al.*, 2009) for a fully operational wind-power system over the project’s lifetime, with financial flows discounted to a common year. However, empirical methods that use the more extensive databases currently available for onshore wind-power projects in estimating the LCOE for new offshore projects are not reliable (IRENA, 2012).

Between 40% and 70% of costs for conventional fossil-fuel-fired technologies are related to fuel, operation and maintenance (Søren *et al.*, 2009). Hence, since fuel costs have no impact on wind-power generation costs, wind turbines are more capital intensive compared with fossil-fuel-fired technologies. In China for instance, the LCOE for onshore wind was almost 300% and 200% more costly compared with electric power generation from natural gas and coal, respectively (YFH, 2011), although such cost comparisons are somewhat dependent on the accuracy of projected trends for the costs of fuel, other commodities and logistic facilities. Initial capital investment costs for offshore are approximately double (YFH, 2011) and may reach up to three times that for onshore wind-power projects having similar power generation capacity on account of increased investment required in transportation of materials and turbines, construction and installation of foundations, equipment and turbines at sea

Parameters	Correlation
Rotor diameter ( $D$ , in m) and RPC (MW)	$D = 59.354(RPC)^{0.47}$
Rotor speed ( $R_{speed}$ , in rpm) and RPC (MW)	$R_{speed} = 22.781(RPC)^{-0.3595}$
Hub height (HH) and rotor diameter ( $D$ )	$HH = D/0.255(D)^{0.3464}$
Hub mass including pitch, bearing and driver system ( $M_{(pb+ds)}$ , in t) and RPC (MW)	$M_{(pb+ds)} = 8.6421(RPC)^{1.1194}$
Rotor mass including hub, pitch system and blades ( $M_{(hb+ps+bl)}$ , in t) and RPC (MW)	$M_{(hb+ps+bl)} = 18.453(RPC)^{1.1357}$
Mass of main rotor shaft ( $M_{(ms)}$ , in t) and RPC (MW)	$(M_{(ms)}) = 0.2415(RPC)^2 + 3.0699(RPC)$
Mass of main bearing ( $M_{(mb)}$ , in t) and RPC (MW)	$M_{(mb)} = 0.1246(RPC)^2 + 1.2623(RPC)$
Mass of rotor, drive-train support structure and nacelle ( $M_{(r+d+n)}$ , in t) and RPC (MW)	$M_{(r+d+n)} = 37.45(RPC)^{0.984}$
Mass of all components at top of tower ( $M_{(thm)}$ , in t) and RPC (MW)	$M_{(thm)} = 55.9216(RPC)^{1.0341}$

Table 1. Effect of RPC on size and mass of wind-turbine components (Tong, 2010)

and laying offshore cables (IRENA, 2012; Martin *et al.*, 2004). The trend for OWT installations at increasing distances offshore and hence location in greater water depths constitutes a significant factor in the cost analysis for offshore projects. Cost comparisons between onshore and offshore wind-power technologies should be based on evaluations for a specific region and/or country (EEA, 2009). Table 2 shows comparisons between costs for different components of onshore and offshore wind-energy projects.

For wind-power generation, the overall contribution of operation and maintenance (O&M) costs to the LCOE is significant and also site specific. Data from different countries including the USA, China and many European countries indicate that O&M costs for onshore wind power account for between 11% and 30% of the total LCOE (IRENA, 2012). The lowest contribution of US\$0.010/kW was reported for the USA, with approximately US\$0.013–0.015/kW reported for best practice in Europe (IRENA, 2012). However, O&M costs for offshore are significantly greater on account of higher costs incurred in accessing and maintaining the wind turbines, towers and cabling. In the UK, for example, Feng *et al.* (2010) reported O&M costs for offshore wind-power projects in shallow water depth were approximately 1.5 times that for onshore projects. Offshore maintenance costs are also higher on account of the harsher marine environment and higher expected failure rates for some electrical and mechanical components. In general, O&M costs for offshore wind power are typically in the range US\$0.027–0.054/kWh (ECN, 2011b). Many existing offshore wind farms are only at the beginning or early stage of their deployment phase. Since data on their O&M costs remain highly project specific, it will be some time before observable trends emerge and means of reducing these costs are identified. Offshore maintenance facilities may

also be necessary to ensure smooth operation of the next generation of OWTs to be installed at greater distances from the shore line. Hence it is clear that the reduction of O&M costs for offshore wind farms is a key challenge, and once addressed, may improve the economics of offshore wind energy (Douglas-Westwood Limited, 2002; IRENA, 2012).

