Lecture V

 The higher dimensional case of general real symmetric matrices

Extension and Applications

The General Case

We already proved the result with N = 2. By induction, let us assume that for each integer $1 \le k \le N$, we can find an orthogonal matrix O_k which reduces a real symmetric matrix $A_k = \left(a_{ij}\right)_{k \times k}$ to the diagonal form:

$$O_k^T A_k O_k = egin{pmatrix} \lambda_1 & \cdots & 0 \ dots & \ddots & dots \ 0 & \cdots & \lambda_k \end{pmatrix}$$

The General Case: Goal

We want to find an orthogonal matrix O_{N+1} of order N+1, which reduces a real symmetric matrix $A_{N+1} = \left(a_{ij}\right)_{(N+1)\times(N+1)}$ to the diagonal form:

$$O_{N+1}^T A_{N+1} O_{N+1} = egin{pmatrix} \lambda_1 & \cdots & 0 \ dots & \ddots & dots \ 0 & \cdots & \lambda_{N+1} \end{pmatrix}$$

Systematic Procedure

Let us name the rows of $A_{N+1} = (a_{ij})_{(N+1)\times(N+1)}$ as:

$$A_{N+1} \doteq \begin{pmatrix} a^1 \\ a^2 \\ \vdots \\ a^{N+1} \end{pmatrix}$$

and take an eigenvalue λ_1 and its associated normalized eigenvector x^1 .

Systematic Procedure (cont'd)

By means of the Gram-Schmidt orthogonalization process, we can form an orthogonal matrix O_1 whose first column is the given $x^1 = y^1$:

$$O_1 = (y^1, y^2, ..., y^{N+1})$$

Then, as shown in Case N = 2, it holds:

$$O_1^T A_{N+1} O_1 = \begin{pmatrix} \lambda_1 & b_{12} & \cdots & b_{1,N+1} \\ 0 & & & \\ \vdots & & & \\ 0 & & & \end{pmatrix}, \quad A_N \in \mathbb{R}^{N \times N}$$

Exercise

Can you prove the above identity?

Answer

Carrying out the multiplication, we have

$$A_{N+1}O_{1} = \begin{pmatrix} \left\langle a^{1}, x^{1} \right\rangle & \dots & \left\langle a^{1}, x^{N+1} \right\rangle \\ \vdots & \ddots & \vdots \\ \left\langle a^{N+1}, x^{1} \right\rangle & \dots & \left\langle a^{N+1}, x^{N+1} \right\rangle \end{pmatrix}$$

$$= \begin{pmatrix} \lambda_{1}x_{11} & \left\langle a^{1}, x^{2} \right\rangle & \dots & \left\langle a^{1}, x^{N+1} \right\rangle \\ \vdots & \vdots & \ddots & \vdots \\ \lambda_{1}x_{1,N+1} & \left\langle a^{N+1}, x^{2} \right\rangle & \dots & \left\langle a^{N+1}, x^{N+1} \right\rangle \end{pmatrix}$$

Answer (cont'd)

Since O_1 is an orthogonal matrix, it follows that

$$O_1^T A_{N+1} O_1 = egin{pmatrix} \lambda_1 & b_{12} & \cdots & b_{1,N+1} \ 0 & & & A_N \ dots & & & \end{pmatrix}, \ A_N \in \mathbb{R}^{N imes N}$$

Comment 1

Furthermore, since $O_1^T A_{N+1} O_1$ must be symmetric, we have $b_{1j} = 0$, j = 2,..., N+1, and A_N is symmetric. Thus,

$$O_1^TA_{N+1}O_1=egin{pmatrix} \lambda_1 & 0 & \cdots & 0\ 0 & & A_N \ dots & & \end{pmatrix}, \ \ A_N=A_N^T.$$

Comment 2

Given the identity

$$O_1^T A_{N+1} O_1 = egin{pmatrix} \lambda_1 & 0 & \cdots & 0 \ 0 & & & A_N \ dots & & & \end{pmatrix}, \ A_N = A_N^T \ 0 & & & \end{pmatrix}$$

we conclude that the eigenvalues of A_N must be λ_2 , λ_3 , ..., λ_{N+1} , the remaining eigenvalues of A_{N+1} .

Systematic Procedure (cont'd)

By induction, there is an orthogonal matrix O_N which reduces A_N to diagonal form. Form the (N+1)-dimensional matrix

$$S_{N+1} = \begin{pmatrix} 1 & 0 & \cdots & 0 \\ 0 & & & O_N \\ \vdots & & & 0 \end{pmatrix}$$

Clearly, S_{N+1} is also orthogonal, i.e., $S_{N+1}^T S_{N+1} = I$.

Systematic Procedure (cont'd)

It can be directly checked that

$$S_{N+1}^{T} \left(O_{1}^{T} A_{N+1} O_{1} \right) S_{N+1} = \begin{pmatrix} \lambda_{1} & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \lambda_{N+1} \end{pmatrix}$$

or, equivalently,

$$O_{N+1}^T A_{N+1} O_{N+1} = \begin{pmatrix} \lambda_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \lambda_{N+1} \end{pmatrix}$$

with
$$O_{N+1} = O_1 S_{N+1}$$
.

