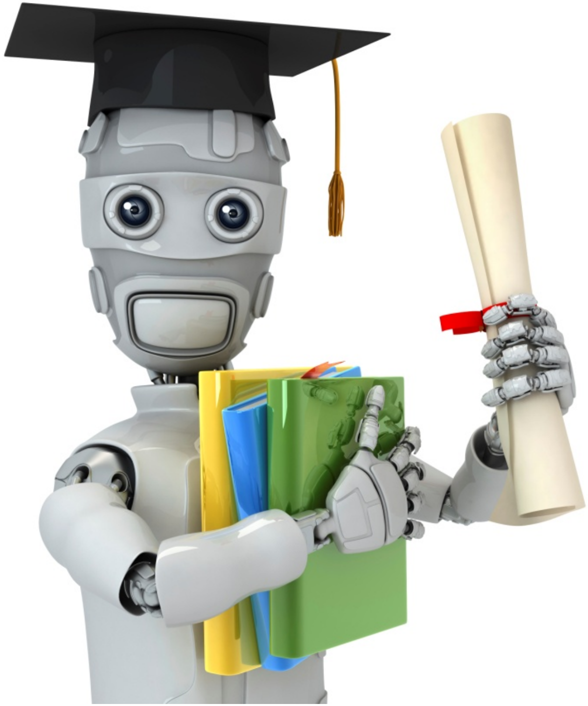
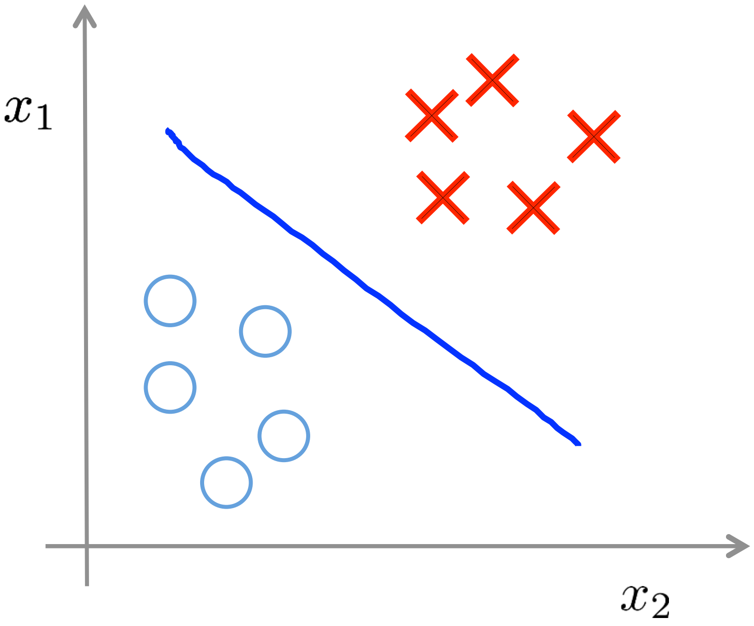


Machine Learning

Clustering

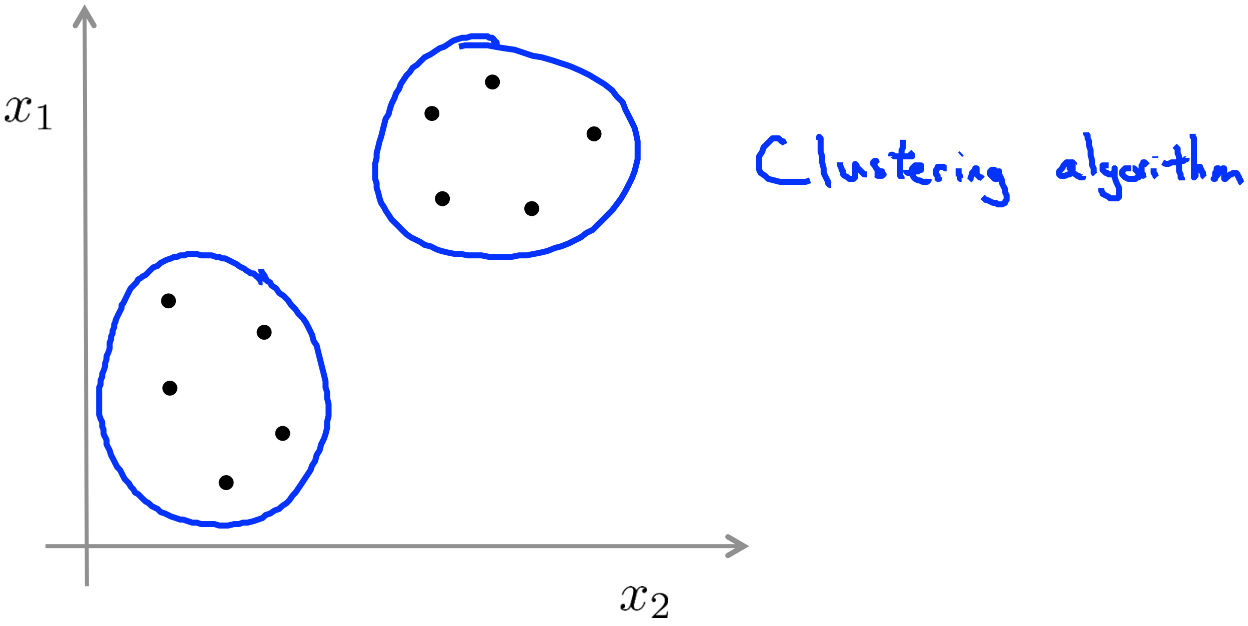
Unsupervised learning introduction

Supervised learning



Training set: $\{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), (x^{(3)}, y^{(3)}), \ldots, (x^{(m)}, y^{(m)})\}$

Unsupervised learning



Training set: $\{x^{(1)}, x^{(2)}, x^{(3)}, \ldots, x^{(m)}\} \leftarrow$

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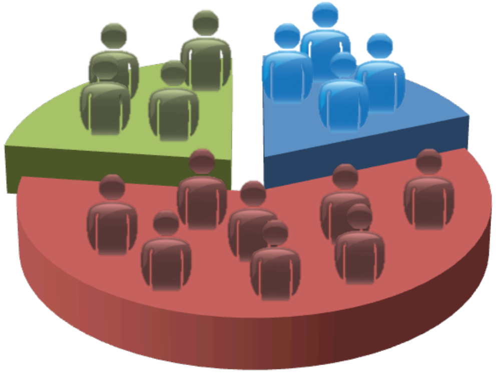
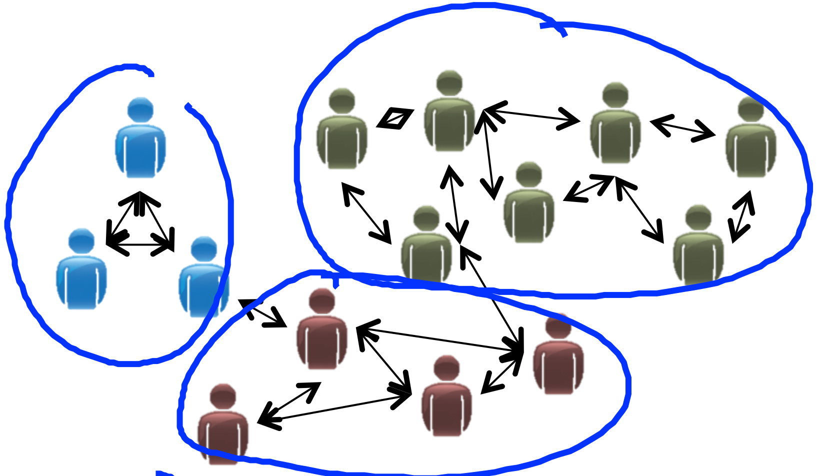
Applications of clustering



Market segmentation

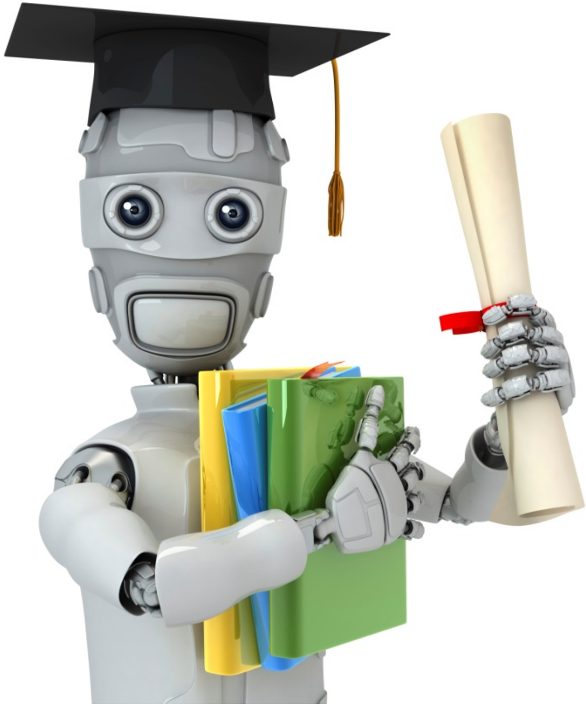


Social network analysis

Organize computing clusters

Image credit: NASA/JPL-Caltech/E. Churchwell (Univ. of Wisconsin, Madison)

