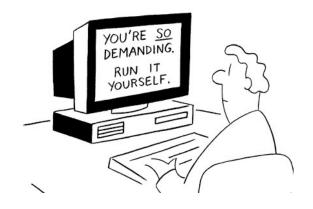
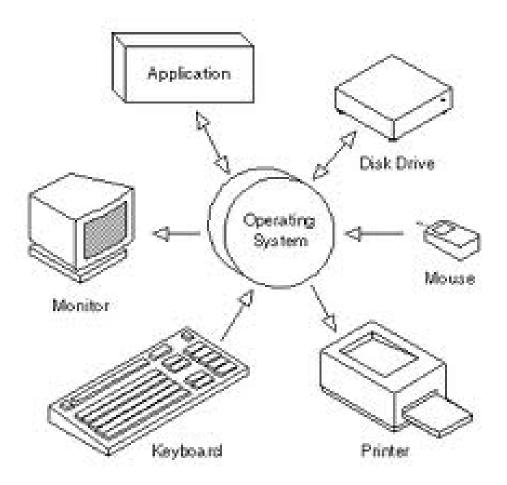
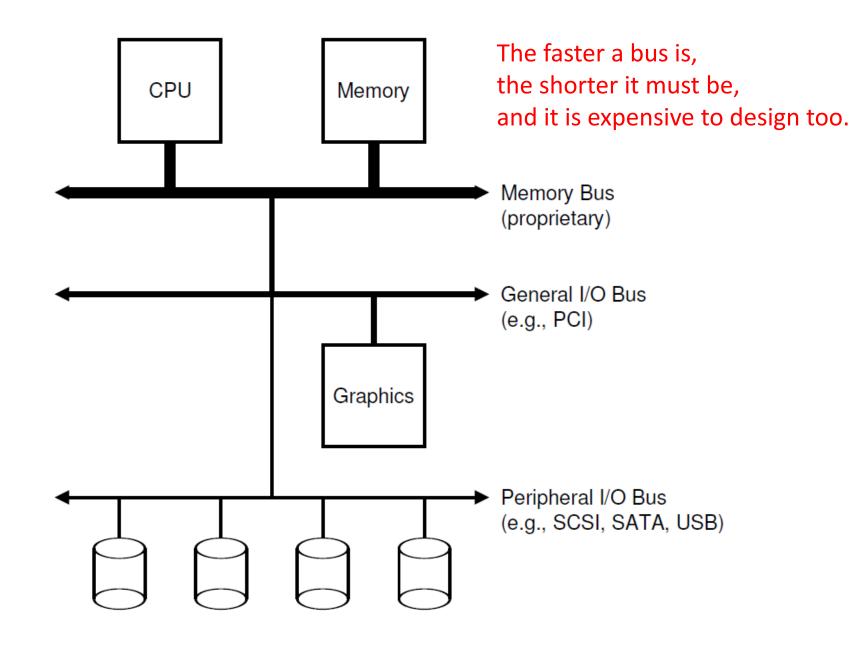


# Operating Systems 1/0

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### Categories of I/O Devices

External devices that engage in I/O with computer systems can be grouped into three categories:

#### **Human readable**

- suitable for communicating with the computer user
- printers, terminals, video display, keyboard, mouse

#### Machine readable

- suitable for communicating with electronic equipment
- disk drives, USB keys, sensors, controllers

#### Communication

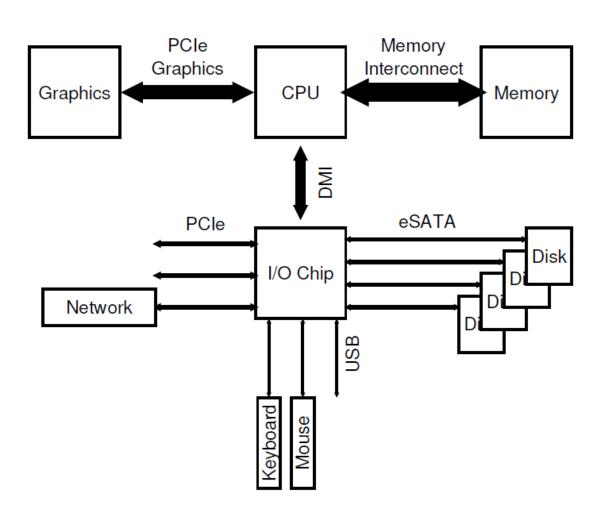
- suitable for communicating with remote devices
- ethernet cards, wifi adapters

## A Simple Definition

 The main concept of I/O is to move data from/to I/O devices to the processor using some modules and buffers.

