



Looking for the Maximum Independent Set: A New Perspective on the Stable Path Problem

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Yale University



同濟大學
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What is the Stable Path Problem?

Powerful tool for BGP convergence analysis [1]

[1] Griffin, Timothy, et al. "The Stable Paths Problem and Interdomain Routing." *IEEE/ACM Transactions On Networking* 10, no. 2 (2002): 232-243.

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- An undirected graph $G=(V, E)$
 - $n+1$ nodes, node 0 represents the destination; a link represents neighborship
- Each node i
 - runs SPVP, an abstract version of BGP
 - has a set of permitted paths
 - has a ranking function to rank permitted paths

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 - belongs to its permitted paths, and
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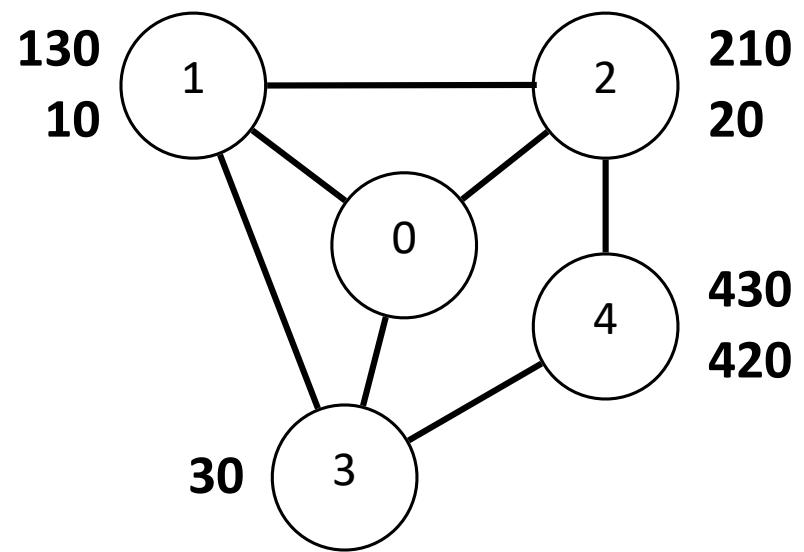
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- **Stable path assignment:** each node's selected path
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- **Stable path problem (SPP):** does a stable path assignment exists?

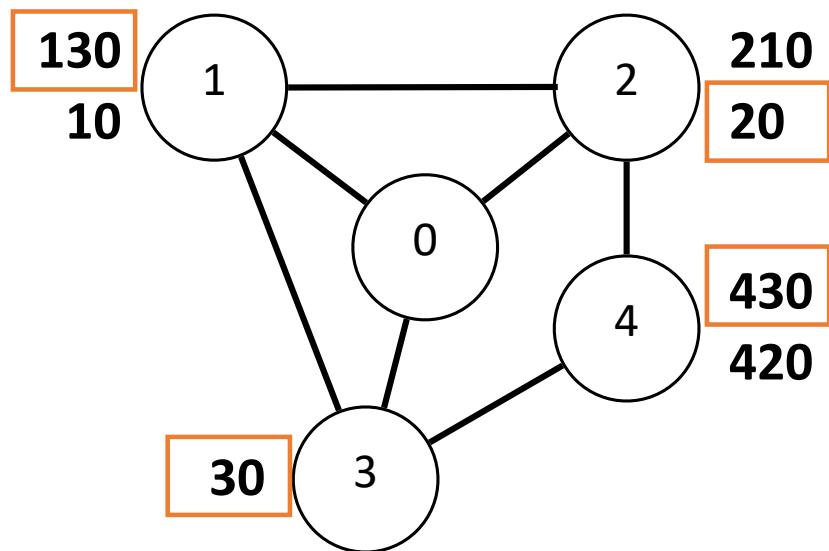
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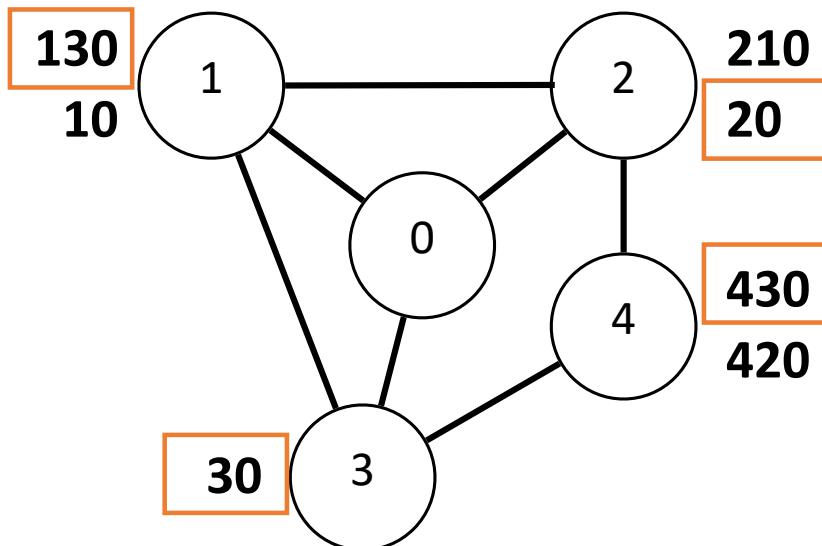
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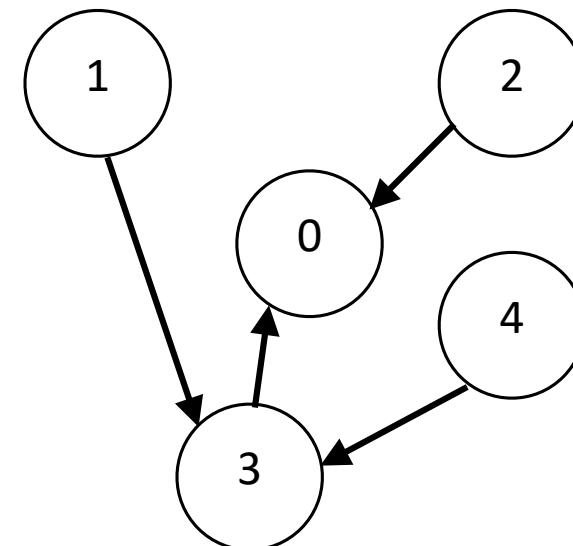
Good gadget

Example: Good Gadget

- A stable path assignment defines a tree rooted at node 0



Good gadget



Stable path assignment of
good gadget

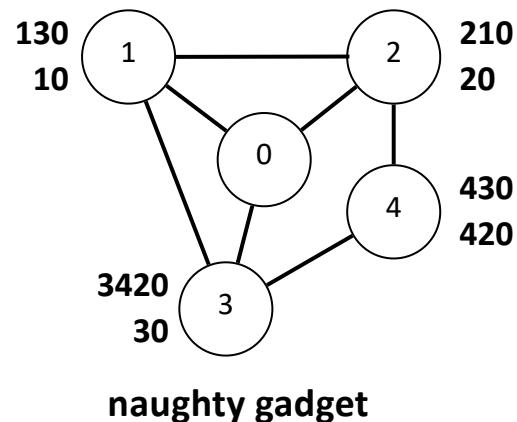
Categories on SPP Instances

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- **Safe:** SPVP always converges, e.g., good gadget

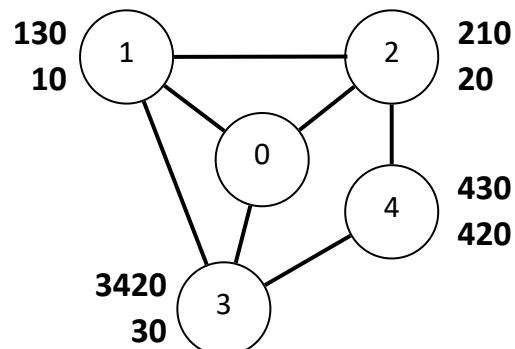
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- **Safe:** SPVP always converges, e.g., good gadget
- **Unique:** has one and only one stable path assignment, e.g., good gadget and naughty gadget

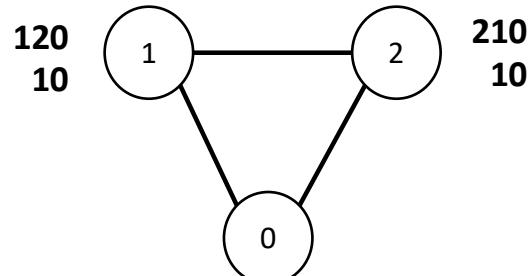


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- **Safe:** SPVP always converges, e.g., good gadget
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- **Solvable:** has at least one stable path assignment, e.g., disagree



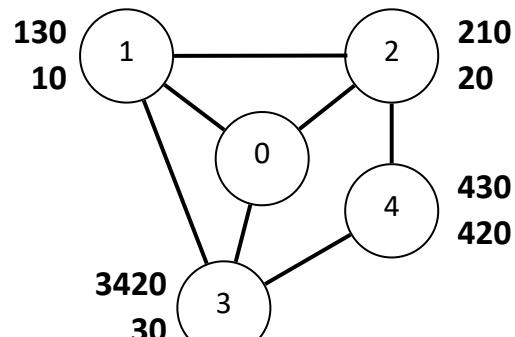
naughty gadget



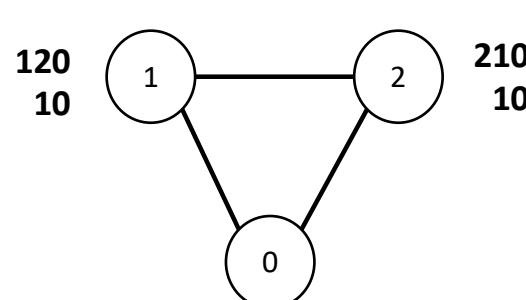
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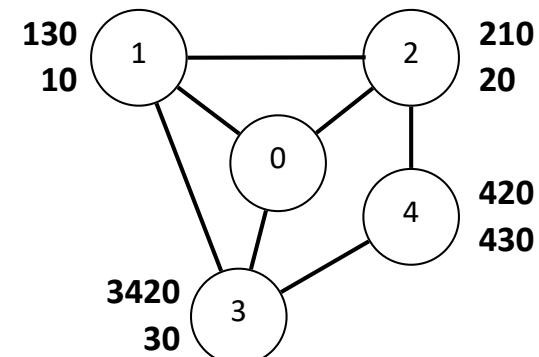
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- **Unique:** has one and only one stable path assignment, e.g., good gadget and naughty gadget
- **Solvable:** has at least one stable path assignment, e.g., disagree
- **Unsolvable:** has no stable path assignment, e.g., bad gadget



naughty gadget



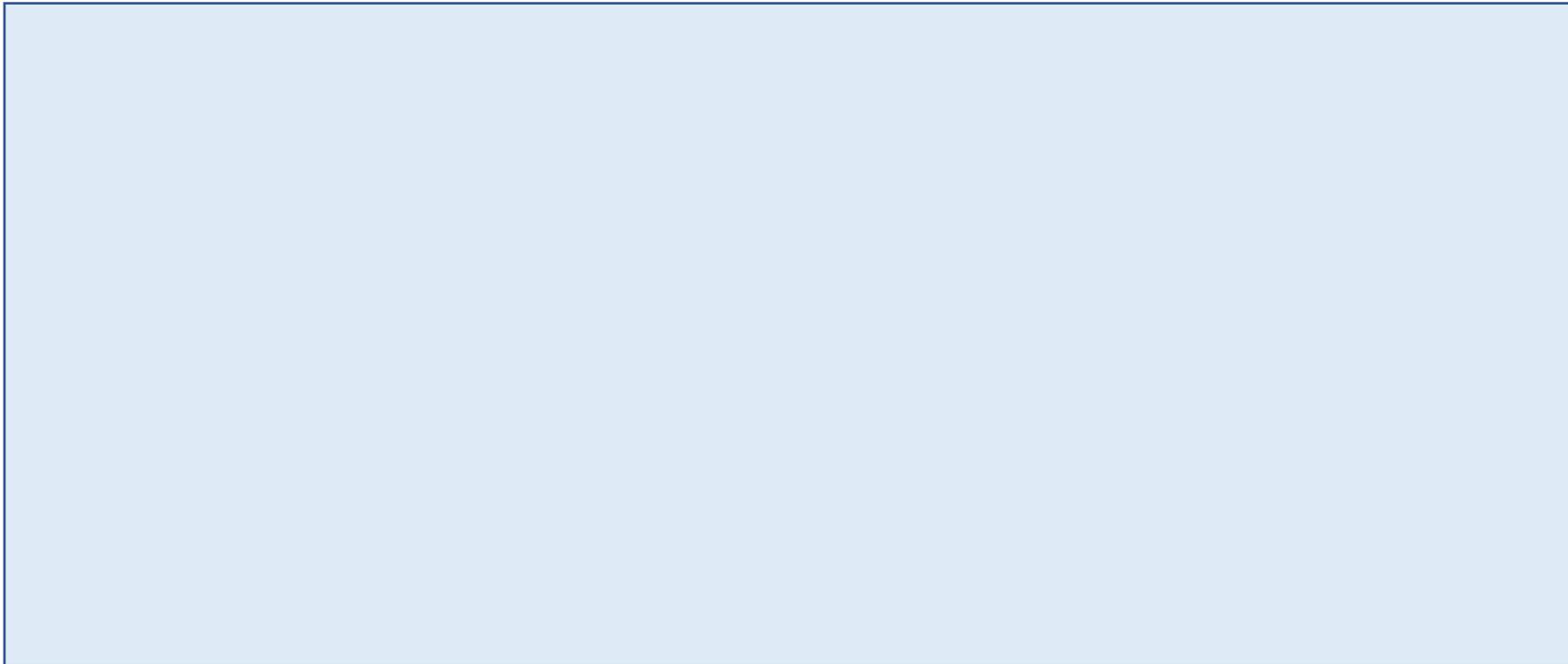
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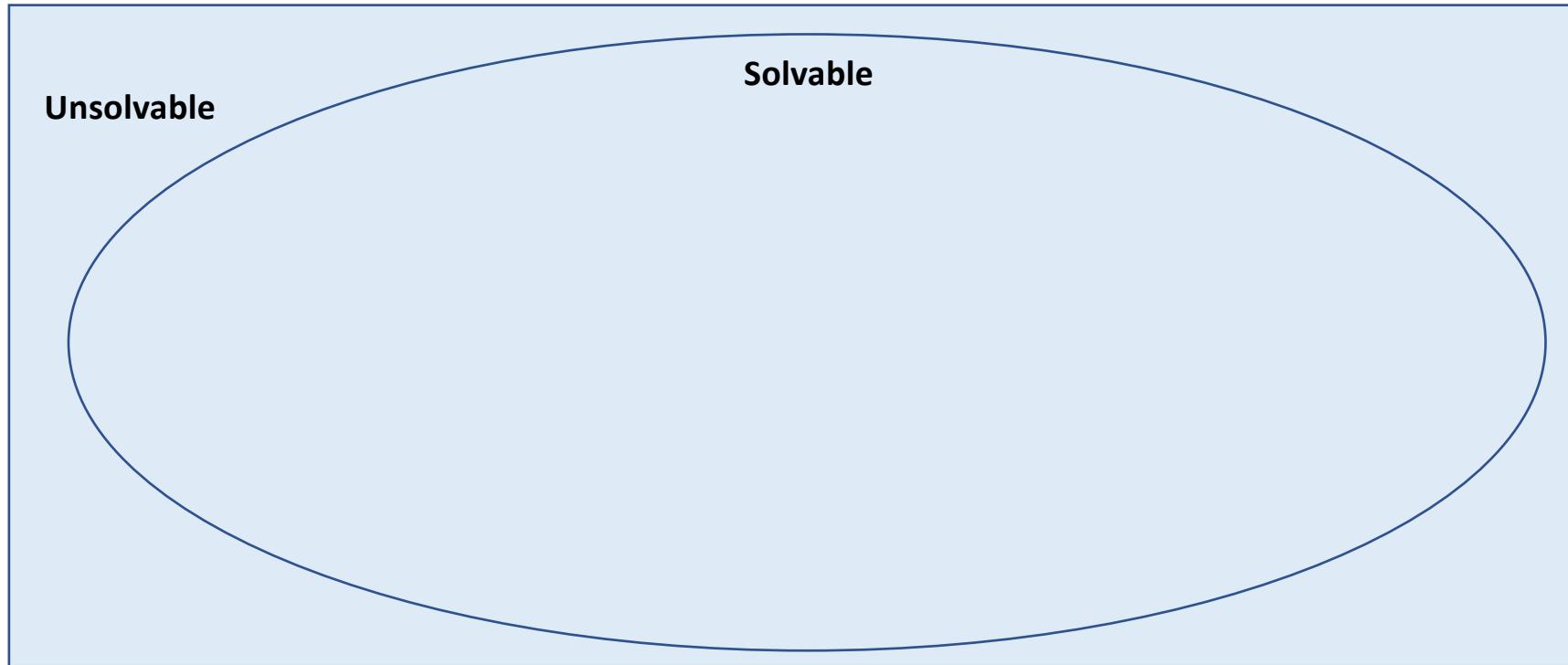
bad gadget