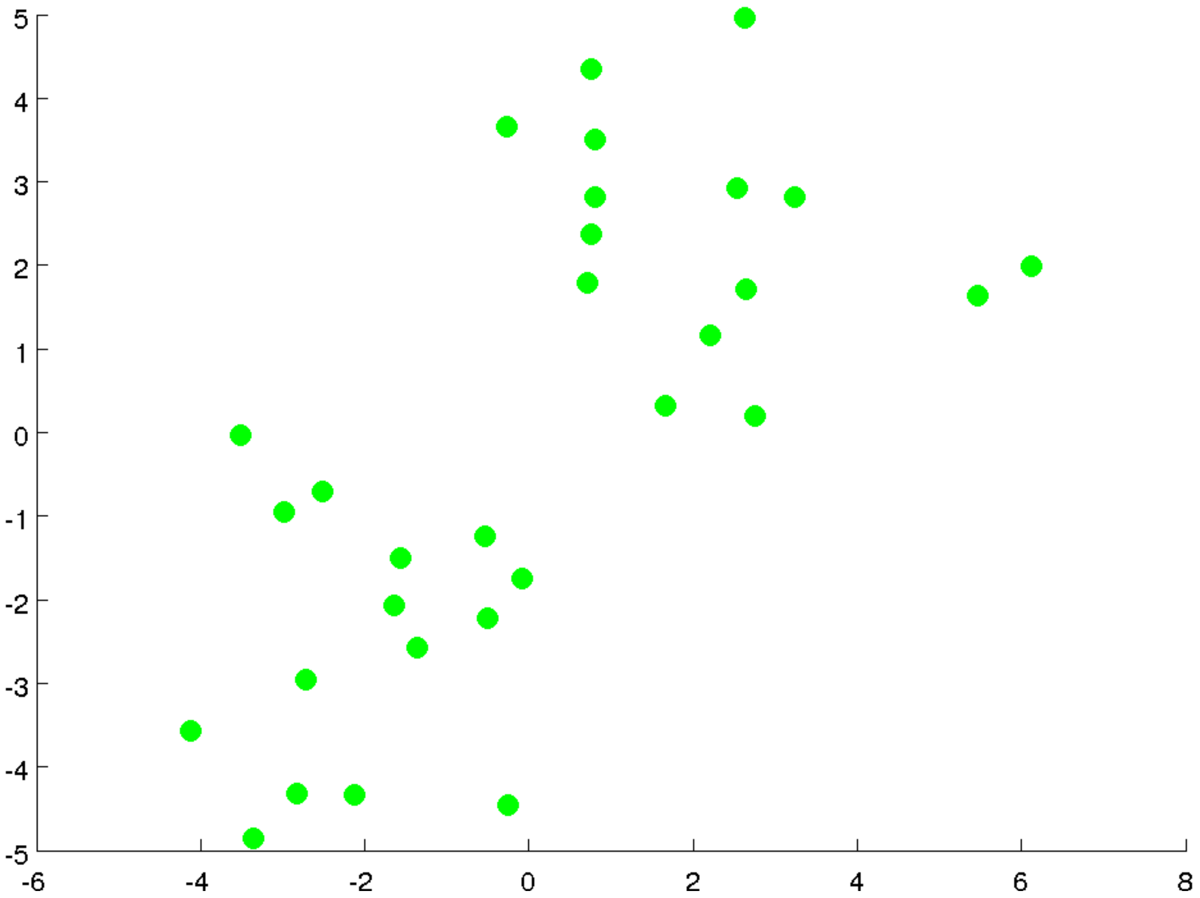
Astronomical data analysis



Machine Learning

Clustering

K-means algorithm



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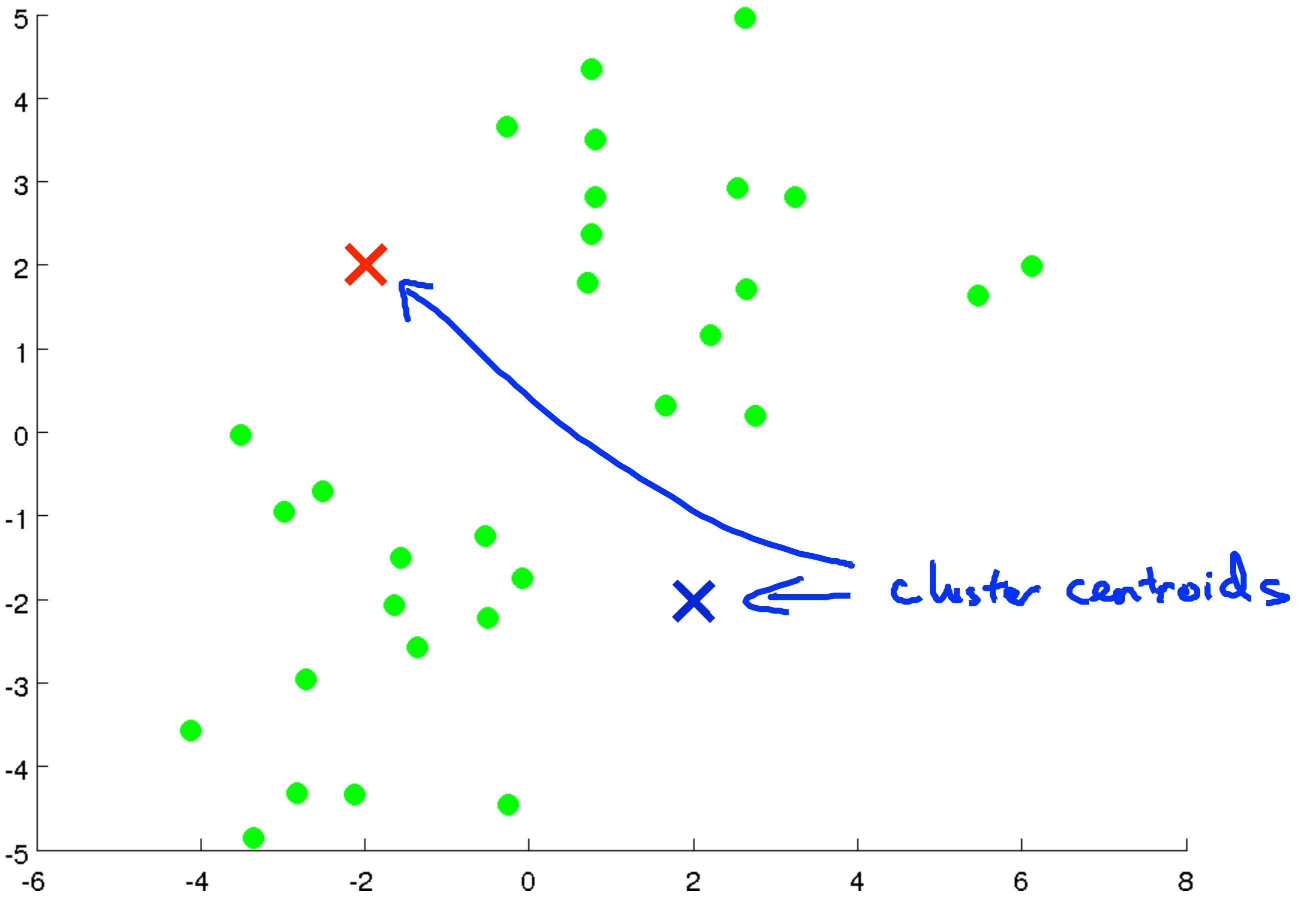

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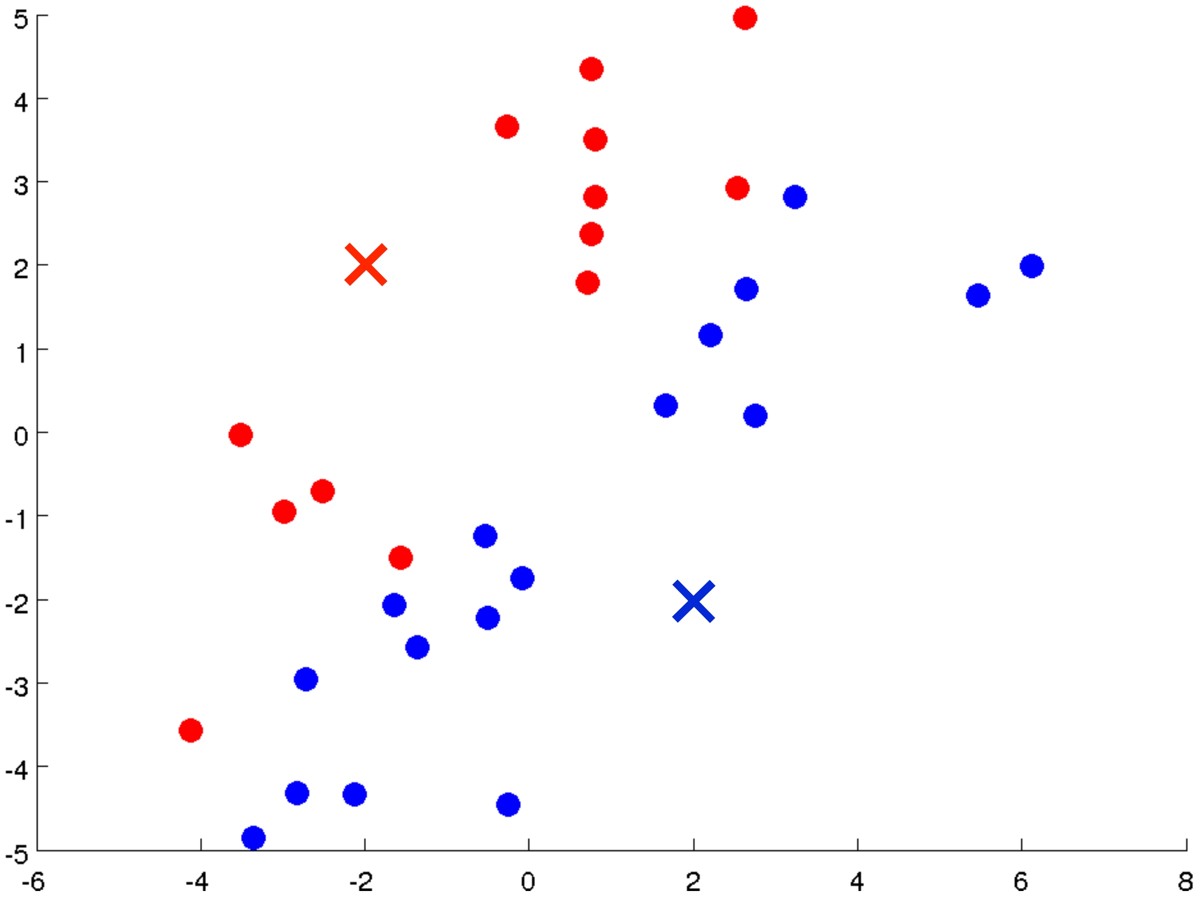
cluster centroids