 This is the way the processor deals with the outside world.

### Modern System Architecture



Example of one of Intel Chipsets.

DMI: Intel's proprietary Direct Media Interface.

### The OS and I/O

The OS controls all I/O devices

 Provides an interface between the devices and the rest of the system.

#### **Applications**

File System

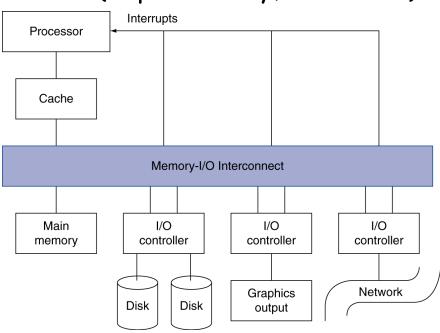
OS

Low-Level Interface

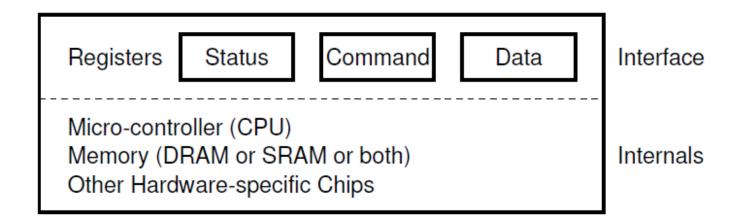
I/O Devices

## I/O Devices: Challenges

- Very diverse devices
  - behavior (i.e., input vs. output vs. storage)
  - partner (who is at the other end?)
  - data rate
- I/O Design affected by many factors (expandability, resilience)
- Performance:
  - access latency
  - throughput
  - connection between devices
     and the system
  - the memory hierarchy
  - the operating system
- A variety of different users



#### How Does a Generic I/O Device Look Like?



The OS can deal with the above device as follows:

```
While (STATUS == BUSY)
   ; // wait until device is not busy
Write data to DATA register
Write command to COMMAND register
   (starts the device and executes the command)
While (STATUS == BUSY)
   ; // wait until device is done with your request
```

#### Efficient OS-Device Interaction

- Polling (see previous slide)
  - Called programmer I/O

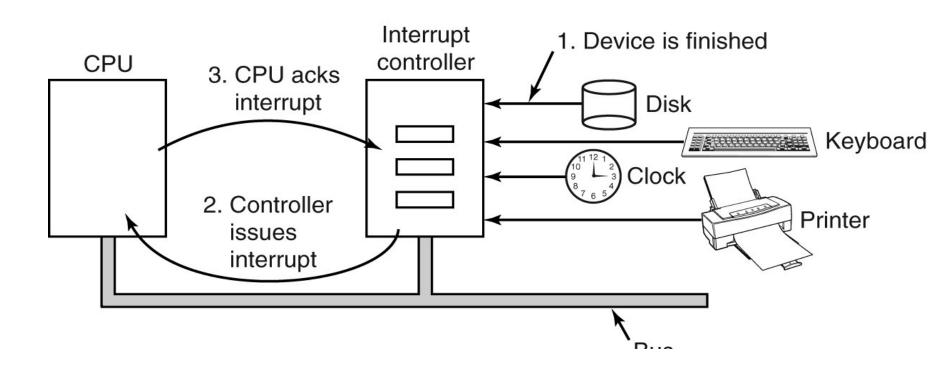
Interrupts

DMA

# Efficient OS-Device Interaction: Interrupts

- OS issues a request and puts the calling process to sleep.
- OS context switches to another process.
- When done, the device raises an interrupt.
- CPU moves to kernel mode and OS executes the needed interrupt service routine (ISR).
- The OS wakes the process that needed the I/O.

### Interrupts



# Polling vs Interrupts

- If a device is fast, it may be best to poll.
  - The cost of interrupt handling and context switch may outweigh the benefit of interrupts.