Related Work on SPP

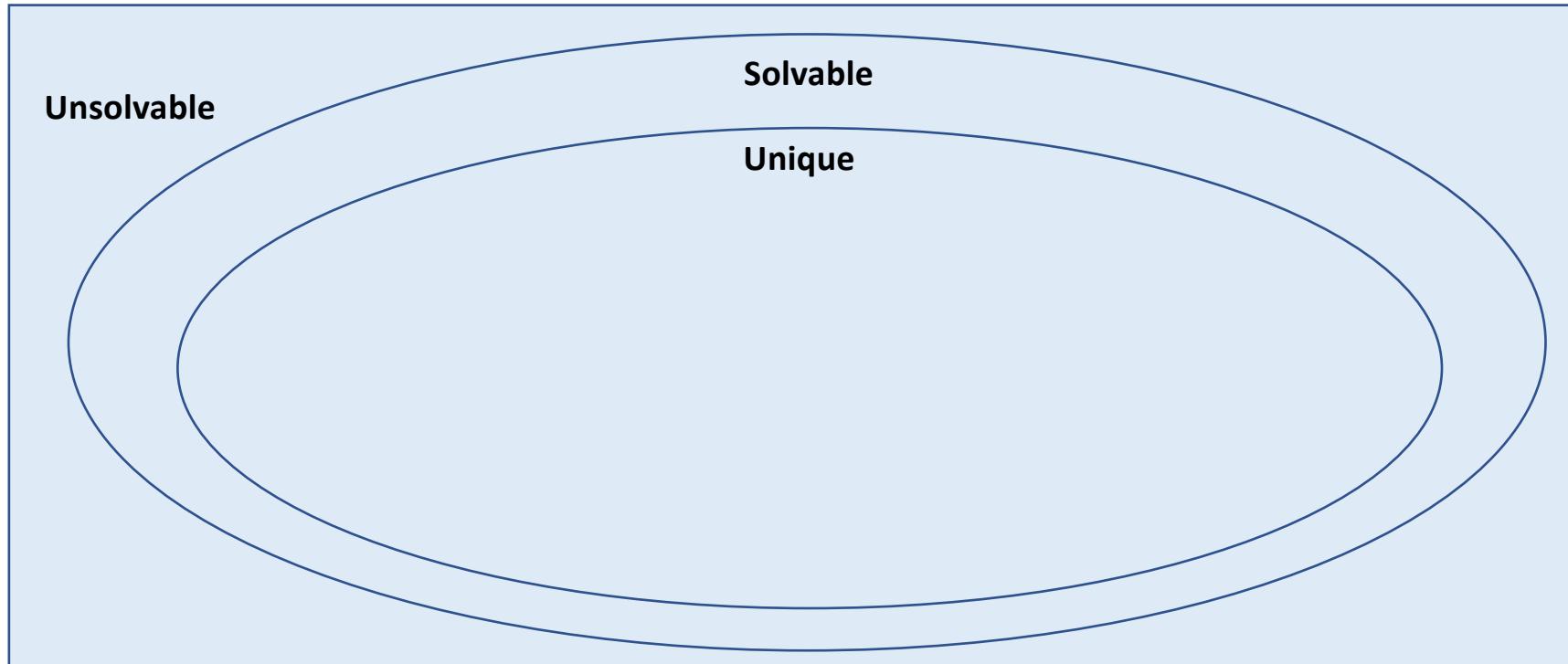
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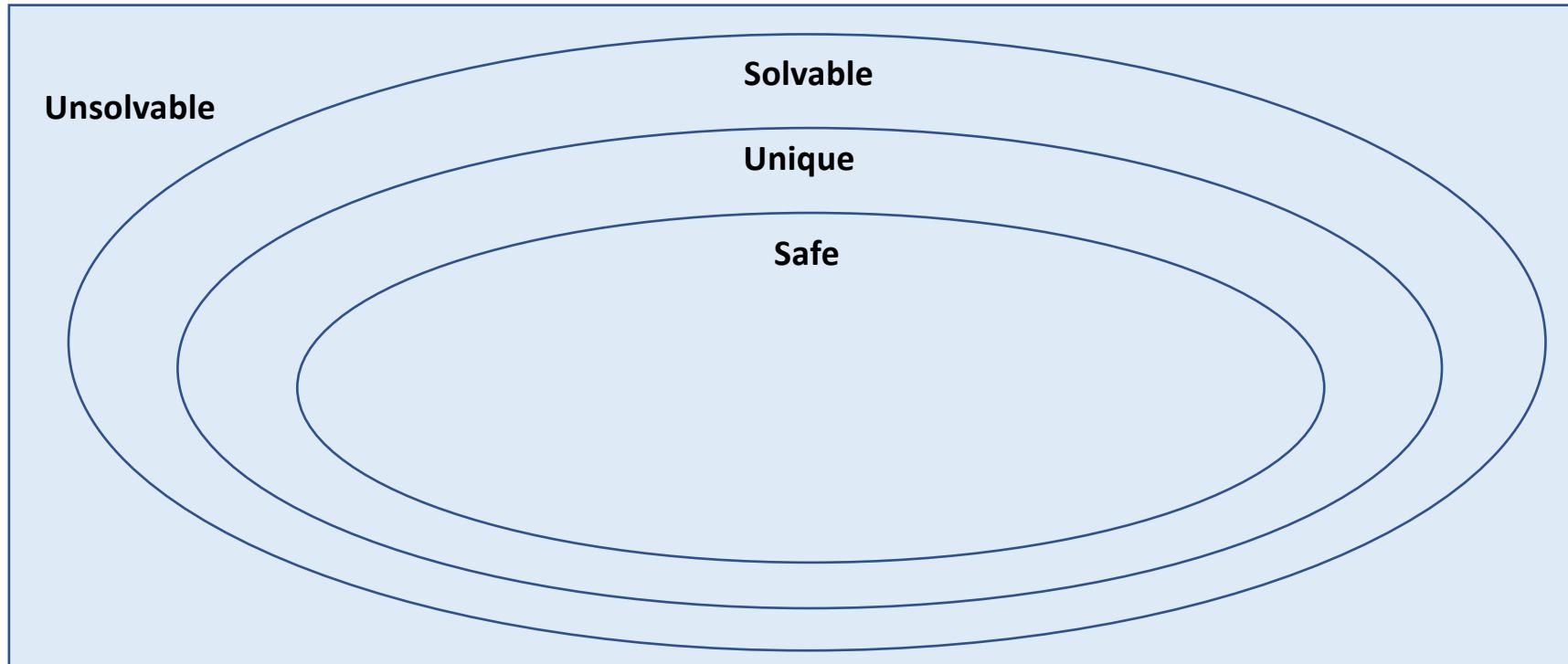
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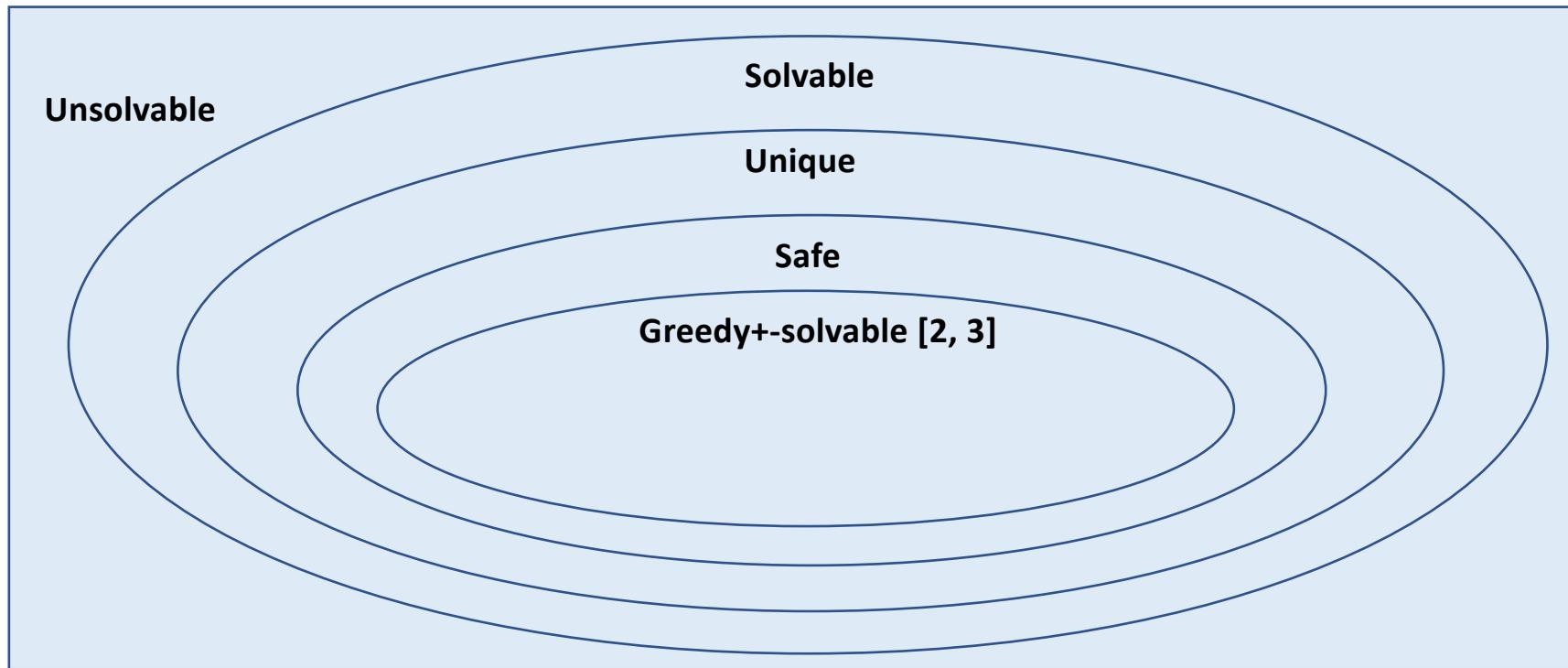
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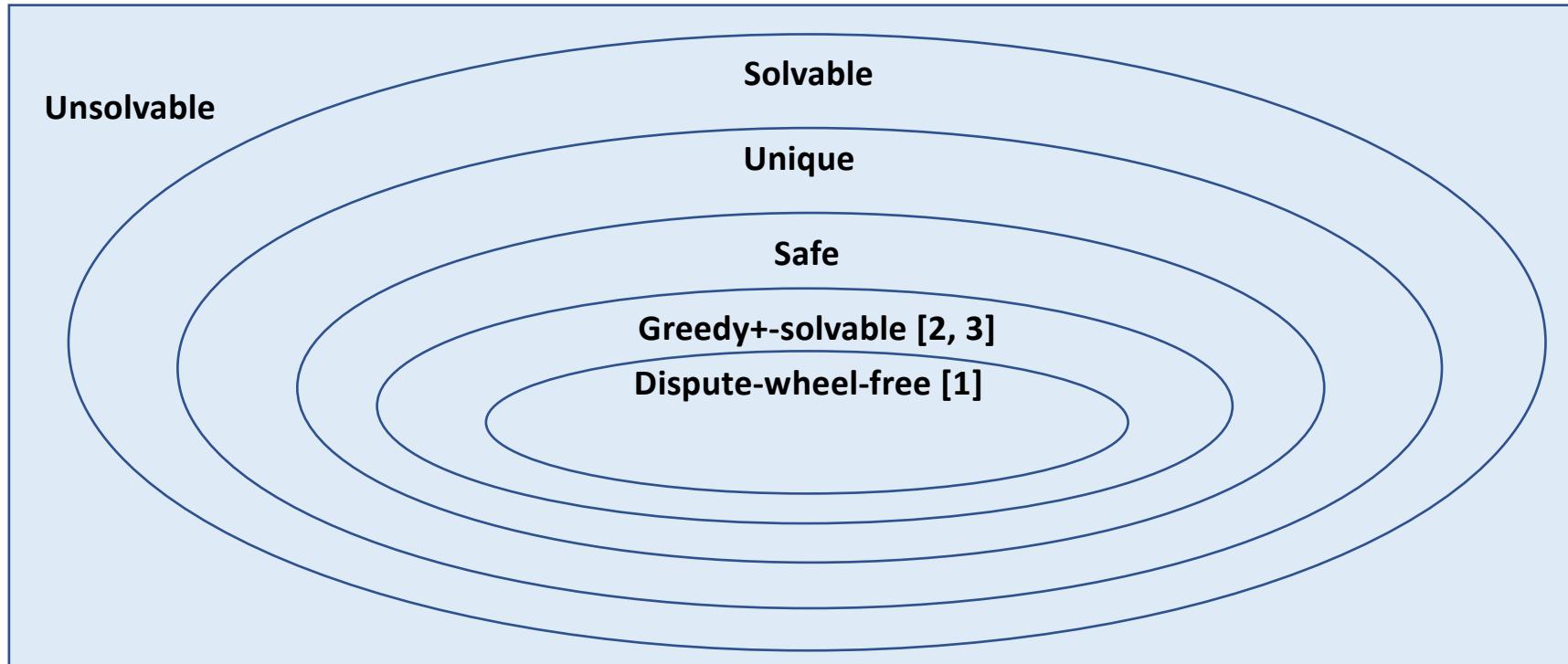
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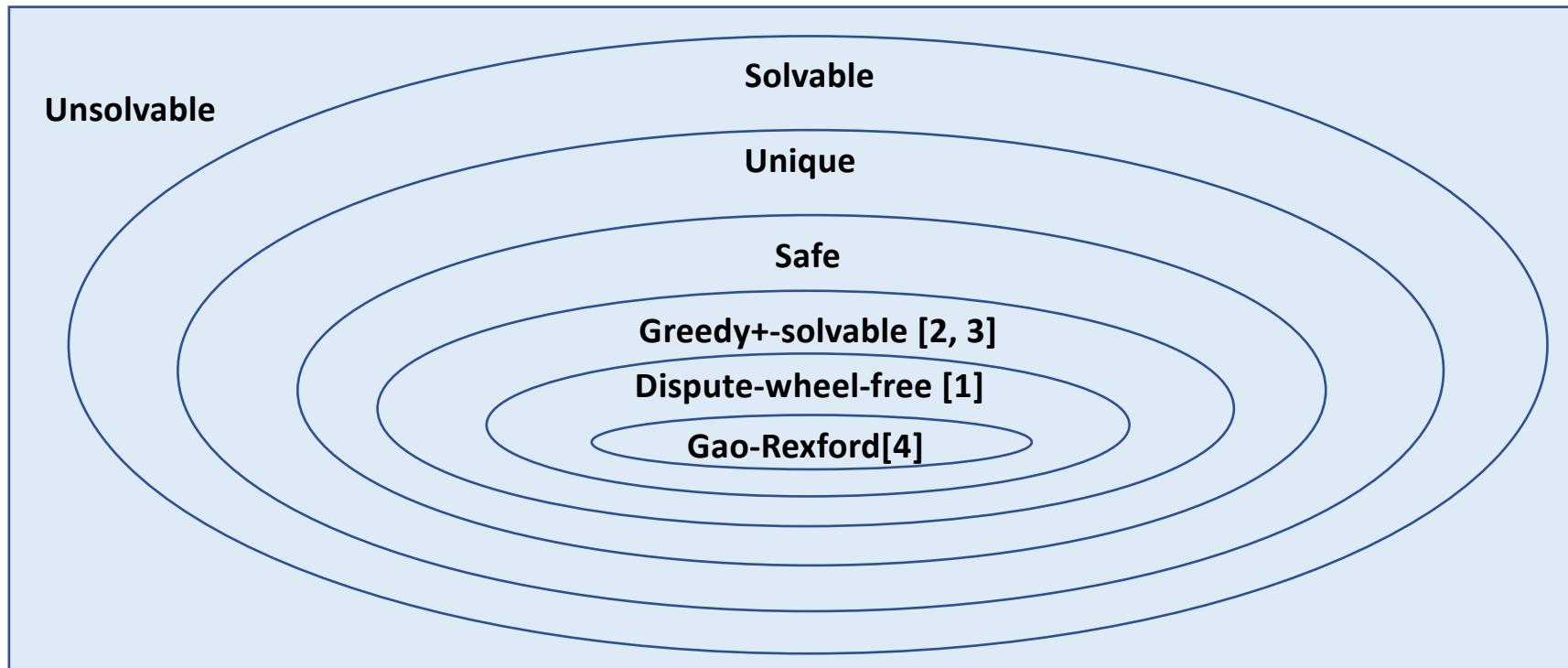
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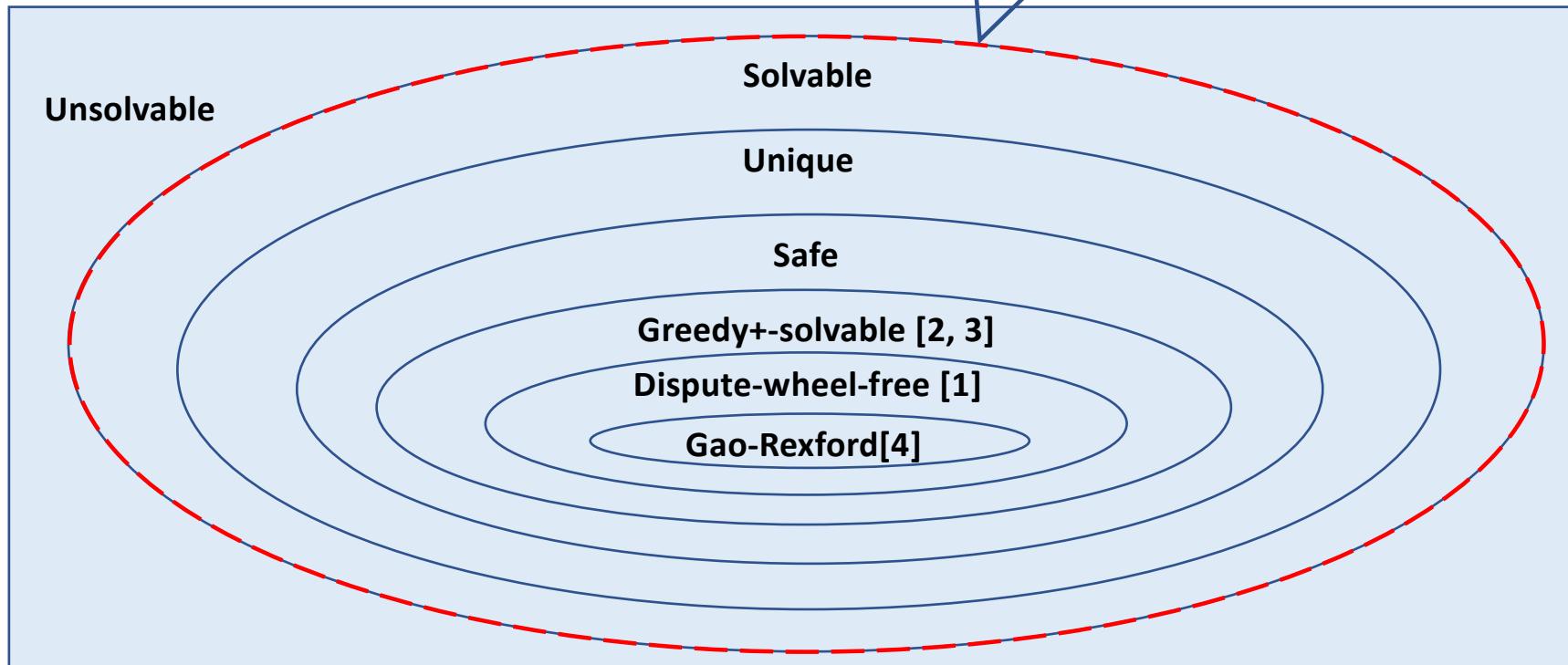
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- [2] Cittadini, Luca, et al. "On the Stability of Interdomain Routing." *ACM Computing Surveys* 44, no. 4 (2012): 1-40.
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- [4] Gao, Lixin et al. "Stable Internet routing without global coordination." *IEEE/ACM Transactions on networking* 9, no. 6 (2001): 681-692.

