LAB SESSION 2: MINI-PROJECT ON GAUSSIAN MIXTURES

This mini-project is marked: you are supposed to hand out your work as a R notebook on the course's moodle before November, 26th. Details on the required format can be found there.

The aim of this lab session is to implement and compare the main computational methods surveyed in this course: EM, Variational Bayes and MCMC. We consider the Gaussian mixture example: given a dataset, the goal is to estimate the mixture distribution. To save time, A skeleton of the functions that you need to write to complete this project is given in the file GM_functions.R. Also all code chunks in the present assignment are gathered in the file code_chunks2.R

In the following, some extra R packages are needed:

```
##install.packages("MASS")
##install.packages("abind")
##install.packages("mnormt")
##install.packages("LaplacesDemon")
##install.packages("coda")
library(MASS)
library(abind)
library(mnormt)
library(LaplacesDemon)
library(coda)
```

1 Preliminaries

Recall the Gaussian mixture model on \mathbb{R}^d : The data $X=(X_1,\ldots,X_n)$ is assumed to be *i.i.d.* according to the density

$$f(x|\rho_{1:k}, \mu_{1:k}, \Sigma_{1:k}) = \sum_{j=1}^{k} \rho_j \mathcal{N}(x|\mu_j, \Sigma_j) , \qquad (1)$$

where k is the number of mixture components, $\mathcal{N}(x|\mu,\Sigma)$ denotes the Gaussian density with parameters μ,Σ , and $\rho_j\geq 0$ is the weight of component j, with $\sum_{j=1}^k p_j=1$. The parameters $\mu_j\in\mathbb{R}^d$, Σ_j are respectively the center and the covariance matrix of component j.

This model can be rewritten using hidden variables $(\xi_i)_{i=1:n}$, with $\xi_i \in \{1,\ldots,k\}$

$$\xi_i \sim \text{Multinomial}(\rho)$$

 $\mathcal{L}(X_i|\xi_i = j) = \mathcal{N}(\mu_j, \Sigma_j), \qquad j \in \{1, \dots, k\}.$

The parameter for the Gaussian mixture is thus $\theta=(\rho_{1:k},\mu_{1:k},\Sigma_{1:k})$, which we shall represent in R as three objects: p, Mu, Sigma, with p a vector of size k, Mu a $k\times d$ matrix and Σ a $d\times d\times k$ array.

We consider a synthetic dataset that we generate ourselves using the following code

```
d <- 2 ## dimension
K <- 3 ## number of mixture components
N <- 500 ## sample size
p <- c(3/10, 2/10, 5/10) ## weight parameter
Mu <- rbind(c(-1, -1), c(0, 1), c(1, -1)) ## centers
set.seed(1)</pre>
```

```
NN <- rmultinom(n = 1, size = N, prob = p)
## NN: number of points in each cluster
Sigma <- array(dim = c(d, d, K)) ## the covariance matrices
X <- matrix(ncol = d, nrow = 0) ## the dataset
for(j in 1:K){
    Sigma[, , j] <- rwishart(nu = 5, S = 0.05*diag(d))
}
for(j in 1:K) {
    X <- rbind(X, mvrnorm(n=NN[j], mu = Mu[j, ], Sigma=Sigma[, , j]))
}
labs <- rep(0, N) ##vector of labels
count=1
for(j in 1:K) {
    labs[count:(count+NN[j]-1)] <- j
    count <- count + NN[j]
}
#' Plot the labelled data
plot(X[,1], X[,2], col=labs)</pre>
```

In the sequel, the functions gmllk, gmcdf, initem, draw_sd will be repeatedly used. They are available in the file GM_functions.R with some comments.

2 EM Algorithm

We start with implementing the EM algorithm for Gaussian mixtures. Remind that the output of the algorithm is an approximation of the maximum likelihood estimates $(\widehat{\rho}, \widehat{\mu}_{1:k}, \widehat{\Sigma}_{1:k})$ respectively for the mixture weights, the mean parameters and the covariance parameters.