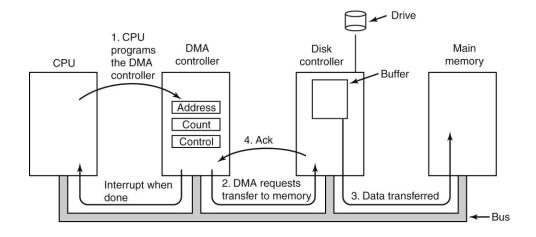
 If a device is slow, then interrupts is better.

# Efficient OS-Device Interaction: DMA

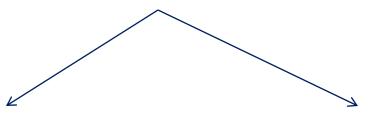
- It is better not to bug the OS with a lot of overhead when moving a large chunk of data.
- DMA = Direct Memory Access
  - A device in the system that orchestrates transfers between devices and main memory without CPU intervention.
- OS tells DMA where the data lives, how much to copy, etc. The OS is done with the transfer and can go do something else.
- When the DMA completes, it raises an interrupt telling the OS the operation is done.

### Direct Memory Access (DMA)

- It is not efficient for the CPU to request data from I/O one byte at a time.
- DMA controller has access to the system bus independent from the CPU



#### I/O Units



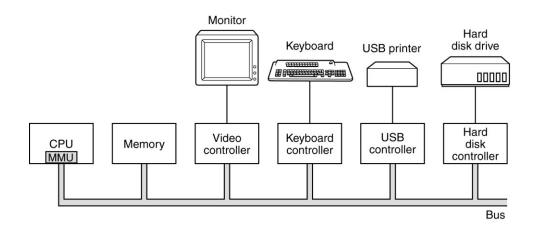
Mechanical component



The Device Itself

**Electronic Component** 





### Controller and Device

- Each controller has few registers used to communicate with CPU
- By writing/reading into/from those registers, the OS can control the devices.
- There are also data buffers in the device that can be read/written by the OS.

# How does the OS deal with controllers and devices?

# How does CPU communicate with control registers and data buffers?

Two main approaches

- I/O Instructions
  - Privileged

Memory-mapped I/O

### I/O Instructions

- Each control register is assigned an I/O port number
- The set of all I/O ports form the I/O port space

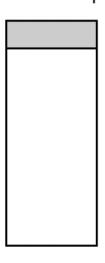
Memory

I/O ports

- I/O port is accessed with special instructions
- I/O port space is protected \*\*FFFF...

# Memory-Mapped I/O

- Map control registers into the memory space
- Each control register is assigned a unique memory address
  One address space



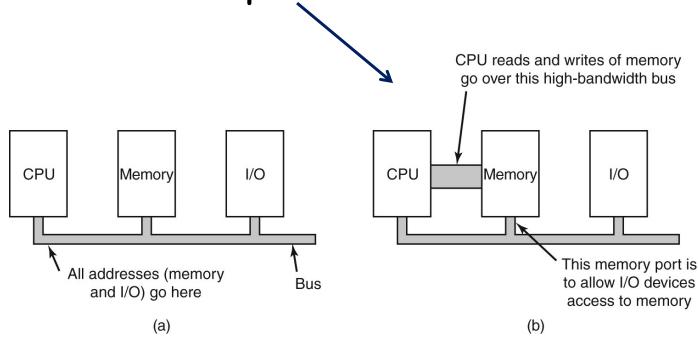
# Advantages of Memory-Mapped I/O

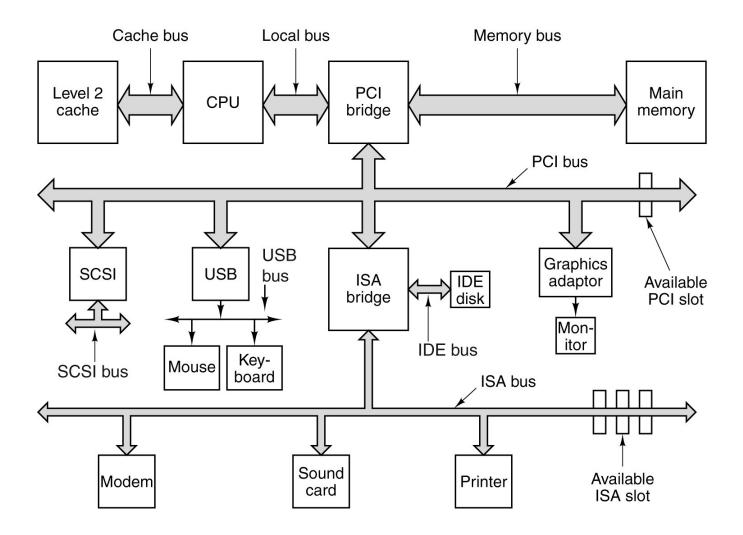
- Device drivers can be written entirely in C (since no special instructions are needed)
- No special protection is needed from OS, just refrain from putting that portion of the address space in any user's virtual address space.
- Every instruction that can reference memory can also reference control registers.