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Focus of this paper



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Why Focus on SPP Solvability?

- Enable new interdomain routing use cases with more flexible policies
 - E.g., collaborative interdomain routing [4], software-defined-interdomain routing [5]
- Better understand the gap between solvable SPP and safe SPP
- Help improve the efficiency of network configuration verification

[4] Pouryousef, Shahrooz, et al. "Towards Logically Centralized Interdomain Routing." In *17th USENIX Symposium on Networked Systems Design and Implementation (NSDI'20)*, pp. 739-757. 2020.

[5] Xiang, Qiao, et al. "Toward Optimal Software-Defined Interdomain Routing." In *IEEE INFOCOM 2020-IEEE Conference on Computer Communications*, pp. 1529-1538. IEEE, 2020.

Outline

- Background on SPP
- Our Contribution

Contribution: New SPP Solvability Results and Interdomain Use Cases

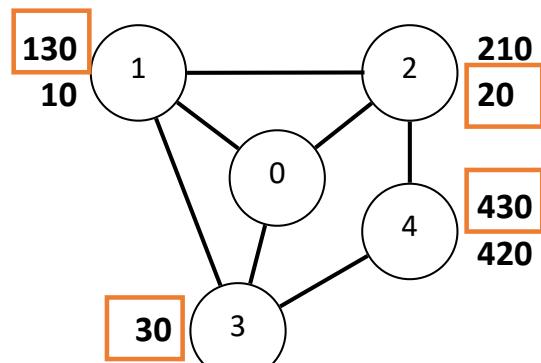
1. **Theorem:** A novel solvability digraph for reasoning SPP solvability
2. **Algorithm:** A polynomial-time heuristic solves more SPP than state-of-the-art
3. **Use case:** collaborative interdomain routing
4. **Use case:** privacy-preserving collaborative interdomain routing

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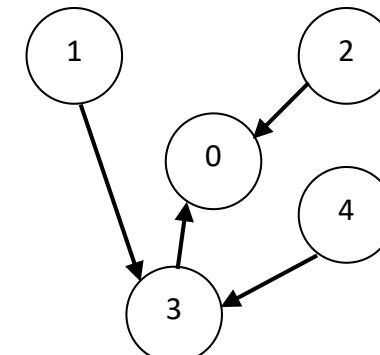
- Background on SPP
- Our Contribution
- Solvability Digraph

Properties of Stable Path Assignment

In a stable path assignment:



Good gadget

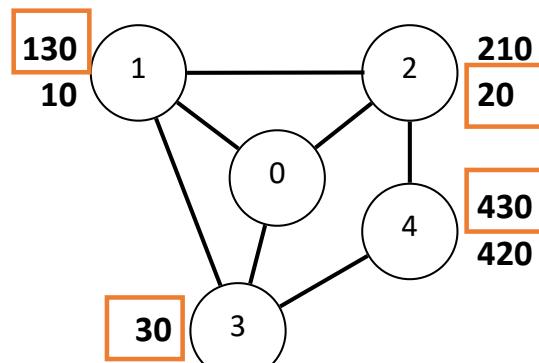


Stable path assignment for
good gadget

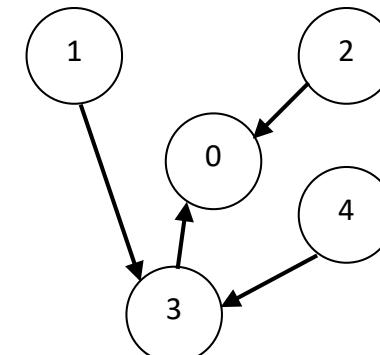
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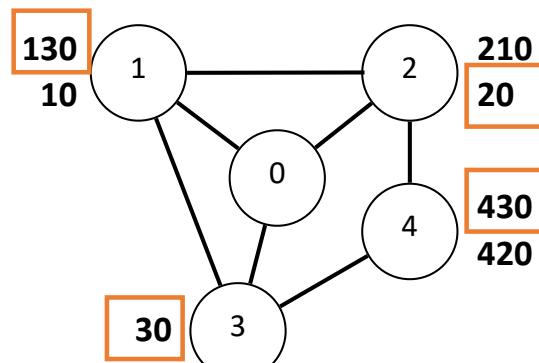


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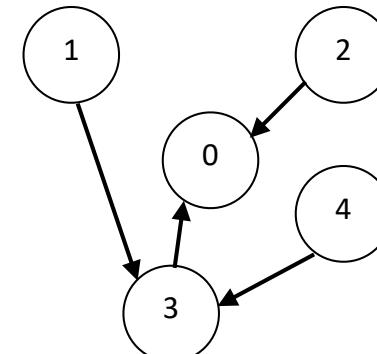
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In a stable path assignment:

1. each node only has one path
2. each path's suffix must also be in the assignment



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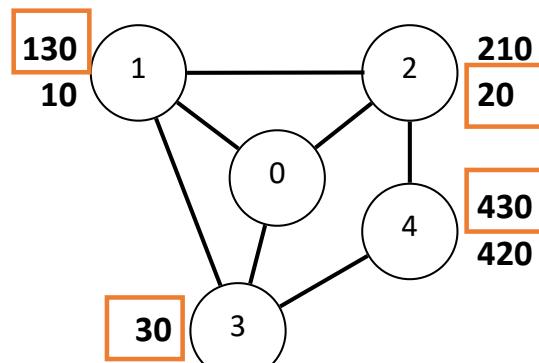


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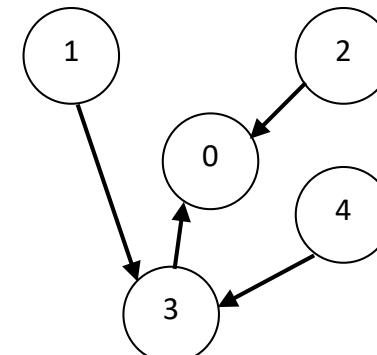
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3. the stable path of each node is its most preferred one among the concatenation of the stable paths of all its neighbors