- 1. What are the coupled equations that are satisfied by the maximum likelihood estimates?
- 2. Complete the code of functions estep, mstep, emalgo from file GM_functions.
- 3. Test your EM algorithm as follows:

```
cex=10*p)
for(j in 1:Kfit) {
  ellips <- draw_sd(outputem$last$Mu[j,], outputem$last$Sigma[,,j])
    lines(ellips[1,], ellips[2,], col='blue')
  }

for(j in 1:K) {
    ellips <- draw_sd(Mu[j,], Sigma[,,j])
    lines(ellips[1,], ellips[2,], col='black')
}</pre>
```

4. Check visually that the objective function to be maximized (the likelihood) increases at each iteration: plot the content of outputem\$objective.

3 Variational Bayes

We turn to the Variational Bayes approach. As in the lectures, we use a mean field variational distribution $q(\rho, \mu_{1:k}, \Lambda_{1:k}) = q(\rho) \prod_{j=1}^k q(\mu_j, \Lambda_j)$, with $\Lambda_j = \Sigma_j^{-1}$. We choose a prior of a similar form:

- a <u>Dirichlet distribution on ρ </u> with parameter $\alpha = (\alpha_0, \dots, \alpha_0)$ for some $\alpha_0 > 0$.
- a <u>Gaussian-Wishart distributions</u> on each pair (ν_j, Λ_j) where $\Lambda_j = \Sigma_j^{-1}$, with parameter $(\nu_0, \underline{\beta_0}, W_0)$.
- ρ and the pairs (μ_i, Λ_i) are independent

We have shown that the <u>variational posterior distribution is of the same form as the prior</u>, with different parameters $\alpha^* = (\alpha_1^*, \dots, \alpha_k^*), \nu^* = (\nu_1^*, \dots, \nu_k^*), \beta^* = (\beta_1^*, \dots, \beta_k^*), W^* = (W_1^*, \dots, W_k^*).$

- 1. What are the coupled equations satisfied by $\alpha^*, \nu^*, \beta^*, W^*$?
- 2. Complete the code of functions <u>vbMStep</u>, <u>vbEstep</u> and <u>vbalgo</u>. As a stopping criterion, the <u>lower bound on the model likelihood is used</u>,

$$\mathcal{F}(q) = \int_{z \in \mathcal{Z}} q(z) \log \frac{p(x, z)}{q(z)} dz$$

Where $z = (\xi_{1:n}, \rho_{1:k}, \mu_{1:k}, \Sigma_{1:k})$. In the present case, this lower bound has an explicit expression (see Bishop (2006), section 10.3.3). It is implemented in function lowerbound.

3. Test your algorithm with the following code

```
#' Bayesian model:
#' p ~ dirichlet(alpha); alpha = (alpha0, ..., alpha0)
#' [ xi | p ] ~ Multinomial(p)
#' [ mu_j | Lambda_j ] ~ Normal(m0, beta0 Lambda_j^(-1))
#' Lambda_j ~ Wishart(W0, nu0)
#' [ X| xi=j, mu, Lambda ] ~ Normal (mu_j, Lambda_j^(-1))

#' hyper-parameters : to be varied
alpha0 <- 0.1
m0 <- rep(0,2)
beta0 <- 0.1
W0 <- 1*diag(2)</pre>
```

4. As a first approximation we consider the posterior expectancy of the parameters in the variational approximation. Give the explicit expressions of

$$\widehat{\rho}_{vb} = \mathbb{E}_{q^*}(\rho), \quad \widehat{\mu}_{j,vb} = \mathbb{E}_{q^*}(\mu_j), \quad \widehat{\Sigma}_{j,vb} = (\mathbb{E}_{q^*}(\Lambda_j))^{-1},$$

as functions of the posterior predictive parameters. You may refer to Bishop (2006), <u>Appendix B</u> for expressions of expectancy's of classical distributions.