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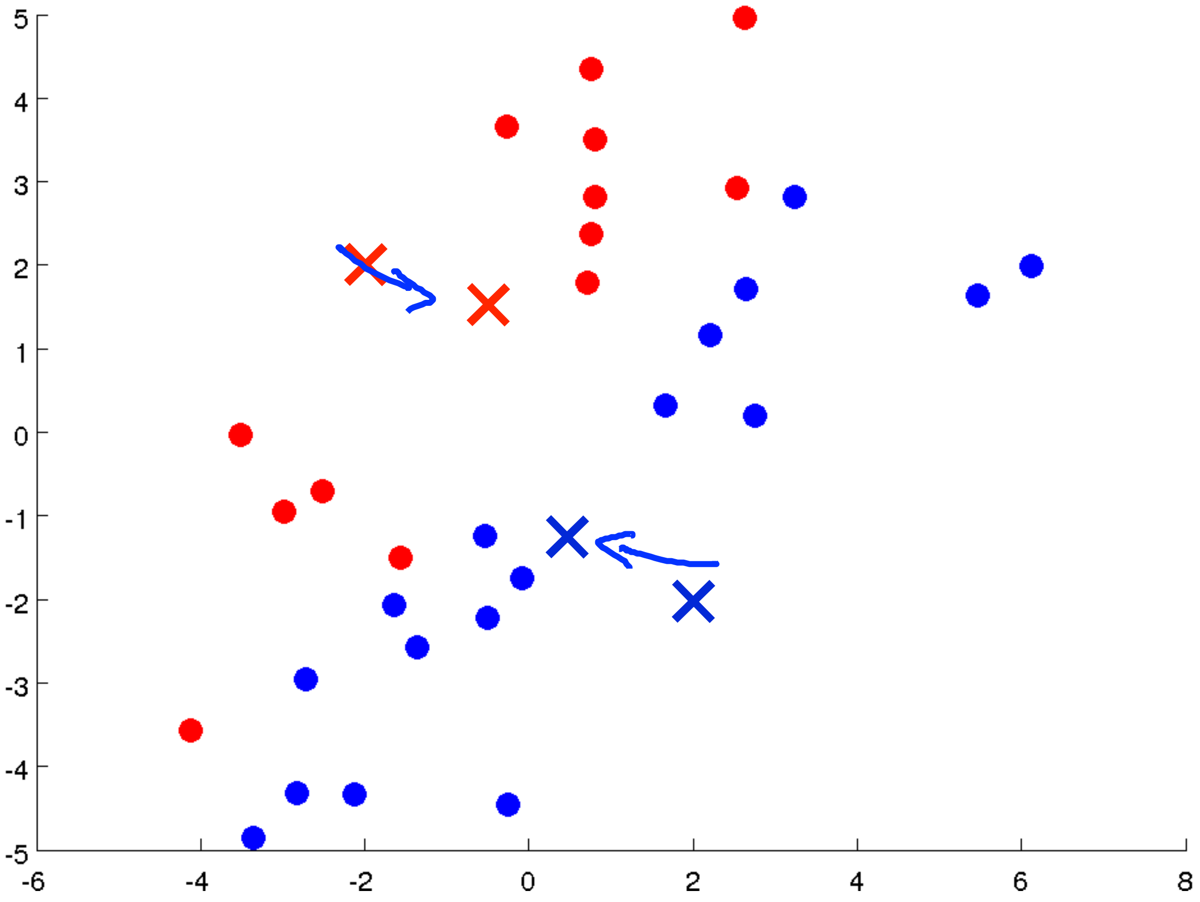

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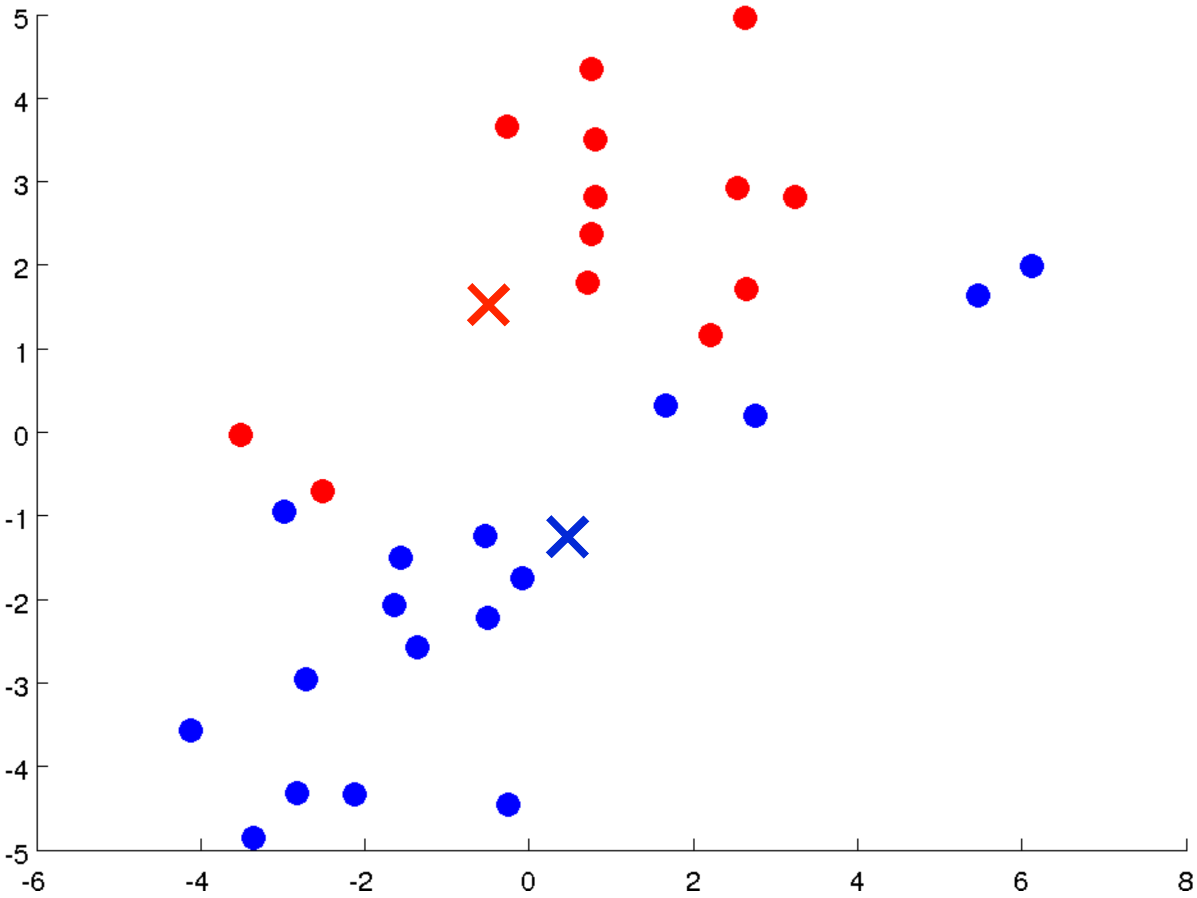
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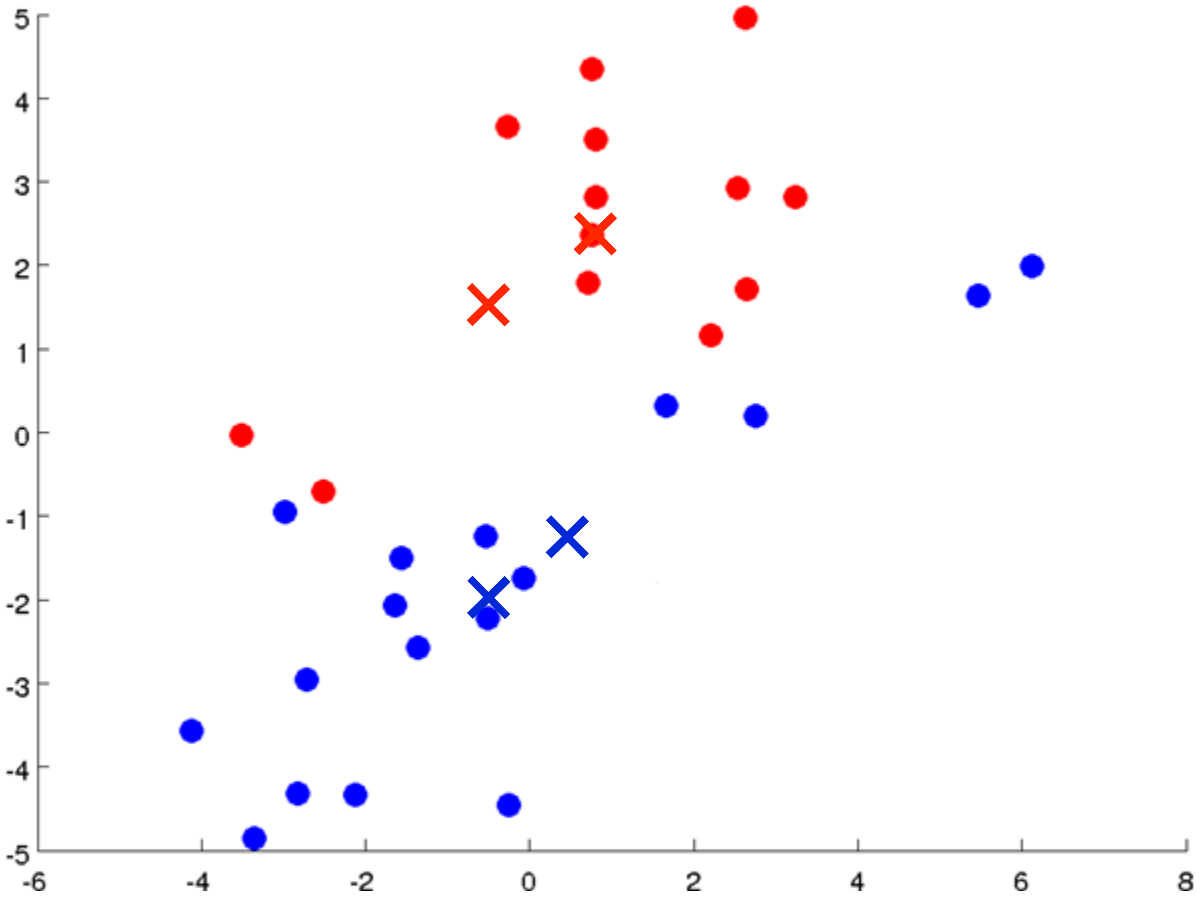