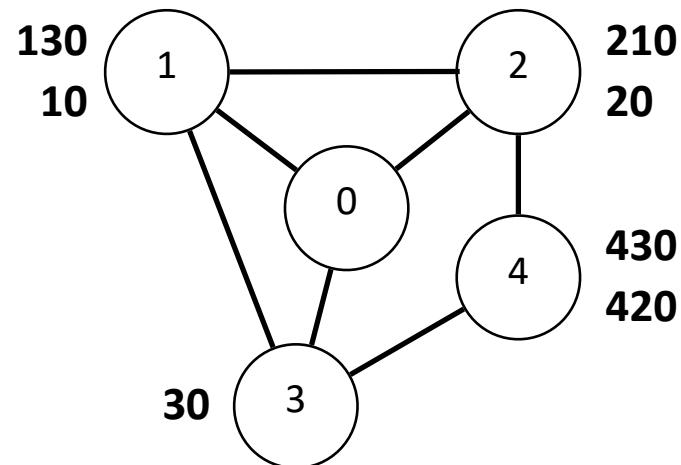
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Solvability Digraph

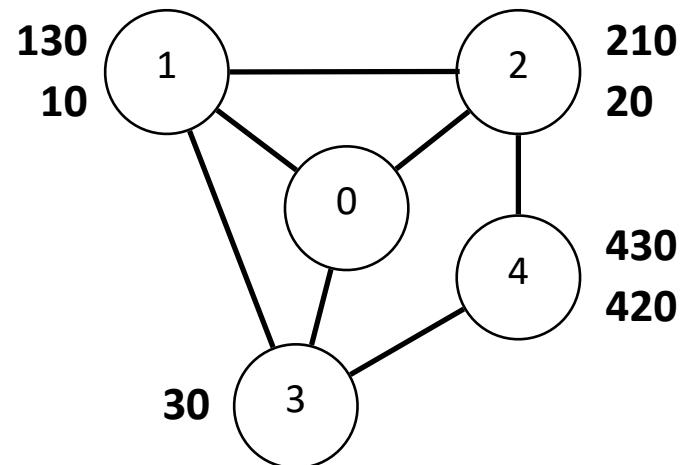
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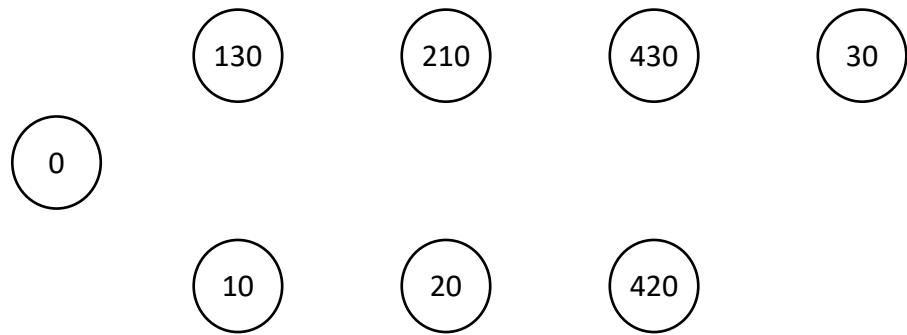
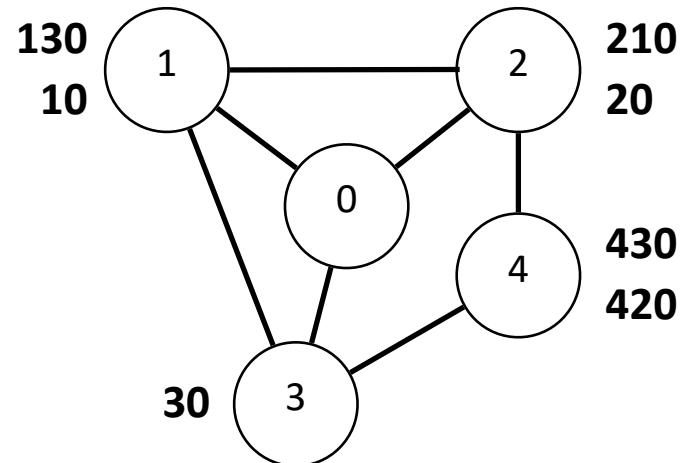
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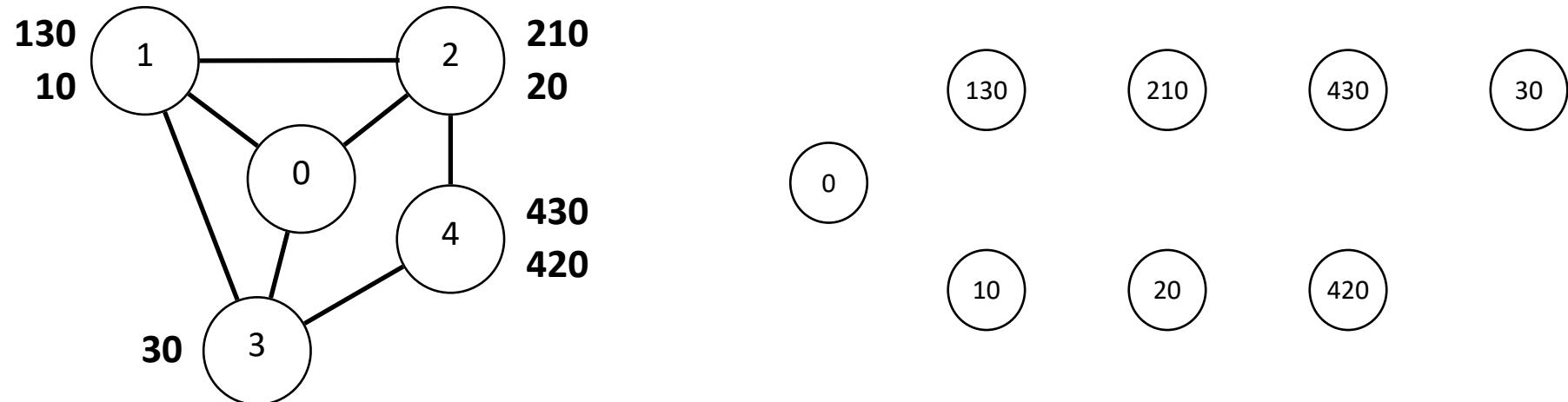
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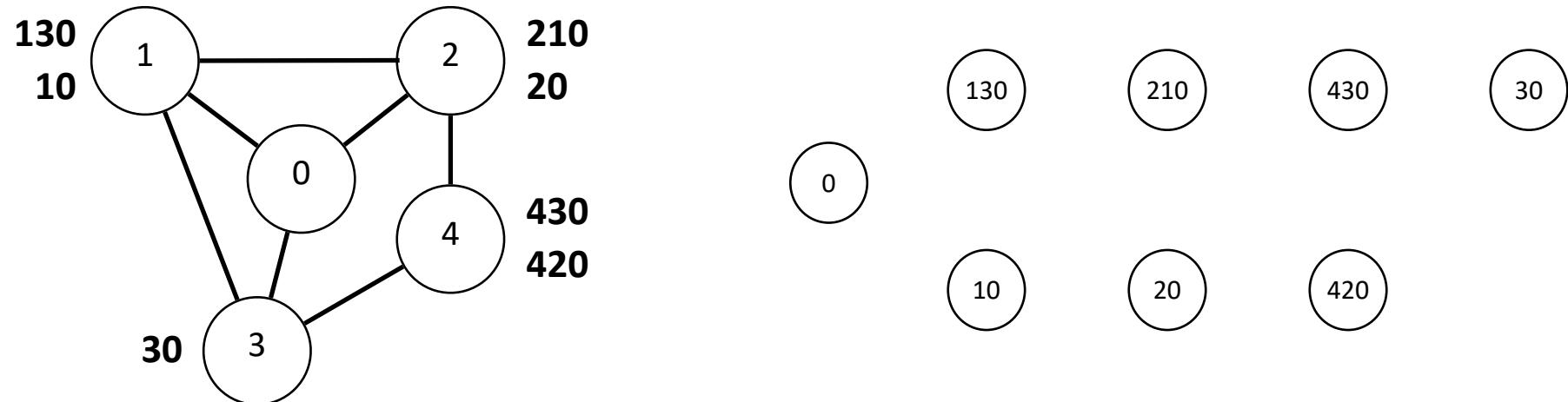


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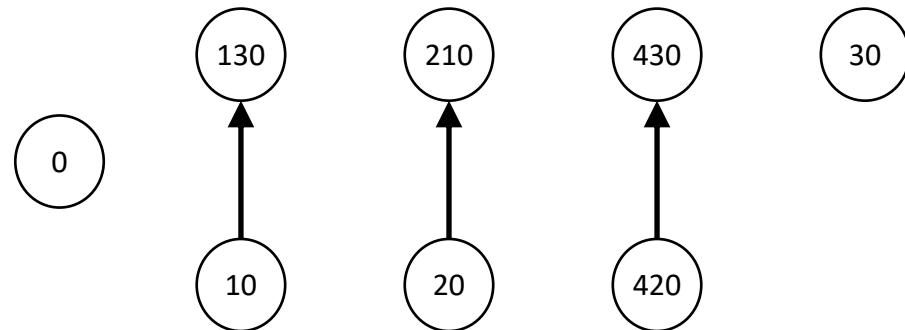
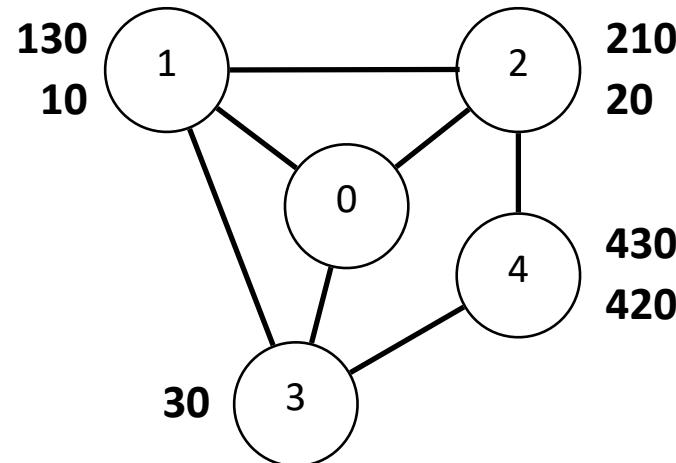


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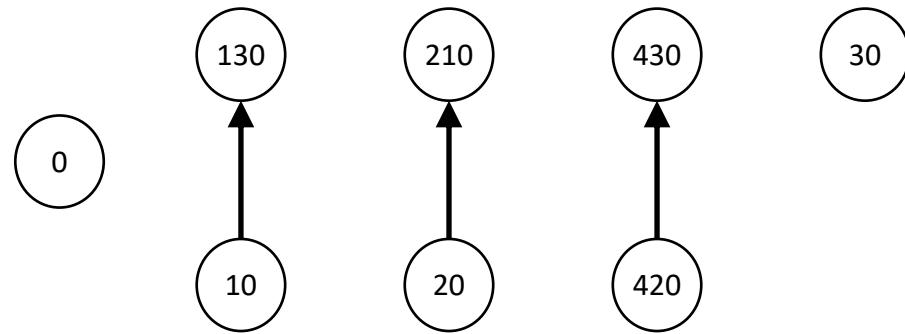
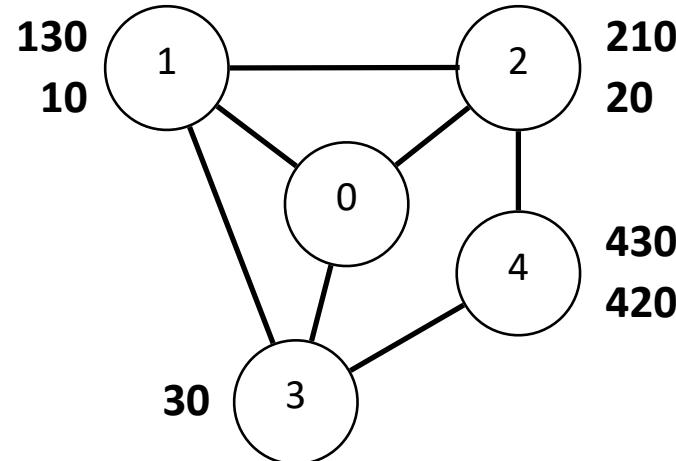


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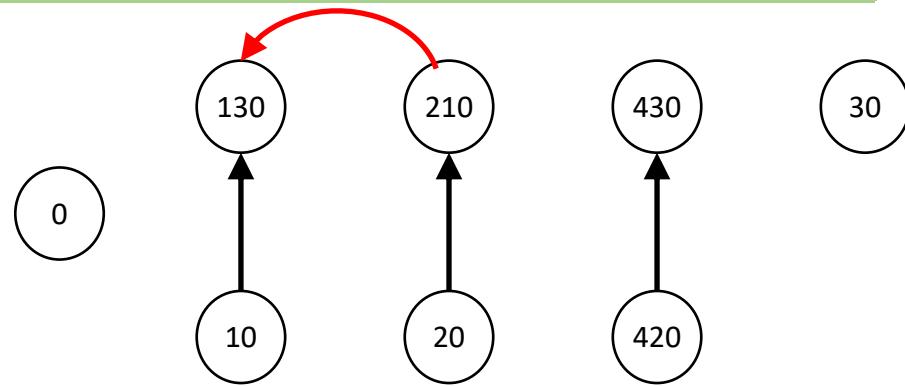
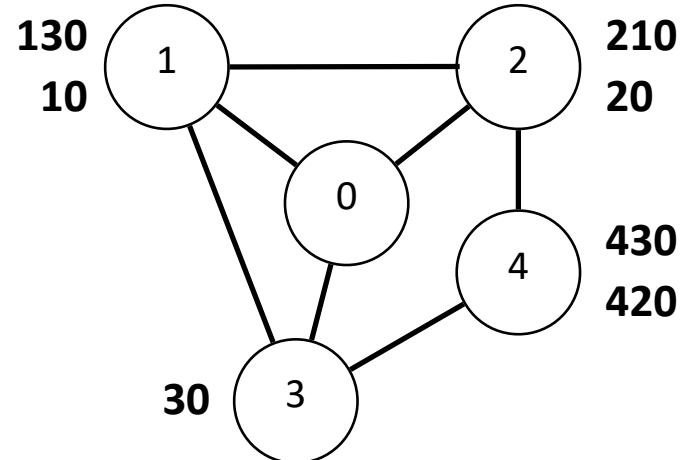