Plot a summary of the corresponding Gaussian mixture by completing the following code

```
#' Visual summary of VB's output :
#' posterior expectancy of each parameter
p_vb <- ## complete the code</pre>
   ## (variational posterior expectancy of mixture weights)
Mu vb <- ## complete the code
   ## (variational posterior expectancy of mixture centers)
Sigma_vb <- array(dim=c(d,d,Kfit))</pre>
for(j in 1:Kfit){
   Sigma_vb[,,j] <- ## complete the code</pre>
   ## (variational posterior expectancy of mixture covariances)
## show the data, true centers and initial positions from K-means
graphics.off()
plot (X[,1], X[,2], col=labs)
points (Mu[,1], Mu[,2], col="black",pch=8,cex=10*p)
set . seed (seed)
Init <- initem(X,Kfit)</pre>
points(Init$Mu[,1],Init$Mu[,2], col="orange",pch=18,cex = 10*Init$p)
## Add a summary of the VB solution
nonneg <- which (p_vb>0.001)
for(j in nonneg) {
   points(Mu_vb[j,1], Mu_vb[j,2], col="blue",
        pch=18,cex= 10 * p_vb[j])
   ellips <- draw_sd(mu = Mu_vb[j,],</pre>
                 sigma = Sigma_vb[,,j])
```

```
lines(ellips[1,], ellips[2,], col='blue')
}
```

- 5. Study the influence of the hyper-parameter α_0 : check that values less than one lead to 'sparse' solutions, in the sense that some mixture components are automatically granted negligible weights, so that the true number of components is automatically recovered (contrary to EM).
- 6. Study the influence of the other hyper-parameters.

4 Metropolis-Hastings algorithm

We now implement a Metropolis-Hastings algorithm for sampling the posterior distribution in the model described in Section 3.

Prior: The prior density is implemented in function dprior in the file GM_functions.R. It takes as argument a list of hyper-parameters hpar, see the function definition for details.

Proposal kernel: Denoting by $\theta^t = (\rho^t_{1:k}, \mu^t_{1:k}, \Sigma^t_{1:k})$ the current value of the parameter, we consider a proposal kernel $Q_{\mathrm{MH}}(\theta^t, \theta^*)$, generating a proposal $\theta^* = (\rho^*, \mu^*_{1:k}, \Sigma^*_{1:k})$ as follows:

- $\rho^* \sim \mathcal{D}iri(\alpha_p \times \alpha^t)$ where $\alpha_p > 0$ is a concentration parameter fixed by the user.
- $\mu_i^* \sim \mathcal{N}(\mu_i^t, \sigma_\mu^2 I_d)$ where σ_p^2 is a <u>variance</u> parameter fixed by the user.
- $\Sigma_j^* \sim \operatorname{Wishart}(\nu = \nu_{\Sigma}, W = (\nu_{\Sigma})^{-1}\Sigma_j^t)$, where ν_{Σ} is a degree of freedom parameter fixed by user. Thus $\mathbb{E}_{Q_{\operatorname{MH}}}(\Sigma_j^*|\Sigma_j^t) = \Sigma_j^t$ and the distribution of Σ_j^* is more peaked around Σ_j^t for large values of ν_{Σ} .
- 1. Complete the code for the function rproposal in file GM_functions.R to generate such a proposal.
- 2. Complete the code for the Metropolis-Hastings sampler MHsample.
- 3. Test your code on the following example (fix nsample to a lower value for debugging). For comparison purposes, the hyper-parameter values should be the same as those used with Variational Bayes.

```
init=init, hpar=hpar, ppar=ppar)
newpct <- proc.time()
elapsed <- newpct - pct
elapsed
outputmh$naccept ## should not be ridiculously low.</pre>
```

For convergence diagnostics, tracing the evolution of a single parameter (such as p[1]) is not relevant because of possible re-labelling of the mixture components (the model is not identifiable). However relevant numerical summaries can be constructed, such as the value of the cumulative distribution function (cdf) at a given point $x = (x_1, \ldots, x_d)$,

$$F(y|\rho^t, \mu_{1:k}^t, \Sigma_{1:k}^t) = \mathbb{P}(X_1 \le y_1, \dots, X_d \le y_d | \rho^t, \mu_{1:k}^t, \Sigma_{1:k}^t), \quad t \in \{1, \dots, N_{sample}\},$$

where N_{sample} is the number of iterations

- 4. To obtain such a time series, complete the code of function cdfTrace from file GM_functions.R. Notice that parameters <u>thin</u> and <u>burnin</u> allow respectively to <u>keep only one out of 'thin' sample</u> and to discard the first burnin samples.
- 5. The Heidelberger and Welch's test is a convergence test based on the stationarity hypothesis (see the help for function heidel.diag from package coda). Use the function heidel.diag from package coda in combination with cdfTrace to propose a reasonable number of iterations to achieve convergence. Use various values of x as argument of cdfTrace.