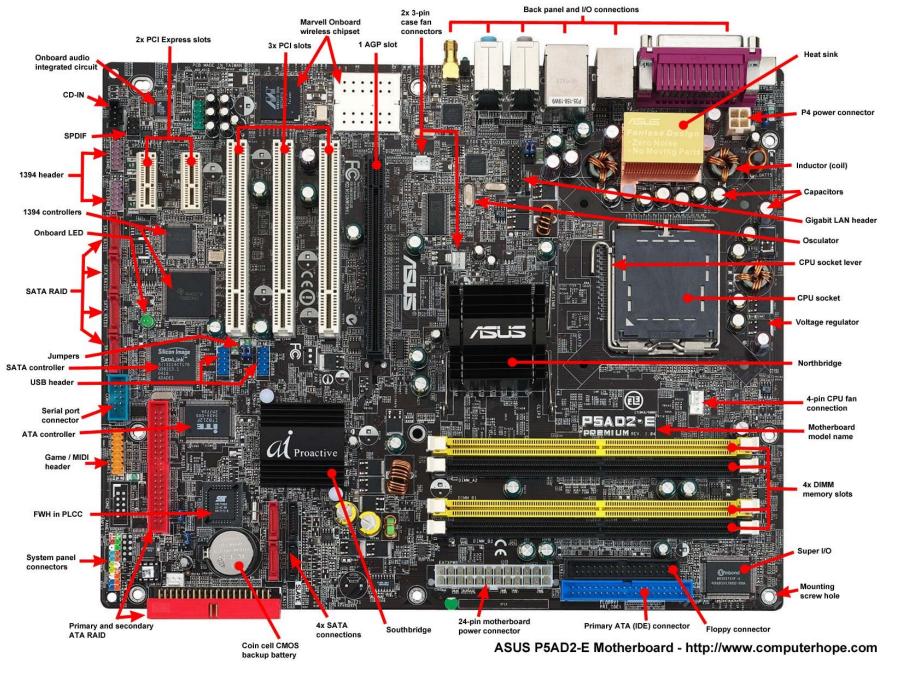
# Disadvantages of Memory-Mapped I/O

 Caching a device control register can be disastrous.

Hardware complications



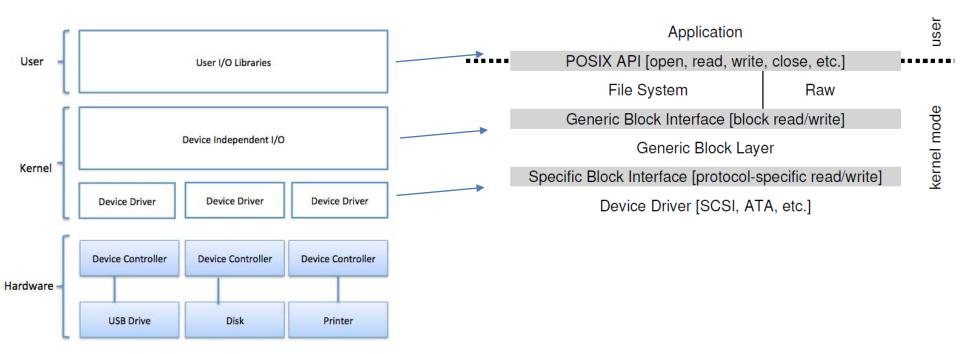




Source: https://www.computerhope.com/cdn/bigmb.jpg

### The Software Part

# The Big Picture



Source: https://www.tutorialspoint.com/operating\_system/images/io\_software.jpg

# Device Independent I/O Software

Uniform interfacing for device drivers

Buffering

Error reporting

Allocating and releasing dedicated devices

Providing a device-independent block size

# Device Independent I/O Software

- Uniform interfacing for device drivers
  - Trying to make all devices look the same
  - For each class of devices, the OS defines a set of functions that the driver must supply.
  - This layer of OS maps symbolic device names onto proper drivers

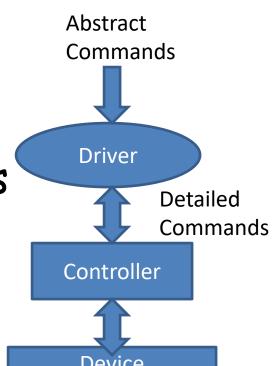
### How About Device Drivers?