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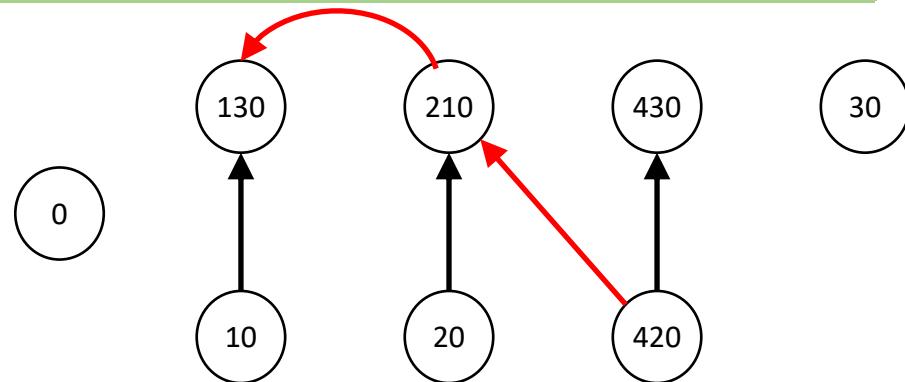
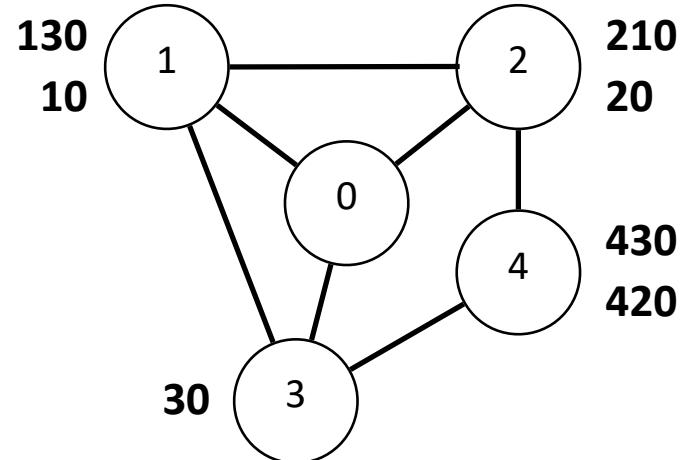


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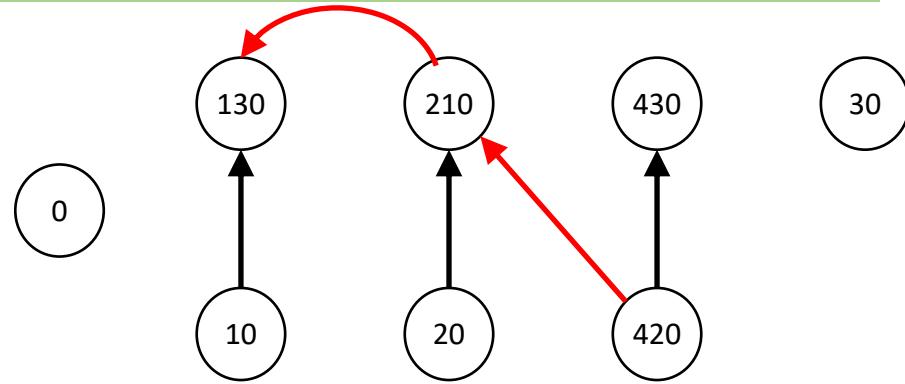
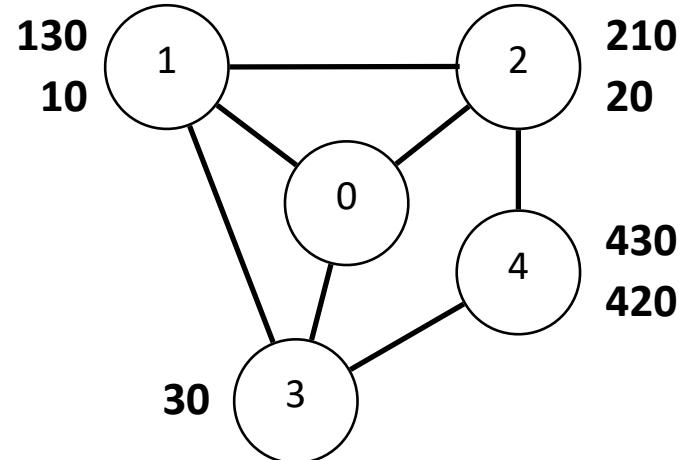


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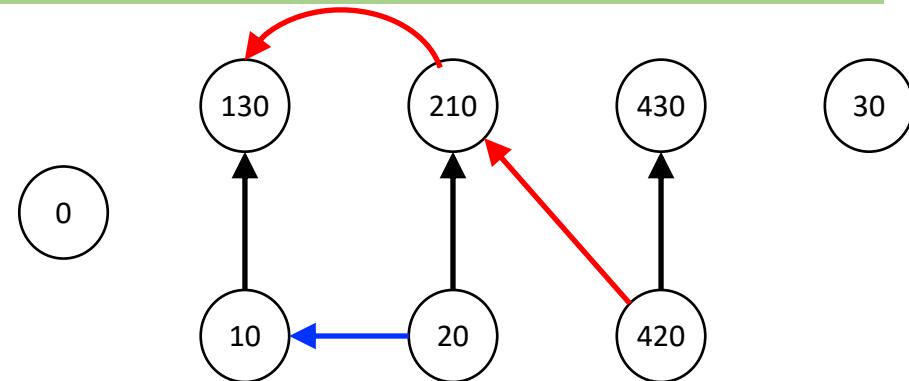
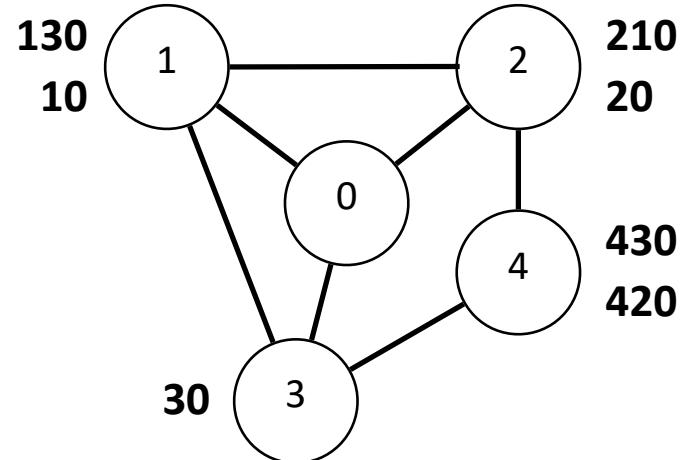


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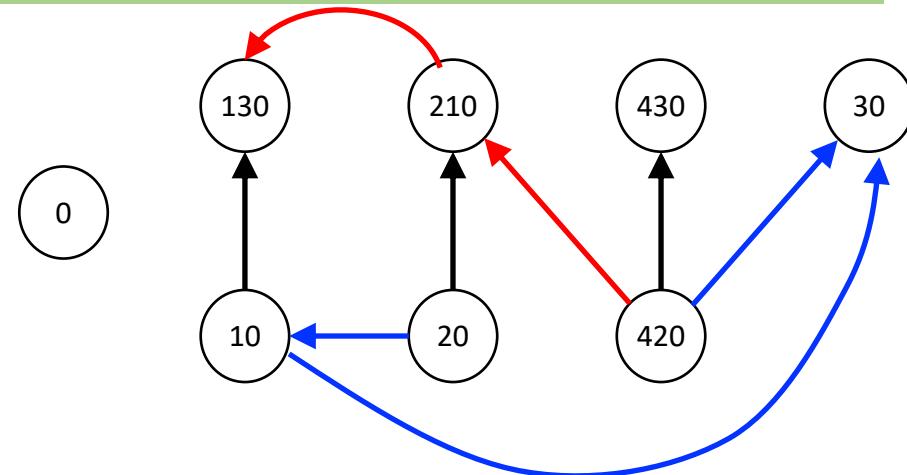
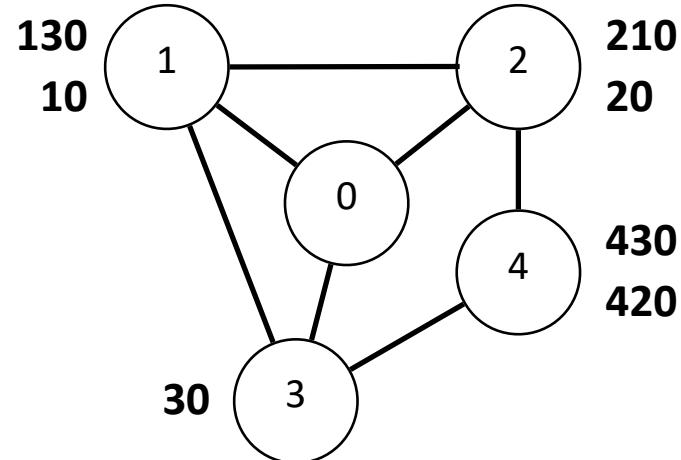


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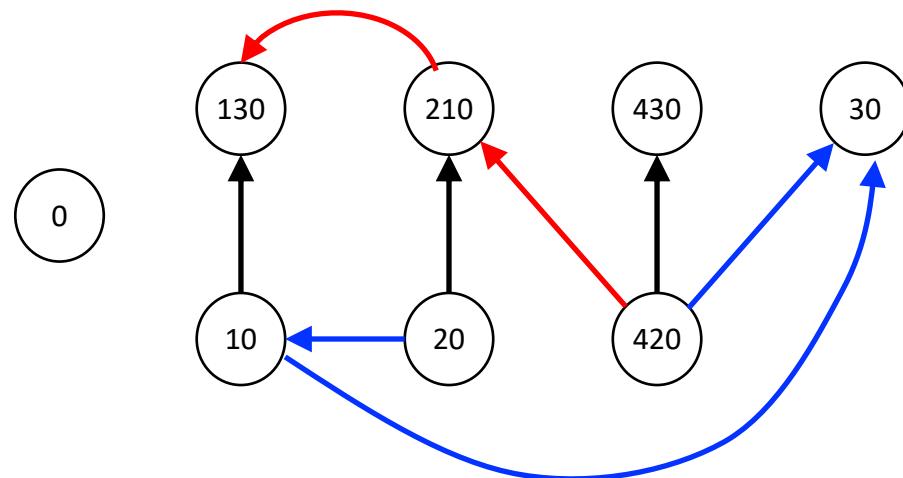
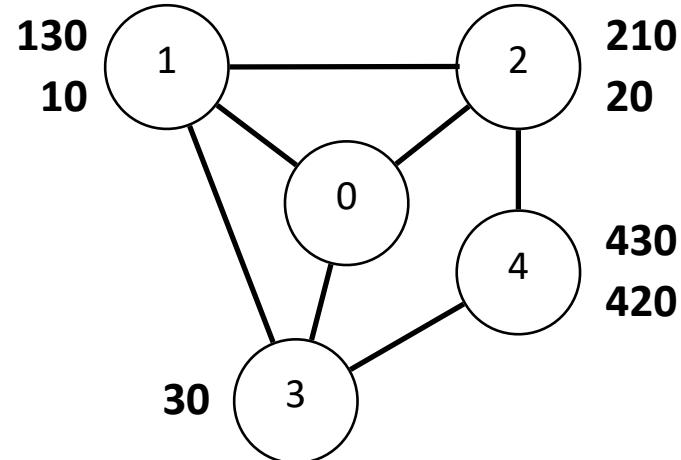
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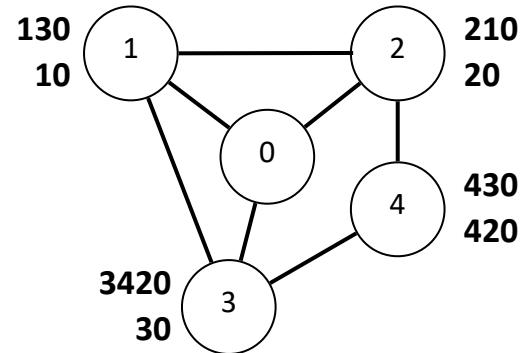
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Solvability Graph - More Examples

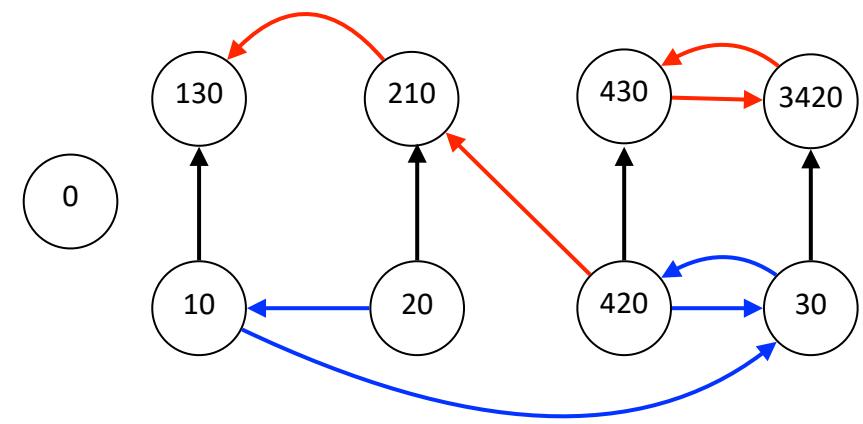
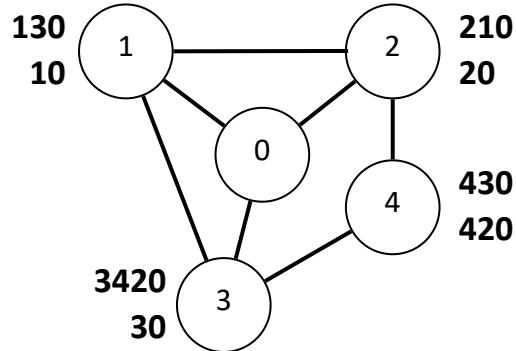
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Naughty Gadget