In Europe, LCOE estimates of between 0.10 and 0.13 US\$/kWh were reported by IEA (2009) for onshore wind in 2011, assuming a typical capacity factor (ratio of average power delivered to theoretical maximum power) for new onshore projects of between 25% and 30%. For a given capacity factor, assumed cost reductions achievable by 2015 may allow reductions in LCOE of between 6% and 7%. In North America, the LCOE for onshore wind having a capacity factor of 30% was estimated at between 0.10 and 0.11 US\$/kWh for 2011. By 2015, anticipated cost reductions for a given capacity factor may allow reductions in LCOE of between 5% and 9% (Wiser and Bolinger, 2011). Compared with Europe and North America, LCOE estimates for onshore wind power in China and India were significantly lower at between 0.07 and 0.08 US\$/kWh (2011 data) for a capacity factor of 25%. However, since China and India already have very competitive installation costs for wind-power projects compared to the norm in other developed countries, opportunities for further cost reductions are comparatively smaller. By 2015, average installation costs may also increase somewhat on account of projected increases in engineering project costs, manufacturing costs for wind turbines in emerging economies and/or the supply situation becoming tighter (E.ON Climate & Renewables, 2011).

As a general trend, the LCOE for offshore wind-power generation around the globe is typically almost double that of

Item	Offshore	Onshore
Initial capital investment cost: US\$/kW	3300–5000	1700–2450
Wind-turbine cost, including production, transportation and installation: % of initial capital investment cost	30–50	65–84
Cost of grid connection including cabling, substations and buildings: % of initial capital investment cost	15–30	9–14
Construction cost including foundation, transportation and installation of tower and turbine and other infrastructure (e.g. access roads for onshore) necessary for turbine installation: % of initial capital investment cost	15–25	4–16
Other capital costs including development and engineering costs, licensing procedures, consultancy, permits, supervision, control and data acquisition, monitoring systems: % of initial capital investment cost	8–30	4–10

**Table 2.** Cost comparisons for offshore and onshore wind projects (Douglas-Westwood Limited, 2002; Henderson *et al.*, 2003; IRENA, 2012; Junginger *et al.*, 2004; Kooijman *et al.*, 2001)



onshore having similar capacity factors (Roddy *et al.*, 2009). For instance, reported ratios of LCOE for offshore to onshore wind-power projects were 1.3 for Denmark and 1.46 for the UK (Feng *et al.*, 2010; Krohn *et al.*, 2009). Between 2009 and 2011, the overall trend in the LCOE for offshore wind power continued to increase gradually, compared with onshore, which typically showed a small reduction (BNEF, 2011). Hence the LCOE for offshore wind power is likely to remain greater than for onshore (even taking into account higher capacity factors achievable offshore) and will probably remain so, given the significant challenges involved in reducing capital and O&M costs (Tricklebank, 2008). The main reason for this is the trend of increasing distance offshore (and hence greater water depth) necessary for the next generation of offshore wind-farm operations, which leads to increased costs in all aspects of the supply chain. Turbine prices are increasing due to necessary design improvements to achieve greater reliability in the harsh marine environment and also on account of larger, more sophisticated wind turbines necessary to increase capacity factors (Maria, 2009). Construction and cabling costs also increase as a function of water depth/distance offshore. However, encouragingly, a recent study performed in China (IEA, 2011) indicated that by 2020, 2030 and 2050, initial capital investment costs for offshore wind-power projects located in up to 50 m water depth are estimated to reduce by 25%, 36% and 50%, respectively, compared with current initial capital investment costs (2010 data). Furthermore a 33% reduction in O&M costs was predicted by 2030, although no further reduction was anticipated between 2030 and 2050. In Europe, respective reductions of 15% and 20% in initial capital investment and O&M costs are estimated to occur between 2006 and 2015, although further reductions of approximately 10% in initial capital investment costs are expected for offshore wind-power projects between 2020 and 2050 (CEC, 2007; Søren *et al.*, 2009).

#### 4. Foundation systems

Support structures/foundations for offshore wind farms are generally more complex than for onshore, involving greater technical challenges, including design requirements to withstand the harsh marine environment and prolonged impact under large wave loading (see Figure 3). The various support structure/foundation concepts employed (Figure 4), which have been adopted from the offshore oil and gas industry, are usually categorised as either bottom-mounted structures (i.e. rigidly connected to the seabed through a foundation system) or floating-support structures that have no rigid connection with the seabed. The foundation solution adopted depends on local seabed conditions, water depth and financial constraints (AWS True wind, 2010; Igoe *et al.*, 2013).