#### Device Drivers

- · Device specific code for controlling the device
  - Read device registers from controller
  - Write device registers to issue commands
- Usually supplied by the device manufacturer.
- Can be part of the kernel or at user-space (with system calls to access controller registers).
- OS defines a standard interface that drivers for block devices must follow and another standard for driver of character devices.

### Device Drivers

- Main functions:
  - Receive abstract read/write from layer above and carry them out
  - Initialize the device
  - Log events
  - Manage power requirements
- Drivers must deal with events such as a device removed or plugged

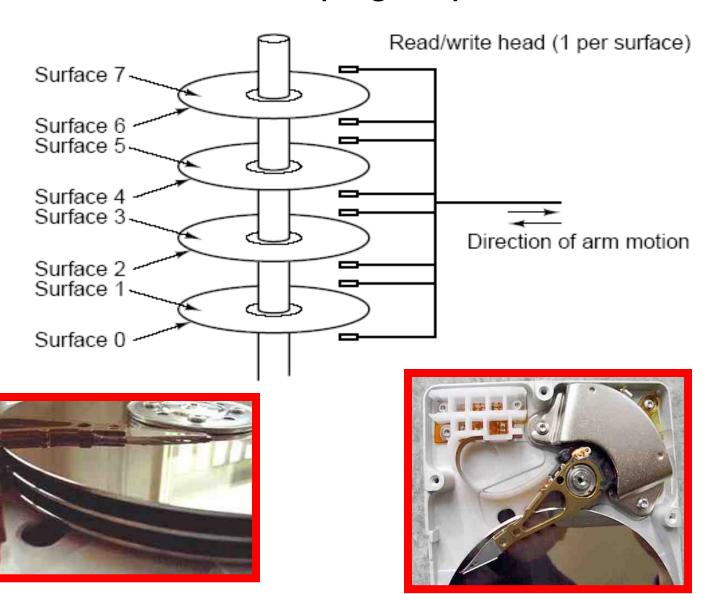


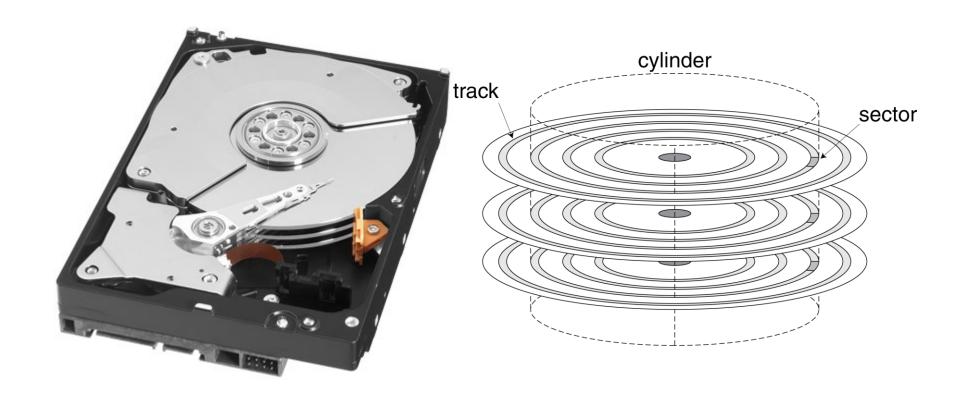
## Example of I/O Devices



Hard-Disk Drive (HDD)