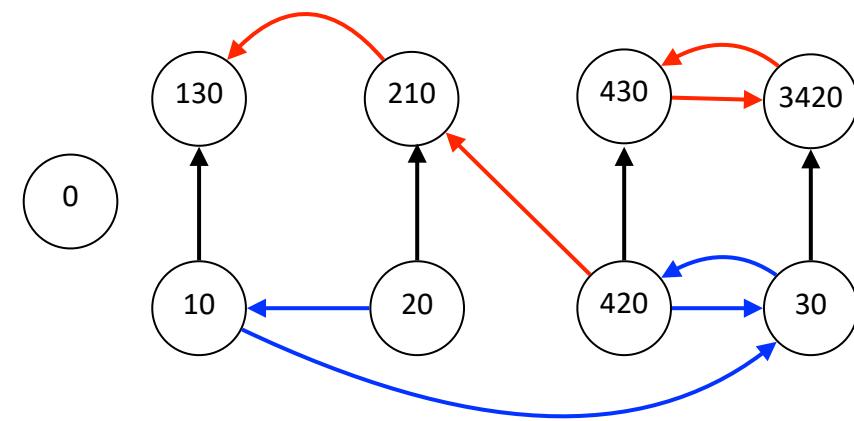
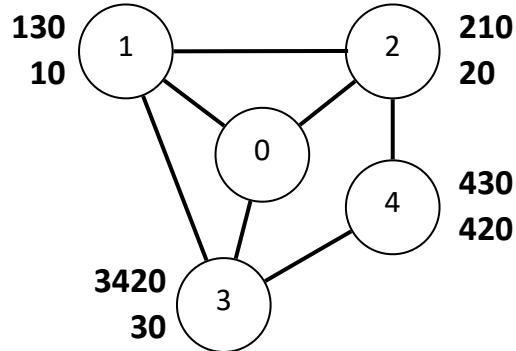
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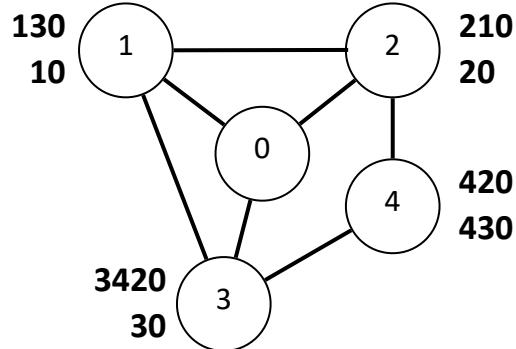


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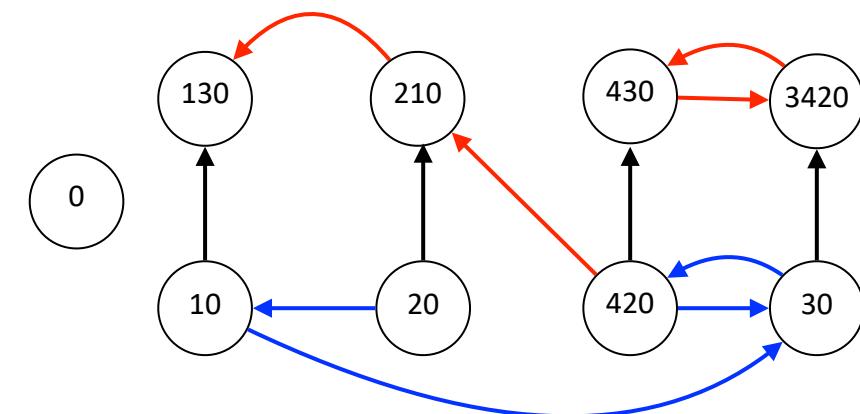
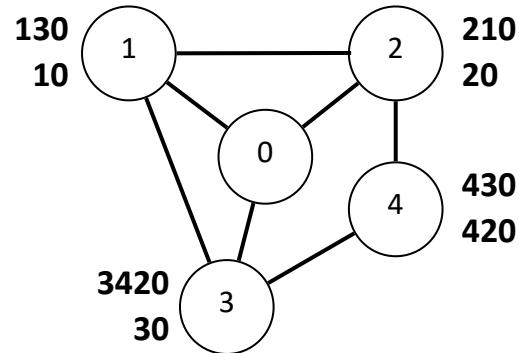


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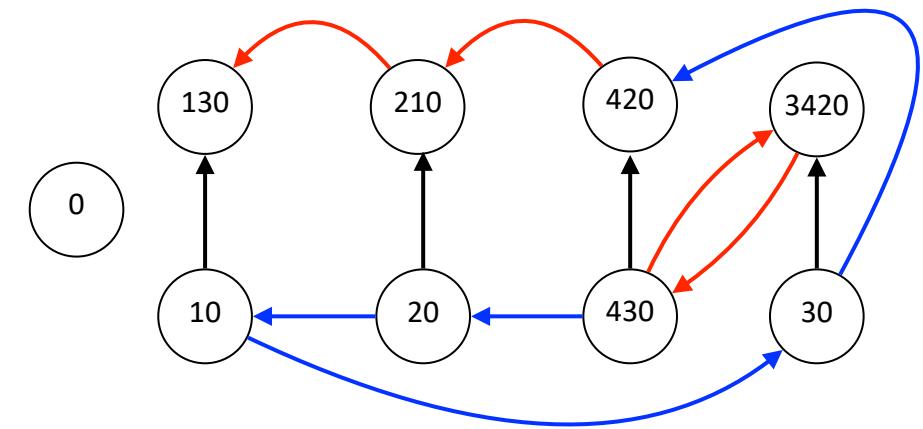
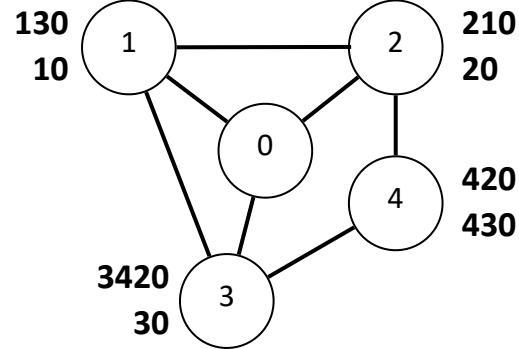


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Naughty Gadget



Bad Gadget

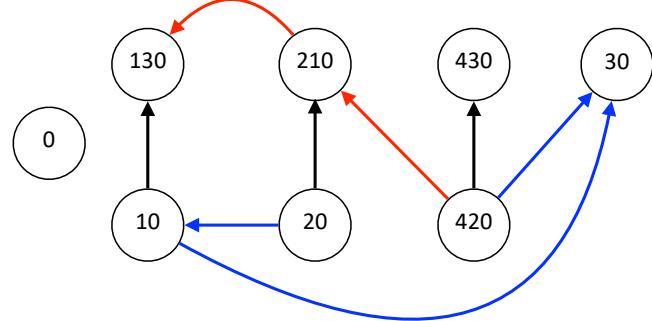


Solvability Graph and SPP Solvability

Theorem 1: Given an SPP instance with $n+1$ nodes, it is solvable if and only if the corresponding solvability digraph has a maximum independent set of size $n+1$. (proof in the paper)

Solvability Graph and SPP Solvability

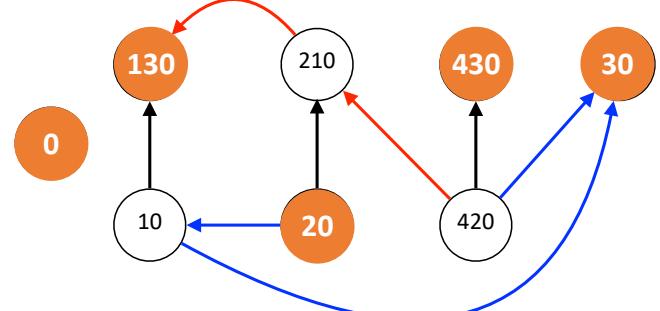
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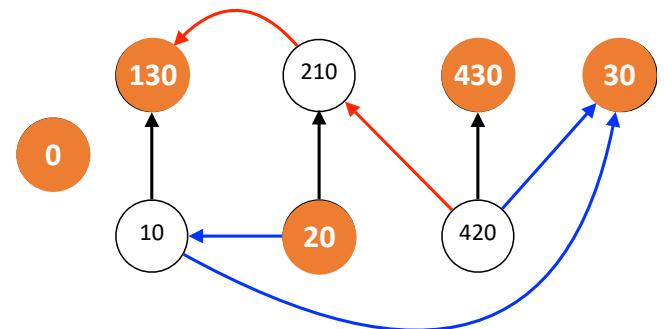
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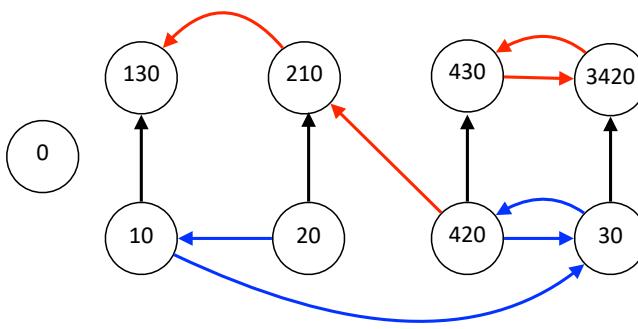
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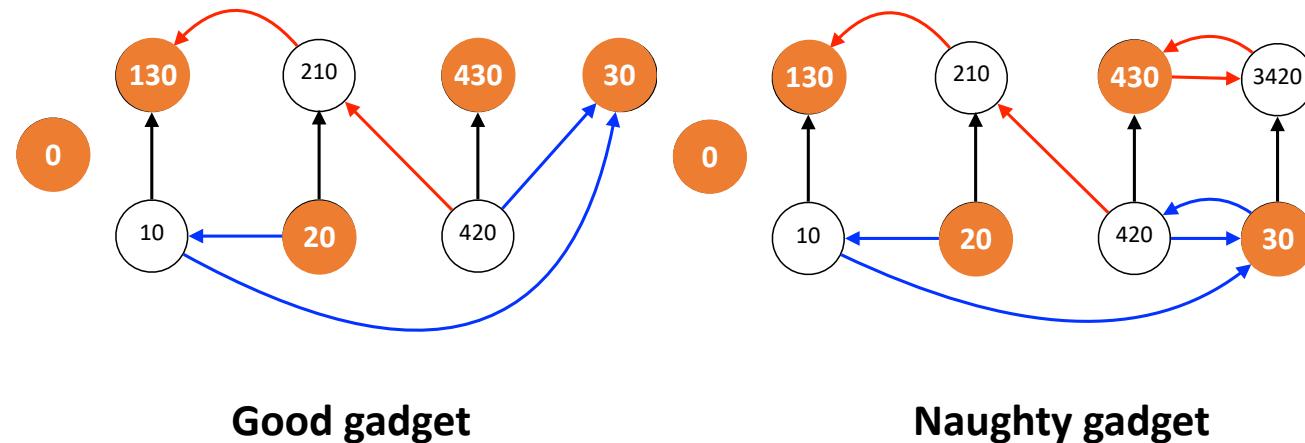
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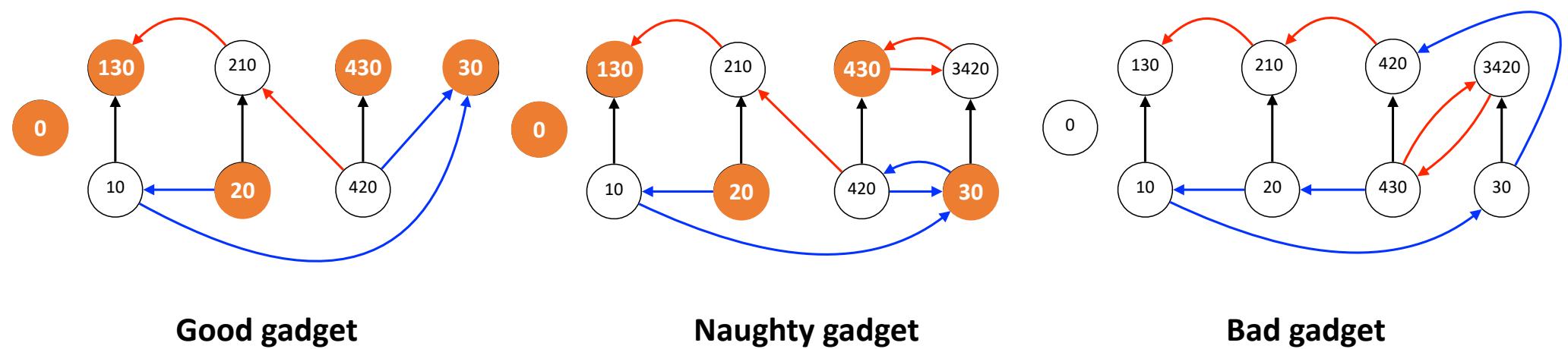
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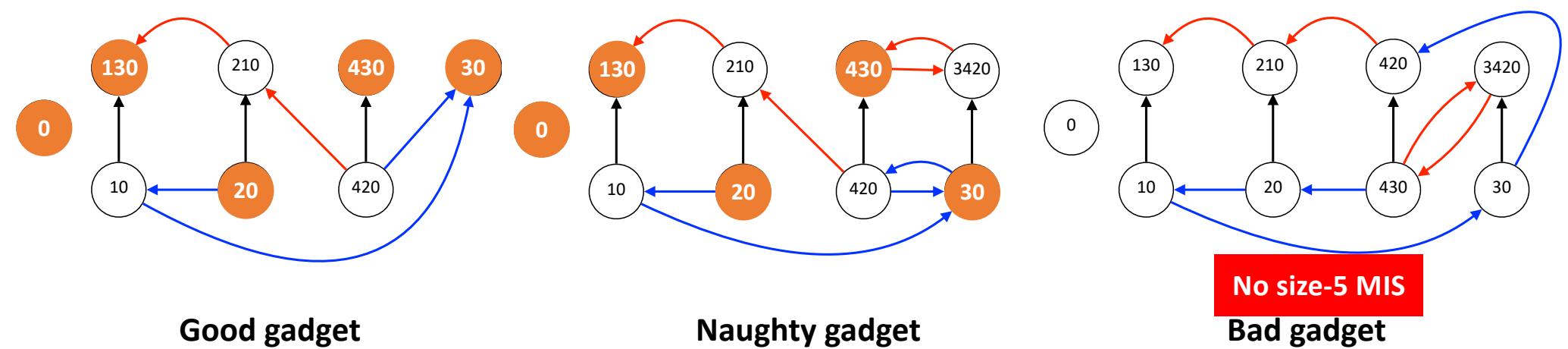
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Outline

- Background on SPP
- Our Contribution
- Solvability Digraph
- GreedyMIS: A Polynomial-Time Heuristic for SPP

GreedyMIS: Basic Idea

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- Iteratively add nodes into an independent set of the solvability digraph