At present, monopiles (Figures 4(b) and 4(c)) are by far the most widely adopted substructure–foundation system for modern

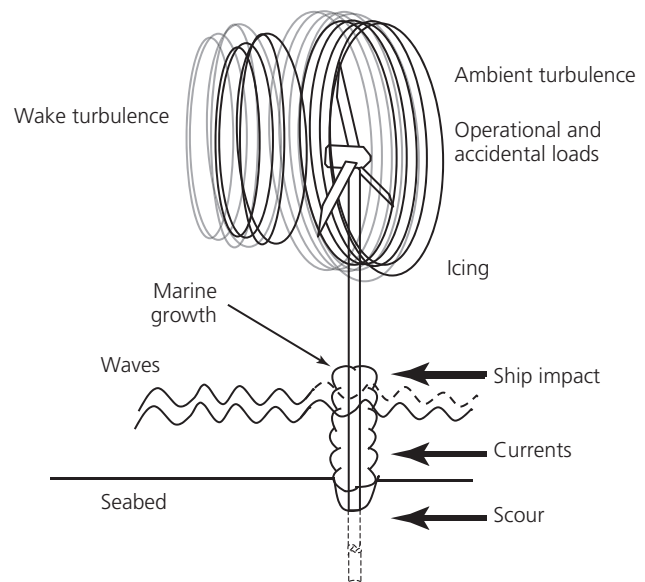
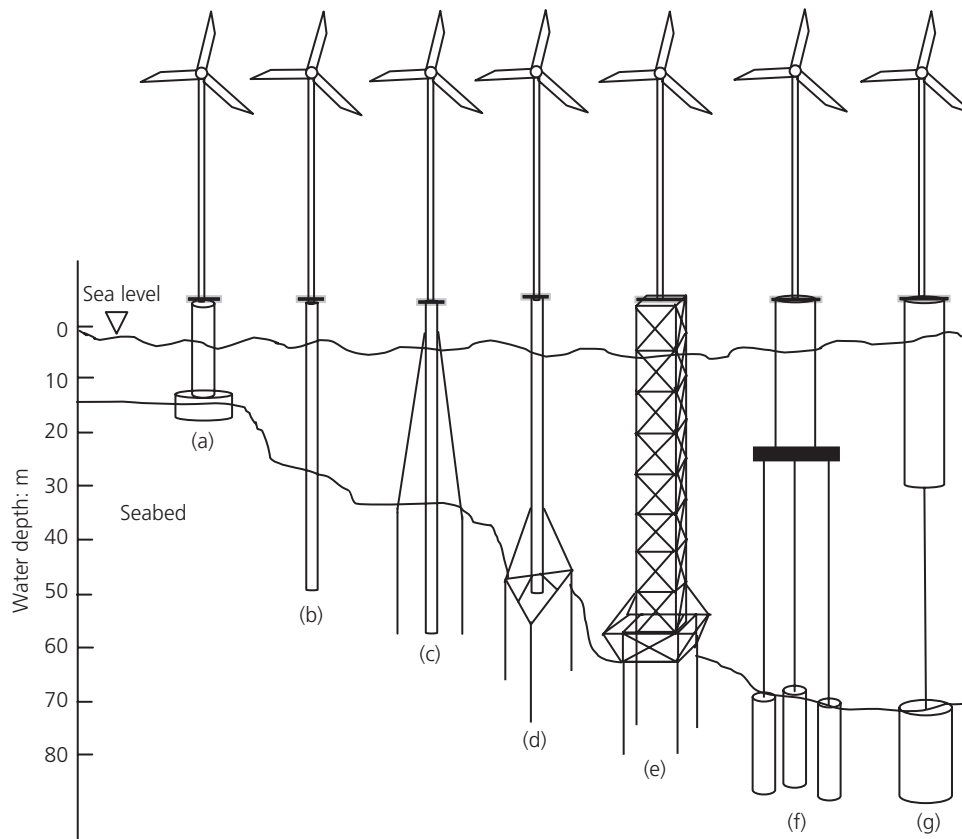