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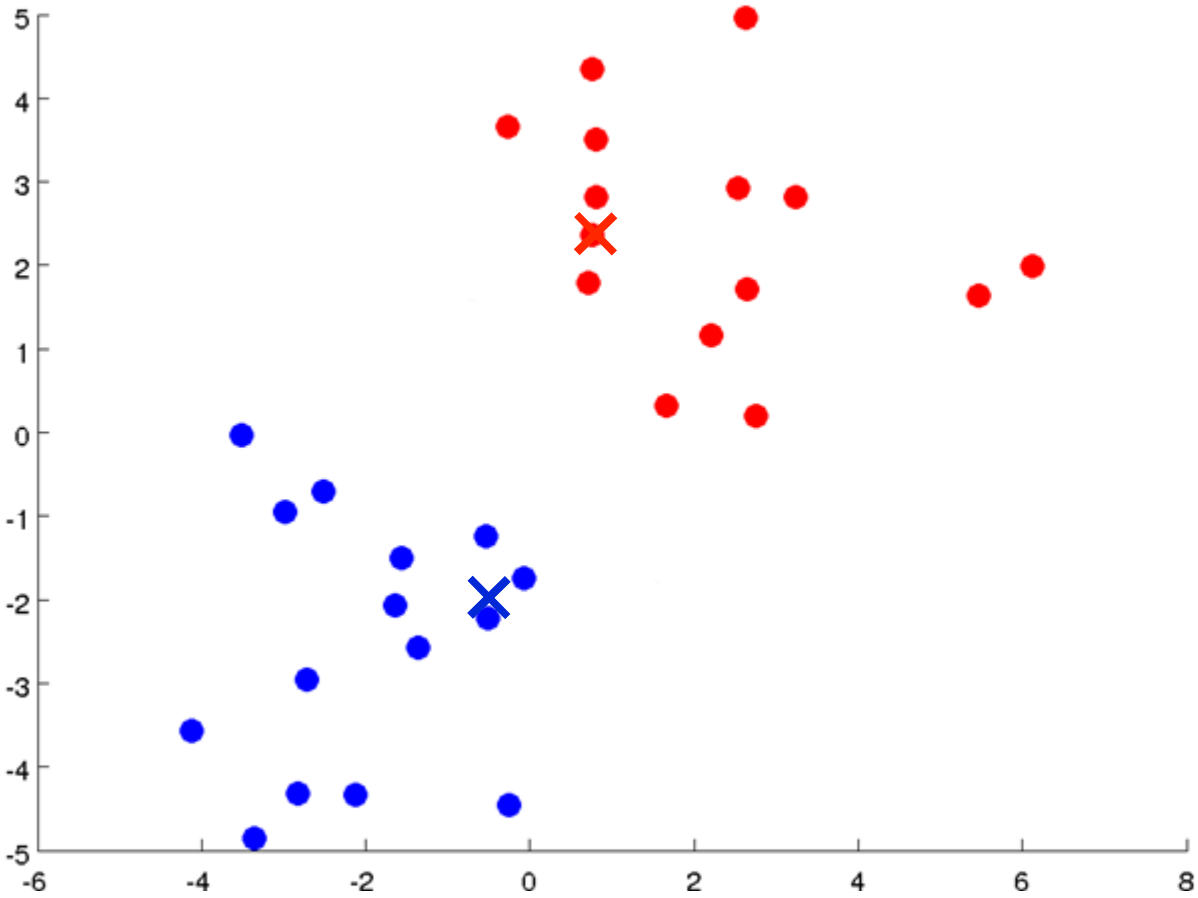
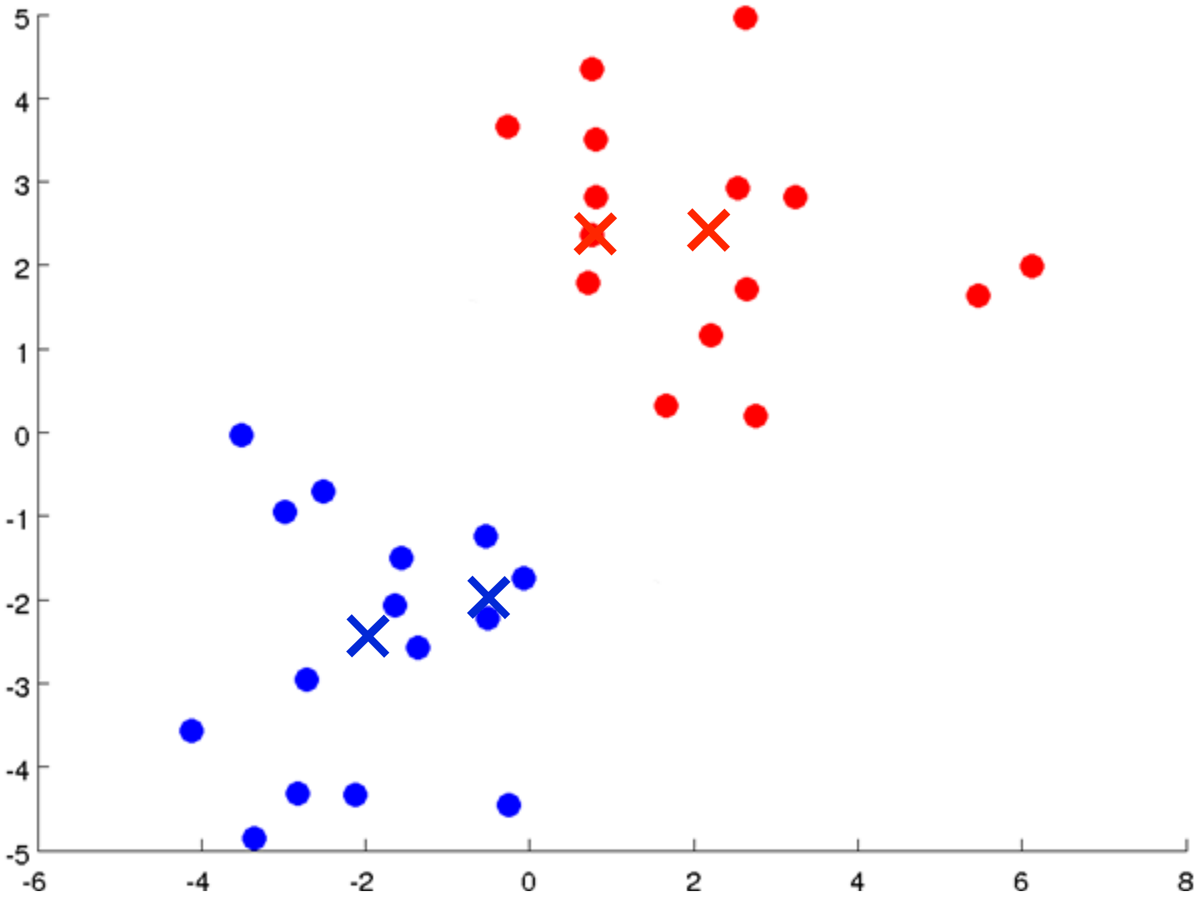


