

Diffusion probabilistic Model

Diffusion probabilistic Model

Overview

1. Overview of the model
2. Training process
 - o Denoise process: $p(z_t | z_{t-1})$ is modeled by a denoiser $\epsilon_\theta(z_t, t)$ at each step
 - o Denoise process: **Noise Predictor** $\epsilon_\theta(z_t, t)$ predicts the noise added at each step

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Model

Latent space

VAE (Variational Autoencoder)

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$q(z_t | z_{t-1})$ is modeled by $p(z_t | z_{t-1})$

$p(x, z_1, z_2, \dots, z_T) = p(x, z_{1:T}) = p(z_T) p_{\theta}(z_{1:T} | z_T)$

$q_{\phi}(z_{1:T} | x) = q_{\phi}(z_1, z_2, \dots, z_T | x) = q_{\phi}(z_{1:T} | x)$
 $p(x) = \int p(x, z_{1:T}) q_{\phi}(z_{1:T} | x) dz_{1:T}$
 $\ln p(x) = \ln \int p(x, z_{1:T}) q_{\phi}(z_{1:T} | x) dz_{1:T}$
 $\ln p(x) \leq \ln \int p(x, z_{1:T}) q_{\phi}(z_{1:T} | x) dz_{1:T} = \ln \int p(x, z_{1:T}) \frac{p(x, z_{1:T})}{p(x, z_{1:T})} q_{\phi}(z_{1:T} | x) dz_{1:T} = \ln \int p(x, z_{1:T}) q_{\phi}(z_{1:T} | x) dz_{1:T}$
 $\ln p(x) \leq \ln \int p(x, z_{1:T}) q_{\phi}(z_{1:T} | x) dz_{1:T} = \ln \int p(x, z_{1:T}) \frac{p(x, z_{1:T})}{p(x, z_{1:T})} q_{\phi}(z_{1:T} | x) dz_{1:T} = \ln \int p(x, z_{1:T}) q_{\phi}(z_{1:T} | x) dz_{1:T}$

Latent space

$q(x_t | x_{t-1})$ is modeled by $p(x_t | x_{t-1})$

$x_t = z_t + \epsilon_t$

T is the number of steps, x_T is the input, x_0 is the output, 1 is the number of steps

Latent space

Latent space

$p(x_0) = q(x_0) \prod_{t=1}^T q(x_t | x_{t-1})$

$p(x_T) = p(x_0) \prod_{t=1}^T p(x_t | x_{t-1})$

Latent space

$p(x_0) = p(x_0) \prod_{t=1}^T p(x_t | x_{t-1})$
 $p(x_{1:T} | x_0) = q(x_{1:T} | x_0) \prod_{t=1}^T q(x_t | x_{t-1})$

$$\begin{aligned} & \{q(x_{1:T}|x_0)\} \left[\frac{p(x_{0:T})}{p(x_{0:T})} \right] \{q(x_{1:T}|x_0)\} \mid \geq \mathbb{E} \{q(x_{1:T}|x_0)\} \\ & \left[\ln \left\{ \frac{p(x_{0:T})}{p(x_{0:T})} \right\} \{q(x_{1:T}|x_0)\} \right] \&= \mathbb{E} \{q(x_{1:T}|x_0)\} \\ & \left[\ln \left\{ \frac{p(x_T)}{\prod_{t=1}^T p_{\theta}(x_{t-1}|x_t)} \right\} \{q(x_{1:T}|x_0)\} \right] \&= \mathbb{E} \{q(x_{1:T}|x_0)\} \\ & \&= \mathbb{E} \{q(x_{1:T}|x_0)\} \left[\ln \left\{ \frac{p(x_T)}{p_{\theta}(x_0|x_1)} \prod_{t=2}^T p_{\theta}(x_{t-1}|x_t) \right\} \{q(x_{1:T}|x_0)\} \right] \&= \mathbb{E} \{q(x_{1:T}|x_0)\} \\ & \left[\ln \left\{ \frac{p(x_T)}{p_{\theta}(x_0|x_1)} \prod_{t=1}^{T-1} p_{\theta}(x_t|x_{t+1}) \right\} \{q(x_{1:T}|x_0)\} \right] \&= \mathbb{E} \{q(x_{1:T}|x_0)\} \\ & \left[\ln \left\{ \frac{p(x_T)}{p_{\theta}(x_0|x_1)} \{q(x_T|x_{T-1})\} \right\} \right] + \mathbb{E} \{q(x_{1:T}|x_0)\} \\ & \left[\ln \left\{ \prod_{t=1}^{T-1} \left\{ \frac{p_{\theta}(x_t|x_{t+1})}{q(x_t|x_{t+1})} \right\} \{q(x_t|x_{t+1})\} \right\} \right] \&= \mathbb{E} \{q(x_{1:T}|x_0)\} \\ & \left[\ln \left\{ p_{\theta}(x_0|x_1) \right\} \right] + \mathbb{E} \{q(x_{T-1}, x_T|x_0)\} \left[\ln \left\{ \frac{p(x_T)}{q(x_T|x_{T-1})} \right\} \right] + \sum_{t=1}^{T-1} \mathbb{E} \{q(x_{t-1}, x_t, x_{t+1}|x_0)\} \left[\ln \left\{ \frac{p_{\theta}(x_t|x_{t+1})}{q(x_t|x_{t+1})} \right\} \right] \&= \underbrace{\mathbb{E} \{q(x_{1:T}|x_0)\} \left[\ln \left\{ p_{\theta}(x_0|x_1) \right\} \right]}_{\text{KL}} - \underbrace{\mathbb{E} \{q(x_{T-1}, x_T|x_0)\} \left[\ln \left\{ \frac{p(x_T)}{q(x_T|x_{T-1})} \right\} \right]}_{\text{KL}} - \underbrace{\sum_{t=1}^{T-1} \mathbb{E} \{q(x_{t-1}, x_t, x_{t+1}|x_0)\} \left[\ln \left\{ \frac{p_{\theta}(x_t|x_{t+1})}{q(x_t|x_{t+1})} \right\} \right]}_{\text{KL}} \end{aligned}$$