Figure 3. Environmental impacts on OWTs

offshore wind farms located in shallow water depths ( $\leq \sim 40$  m). Such monopiles consist of a steel tubular section (pipe pile), typically 4–6 m in diameter and up to 1000 t in mass, which transfers the applied vertical and larger lateral loading into the seabed foundation. Its complete installation is usually achieved within 24 h (Fischer, 2011; Junginger *et al.*, 2004; Saleem, 2011). Cyclic lateral and moment loading on the monopile are resisted by horizontal earth pressures mobilised in the surrounding soil along the monopile embedded length. The monopile embedment length is dependent on seabed characteristics/properties and total applied load. An embedment length of 30 m is usually deemed sufficient to meet design criteria, including vertical stability and horizontal deflection requirements (Musial and Bonnie, 2010; Tricklebank, 2008).

Braced support structures (i.e. tripod and jacket/truss) are more suitable for deeper water and heavier turbines (Esteban *et al.*, 2011; Fischer, 2011). Tripods consist of a large-diameter central steel tubular section that is supported over its lower length by three braces (Figure 4(d)), which are connected to the seabed. A range of different foundations can be employed including gravity bases, suction buckets or piles. In this manner, the structural and environmental loads applied on the OWT and the supporting structure are mostly transferred axially through the braces to the seabed foundation. Complete installation of a tripod foundation system with, for example, a water surface to seabed length of up to 50 m and mass of up to 700 t, typically takes between two and three working days, often requiring special equipment for driving/drilling and working under water (Esteban *et al.*, 2011; Fischer, 2011). A jacket/braced frame structure (Figure 4(e)) is a lattice frame



**Figure 4.** Support structure/foundation options for OWTs:  
(a) gravity; (b) monopile; (c) monopile with guy wire; (d) tripod;  
(e) braced frame; (f) tension leg with suction buckets (ballast stabilised);  
(g) buoy with suction anchor

of small-diameter steel struts that (similar to tripods) is anchored to the seabed using one of the different foundation options. Complete installation generally takes up to 3 days. Braced frame structures are particularly suitable for severe maritime weather since the strut components offer lower resistance to prevailing ocean wave and current flow in comparison with monopile or tripod structures. Braced frame structures are also more adaptable to conditions encountered on site, increasing their application range, with geometrical variations of the substructure achieved relatively simply but without altering the stiffness of the whole structure (Vries, 2007).

In the future, it is anticipated that floating structures, which are currently only at research and development stage, will be commercially used, particularly for water depths greater than 50 m (Saleem, 2011). Such floating platforms for wind turbines will impose many new design challenges. Currently, tension-leg platform concepts (see Figure 4(f)) are considered as most economical (Fischer, 2011) because rigid body modes of the floater are limited to horizontal translation (surge and sway)

and rotation around the vertical axis (yaw). Other examples include spar-floater and barrage-floater systems. For the spar-floater (Figure 4(g)), buoyancy is provided to the wind-turbine structure by a long, slender cylinder/capsule that protrudes below the water line (Esteban *et al.*, 2011; Fischer, 2011; Vries, 2007). For the barrage floater, the wind-turbine structure is placed on a barrage and attached by way of anchor lines to the seabed.

From the various foundation systems described above, monopiles are currently by far the most popular solution used worldwide, with 75% share, in comparison with only 5% for jacket/tripod options (E.ON Climate & Renewables, 2011). However, it is estimated that by 2020, between 50% and 60% of new OWTs will be supported by monopiles and a further 35–40% by jacket/tripod systems (Babcock and Brown Company, 2012). The main reason for this shift is the attraction of jacket/tripod systems for deeper sea locations, which provide consistently higher wind speeds and hence greater wind energy (Tempel and Molenaar, 2002).

## 5. Comparison of environmental loading for offshore and onshore wind-turbine structures

Offshore wind-turbine structures are designed to resist loading from hydrodynamic, aerodynamic and also ice and ship-impact sources, whereas onshore structures are principally designed to withstand aerodynamic loading. Aerodynamic loading results from interactions of the rotor and parts of the tower within the turbulent air field, with the generated wind power directly proportional to the cube value of mean wind speed. Aerodynamic conditions for offshore and onshore scenarios are markedly different, with considerably lower fluctuation in loading experienced for offshore on account of associated free-flow conditions and lower surface roughness, although advantages of reduced dynamic loading are partly undone by higher mean wind speeds (Fischer, 2011; Tricklebank, 2008). In general, aerodynamic loading can be characterised by (DNV, 2011)

- vertical wind profile
- mean wind-speed distribution
- turbulence effects.