Andrew Ng



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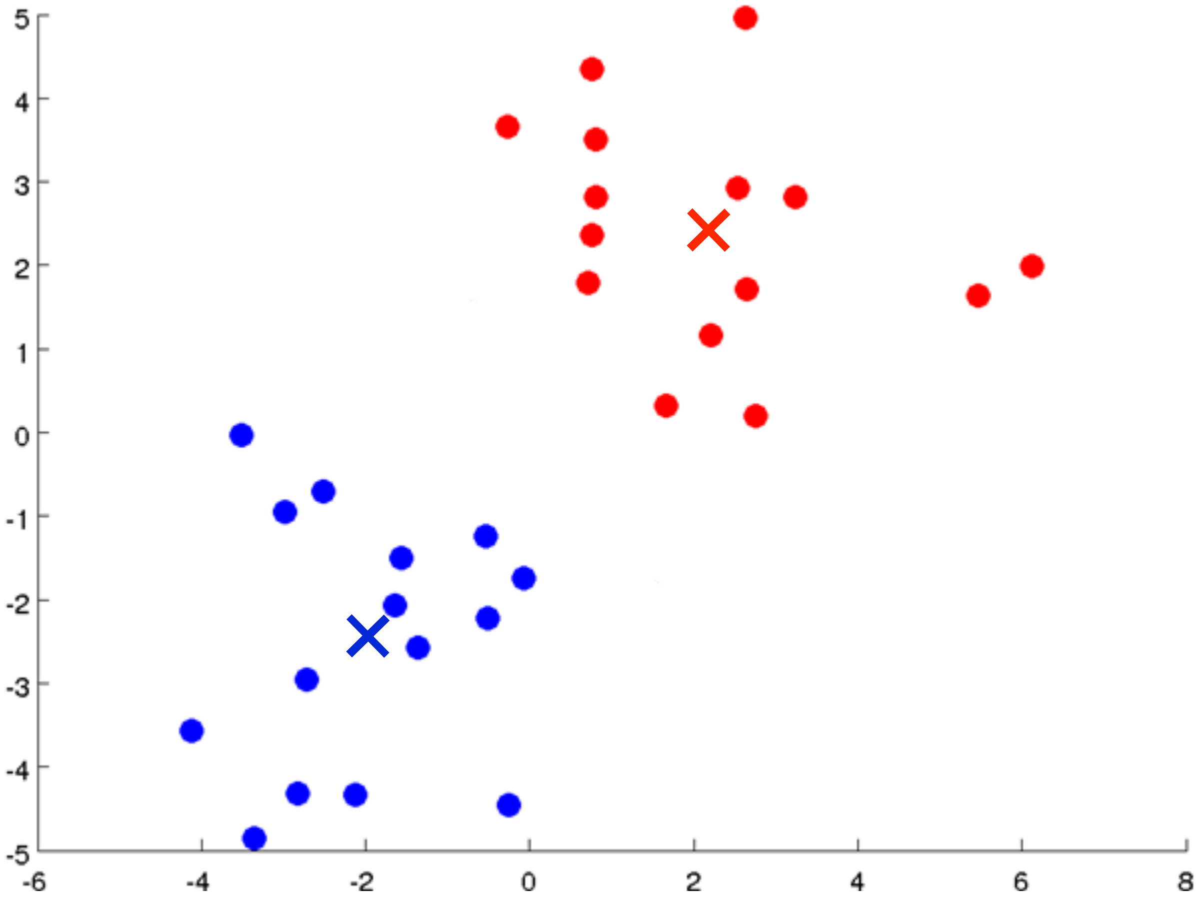

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K-means algorithm

Input:

- K (number of clusters)
- Training set $\{x^{(1)}, x^{(2)}, \ldots, x^{(m)}\}$

$x^{(i)} \in \mathbb{R}^n$ (drop $x_0 = 1$ convention)

K-means algorithm

Randomly initialize K cluster centroids $\mu_1, \mu_2, \ldots, \mu_K \in \mathbb{R}^n$

Repeat {

for i = 1 to m

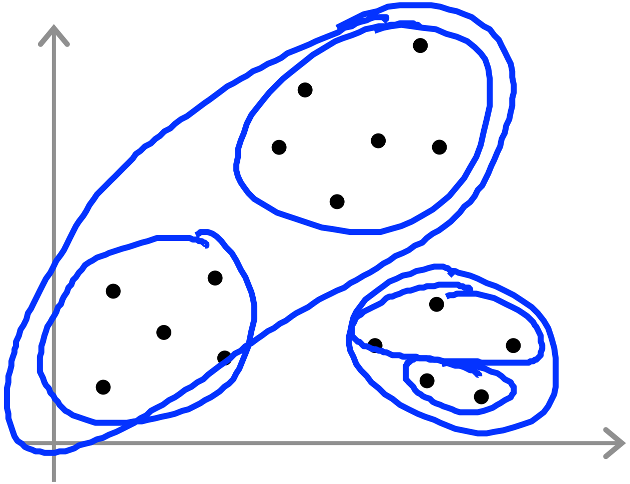
$c^{(i)}$:= index (from 1 to K) of cluster centroid closest to $x^{(i)}$

for k = 1 to K

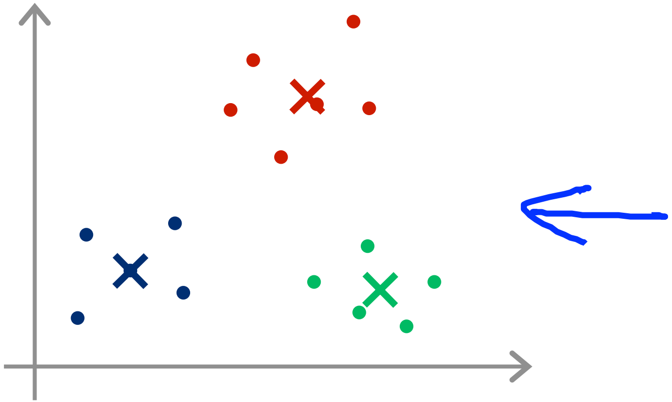
μ_k := average (mean) of points assigned to cluster k

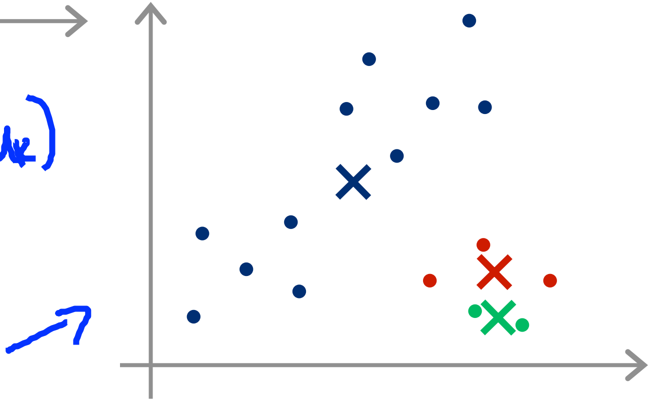
}

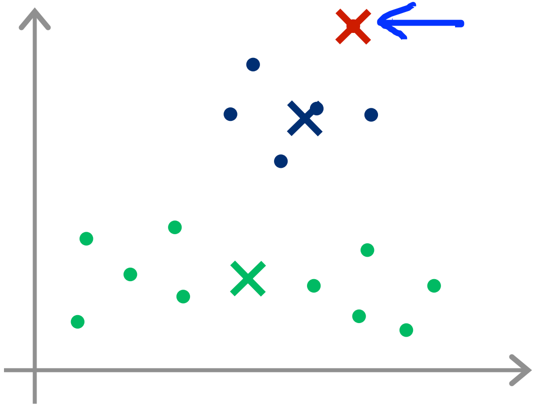
Local optima



$J(c^{(1)},\dots,c^{(m)},\mu_1,\dots,\mu_K)$







Random initialization

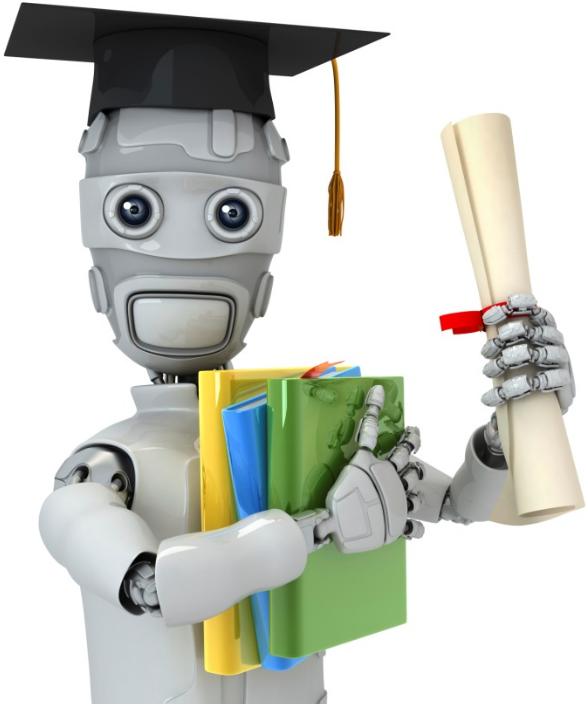
For i = 1 to 100 {

Randomly initialize K-means.
Run K-means. Get $c^{(1)}, \ldots, c^{(m)}, \mu_1, \ldots, \mu_K$.
Compute cost function (distortion)

$$J(c^{(1)}, \ldots, c^{(m)}, \mu_1, \ldots, \mu_K)$$

}

Pick clustering that gave lowest cost $J(c^{(1)}, \ldots, c^{(m)}, \mu_1, \ldots, \mu_K)$

