



Compilation Principle 编译原理

第17讲: 中间代码(2)

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Review Questions (1)

- What are the main tasks of compilation backend?
 Intermediate code generation, optimizations, target code generation
- What is IR (specifically, the low-level IR)?
 Intermediate Representation. A machine- and language-independent version of the original source code.
- Why do we use IR?
 Clean separation of front- and back-end; easy to optimize and extend
- What is three-address code (TAC)?
 A type of IR, with at most three operands. (High-level assembly)
- TAC of x + y * z + 5? $t_1 = y * z$; $t_2 = x + t_1$; $t_3 = t_2 + 5$;





Review Questions (2)

Possible ways to implement TAC?

Quadruples: op arg1, arg2, result

Triples: op arg1 arg2

Indirect triples: op arg1 arg2

What is Single Static Assignment?

An IR that facilitates certain code optimization. Give variable different version name on every assignment.

- In code generation, how to layout variables in memory?
 Calculate the location using base address and type width.
- What is address alignment?

Enforce addr(x) % sizeof(x.type) == 0, to respect the hardware constraints to avoid unexpected performance degradation.





Code Generation [代码生成]

- To generate three-address codes (TACs)
 - By now, we have
 - an AST, annotated with scope and type information
 - Do another round of tree traversal
 - Lay out variables in memory
 - Generate TAC for any subexpressions or substatements
 - Using the result, generate TAC for the overall expression
- We will use the syntax-directed formalisms to specify translation
 - Variable definitions [变量定义]
 - Assignment [赋值]
 - Array references [数组引用]
 - Boolean expressions [布尔表达式]
 - Control-flow statements [控制流语句]





Type Expressions [类型表达式]

- A **type expression** is either a basic type or is formed by applying an operator called a <u>type constructor</u> [类型构造符] to a type expression
 - Basic type: integer, float, char, Boolean, void
 - Array: array(I, T) is a type expression, if T is
 - int[3] <--> array(3, int)
 - int[2][3] <--> array(2, array(3, int))
 - Pointer: pointer(T) is a type expression, if T is
 - int *val <--> pointer(int)

$$P \rightarrow D$$
 $D \rightarrow T \text{ id}; D_1 \mid \epsilon$
 $T \rightarrow B C \mid *T_1$
 $B \rightarrow \text{int} \mid \text{real}$
 $C \rightarrow [\text{num}] C_1 \mid \epsilon$





CodeGen: Variable Definitions

- Translating variable definitions
 - enter(name, type, offset)
 - Save the type and relative address in the symbol-table entry for the name

```
(1) P \rightarrow \{ offset = 0 \} D
② D -> T id; { enter( id.lexeme, T.type, offset );
                  offset = offset + T.width; D_1
(3) D \rightarrow \varepsilon
4 T \rightarrow B \{ t = B.type; w = B.width; \}
         C { T.type = C.type; T.width = C.width; }
\textcircled{5} T \rightarrow *T_1 \{ T.type = pointer(T_1.type); T.width = 4; \}
⑥ B -> int { B.type = int; B.width = 4; }
(7) B -> real { B.type = real; B.width = 8; }
\otimes C -> \varepsilon { C.type = t; C.width = w; }
9 C \rightarrow [num]C_1 \{ C.type = array(num.val, C_1.type);
                       C.width = num.val * C_1.width;
```

- Examples:
 - real x; int i;
 - int[2][3];
- type, width
 - Syn attributes
- t, w
 - Vars to pass type and width from B node to the node for C -> ε
- offset
 - The next relative address





Example

```
Input: real x; int i;
```

 $\hat{\mathbf{B}}_{\dots,a+b-8}^{\text{type} = \text{real}}\{\mathbf{a}\}$

width = 8

{a}

real

{a}

type = real

3

width = 8 id;

C type = real $\{a\}$

width = 8

{**a**}

```
(1) P \rightarrow \{ offset = 0 \} D
              ② D -> T id; { enter( id.lexeme, T.type, offset );
                                offset = offset + T.width; D_1
              ③ D -> ε
              (4) T -> B \{ t = B.type; w = B.width; \}
                       C { T.type = C.type; T.width = C.width; }
              \textcircled{5} T \rightarrow *T_1 \{ T.type = pointer(T_1.type); T.width = 4; \}
              (6) B -> int { B.type = int; B.width = 4; }
              To B -> real { B.type = real; B.width = 8; }
              \otimes C -> \varepsilon { C.type = t; C.width = w; }
              (9) C \rightarrow [num]C_1 \{ C.type = array(num.val, <math>C_1.type);
                                    C.width = num.val * C_1.width; }
         enter(x, real, 0)
       {a}
                                     enter(i, int, 8)
                    type = int
                                          {a} D
                    width = 4 id
                          type = int {a}
B_{\text{width}=4}^{\text{type}=\text{int}} \{a\}
     {a}
```

offset =12

t = int

w = 4



CodeGen: Assignment Statement

- Translate into *three-address code* [赋值语句]
 - An expression with more than one operator will be translated into instructions with at most one operator per instruction
- Helper functions in translation
 - lookup (id): search id in symbol table, return null if none
 - emit()/gen(): generate three-address IR
 - newtemp(): get a new temporary location

①
$$S \rightarrow id = E$$
;

②
$$E \rightarrow E_1 + E_2$$
;