For offshore, surface roughness is low, increasing only marginally in the event of severe sea states with high waves. Hence wind speed increases sharply with increasing elevation above sea level, producing very steep wind-speed profiles compared with onshore sites. The mean value of 10 min wind-speed data (either measured at a reference elevation of 10 m above mean sea level or usually determined at hub height for OWTs) is referred to as wind speed  $\bar{U}_{10}$ . The mean wind speed  $\bar{U}_z$  at some other elevation  $z$  above mean sea level can be approximated by

$$1. \quad \bar{U}_z = \bar{U}_{10} \left( \frac{z}{10} \right)^\alpha$$

where values of  $\alpha$  range between 0.11 and 0.40 depending on site location; for example,  $\alpha = 0.11$  for open sea conditions, 0.16 for grassland and 0.40 for city centre/urban environments (Haritos, 2007; Journée and Massie, 2001).

For offshore sites, steep profiles of wind speed for the vertical direction usually necessitate lower hub heights, with minima values generally dictated by clearance limits to the turbine's service platform (see Figure 1(a)). Periodic loading effects are also reduced since the difference in mean wind speed between upward and downward moving blades is low (Fischer, 2011). In contrast, the gain in wind energy with increasing hub height is the driver for onshore design. Wind-speed distribution, which also differs between onshore and offshore, is generally described by a Weibull distribution function (DNV, 2011) that quantifies the probability of different mean wind speeds occurring over a given time period at the site location. The

probability density function ( $f_{\text{wind}}$ ) of a Weibull random variable  $v$  is given by

$$2. \quad f_{\text{wind}} = \frac{k}{A} \left( \frac{v}{A} \right)^{k-1} \exp \left[ - \left( \frac{v}{A} \right)^k \right]$$

where  $A$  is a scalar and  $k$  is a shape factor that quantifies the width of the wind-speed distribution.

The values of  $A$  and  $k$  are larger for offshore, indicating higher probability of greater wind speeds compared with onshore (Fischer, 2011; Tricklebank, 2008). Greater differences in wind-speed distributions over time for offshore compared with onshore produce higher levels of mean wind load and hence greater power output. Long-term variations in wind speed are significant in terms of predicting energy yield from a wind turbine, whereas short-term fluctuations are more relevant for generated wind loads. The degree of turbulence (defined as momentary deviations from the mean wind speed) depends on meteorological and geographical conditions, for example, atmospheric layering and terrain. The main contributors to extreme loading and fatigue are stochastic effects in short-term fluctuations of wind speed, such as turbulence/transient events such as gusts (Quarton *et al.*, 1996). A measure for turbulence is turbulence intensity: the ratio of the standard deviation of wind speed to mean wind speed for a given time period (DNV, 2011). For a particular site, turbulence intensity correlates with wind speed and surface roughness; higher wind speed and lower surface roughness produce lower turbulence (Vries, 2007). Since wind is the primary energy source for ocean waves, higher wind speed may produce marginal increases in turbulence on account of ensuing increases in roughness of the ocean surface (Letchford and Zachry, 2009). Another aspect of fluctuating wind speed is turbulence induced in wake conditions (see Figure 3). Ambient non-obstructed turbulence is the 'normal' turbulence experienced by a single stand-alone turbine at a particular site (Frandsen and Thøgersen, 1999). Wake effects can be significant, especially for dense wind-park layouts, where neighbouring turbines experience a superimposed turbulent wind coming from the ambient and wake.

Since surface roughness and hence ambient turbulence are lower for offshore sites, the combination of ambient and wake-induced turbulence is also comparatively lower although wake fields remain longer in the atmosphere compared with onshore. The frequency of energy-rich wind turbulence is below 0.1 Hz (LeBlance, 2009). Hence, turbulence is not significant in the determination of the structural design loads for extreme levels of environmental loading, although its effect on fatigue life of wind-turbine structures cannot be ignored (Vries, 2007). Offshore wind turbines are generally designed for more severe wind classes since the probability of



extreme wind speeds (e.g. due to gusts or changes in wind direction) is more significant compared with most onshore sites (GL, 2005).