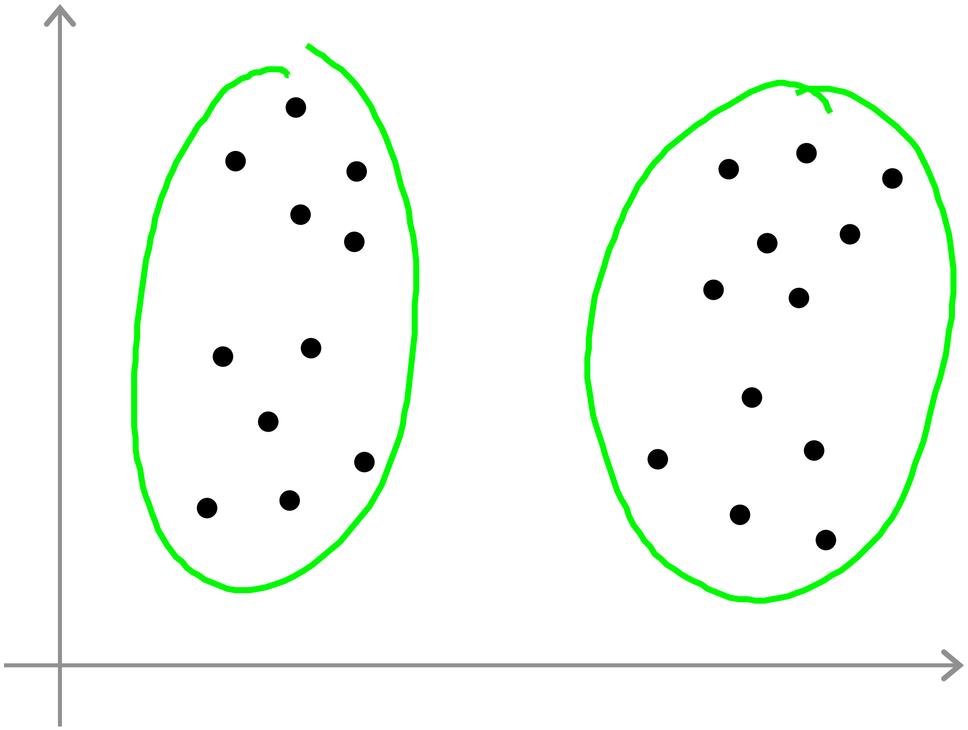


Machine Learning

Clustering

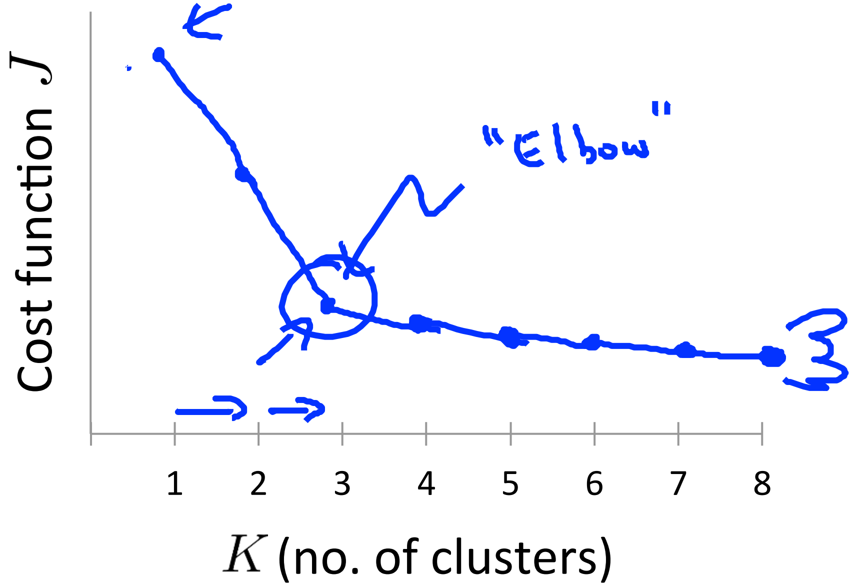
Choosing the number of clusters

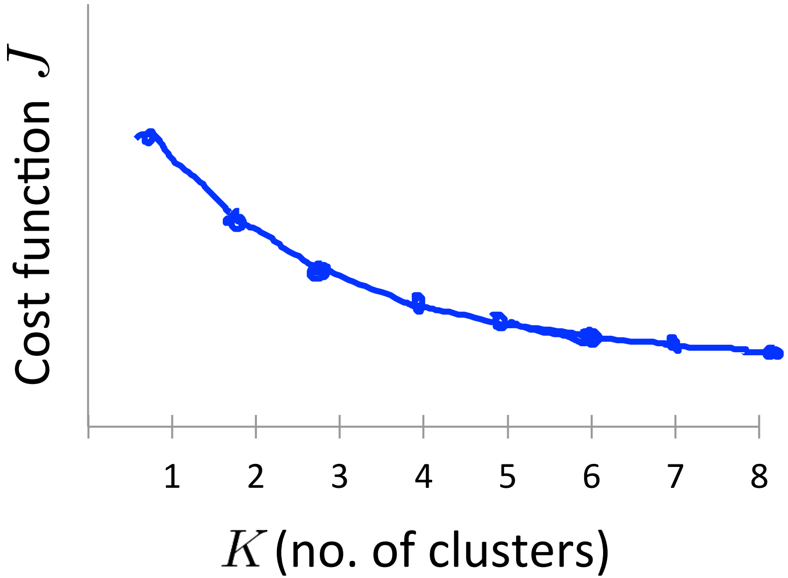
What is the right value of K?



Choosing the value of K

Elbow method:





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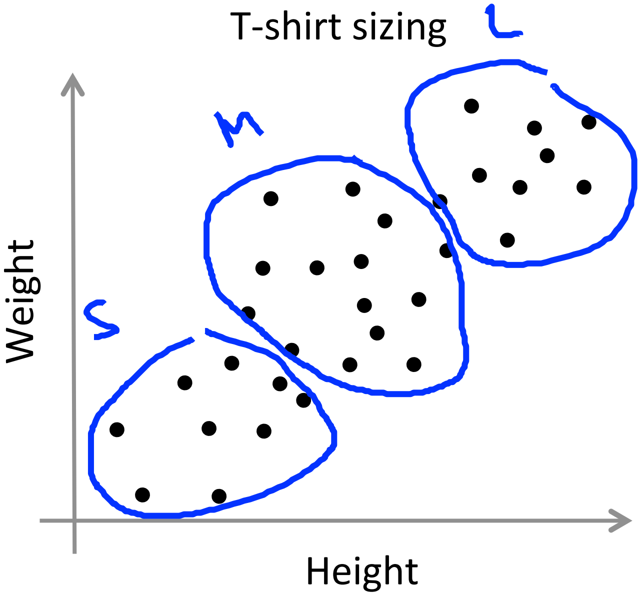
Choosing the value of K

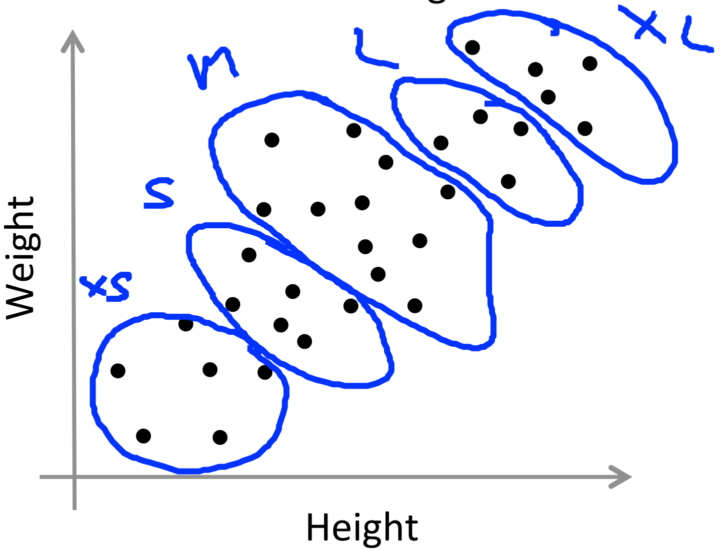
Sometimes, you're running K-means to get clusters to use for some later/downstream purpose. Evaluate K-means based on a metric for how well it performs for that later purpose.

K=3 S, M, L

K=5 XS, S, M, L, XL

E.g.





DATA MINING
CLUSTERING

by Panayiotis Tsaparas

The k-means algorithm

Hierarchical Clustering

The DBSCAN algorithm

Evaluation

DBSCAN

DBSCAN: Density-Based Clustering

- DBSCAN is a Density-Based Clustering algorithm

- Reminder: In density-based clustering we partition points into dense regions separated by not-so-dense regions.

