Word2Vec

□□CBOW□□skip-gram□□□□□□□□□□□□□□□□□□

□□□□□□□□□□□□□□

□□□□□$v=W \times one_hot(v)$

□□□W□$Word2Vec$□□□□□□□

CBOW

□□□□□□□□□□□

□□□□

□□□□□□□□□ `one-hot` □□□

image-20250705224627824

□□□□

□□□□□□□□C□□□□□□□□□□□□ $$ X =(x_{i-c},x_{i-c+1},\dots,x_{i-1},x_{i+1}\dots,x_{i+c}) \in \mathbb{R}^{V\times2C} $$ □□□x_i□□□□□$x_i \in \mathbb{R}^{V \times 1}$

□□□□□

□□□□x_i□□□□□□□□□□□□W□□□□□□□□$b\in \mathbb{R}^{D \times 1}$□□$x_j'$□□$X_j'= WX_j + b$□□□□□□□ $$ X' = WX + b $$ □□ $$ X =[x_{i-c},x_{i-c+1},\dots,x_{i-1},x_{i+1}\dots,x_{i+c}] \ X' = [x_{i-c}',x_{i-c+1}',\dots,x_{i-1}',x_{i+1}'\dots,x_{i+c}'] $$

□□□□□

□□□□□□□□X_j'□□□□□□□h $$ h=\sum_{j=i-C,j\neq i}^{i+C}{\frac{1}{2C}(x_{i-c}'+x_{i-c+1}'+x_{i-1}'+x_{i+1}'+x_{i+c}')} $$

□□□□□

□□□h□□□□□□□□□□□□□□□P□$P = (P_1,P_2,\dots,P_V)^T$□$P_i \in R$□□□□□□□□$i$□□□□□□□ $$ P = W'h + b' $$

Softmax□

□□□□□□□□Softmax□□□□□P'□$P' = (p_1',p_2',\dots,p_V')$□$p_i'$□□□□□□□□i□□□□□□□ $$ p_i' = softmax(p_i) = \frac{exp(p_i)}{\sum_{k=1}^Vexp(p_k)} $$ □□□□□□P'□□□□□□□□□□□□□□□□□□1□□□□□□□0□□□□□□□□□□□□□□□□□□□□□□□□□□□□□

□□□□

□□□□□□□□Cross Entropy□□□□□□□□□□□□□□□Softmax□□□□□□□□□P'□□□□□□□T□□□$P'= (P_1',P_2',\dots,P_V')^T$□□□□□□□$T=(t_1,t_2,\dots,t_V)$□□□□□□□□□□ $$ Loss = -\sum_{i=1}^Vt_i\log (P_i') $$

skip-gram

□□□□□□□□□□□

□□□□

□□□

image-20250705224657637

□□□

□□□□□□□□□□□□□□$x_i\in \mathbb{R}^{V \times 1} $□i□□□□□□□□

□□□□

□□□□□□□$x_i\in \mathbb{R}^{V \times 1} $□□□□□□□□□$h$ $$ h = Wx_i + b $$

□□□□

□□□□□□h□□□□□□□□□W_j'□□□□□□□b_j'□□□□□□□□□□□□□□□□$S_j\in \mathbb{R}^{V\times 1}$□$S = (S_1,S_2,\dots,S_{2C})^T$□ $$ S_j=W_j'h+b_j' $$

Softmax□

□□□□□□□S_j□softmax□□□□P_j□$P_j = (P_j(0),P_j(1),\dots,P_j(V-1))^T$ $$ P_j(k) = Softmax(S_j) = \frac{exp(S_j(k))}{\sum_{l=0}^{V-1}{exp(S_j(l))}} $$

□□□

□□□□□P□□□□□□□□□□□□□1□□□□□0□□□□□□□□□□□□□□□□□□□□□□□□□□□

□□□

□□□□□□□Cross Entropy□□□□□□□□□□□□$P_j(k)$□□□□□□□T□□□$P_j = (P_1,P_2,\dots,P_{2C})$□□□ □□□$T_j=[t_j(1),t_j(2),\dots,t_j(V)]$□□□□□□□□□□□ $$ L_j = -\sum_{k=1}^{V}t_k\log(P_j(k)) \ Loss = \sum_{j=1}^{2C}L_j $$

□□

□□□word2vec□□□□□□□□V□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□**Huffman**□□□□□□□□□□□$\log V$□

□□Softmax

□□□□□□□□□□□□□□□□□□□□Huffman□□□□□□□□□□□□□□□□□□

- □□□□□□
- □□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□

□□□□

image-20250705162047281

□□□□□□□

1. □□□□□□□□□□□□□□□□□□□□□□□**softmax**□□□□□□□P□□□□□□
2. □□□□□□□□□□□□□□□□P□□□□□□□□□□□□□□□□$1-P$
3. □□□□□□□□□□□□□□□□□□□□□□□□□□
4. □□□□□□□□□□□□□□□□□□□□□

□□

□□□□□□□□□□□□□□□□□□□□□

□□□

[illegible]“[illegible]”[illegible]**1**[illegible]**0**[illegible]

[illegible]

[illegible]

[illegible]

[illegible]T_1[illegible]$T_1 = (t_1,t_2,\dots,t_V)^T$[illegible]$P$[illegible]$P=(P_1,P_2,\dots,P_V)$[illegible]$T$[illegible]**1**[illegible]$S_1 = (\theta_1h)^TT_1$

[illegible]sigmoid[illegible]Cross Entropy $$ P_1 = \sigma(S_1) = \sigma((\theta_1h)^TT_1) = \frac{1}{1+e^{-((\theta_1h+b_1')^TT_1)}}\ Loss_+ = -log(P_1) = -log(\frac{1}{1+e^{-((\theta_1h+b_1')^TT_1)}}) $$ [illegible]

[illegible] $$ f(w) = \frac{[count(w)]^{\frac{3}{4}}}{\sum_{i=1}^V[count(i)]^{\frac{3}{4}}} $$ [illegible]$count(index)$[illegible]index[illegible]w[illegible]V[illegible]

[illegible]k[illegible]5[illegible]5~20[illegible]

[illegible] [illegible]$Sigmoid$[illegible]

[illegible]θ_0[illegible]h[illegible] $$ S_{0,i} = -(\theta_0h+b_0')^TT_{0,i} $$ [illegible]$T_{0,i}$[illegible]Sigmoid[illegible] $$ P_1 = \sigma(S_{0,i}) $$ [illegible] $$ Loss_- = \sum_{i=1}^k\log(P_{0,i}) $$ [illegible]$Loss_+$[illegible]$Loss_-$[illegible]$Loss$ $$ Loss = Loss_-+Loss_+ $$