Compared with the rotor thrust reaction to wind loads, the hydrodynamic forces acting on OWTs generally only have a minor role in the development of tower deflection. LeBlance (2009) reported that this was largely due to the reduced wave-interaction area of the substructure as compared with the overall tower length and greater lever arm of the rotor thrust (see Figure 1(a)). However, the density of the medium must also be considered when comparing aerodynamic and hydrodynamic lateral loading, with the density of sea water significantly greater than that for air. Hydrodynamic forces generally only become significant for greater water depths and/or wave heights, which cause the lever arm of the hydrodynamic force to increase along with the intensity of the lateral force generated by the water (Fischer, 2011). The height of the ocean waves is usually expressed in terms of 'significant wave height'; this is defined as the mean value of the highest one-third of the waves in a given wave record. Ocean waves that induce fatigue loading with high frequency usually have significant wave heights of  $\sim 1.0$ – $1.5$  m and a zero-crossing period of 4–5 s (Vries, 2011).

## 6. Loading frequency, natural vibration frequency and resonance

It is essential to consider the fundamental natural frequency of a wind-turbine structure for a proper description and evaluation of its dynamic behaviour. As for all dynamic systems, resonance occurs when an excitation frequency gets close to the structure's fundamental natural frequency. For wind-turbine structures,

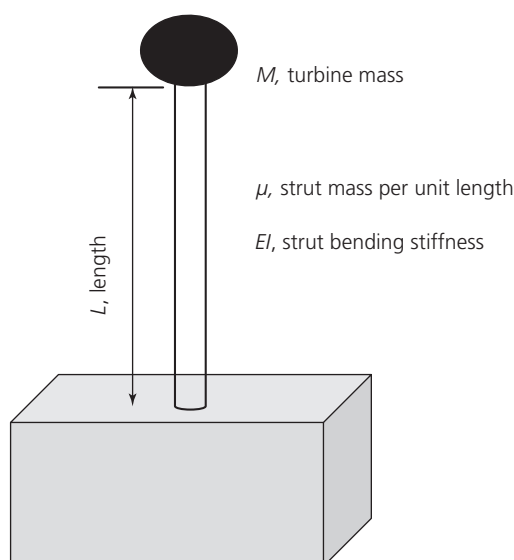


Figure 5. Structural model for flexible wind-turbine system

this invariably leads to the development of higher stresses in the support structure and foundation, but more significantly to a higher range of stresses – an unfavourable situation in considering fatigue life. Hence it is important to ensure that excitation frequencies having high energy levels do not coincide with the support structure's fundamental natural frequency. As a first approximation, the support structure's fundamental natural frequency can be determined by considering a simplified geometry for the whole structure (Figure 5). The turbine mass ( $M$ ) is concentrated at the top (free end) of an equivalent steel pipe representing the support structure, with similarities to a cantilevered vertical strut. In this instance, the first natural frequency ( $f_{\text{nat}}$ , in Hz) of the combined structure can be approximated by (Tempel, 2006)

$$3. \quad f_{\text{nat}}^2 = \frac{3.04}{4(\pi)^2} \frac{EI}{(0.227\mu L + M)L^3}$$

where  $\mu$  is the strut mass per unit length,  $L$  is the strut length and  $EI$  is its bending stiffness ( $\text{N m}^2$ ).

Offshore wind-turbine structures are excited by both wind and waves, with the effective wind load determined by complex interactions between the structural dynamics of the turbine and wind field. Site-specific spectral densities for wind and waves can be derived either from data measured for the particular site location, from met-ocean databases or numerical models (LeBlance, 2009).

Dynamic amplification and large excitation forces affect monopiles in a cumulative unfavourable manner. With rotational speeds of the main rotor shaft typically between 10 and 20 rpm, the first excitation frequency '1P' (i.e. corresponding to one full revolution) occurs in the range 0.17–0.33 Hz. In general, only light excitation of the 1P frequency should occur, with large excitations arising on account of excessive mass and/or aerodynamic imbalances. For a three-bladed turbine, the blade passing frequency of typically 0.5–1.0 Hz is

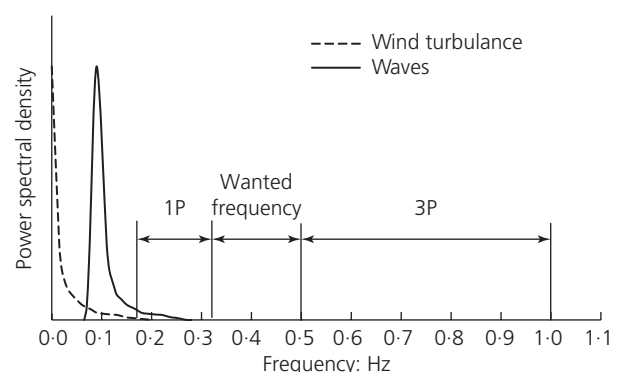


Figure 6. Excitation ranges for OWT structures

denoted as the '3P' frequency and is heavily excited on account of impulse-like excitation arising from the individual blades passing by the tower.