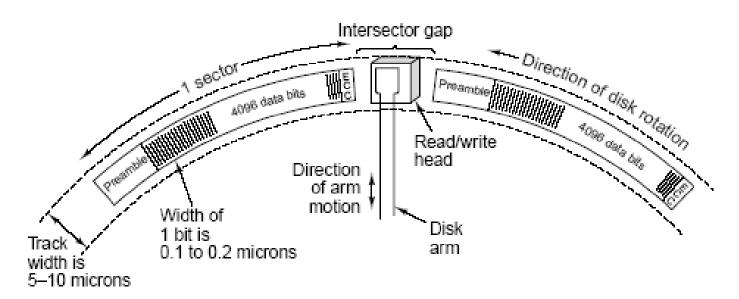
#### A Conventional Hard Disk (Magnetic) Structure





# Hard Disk (Magnetic) Architecture

- Surface = group of tracks
- Track = group of sectors
- Sector = group of bytes
- · Cylinder: several tracks on corresponding surfaces

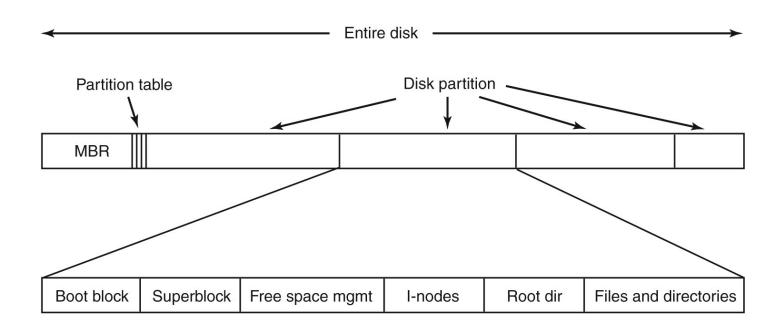


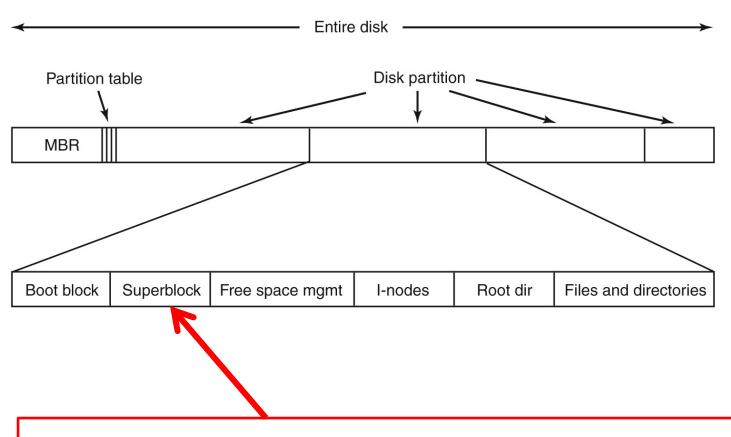
### File System Layout

- Stored on disks
- Disks can have partitions with different file systems
- Sector 0 of the disk called MBR (Master Boot Record)
- MBR used to boot the computer
- The end of MBR contains the partition table

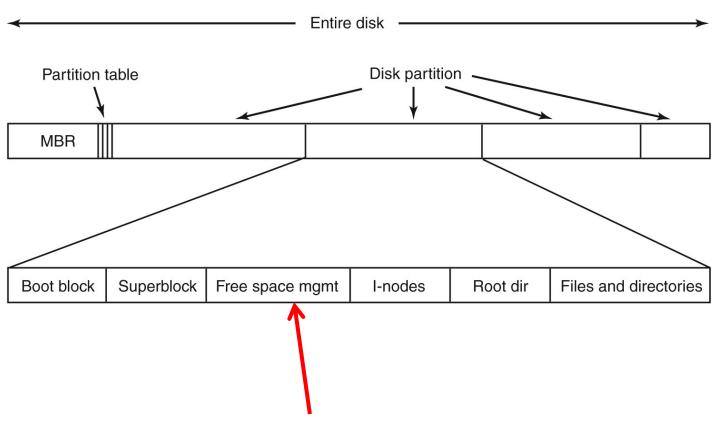
#### MBR and Partition Table

- Gives the starting and ending addresses of each partition
- One partition in the table is marked as active.
- When the computer is booted, BIOS executes MBR.
- MBR finds the active partition and reads its first block (called boot block) and executes it.
- Boot block loads the OS contained in that partition.