Formal Statement of the Main Result

Let $A \in \mathbb{R}^{n \times n}$ be a real symmetric matrix. Then, it may be transformed into a diagonal form by using an orthogonal matrix O so that

$$O^T A O = \begin{pmatrix} \lambda_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \lambda_n \end{pmatrix}$$

where $\{\lambda_i\}_{i=1}^n$ are the eigenvalues of A.

Test for Positive Definiteness

A necessary and sufficient condition for a real symmetric matrix *A* to be *positive definite* is that all eigenvalues of *A* are positive.

Indeed,

Recall that a real matrix A is positive definite if

$$x^T A x > 0, \ \forall x \in \mathbb{R}^n, x \neq 0.$$

Then,

$$x^{T}Ax = x^{T}O\Lambda O^{T}x$$
, where $\Lambda = diag(\lambda_{i})$
= $y^{T}\Lambda y$, where $y = O^{T}x = (y_{i})_{n \times 1}$

$$=\sum_{i=1}^n \lambda_i y_i^2$$

So, the equivalence property follows readily.

Repeated Eigenvalues

As shown previously, if a matrix *A* has *distinct* eigenvalues, then its associated eigenvectors are linearly independent.

Questions:

- What if A has a repeated eigenvalue λ_1 of (algebraic) multiplicity k?
- Are there always *k* linearly independent eigenvectors?

Comment

As shown in Lecture IV, the answer is generally negative for a real matrix which is *not* be symmetric.

However, for a real symmetric matrix, we can always find *k* linearly independent eigenvectors for *any* repeated eigenvalue of multiplicity *k*.

Indeed,

 \exists an orthogonal matrix O such that

$$AO = O \begin{pmatrix} \lambda_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \lambda_n \end{pmatrix}$$

where $\lambda_1 = \cdots = \lambda_k$, $\lambda_i \neq \lambda_1$, $\forall i = k+1,...,n$.

Now, the first k columns of O are of course linearly independent, and are eigenvectors associated with λ_1 .

In addition,

Any other eigenvector y associated with λ_1 is linear combination of these k vectors.

In fact,
$$y = \sum_{i=1}^{n} c_i x^i$$
, with x^i the *i*th column of O .

 $c_i = 0, \forall i = k+1, ..., n$ because these eigenvectors x_i are orthogonal with $x_j, y, 1 \le j \le k$.

(see Lecture IV)

Special Case of Cayley-Hamilton Theorem

As a direct application of the diagonal canonical form, we have

Any real symmetric matrix satisfies its own characteristic equation: $\rho_A(A) = 0$,

where
$$\rho_A(\lambda) = \det(\lambda I - A) = \lambda^n + \sum_{i=1}^n \alpha_i \lambda^{n-i}$$
,

$$\rho_A(A) := A^n + \sum_{i=1}^n \alpha_i A^{n-i}$$
, with $A^0 = I$.

Application:

Solving Differential Equations

Solving for the solutions of

$$\dot{x} = Ax$$

boils down to an easier problem for

$$\dot{y} = A_c y$$

where A_c is a canonical form of A under

a nonsingular transformation

$$P^{-1}: x \to y = P^{-1}x$$

so that
$$A_c = P^{-1}AP$$
 and $x = Py$.

Exercise 1

Solve the following initial-value problem:

$$\dot{x}(t) = \begin{pmatrix} -1 & 3 \\ 3 & -1 \end{pmatrix} x(t), \quad x(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$$

i.e,

$$x(t) = ?, \forall t \ge 0.$$

Exercise 2: Extension to Difference Equations

Find an explicit expression for x_n , n = 0,1,..., given that

$$x_0 = -1$$
, $x_1 = 2$ and

$$x_n = ax_{n-1} + x_{n-2}, \quad n = 2, 3, \dots$$

Hint

Rewrite the second-order difference equation as:

$$\begin{bmatrix} x_{n-1} \\ x_n \end{bmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & a \end{pmatrix} \begin{bmatrix} x_{n-2} \\ x_{n-1} \end{bmatrix}, n = 2, 3, \dots$$

Equivalently,

$$\xi_n = A\xi_{n-1}, \ n = 1, 2, \dots$$

with

$$\xi_n \coloneqq \begin{bmatrix} x_{n-1} \\ x_n \end{bmatrix}.$$

Another Extension

Question: When does there exist an orthogonal matrix O which simultaneously reduces two real symmetric matrices A, B to diagonal form?

Motivational Problem

Solve the 2nd-order differential equation:

$$A\ddot{x}(t) + Bx(t) = 0, x \in \mathbb{R}^n$$

where $A, B \in \mathbb{R}^{n \times n}$ are symmetric matrices.

Note that such equations often occur in mass-spring problems.