Figure 6 shows the excitation ranges of 1P and 3P, along with realistic, normalised power spectra for wind and wave excitations. Referring to the figure, the 'soft-stiff' zone includes the 1P, 3P and 'wanted frequency' regions; the region before the 1P range is referred to as the 'soft-soft' zone and the region after the 3P range as 'stiff-stiff'. 'Soft-soft' and 'stiff-stiff' zones are unsuitable for the design solution. The structure is considered too flexible if its fundamental natural frequency falls within the 'soft-soft' zone and too rigid (heavy and expensive) within the 'stiff-stiff' zone. Another important reason for avoiding the 'soft-soft' frequency region is that wave- and wind-turbulence excitation frequencies usually fall within this zone (LeBlance, 2009); see Figure 6.

Excitation/resonance of a dynamic system can be mitigated by damping, achieved either internally by friction in components of the structural system or externally by some source/force. Overall damping of an offshore structure can be achieved by combinations of aerodynamic, hydrodynamic, structural and/or soil damping (refer to Bittkau (2010), Genta (1998) and Rodenhausen (2010) for further details).

For the popular monopile foundation systems, 'soft-stiff' design necessitates relatively high structural and dynamic stiffness, which can be achieved by increasing the monopile diameter, or less efficiently, by increasing (reinforcing) the pile wall thickness. However, larger diameter monopiles introduce drawbacks, including greater wave loading and also larger driving equipment/forces necessary for installation (Schaumann and Böker, 2005). Hence there is a corresponding increase in the initial capital investment costs of the project, although from the authors' perspective the LCOE may not be adversely affected if rated power capacity is also increased by using larger rotor blades. Compared with monopiles, the lattice frame of jacket/truss support structures (Figure 4(e)) provides large structural bending stiffness and more favourable mass-to-stiffness ratio, resulting in relatively high bending Eigen-frequencies and reduced hydrodynamic excitation (Vries, 2011), although torsional stiffness is reduced, potentially leading to dynamic problems. Jacket support structures are designed for operation in or around 'stiff-stiff' regions (Fischer, 2011). In the case of tripods, bracing along the lower length of the central tubular section increases overall bending stiffness and reduces bending moment loading on the foundation (Saleem, 2011; Schaumann and Böker, 2005), with typical Eigen-frequencies ranging between those for monopile (at lower end of this range) and jacket support structures/foundations under similar rotor-nacelle configurations and environmental conditions.

## 7. Challenges for offshore wind-power generation

Offshore wind-power generation has arguably greater potential compared with onshore, but marine conditions pose great challenges to project delivery because outcomes are highly influenced by environmental conditions. Some outlooks and new approaches to offshore windpower are discussed below.

### 7.1 Implementation, fabrication, operation and maintenance

It could be argued that, owing to the involvement of multiple regulatory and planning bodies, the current planning and implementation process for offshore wind-power farms is too complex and time-consuming. Some primary legislation may be helpful in order to facilitate relevant government bodies working amicably with investors and developers for offshore wind-power farms (CT, 2008).

Fabrication and O&M issues place major pressures on the LCOE for offshore wind farms (ABB, 2012; IRENA, 2012). New offshore strategies must be developed to minimise the number of tasks performed at offshore sites. Materials for wind-turbine fabrication must be selected for durability and environmental tolerance. Engineering design, beginning from preliminary concepts, must rigorously place higher premiums on reliability, float-out deployments and in situ repair methods. Fabrication facilities must be strategically located for mass production, onshore assembly and rapid deployment offshore, with minimal dependence on large vessels (EWEA, 2007). Sensitive electronic devices for remotely sensing weather conditions and self-diagnostic systems to manage O&M of electromechanical components are required in order to minimise downtime and reduce equipment necessary for repairs (CleanTech, 2012). Ultimately a new balance between initial capital investment costs and long-term operating costs needs to be established that will have a broad impact on the LCOE for offshore wind technology.