 N.B: the functions takes as argument a mcmc object. Any vector y may be coerced into an mcmc object via: y <- mcmc (y).
- 6. Generate three different chains outputmh1, outputmh2, outputmh3 with different starting values and use the Gelman and Rubin's diagnostic (coda functions gelman.diag and gelman.plot) as an additional convergence check. Discuss your results in combination with the previous ones to determine a reasonable number of iterations.
- 7. Remind that the predictive density is the posterior mean

$$f_{\text{pred}}(y) = \int f(y|\rho, \mu_{1:k}, \Sigma_{1:k}) \pi(\rho, \mu_{1:k}, \Sigma_{1:k}|x_{1:n}) \, \mathrm{d}\rho \, \mathrm{d}\mu_{1:k} \, \mathrm{d}\Sigma_{1:k},$$

which can be estimated from the MH sample by computing the empirical mean of the <u>density over</u> the MH output,

$$\widehat{f}_{MH}(y) = \frac{1}{M} \sum_{t=1}^{M} f(y|\rho^t, \mu_{1:k}^t, \Sigma_{1:k}^t),$$

where M is the number of remaining samples after discarding the burn-in period and thinning. Notice that thinning does not make the estimator better, it is just a convenient way to reduce the computational time when the number of samples is large and when consecutive samples are highly correlated.

The goal of this question is to plot the numerical approximation $\hat{f}_{MH}(y)$ on a grid of size 20×20 , together with the true density.

- ullet Complete the code of function MHpredictive, which returns $\widehat{f}_{\mathrm{MH}}(x)$.
- Complete the following code chunk in order to plot the desired result together with the true density. Define outputmh as one of the three previously generated chains with good p-values for the Heidelberger and Welch's test. Notice that the wrapper function from file GM_functions.R is a convenient auxiliary allowing to apply a function on a grid via the R function outer.

```
xx \leftarrow seq(-2, 2, length.out=20)
yy <- xx
dtrue <- outer (X= xx, Y=yy,
         FUN = function(x, y) {
             wrapper(x=x, y=y,
                   FUN=function(u, v) {
                     exp(gmllk(x = c(u, v), Mu = Mu,
                     Sigma = Sigma, p = p)
                   })
         })
dpredmh <- outer(X= xx, Y=yy,
         FUN = function(x, y) {
            wrapper(x = x, y = y,
                   FUN =function(u, v) {
                 ## complete the code })
         })
breaks <- c(seq(0.01,0.09, length.out=5), seq(0.1,0.3,length.out=5))
nbreaks <- length(breaks)</pre>
contour(xx,yy, z = dtrue, nlevels=nbreaks, levels = breaks)
contour(xx,yy, z = dpredmh, nlevels=nbreaks, levels = breaks,
        add=TRUE, col='red')
```

Comment your results.

5 Predictive distributions versus maximum likelihood distribution

In this section we focus on the probability of an excess of a threshold $u \in \mathbb{R}$:

$$\varphi(u, \rho, \mu_{1:k}, \Sigma_{1:k}) = 1 - F(u|\rho, \mu_{1:k}, \Sigma_{1:k}) = \mathbb{P}(X_1 > u \text{ or } \dots \text{ or } X_d > u|\rho, \mu_{1:k}, \Sigma_{1:k}).$$

where $F(y|\rho, \mu_{1:k}, \Sigma_{1:k})$ is the cdf for the Gaussian Mixture. The latter is already coded as function gmodf in file GM_functions.R. Our goal is to compare the performance of the estimators obtained by EM (maximum likelihood), Variational Bayes and Metropolis-Hastings, namely

$$\widehat{\varphi}_{1}(u) = \varphi(u, \widehat{\rho}, \widehat{\mu}_{1:k}, \widehat{\Sigma}_{1:k}),$$

$$\widehat{\varphi}_{2}(u) = \mathbb{E}\left[\varphi(u, \rho, \mu_{1:k}, \Sigma_{1:k})\right] \text{ with } (\rho, \mu_{1:k}, \Sigma_{1:k}) \sim Q^{*}$$

$$\widehat{\varphi}_{3}(u) = \frac{1}{M} \sum_{t=1}^{M} \varphi(u, \rho^{t}, \mu_{1:k}^{t}, \Sigma_{1:k}^{t})$$

where $\widehat{\rho}$, $\widehat{\mu}_{1:k}$, $\widehat{\Sigma}_{1:k}$ are the maximum likelihood estimates issued by the EM algorithm, Q^* is the posterior variational distribution and where M is the number of remaining samples after discarding the burn-in period and thinning.