$$\begin{aligned} & \begin{aligned} & \&= \int q(x_1|x_0) q(x_2|x_1) \dots q(x_{T-1}|x_{T-2}) dx_{1:T-2} \mid \&= \int q(x_1|x_0) q(x_2|x_1, x_0) \dots q(x_{T-1}|x_{T-2}, x_{T-3}) \dots dx_{1:T-2} \mid \&= \int \frac{p(x_{0:T})}{p(x_0)} dx_{1:T-2} \mid \&= \\ & \int q(x_{1:T}|x_0) dx_{1:T-2} \mid \&= q(x_{T-1}|x_0) \end{aligned} \end{aligned}$$

$$\begin{aligned} & \mathbb{E} \{q(x_{1:T}|x_0)\} \left[\ln \left\{ p_{\theta}(x_0|x_1) \right\} \right] \&= \int \left[\ln \left\{ p_{\theta}(x_0|x_1) \right\} q(x_{1:T}|x_0) \right] d\{x_{1:T}\} \mid \&= \int \left[\ln \left\{ p_{\theta}(x_0|x_1) \right\} q(x_1|x_0) \right] d\{x_1\} \underbrace{\int \prod_{t=2}^{T-1} \{q(x_t|x_{t-1})\} d\{x_{2:T}\}}_{1} \mid \&= \mathbb{E} \{q(x_1|x_0)\} \left[\ln \left\{ p_{\theta}(x_0|x_1) \right\} \right] \end{aligned}$$

$$\begin{aligned} & \mathbb{E} \{q(x_{1:T}|x_0)\} \left[\ln \left\{ \frac{p(x_T)}{q(x_T|x_{T-1})} \right\} \right] \&= \\ & \int \left[\ln \left\{ \frac{p(x_T)}{q(x_T|x_{T-1})} \right\} \{q(x_T|x_{T-1})\} \right] q(x_{1:T}|x_0) d\{x_{1:T}\} \mid \&= \\ & \int \left[\ln \left\{ \frac{p(x_T)}{q(x_T|x_{T-1})} \right\} \right] q(x_T|x_{T-1}) dx_{T-1,T} \\ & \underbrace{\int \prod_{t=1}^{T-1} q(x_t|x_{t-1}) dx_{1:T-2}}_{\int p_{\theta}(x_{1:T-1})} q(x_{T-1}|x_0) \mid \&= \\ & \int \left[\ln \left\{ \frac{p(x_T)}{q(x_T|x_{T-1})} \right\} \right] q(x_T|x_{T-1}) q(x_{T-1}|x_0) dx_{T-1,T} \mid \&= \\ & \int \left[\ln \left\{ \frac{p(x_T)}{q(x_T|x_{T-1})} \right\} \right] q(x_{T-1}, x_T|x_0) dx_{T-1,T} \mid \&= \mathbb{E} \{q(x_{T-1}, x_T|x_0)\} \left[\ln \left\{ \frac{p(x_T)}{q(x_T|x_{T-1})} \right\} \right] \end{aligned}$$

