CSC4140 Assignment I

Computer Graphics February 4, 2022

Learn to use VirtualBox and Mathematic Review

This assignment is 5% of the total mark.

Strict Due Date: 11:59PM, Feb $14^{th},\,2022$

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This assignment represents my own work in accordance with University regulations.

Signature:

1 Readme

1.1 File firectory

Please organize files in the following structure.

bin
compile_run.sh //linux executable file
lenna.png //sample image
doc
l_120090453_HW1_1.pdf
src
CMakeLists.txt
q2_1.cpp
q2_2.cpp
q2_3.cpp
q2_3.cpp
Q2_4.cpp
CMakeLists.txt
main.cpp //main program

1.2 How to run the program

- 1. Make sure your work directory under "./bin/" when you run the executable file.
- 2. Run the executable file "./compile_run.sh 2-x" when you want to check the outcome in Section 2-x. E.g. if you want to check Section 2-1, input the following command in the terminal:

./compile_run.sh 2-1

2 Basic operations of vector and matrix

2.1 Basic vector operations

2.1.1 Define v and w

The vectors are defined as tow float vectors $\boldsymbol{v} = \begin{bmatrix} 1 \\ 1.5 \\ 2 \\ 3 \end{bmatrix}$ and $\boldsymbol{m} = \begin{bmatrix} 0 \\ 1 \\ 2 \\ 4 \end{bmatrix}$, which is homogeneously

normalized as
$$\boldsymbol{v} = \begin{bmatrix} 0.333333 \\ 0.5 \\ 0.666667 \end{bmatrix}$$
 and $\boldsymbol{w} = \begin{bmatrix} 0 \\ 0.25 \\ 0.5 \\ 1 \end{bmatrix}$.

2.1.2 vector add

$$\mathbf{v} + \mathbf{w} = \begin{bmatrix} 0.333333 \\ 0.75 \\ 1.16667 \\ 1 \end{bmatrix}$$

2.1.3 vevtor inner product

$$\boldsymbol{v} \cdot \boldsymbol{w} = 0.458333$$

2.1.4 vector cross product

$$\mathbf{v} \times \mathbf{w} = \begin{bmatrix} 0.0833333 \\ -0.166667 \\ 0.0833333 \\ 1 \end{bmatrix}$$

2.1.5 Result crops

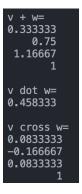


Figure 1. Basic vector operations

2.2 Basic matrix operations

2.2.1 Define i and j

The matrixs i and j are defined as following:

$$i = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \\ 13 & 14 & 15 & 16 \end{bmatrix} \quad j = \begin{bmatrix} 4 & 3 & 2 & 1 \\ 8 & 7 & 6 & 5 \\ 12 & 11 & 10 & 9 \\ 16 & 15 & 14 & 13 \end{bmatrix}$$

2.2.2 matrix add i+j

$$m{i} + m{j} = egin{bmatrix} 5 & 5 & 5 & 5 \ 13 & 13 & 12 & 14 \ 21 & 21 & 21 & 21 \ 29 & 29 & 29 & 29 \end{bmatrix}$$

2.2.3 matrix add i*j

$$i \times j = \begin{bmatrix} 120 & 110 & 98 & 92 \\ 280 & 254 & 222 & 208 \\ 440 & 398 & 346 & 324 \\ 600 & 542 & 470 & 440 \end{bmatrix}$$

2.2.4 matrix mutiply vector add i*v

The vector is defined as
$$\mathbf{v} = \begin{bmatrix} 1 \\ 1.5 \\ 2 \\ 3 \end{bmatrix}$$
 and the matrix is defined as $\mathbf{i} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \\ 13 & 14 & 15 & 16 \end{bmatrix}$. There-

fore,

$$m{i} imes m{v} = egin{bmatrix} 22 \\ 52 \\ 82 \\ 112 \end{bmatrix}$$

2.2.5 Result crops

```
matrix add i+j:
5 5 5 5
13 13 12 14
21 21 21 21
29 29 29 29
matrix multiply i*j:
120 110 98 92
280 254 222 208
440 398 346 324
600 542 470 440
matrix multiply vector i*v:
22
52
82
112
```

Figure 2. Basic matrix operations

2.3 SVD decomposition of "lenna"

2.3.1 convert and normalize

The image is converted to gray scale by cv::convert().



Figure 3. "lenna" and it converted to gray scale

2.3.2 Depositie image to U, S, V

The image is depositied to U, S, V with the shape of (512, 512) by Eigen::JacobiSVD.

2.3.3 Save the feature map as an image

The restored images of the feature map with first 1, 10, 50 singular value are saved in the following ways:

Restoration with first 1 singular values: $\boldsymbol{U} \times \boldsymbol{S}[:,1] \times \boldsymbol{V}[:,1]^T$ Restoration with first 10 singular values: $\boldsymbol{U} \times \boldsymbol{S}[:,10] \times \boldsymbol{V}[:,10]^T$ Restoration with first 50 singular values: $\boldsymbol{U} \times \boldsymbol{S}[:,1:50] \times \boldsymbol{V}[:,1:50]^T$



Figure 4. Feature images with first 1, 10, 50 singular values

2.3.4 Explanation

Actually, SVD deposition devides the matrix into the sum of matrixs that Rank = 1. In other words, the matrix can be written in the following way:

$$A = \sigma_1 u_1 v_1^T + \sigma_2 u_2 v_2^T + \ldots + \sigma_r u_r v_r^T = \sum_{i=1}^r \sigma_i u_i v_i^T (\sigma > 0)$$

where r is the number of the matrix's eigenvalues.

Suppose that $B = \sum_{i=1}^k \sigma_i u_i v_i^T (0 < k < r)$. When k increases, B tends to approach A. Therefore, B is the estimation of A when k is large enough. It indicates the outcome in Section 2.3.4.

2.4 Basic transformation operations

The initial point is [1, 2, 3] and the rotation center is [4, 5, 6]. Then the point is rotated with angle $(45^{\circ}, 30^{\circ}, 60^{\circ})$ in turn. Therefore, the new point is [1.6403, 0.912883, 3.82577].

New Point: 1.6403 0.912883 3.82577

Figure 5. The new point