Basic Result

A necessary and sufficient condition for the existence of an orthogonal matrix *O* such that

$$\begin{cases} O^{T}AO = diag(\lambda_{i}) \\ O^{T}BO = diag(\mu_{i}) \end{cases}$$

is that A and B commute, i.e. AB = BA.

Note: See Section 1.3 of the 2013 textbook of Horn and Johnson for extensions to more than 2 matrices.

Proof of the Necessity

Clearly,

 $A = O^{T} diag(\lambda_{i})O$ and $B = O^{T} diag(\mu_{i})O$ commute, because O is orthogonal.

Case 1: Either A or B has distinct eigenvalues.

Assume that A has distinct eigenvalues. Then,

$$Ax = \lambda x \Rightarrow A(Bx) = B(Ax) = \lambda(Bx).$$

So, Bx, if nonzero, is an eigenvector too,

for the same eigenvalue λ . In other words,

Bx is a multiple of x. As a result,

$$Bx^{i} = \mu_{i}x^{i}$$
, for each pair (λ_{i}, x^{i}) .

This equality of course also holds if *Bx*=0.

Case 1 (cont'd)

Now, we observe that A, B have the same eigenvectors x^i , $1 \le i \le n$.

Thus, we can define the orthogonal transformation matrix *O* as follows:

$$O = \left(x^1, x^2, \cdots, x^n\right)$$

Case 2: λ_1 repeats k times associated with (linearly independent/orthonormal) eigenvectors x^1, \dots, x^k .

Then, using previous computation, we have

$$Bx^{i} = \sum_{j=1}^{k} c_{ij}x^{j}, \quad i = 1, 2, \dots, k.$$

In addition,
$$\langle x^j, Bx^i \rangle = c_{ij} = \langle Bx^j, x^i \rangle = c_{ji}$$
.

Now, consider the linear combination $\sum_{i=1}^{\kappa} a_i x^i$.

Case 2 (cont'd): We have

$$B(\sum_{i=1}^k a_i x^i) = \sum_{i=1}^k a_i \left(\sum_{j=1}^k c_{ij} x^j \right) = \sum_{j=1}^k \left(\sum_{i=1}^k c_{ij} a_i \right) x^j.$$

Thus, if we choose a_i so that

$$\sum_{i=1}^{k} c_{ij} a_i = r_1 a_j, \ j = 1, 2, \dots, k, \Leftrightarrow (r_1 I - C) a = 0$$

then we have

$$B\left(\sum_{i=1}^{k} a_i x^i\right) = r_1 \left(\sum_{i=1}^{k} a_i x^i\right)$$

Case 2 (cont'd):
$$B\left(\sum_{i=1}^k a_i x^i\right) = r_1 \left(\sum_{i=1}^k a_i x^i\right)$$

implies r_1 is an eigenvalue of B, associated

with eigenvector $\sum_{i=1}^{k} a_i x^i$.

On the other hand, r_1 is an eigenvalue of $C = (c_{ij})$ associated with eigenvector $a = col(a_i)$.

Case 2 (end):

If T_k is a k-dim. orthogonal transformation reducing

C into a diagonal form, then

$$\left[z^{1}\cdots z^{k}\right] = T_{k}\left[x^{1}\cdots x^{k}\right]$$
 is an orthonormal set

with each z^i being common eigenvector for both

A and B. (left as an exercise)

Exercise 3

Show how to transform the following matrix into a canonical diagonal form, by means of an orthogonal matrix:

$$M = \begin{pmatrix} 1 & 2 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Normal Matrices:

A generalization of real symmetric matrices

Definition: A square matrix A is said to be normal,

if
$$AA^* = A^*A$$
.

- If A is normal and α is a scalar, then αA also is normal.
- If A is normal and $B \sim A$, then B also is normal.
- Every unitary matrix is normal.
- Every real symmetric or skew-symmetric matrix is normal.
- Every Hermitian or skew-Hermitian matrix is normal.

Exercise 4

Let a, b be constants. Show that $\begin{pmatrix} a & b \\ -b & a \end{pmatrix}$ is normal and has eigenvalues $a \pm ib$.

Exercise 5

A matrix $A \in \mathbb{C}^{n \times n}$ is conjugate normal if $AA^* = A^*A$.

Show that a block-upper-triangular matrix

$$A = \begin{pmatrix} A_{11} & A_{12} \\ 0 & A_{22} \end{pmatrix}$$
 is conjugate normal

if and only if its diagonal blocks A_{11} , A_{22} are conjugate normal, and $A_{12} = 0$. In particular, an upper triangular matrix is conjugate normal iff it is diagonal.

See the text (2nd ed.) by Horn-Johnson, p. 268.

Homework #5

1. Using the Gram-Schmidt process find a set of mutually orthonormal vectors u^1 , u^2 , u^3 , based on:

$$x^{1} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix}, \quad x^{2} = \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix}, \quad x^{3} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \end{bmatrix}$$