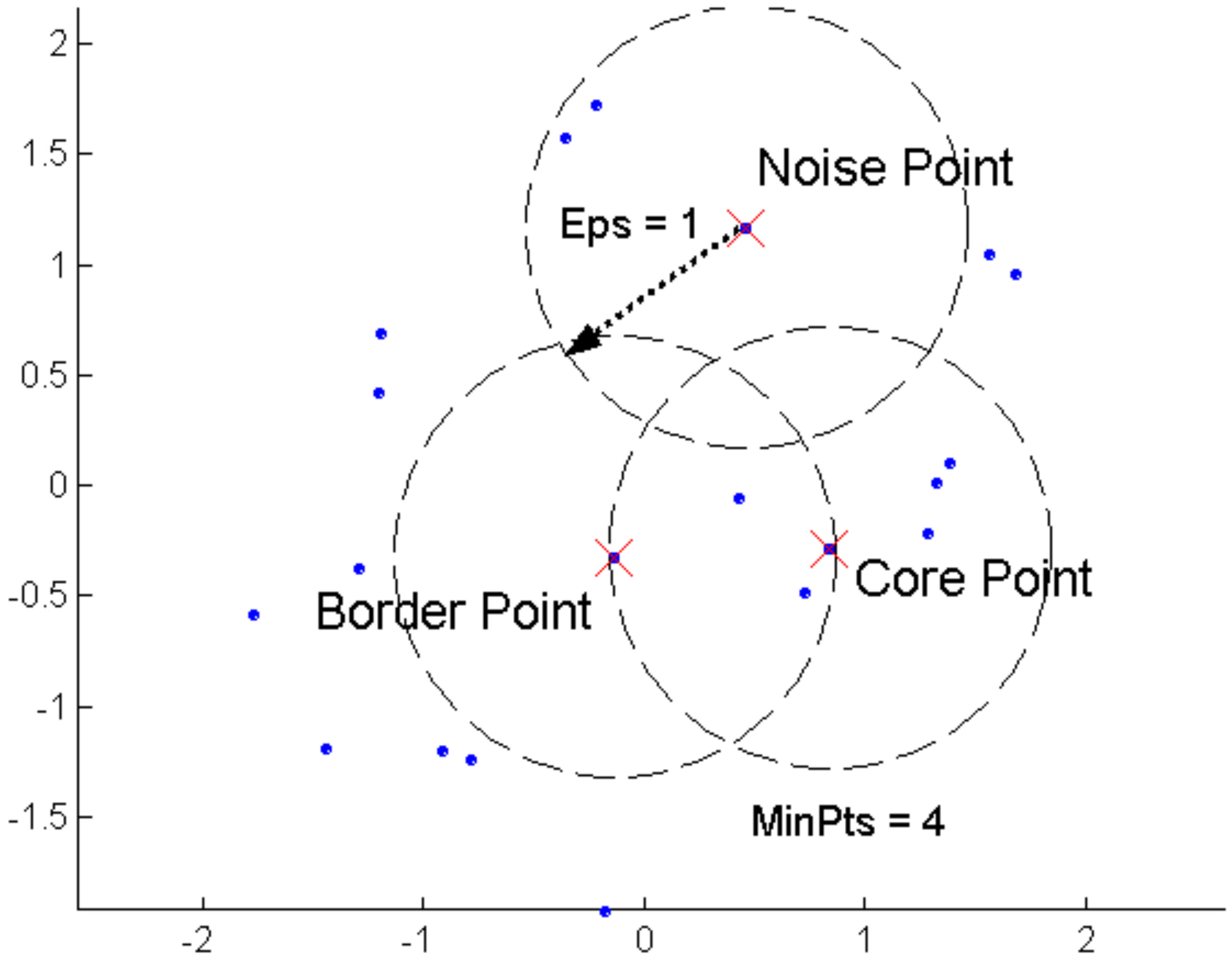
- Important Questions:
  - How do we measure density?
  - What is a dense region?

- DBSCAN:
  - Density at point p: number of points within a circle of radius Eps
  - Dense Region: A circle of radius Eps that contains at least MinPts points

DBSCAN

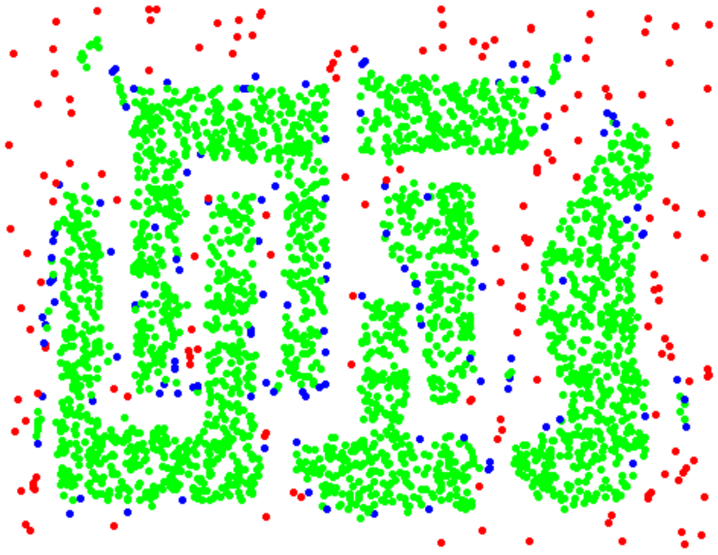
- Characterization of points
  - A point is a core point if it has more than a specified number of points (MinPts) within Eps
    - These points belong in a dense region and are at the interior of a cluster
  - A border point has fewer than MinPts within Eps, but is in the neighborhood of a core point.
  - A noise point is any point that is not a core point or a border point.

DBSCAN: Core, Border, and Noise Points



DBSCAN: Core, Border and Noise Points

Original Points

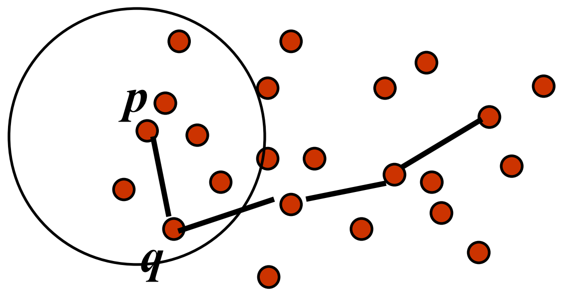


Point types: core, border and noise

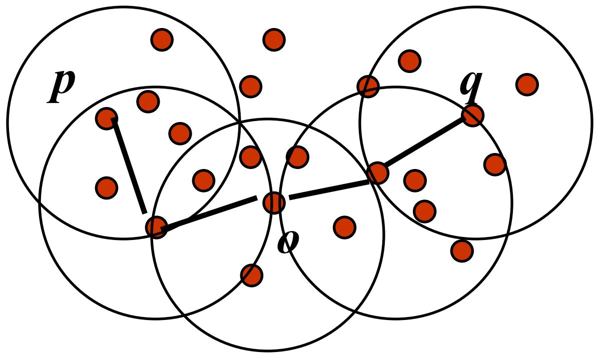
Eps = 10, MinPts = 4

Density-Connected points

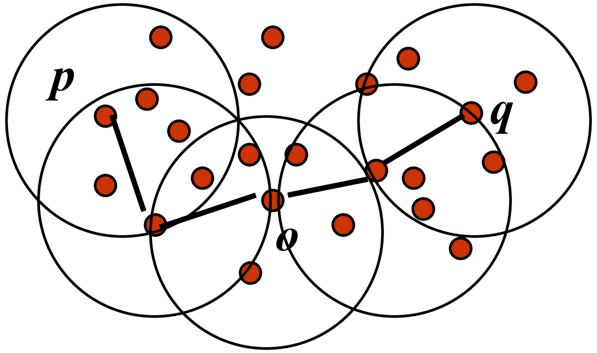
- Density edge
  - We place an edge between two core points q and p if they are within distance Eps.



- Density-connected
  - A point p is density-connected to a point q if there is a path of edges from p to q



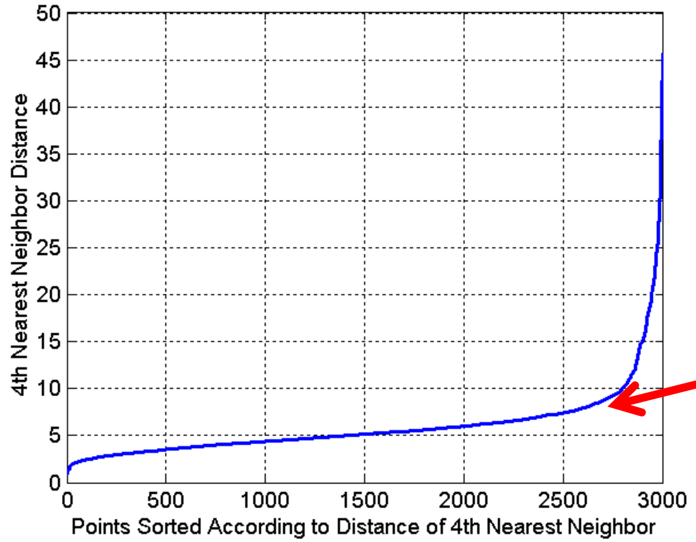
DBSCAN Algorithm



- Label points as core, border and noise
- Eliminate noise points
- For every core point q that has not been assigned to a cluster
  - Create a new cluster with the point q and all the points that are density-connected to q.
- Assign border points to the cluster of the closest core point.