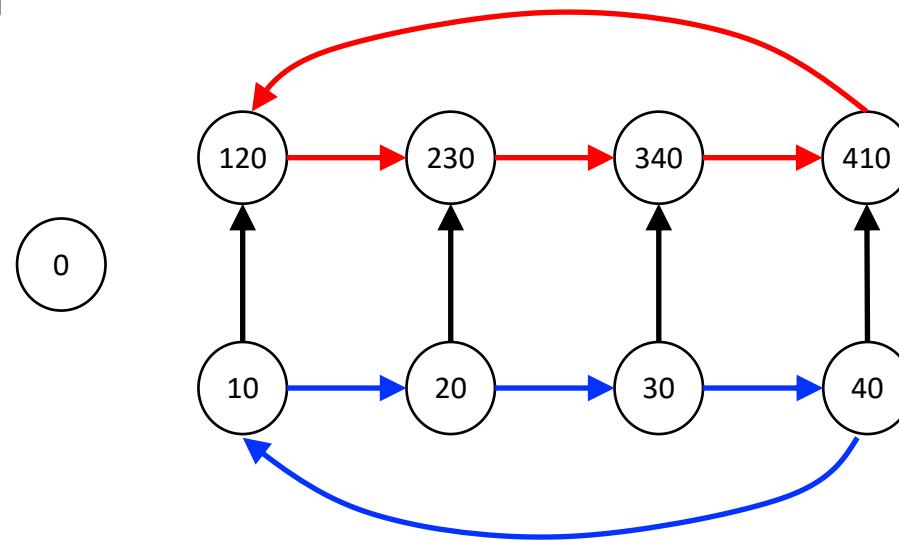
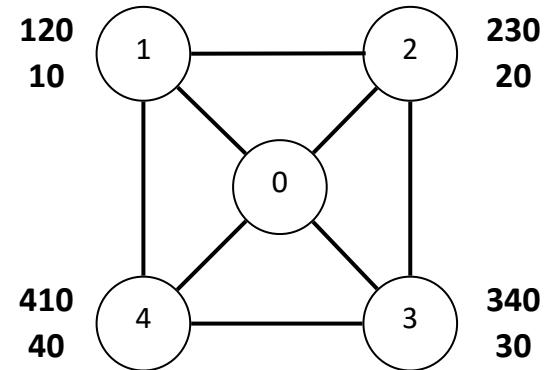
GreedyMIS: Basic Idea

- Iteratively add nodes into an independent set of the solvability digraph
- In each iteration:
 1. add path-vertices with no out edge, if none
 2. add one path-vertex if it is the only one left for the same node in SPP, if none
 3. randomly add one path-vertex with the lowest out degree
 4. remove all added path-vertices, their neighbors and all related edges from the digraph

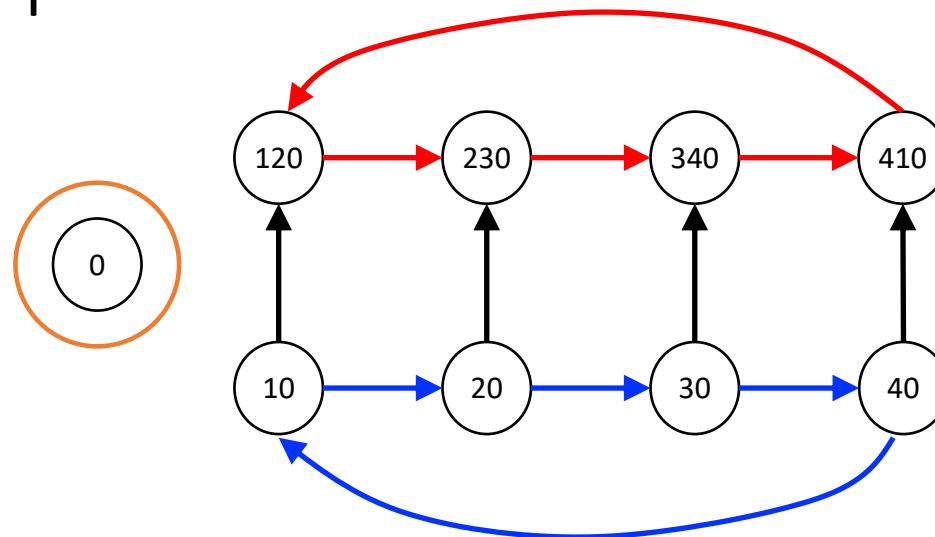
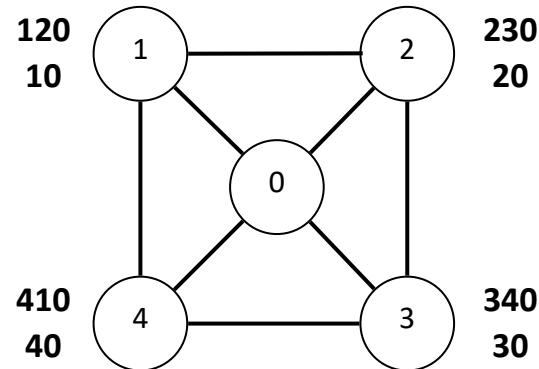
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 4. remove all added path-vertices, their neighbors and all related edges from the digraph
- Terminates when
 - (**solvable**) one of size $n+1$ is found, or
 - (**non-solvable**) no more nodes can be added into the set

GreedyMIS: Example

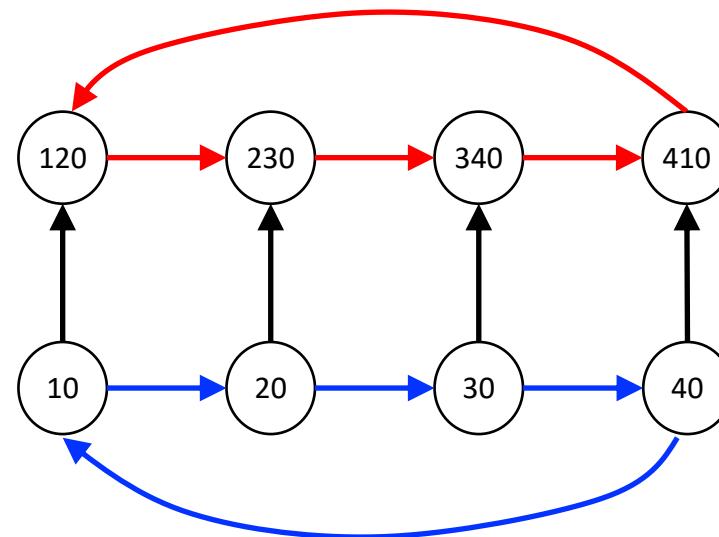
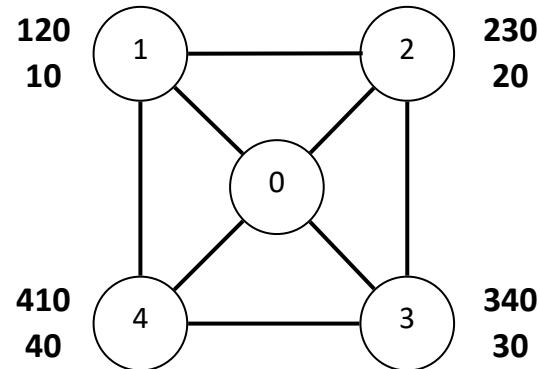


GreedyMIS: Example



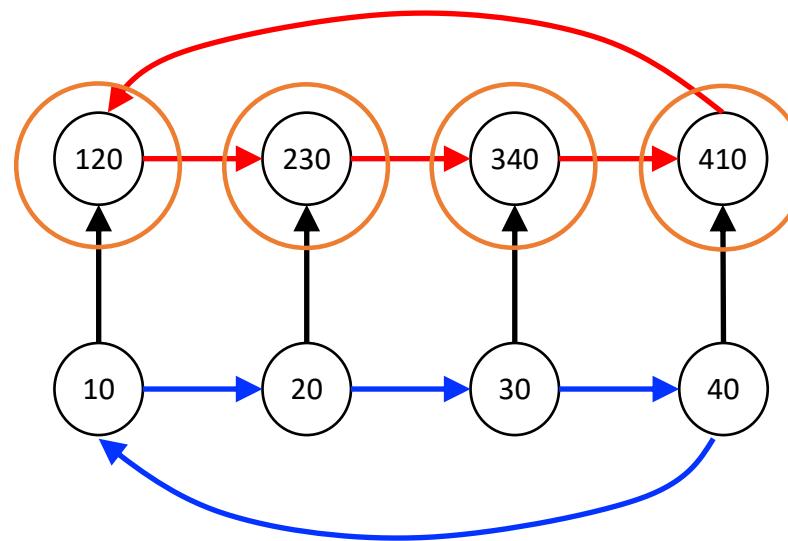
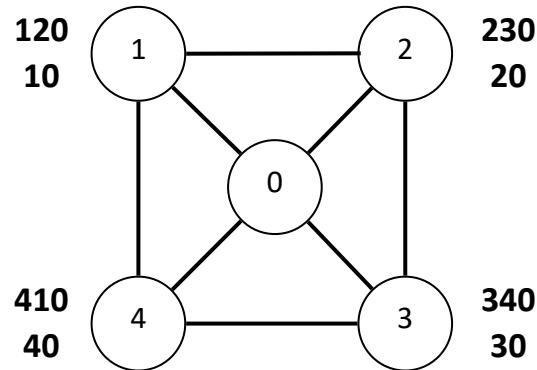
- Iteration 1: 0 is added (zero out edges)

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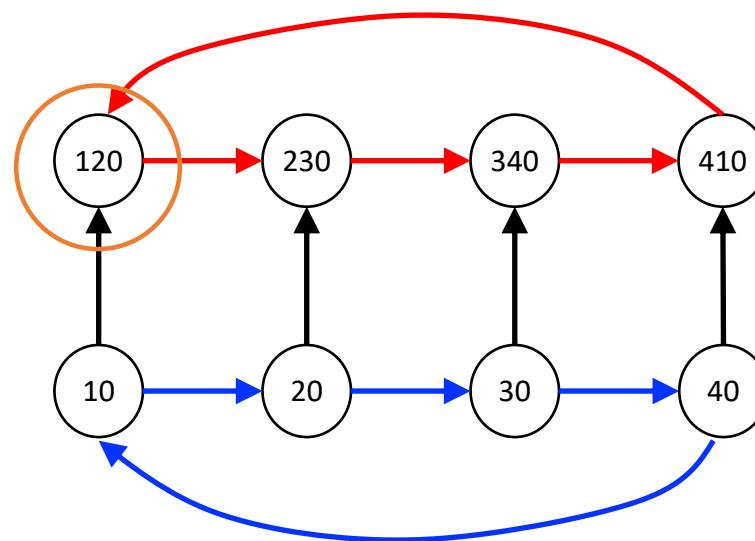
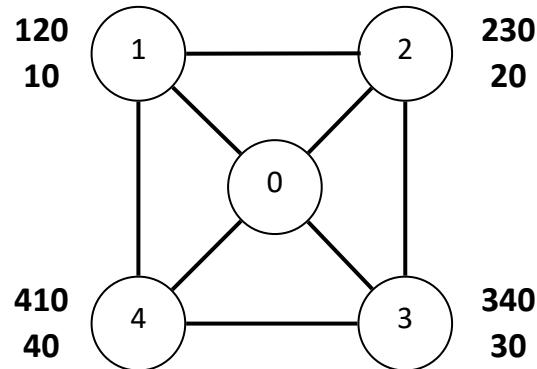
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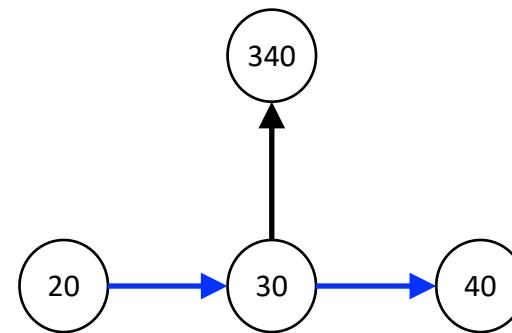
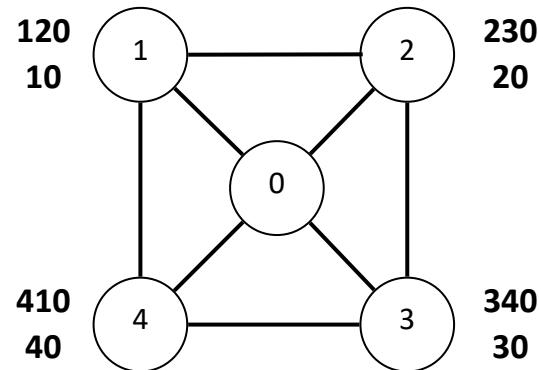
- Iteration 1: 0 is added (zero out edges)
- Iteration 2: {120, 230, 340, 410} all have out degree of 1, randomly add 120 (one with lowest out degree)

GreedyMIS: Example



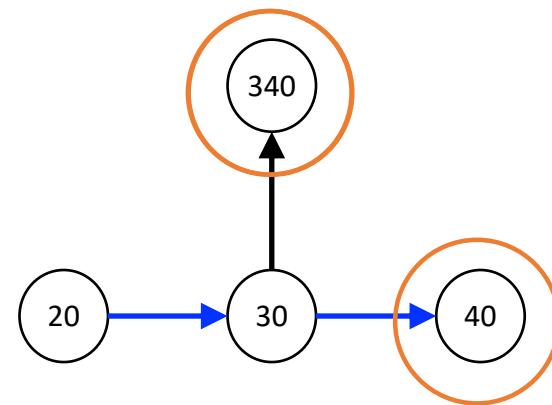
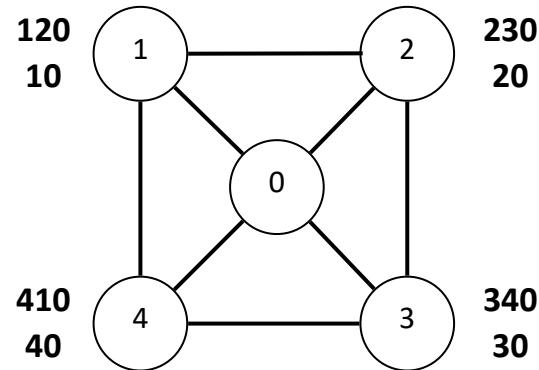
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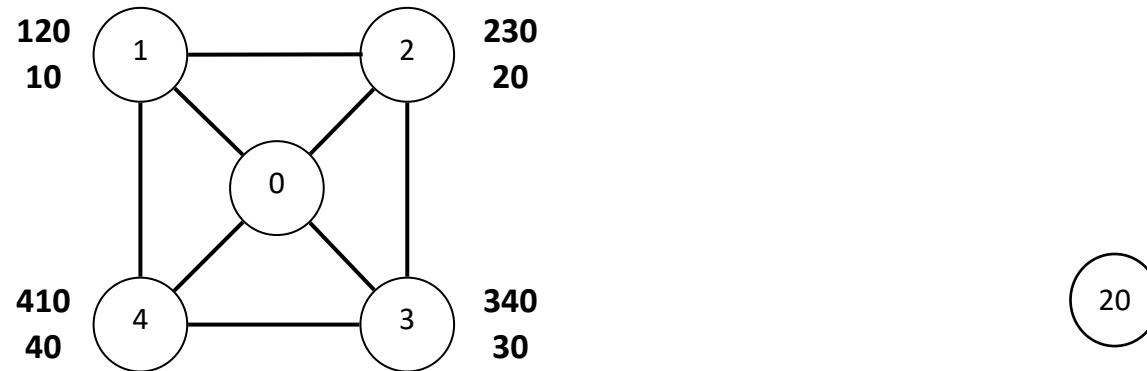
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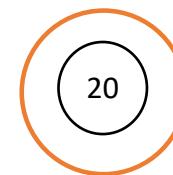
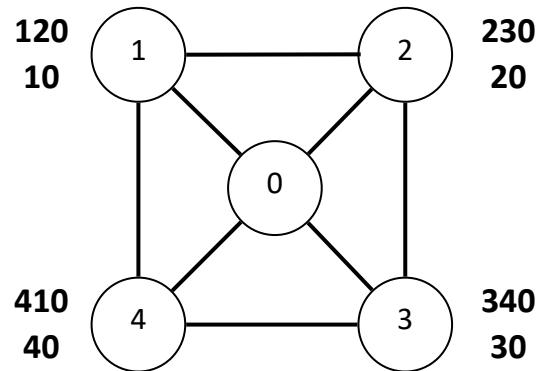
- Iteration 1: 0 is added (zero out edges)
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- Iteration 3: 340, 40 are added (zero out edges)