$$\begin{aligned} & \mathbb{E} \{q(x_{1:T}|x_0)\} \left[\sum_{t=1}^{T-1} \left[\ln \left\{ \frac{p_{\theta}(x_t|x_{t+1})}{q(x_t|x_{t+1})} \right\} \right] \right] \&= \sum_{t=1}^{T-1} \int \left[\ln \left\{ \frac{p_{\theta}(x_t|x_{t+1})}{q(x_t|x_{t+1})} \right\} \right] q(x_{1:T}|x_0) d\{x_{1:T}\} \mid \&= \sum_{t=1}^{T-1} \int \left[\ln \left\{ \frac{p_{\theta}(x_t|x_{t+1})}{q(x_t|x_{t+1})} \right\} \right] q(x_t|x_{t+1}) \prod_{k=1}^{T-t} q(x_k|x_{k-1}) dx_{1:T} \mid \&= \sum_{t=1}^{T-1} \int \left[\ln \left\{ \frac{p_{\theta}(x_t|x_{t+1})}{q(x_t|x_{t+1})} \right\} \right] q(x_t|x_{t+1}) q(x_{t+1}|x_t) d\{x_{t-1}, x_t, x_{t+1}\} \int \prod_{1 \leq k \leq t} q(x_k|x_{k-1}) \end{aligned}$$

ELBO

- $\mathbb{E} \{q(x_{1:T}|x_0)\} \left[\ln \left\{ p_{\theta}(x_0|x_1) \right\} \right] \&= \int \frac{p(x_{0:T})}{p(x_0)} dx_{1:T-2} \mid \&= \int q(x_{1:T}|x_0) dx_{1:T-2} \mid \&= q(x_{T-1}|x_0)$
- $\mathbb{E} \{q(x_{T-1}, x_T|x_0)\} \left[\ln \left\{ \frac{p(x_T)}{q(x_T|x_{T-1})} \right\} \right] \&= \int \frac{p(x_{T-1}, x_T|x_0)}{q(x_{T-1}, x_T|x_0)} dx_{T-1,T} \mid \&= \int q(x_{T-1}, x_T|x_0) \left[\ln \left\{ \frac{p(x_T)}{q(x_T|x_{T-1})} \right\} \right] dx_{T-1,T} \mid \&= \mathbb{E} \{q(x_{T-1}, x_T|x_0)\} \left[\ln \left\{ \frac{p(x_T)}{q(x_T|x_{T-1})} \right\} \right]$

- $\sum_{t=1}^{T-1} \mathbb{E} \{ q(x_{t-1}, x_t, x_{t+1} | x_0) [\ln \frac{p_{\theta}(x_t | x_{t+1})}{q(x_t | x_{t-1})}] \}$ KL 散度 $\mathbb{E} \{ \sum_{t=1}^{T-1} \mathbb{E} \{ \ln \frac{p_{\theta}(x_t | x_{t+1})}{q(x_t | x_{t-1})} \} \}$ 的期望

训练

- 训练数据 $\{x_0, x_1, \dots, x_T\}$ 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度
- 训练数据 $\{x_0, x_1, \dots, x_T\}$ 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度
- 训练数据 $\{x_0, x_1, \dots, x_T\}$ 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度
- DDPI 训练
- 训练数据 $\{x_0, x_1, \dots, x_T\}$ 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度
- 训练数据 $\{x_0, x_1, \dots, x_T\}$ 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度

Denoising Diffusion Probabilistic Models(DDPM)

训练

训练数据

1. 训练数据 $\{x_0, x_1, \dots, x_T\}$ 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度
2. 训练数据 $\{x_0, x_1, \dots, x_T\}$ 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度
3. $\mathcal{N}(0, I)$ 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度
4. $\|\nabla_{\theta} \mathbb{E} [q(x_t | x_{t-1}) - p(x_t | x_{t-1})]\|^2$ 的期望
 - α_t 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度
 - 训练数据 $\{x_0, x_1, \dots, x_T\}$ 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度

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训练

训练数据

1. 训练数据 $\{x_0, x_1, \dots, x_T\}$ 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度
2. 训练数据 $\{x_0, x_1, \dots, x_T\}$ 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度
3. 训练数据 $\{x_0, x_1, \dots, x_T\}$ 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度
 - x_{t-1} 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度
 - α_t 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度
 - $\epsilon_{\theta}(x_t, t)$ 的分布 $p(x_0, x_1, \dots, x_T)$ 与模型 $q(x_t | x_{t-1})$ 的分布 $q(x_t | x_{t-1})$ 的 KL 散度

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