The estimators $\widehat{\varphi}_2$, $\widehat{\varphi}_3$ are numerical approximations of $1 - F_{pred}(u)$ where F_{pred} is the predictive cdf,

$$F_{pred}(x) = \int F(y|\rho, \mu_{1:k}, \Sigma_{1:k}) \pi(\rho, \mu_{1:k}, \Sigma_{1:k}|x_{1:n}) \, d\rho \, d\mu_{1:k} \, d\Sigma_{1:k}$$

To summarize:

- The true φ is easily computed via function gmcdf
- $\widehat{\varphi}_1$ is computed in a similar way using the the output of EM as argument of gmcdf
- It can be shown (See Bishop (2006), Section 10.2.3) that the variational predictive distribution is a mixture of multivariate Student distributions with parameters that are functions of the optimized parameters $(\alpha^*, m_j^*, \beta_j^*, W_j^*, \nu_j^*), j \in \{1, \dots, k\}$ of the variational posterior distribution. The cdf of this mixture is implemented in function <code>vbPredictiveCdf</code> from file <code>GM_functions.R.</code> This function is the main ingredient for computing $\widehat{\varphi}_2$.
- $\widehat{\varphi}_3$ can be computed similarly to the posterior predictive density (Section 4.7) via the function MHpredictiveCdf (to be completed)
- 1. Complete the code of function MHpredictiveCdf
- 2. We consider a range of thresholds on the diagonal line, u = (x, x), for $x \in [-3, 3]$. Complete the following code chunk in order to plot on the same graph, as a function of x,

$$\varphi((x,x)|\rho,\mu_{1:k},\Sigma_{1:k}), \quad \widehat{\varphi}_1(x,x), \quad \widehat{\varphi}_2(x,x), \quad \widehat{\varphi}_3(x,x).$$

Comment your results.

```
Pexcess \leftarrow rep(0,10)
Pexcess_em <- Pexcess; Pexcess_vb <- Pexcess; Pexcess_mh <- Pexcess
thres_vect <- seq(-3, 3, length.out=30)
for(i in seq_along(thres_vect)){
threshold <- rep(thres_vect[i], 2)</pre>
Pexcess[i] <- 1 - gmcdf(x = threshold, Mu = Mu, Sigma=Sigma, p=p)
Pexcess_em[i] <- ## complete the code:</pre>
             ##maximum likelihood estimator using EM output
Pexcess vb[i] <- ## complete the code:
   ## posterior predictive estimator using VB output:
   ## use vbPredictiveCdf
Pexcess_mh[i] <- ## complete the code:</pre>
   ## posterior predictive estimator using MH output:
   ## use MHpredictiveCdf.
ylim <- range(Pexcess, Pexcess_em, Pexcess_vb)</pre>
plot(thres_vect, Pexcess, ylim = ylim)
lines(thres_vect, Pexcess_vb, col='red')
lines(thres_vect, Pexcess_em, col='blue')
lines (thres vect, Pexcess mh, col='green')
```

3. Consider now the tails of the mixture distribution: replace the third line in the above code chunk with

```
thres_vect <- seq(1, 5, length.out=30)
```

Comment your results, in particular explain the behavior of the Variational Bayes estimator.

4. We now focus on $\widehat{\varphi}_3$. Plot on the same graph $\varphi((x,x)|\rho,\mu_{1:k},\Sigma_{1:k})$ and $\widehat{\varphi}_1((x,x))$ together with posterior 90% credible sets obtained with the empirical quantiles of the time series $\varphi((x,x)|\rho^t,\mu_{1:k}^t,\Sigma_{1:k}^t)$, $t\in 1,\ldots,M$ where $(\rho^t,\mu_{1:k}^t,\Sigma_{1:k}^t),t\leq M$ is the output of the MH algorithm after thinning and discarding an appropriate burn-in period. Comment the results.

References

Bishop, C. M. (2006). Pattern recognition and machine learning. springer. 3, 4, 8