DBSCAN: Determining Eps and MinPts

- Try different minPts= k
- So, plot sorted distance of every point to its k^{th} nearest neighbor
- Find the distance d where there is a “knee” in the curve
  - Eps = d, MinPts = k

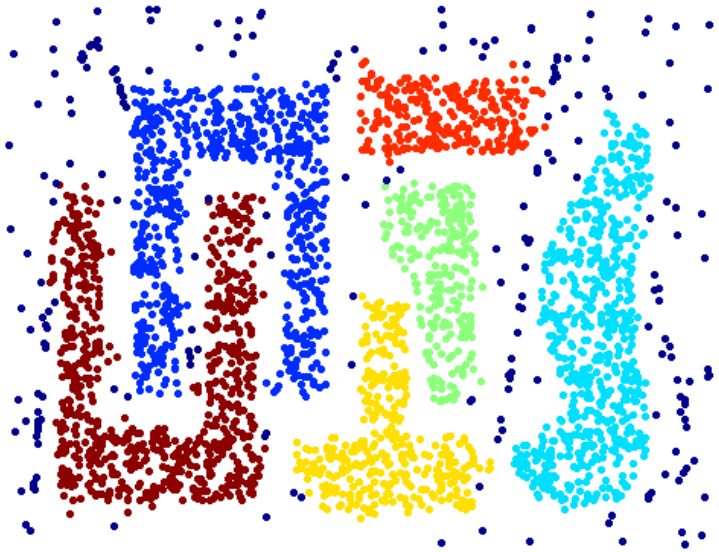


Noise points have the k^{th} nearest neighbor at farther distance

Eps ~ 7-10
MinPts = 4

When DBSCAN Works Well

Original Points



Clusters

- Resistant to Noise
- Can handle clusters of different shapes and sizes

DBSCAN: Sensitive to Parameters

Figure 8. DBScan results for DS1 with MinPts at 4 and Eps at (a) 0.5 and (b) 0.4.

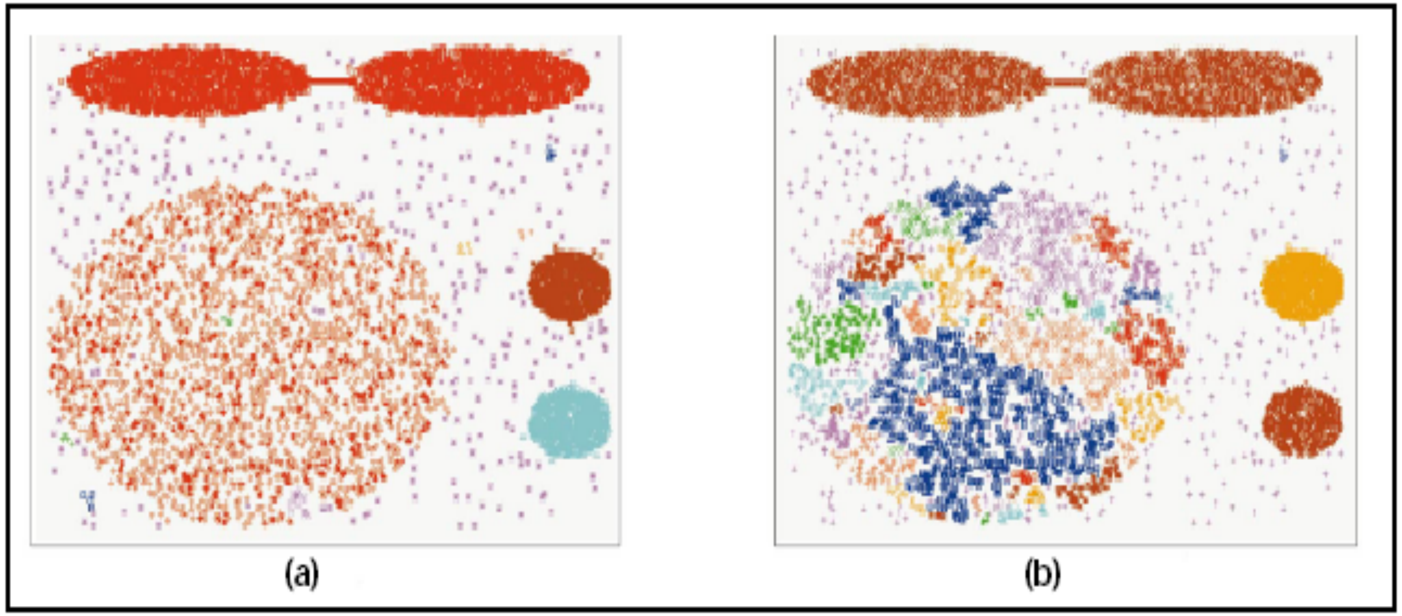
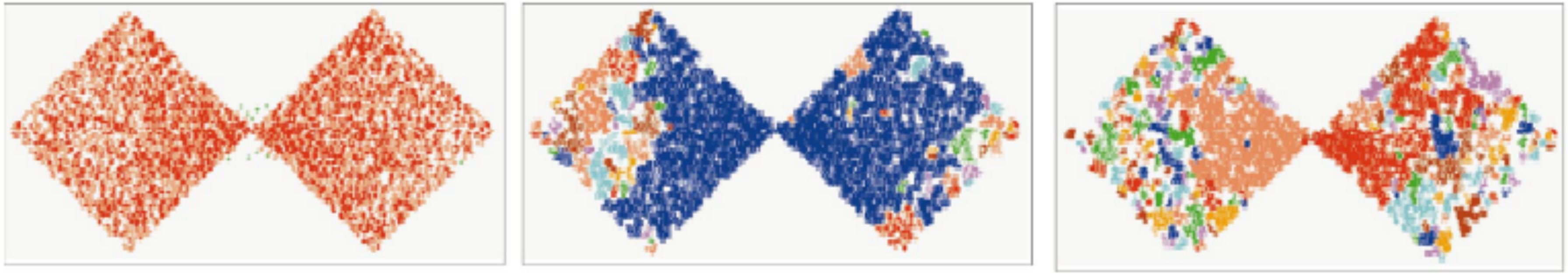
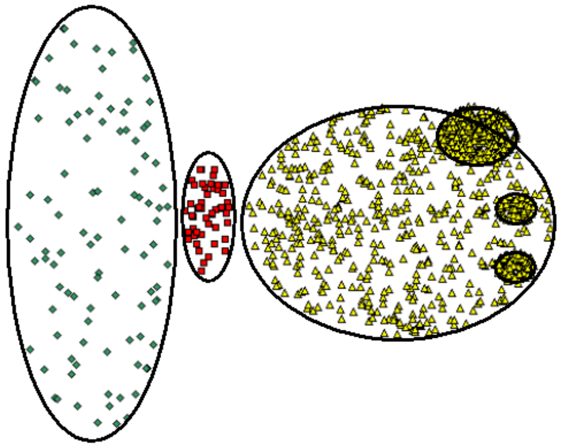


Figure 9. DBScan results for DS2 with MinPts at 4 and Eps at (a) 5.0, (b) 3.5, and (c) 3.0.

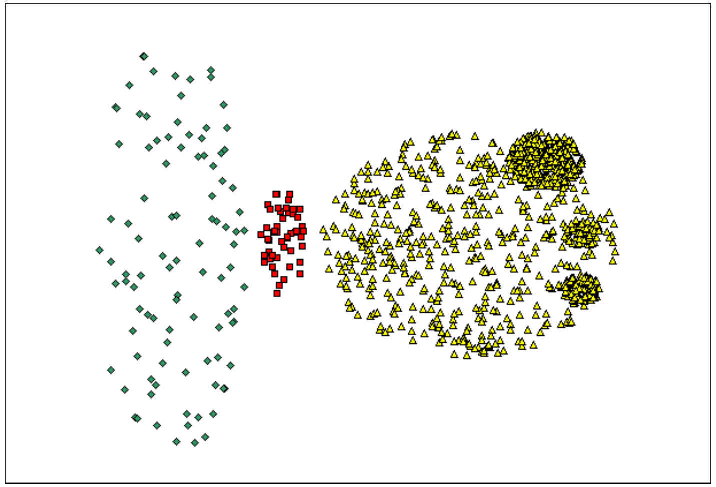


(a) (b) (c)

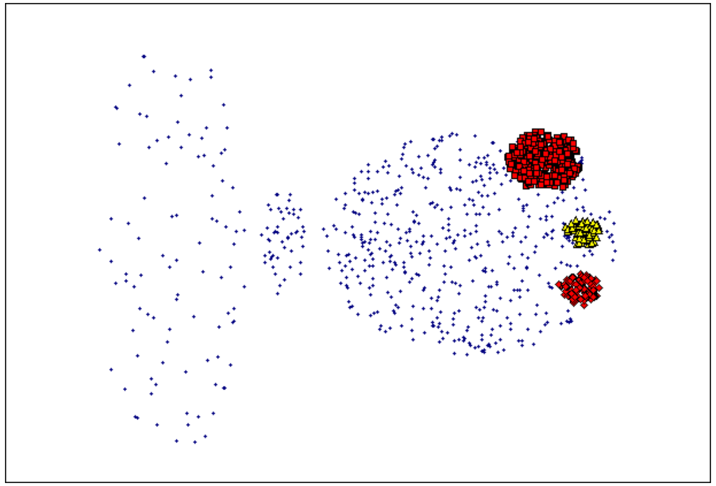
When DBSCAN Does NOT Work Well



Original Points



(MinPts=4, Eps=9.75).



(MinPts=4, Eps=9.92)

- Varying densities
  - •large differences in densities, since the minPts-Eps combination cannot then be chosen appropriately for all clusters.
- High-dimensional data
  - •difficult to find an appropriate value for Eps