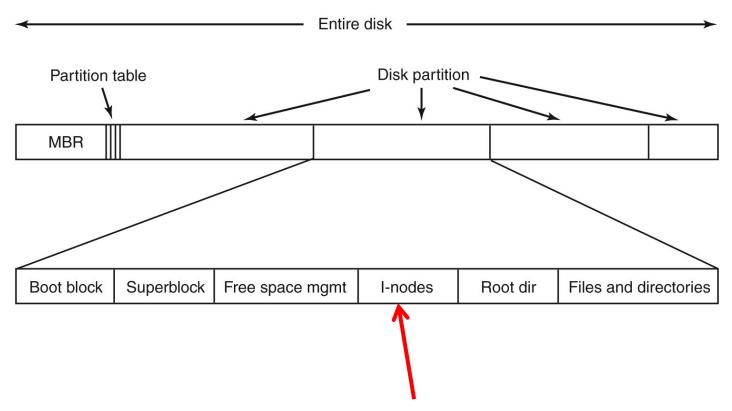




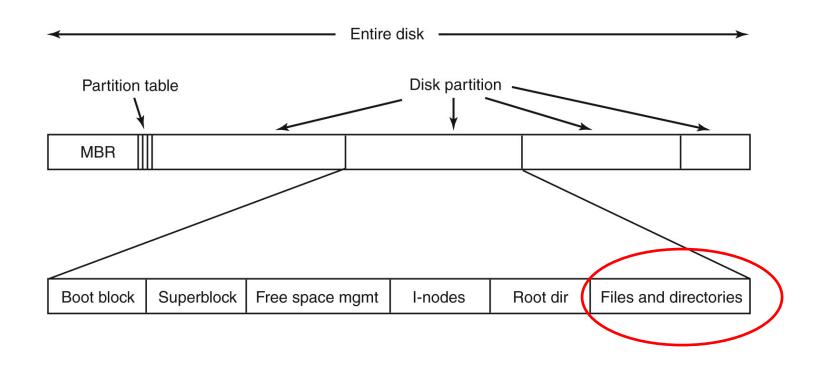
- •Contains all key parameters about the file system.
- •Is read into memory when computer is booted or file system is touched.



Bitmap or linked list



An array of data structures, one per file, telling about the file



Which disk blocks go with which files?



# Solid State Disks (SSD)

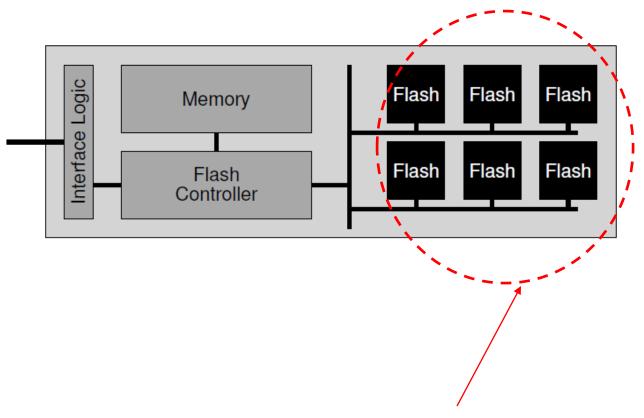
## Advantages over traditional Hard Disk Drive (HDD)

- No moving parts, so:
  - no noise
  - Faster start up
- Deterministic read performance
  - The performance does not depend on the location of data.

## Disadvantages relative to traditional Hard Disk Drive (HDD)

- More expensive
- Write latency is high
- Limited number of writes (~100,000)
  - after wish, the cell becomes unusable.

### Internal Logic



This is where the data are store. But what is inside those flash packages?

### The Flash

- Data saved to a pool of NAND flash.
- Made of transistors, BUT:
  - Unlike designs used in DRAM, the ones used in flash retain their charges even when not powered up → non-volatile.
- Data stored in NAND cells.
  - One cell can store 1 (single-level-cell or SLC), 2 (Multi-Level Cell MLC), 3, or 4 bits.
  - SLC achieves higher performance.
- The NAND flash cells organized as a grid.
  - The entire grid is called a block.
  - Each row of the grid is called a page.

### The Flash

- Page size varies from 2KB to 16KB.
- Each block has 128 to 256 pages.
- A block is then 256KB to 4MB,

#### Conclusions

- The OS provides an interface between. the devices and the rest of the system.
- OS must expand as new I/O devices are added.
- For any I/O device the OS uses device driver to deal with device controllers that control the device itself.
  - software: device driver
  - hardware: device controller
  - hardware: the device