GreedyMIS: Example



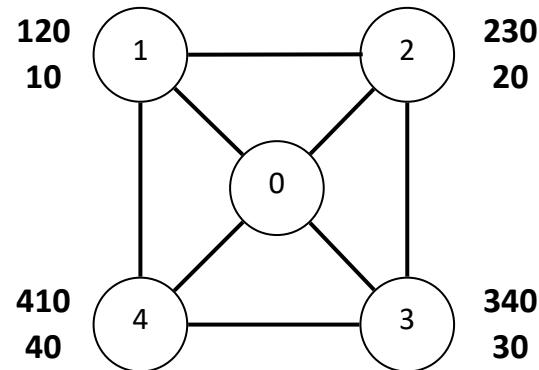
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GreedyMIS: Example



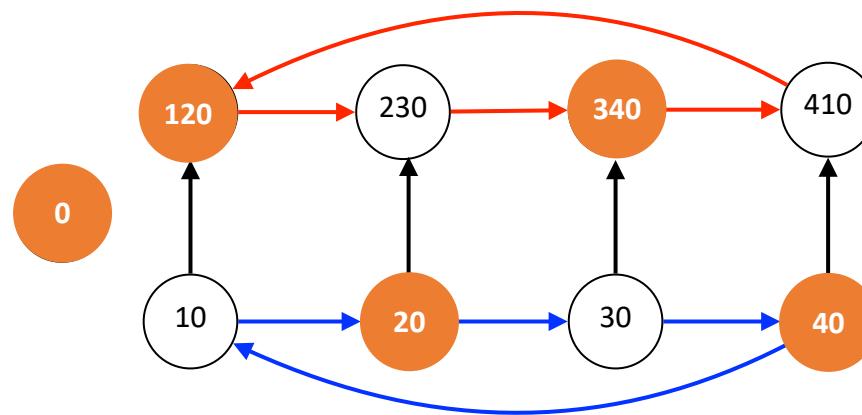
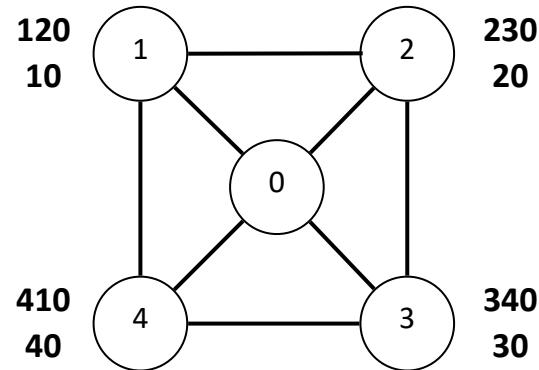
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GreedyMIS: Example



- Iteration 1: 0 is added (zero out edges)
- Iteration 2: {120, 230, 340, 410} all have out degree of 1, randomly add 120 (one with lowest out degree)
- Iteration 3: 340, 40 are added (zero out edges)
- Iteration 4: 20 is added (zero out edges)
- **Final result:** {0, 120, 340, 40, 20}

GreedyMIS: Analysis

Theorem 2: Any SPP instance that is solvable by Greedy+ [3], , the best known polynomial-time heuristic algorithm for SPP, is also solvable by GreedyMIS. (proof in the paper)

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Theorem 3: GreedyMIS solves strictly more SPP instances than Greedy+.

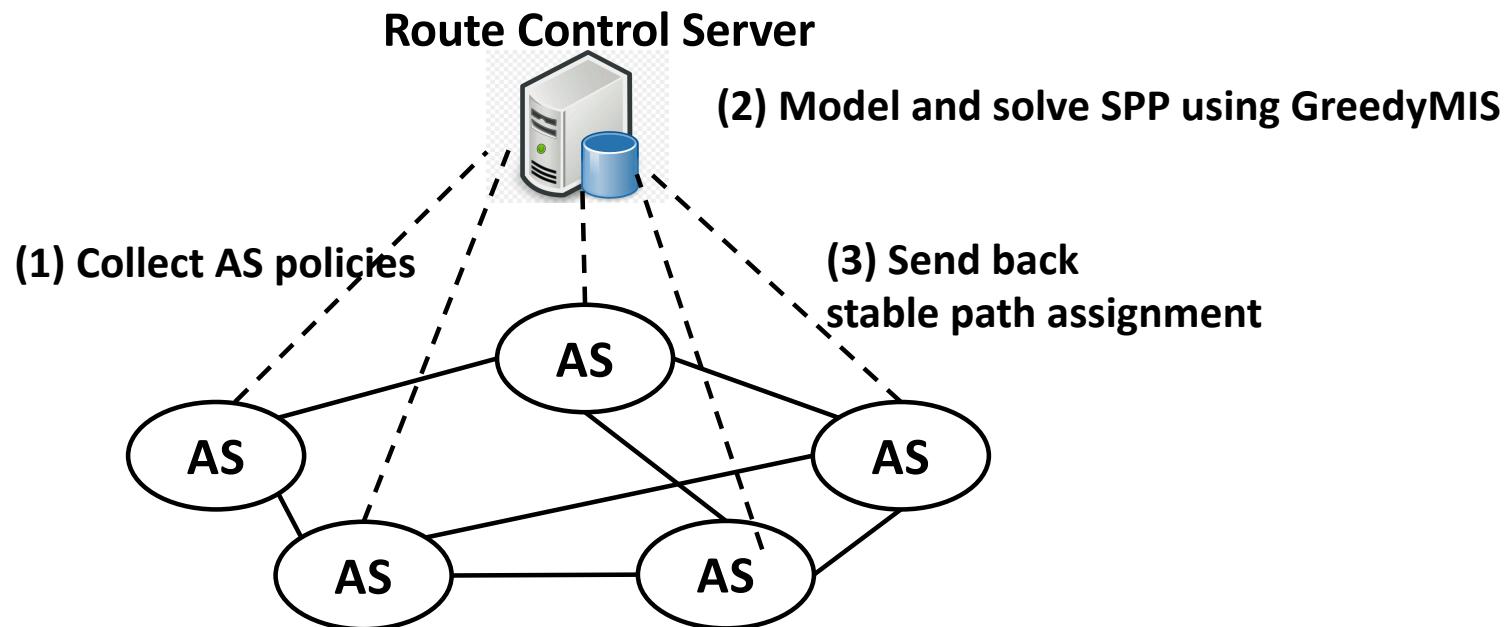
- A direct result from Theorem 2 and the example in the last slide.

Outline

- Background on SPP
- Our Contribution
- Solvability Digraph
- GreedyMIS: A Polynomial-Time Heuristic for SPP
- Use Cases

Use Case 1: Collaborative Interdomain Routing

- **Advantage:** allow more flexible routing policies, i.e., doesn't have to be a "safe" SPP
- **Scenario:** collaborative science networks such as Large Hadron Collider



Use Case 2: Privacy-Preserving, Collaborative Interdomain Routing

- **Scenario:** multi-domain networks desire more flexible policies, but still want to keep policies private

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- **Protocol:** an privacy-preserving version of GreedyMIS that employs linear secret sharing

Outline

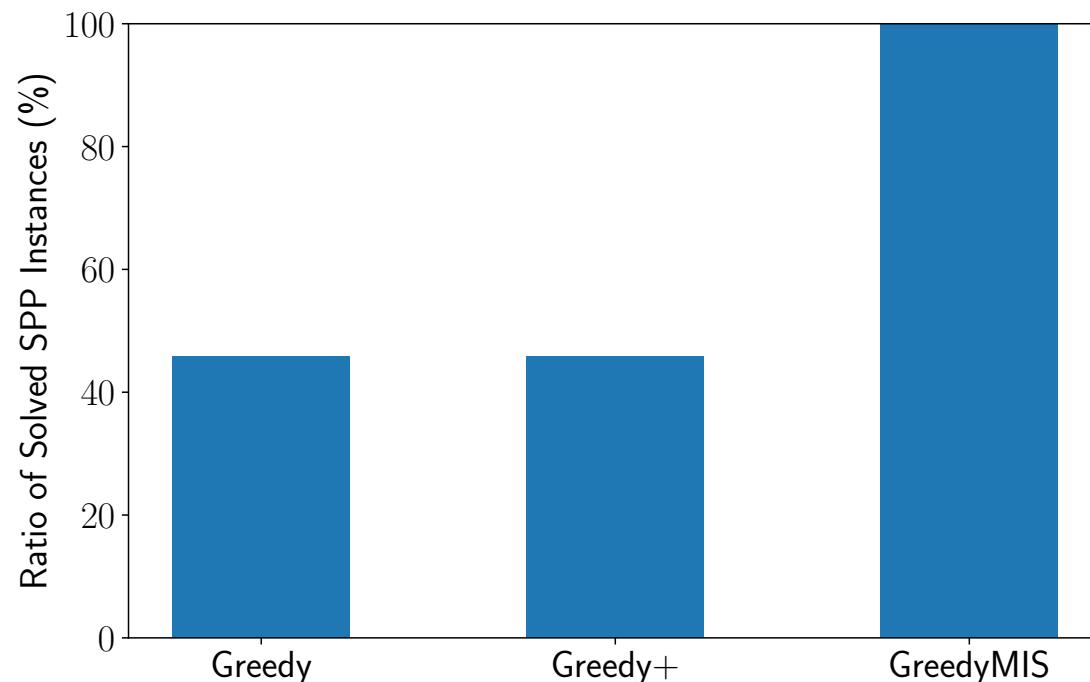
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- **Performance Evaluation**

Performance Evaluation: Settings

- **Topology:** real AS-level topologies from CAIDA Internet topology dataset
- **AS export policies:** (1) C/P relationship, (2) blacklist ASes, (3) forbidden segments.
- **SPP instances:** 11-50 ASes, 8-12k permitted paths
- **Comparison:** GreedyMIS vs. Greedy [1] and Greedy+ [3]

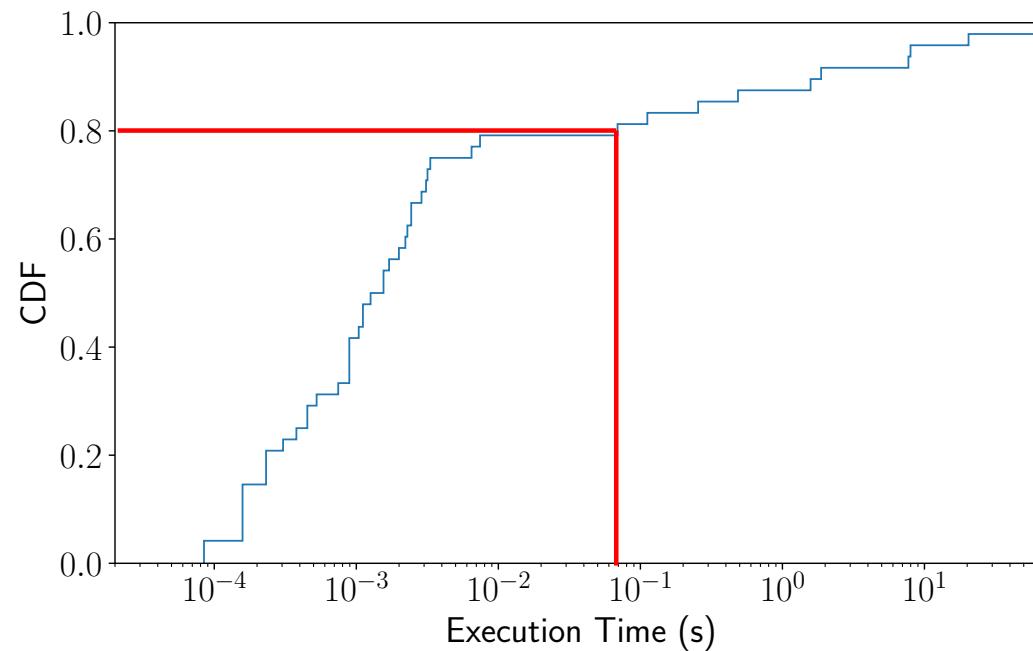
Results: Solvability of GreedyMIS

- GreedyMIS solves all SPP instances in the experiment, while the other two algorithms solves less than 50%.



Results: Efficiency of GreedyMIS

- In 80% of the experiments, GreedyMIS solves SPP in no more than 0.01s



Conclusion and Future Work

- Propose the solvability digraph data structure to reason about SPP solvability
- Design GreedyMIS, a polynomial-time heuristic that solves strictly more SPP instances than known state-of-the-art
- Tailor GreedyMIS to important interdomain routing use cases
- Demonstrate the efficiency and potentials of GreedyMIS via evaluation on real topologies

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Future Work

- Generic exact/approximated MIS algorithm for solving SPP
- Apply the SPP-MIS theorem to network configuration verification

Backup Slides