### 7.2 Offshore design codes and methods

One of the immediate challenges for design is the ability to accurately predict the magnitude and distribution of applied environmental loads and the resulting dynamic response of the coupled wind-turbine and support structure under the action of combined stochastic wave and wind loading (Musial and Butterfield, 2006). At present, analysis, design and installation of monopile foundations for wind-turbine structures usually rely on general geotechnical standards, complemented by more specific guidelines and semi-empirical formulas developed by the offshore oil and gas industry (API, 2007; DIN, 2005; DNV, 2011; GL, 2005).

However, large-diameter monopile foundations for proposed offshore wind-turbine structures are well outside the scope of current experience and analysis/design methods (including the

American Petroleum Institute (API, 2007) and Det Norske-Veritas (DNV, 2011) standards used by the offshore oil and gas industry). These standards are largely based on empirical data obtained for relatively small-diameter flexible piles under low numbers of load cycles. Furthermore, for these standards, wave loading is of primary concern when extrapolating to predict extreme events. However, designers of offshore wind-turbine structures must consider wave and wind load spectra simultaneously (IEC, 2005; Tarp-Johansen, 2005). Hence careful consideration of these differences in applied loading and inherent limitations underpinning semi-empirical formulae for the offshore oil/gas industry are required in extrapolation for design of large-diameter monopile foundation supports for wind-turbine structures. Often these formulations cannot be applied with confidence by the offshore wind-power industry to achieve optimum results and economy (Dobry *et al.*, 1982).

There is also a dearth of knowledge concerning the behaviour of the monopile–soil foundation system and its structural stability under long-term cyclic lateral loading. Existing literature includes Matlock (1970), Reese *et al.* (1974, 1975), Little and Briaud (1988), Ismael (1990) and Long and Vanneste (1994). Hence the development of more realistic strain-accumulation models and also computer codes to predict dynamic forces and resulting displacements of OWTs will provide valuable tools for more reliable designs.

### 7.3 Recommendations for future research and practice

A multidisciplinary approach is suggested in order to strive towards making the offshore wind-power industry more economical and practicable, including the following points.

- Some primary legislation may be helpful in order to facilitate relevant government bodies in working amicably with investors and developers for offshore wind-power farms. Investors and developers for offshore-wind projects could be facilitated by government with some easing of current requirements to obtain obligation certificates.
- Development of innovative fabrication materials (with appropriate strength, durability and lightweight characteristics) for OWTs may contribute to considerable reductions in the LCOE.
- Use of more sophisticated electromechanical parts in OWTs (e.g. direct-drive units that eliminate the requirement for a gearbox, thereby removing one of the key components prone to failure) will increase the efficiency and hence energy yield and also reduce O&M costs for the project.
- In-depth experimental and numerical studies are necessary in order to bridge the knowledge gap between existing design codes/guidelines developed for the offshore oil and gas industry and more onerous applied loading and larger support structures/foundations adopted for OWTs.

## 8. Summary and conclusions

Wind power, particularly from offshore turbines mounted on bottom support structures, appears to be a promising solution to meet the universal demand for clean, cost-effective energy. The rated power-generation capacity of individual OWTs, and also of wind farms, has increased many-fold over the past two decades, with strong growth projected to continue for the near-to-medium future. Concepts for floating foundation systems for OWT structures are also emerging, which will allow installations even farther offshore, thereby benefiting from relatively higher wind speeds/power generation. However, compared with conventional fossil-fuel-fired technologies, initial capital investment costs and LCOE for wind-power generation are both comparatively higher, particularly for offshore, on account of challenges associated with the harsh marine environment. Reductions in the LCOE and projected increases in design life of OWT projects are achievable by developing and implementing improved design criteria/methods for foundations, support structures and the wind turbines themselves, along with the use of innovative materials in their fabrication.

The wind-power generation industry can be facilitated through legislation leading to primary reforms in the rules/regulations imposed by different regulatory and monitoring bodies related to this industry. A multidisciplinary and integrated approach is required, with cost reductions achievable for other offshore industries (e.g. oil/gas sector and offshore cable laying) potentially also benefiting offshore wind-power projects, although developments in commodity prices (particularly steel, copper, cement) will also influence potential cost reductions achievable for wind power. In spite of such challenges, it is projected that wind-power generation will continue to increase many-fold, particularly in Europe, North America and Asia over the next two decades, with associated LCOE anticipated to become comparable with other sources of renewable energy.

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