③
$$E -> - E_1$$

$$4 E -> (E_1)$$

Assignment statement:

$$a = b + (-c)$$

Three-address code:

$$t_1 = minus c$$

 $t_2 = b + t_1$
 $a = t_2$





SDT Translation of Assignment

- Attributes code and addr
 - S.code and E.code denote the TAC for S and E, respectively
 - E.addr denotes the address that will hold the value of E (can be a name, constant, or a compiler-generated temporary)

```
(1) S -> id = E; { p = lookup(id.lexeme); if !p then error;
                S.code = E.code | |
                gen( p '=' E.addr ); }
2E \rightarrow E_1 + E_2; { E.addr = newtemp();
                  E.code = E_1.code \mid \mid E_2.code \mid \mid
                  gen(E.addr'='E_1.addr'+'E_2.addr); \}
E.code = E_1.code | |
              gen(E.addr '=' 'minus' E<sub>1</sub>.addr); }
4 E \rightarrow (E_1) { E.addr = E_1.addr;
              E.code = E_1.code; 
(5) E -> id { E.addr = lookup(id.lexeme); if !E.addr then error;
            E.code = "; }
```





Incremental Translation[增量翻译]

- Generate only the new three-address instructions
 - gen() not only constructs a three-address inst, it appends the inst to the sequence of insts generated so far

```
① S \rightarrow id = E; { p = lookup(id.lexeme); if !p then error;
                                           Code attributes can
               gen( p '=' E.addr ); }
                                             be long strings
2E \rightarrow E_1 + E_2; { E.addr = newtemp();
                 gen(E.addr'='E_1.addr'+'E_2.addr); \}
gen(E.addr'='minus'E_1.addr); \}
4 E \rightarrow (E_1) { E.addr = E_1.addr;
(5) E -> id { E.addr = lookup(id.lexeme); if !E.addr then error;
```





Example

```
    S -> id = E; { p = lookup(id.lexeme); if !p then error; gen( p '=' E.addr ); }
    E -> E<sub>1</sub> + E<sub>2</sub>; { E.addr = newtemp(); gen(E.addr '=' E<sub>1</sub>.addr '+' E<sub>2</sub>.addr); }
    E -> - E<sub>1</sub> { E.addr = newtemp(); gen(E.addr '=' 'minus' E<sub>1</sub>.addr); }
    E -> (E<sub>1</sub>) { E.addr = E<sub>1</sub>.addr; }
    E -> id { E.addr = lookup(id.lexeme); if !E.addr then error; }
```

Input

$$x = (a + b) + c$$



Translated TAC

$$t_1 = a + b$$

 $t_2 = t_1 + c$
 $x = t_2$



$$t_2 = t_1 + c$$

$$x = t_2$$

CodeGen: Array Reference[数组引用]

- Primary problem in generating code for array references is to <u>determine the address of element</u>
- 1D array

```
int A[N];
A[i] ++;
base=A[0] A[i] A[N-1]
```

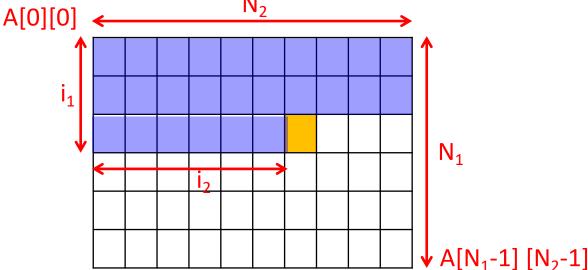
- Base: address of the first element
- Width: width of each element
 - □ *ixwidth* is the offset
- Addressing an array element
 - $addr(A[i]) = base + i \times width$





N-dimensional Array

- Laying out 2D array in 1D memory
 - int $A[N_1][N_2]$; /* int $A[0..N_1][0..N_2]$ */
 - $-A[i_1][i_2]++;$
- The organization can be <u>row-major</u> or <u>column-major</u>
 - C language uses row major (i.e., stored row by row)
 - Row-major: addr(A[i₁,i₂]) = base + (i₁ × N_2 *width + i₂ × width)
- k-dimensional array
 - addr(A[i₁][i₂]...[i_k]) = base + i₁×w₁ + i₂×w₂ + ... + i_k×w_k







Translation of Array References

$$t_1 = i * 4$$

 $t_2 = a[t_1]$
 $c = t_2$

$$addr(a[i_1][i_2]) = base + i_1*20 + i_2*4$$

- Type(a) = array(3, array(5, int))
 c = a[i₁][i₂];
- Type(a) = array(3, array(5, array(8, int)))
 c = a[i₁][i₂][i₃]

$$t_1 = i_1 * 20$$

 $t_2 = i_2 * 4$
 $t_3 = t_1 + t_2$
 $t_4 = a[t_3]$
 $c = t_4$





Translation of Array References (cont.)

- $A[i_1][i_2][i_3]$, type(a) = array(3, array(5, array(8, int)))
 - L.type: the type of the subarray generated by L
 - L.addr: a temporary that is used while computing the offset for the array reference by summing the terms $i_i \times w_i$
 - L.array: a pointer to the symbol-table entry for the array name

array = a

```
L.array.base gives the array's base address
```

```
type = int
                                                                                             offset = i_1 \times 160 + i_2 \times 32 + i_3 \times 4
(1) S \rightarrow id = E; | L = E;
                                                                                        array = a
② E \rightarrow E_1 + E_2 \mid -E_1 \mid (E_1) \mid id \mid L
                                                                                                                                [ E ]
                                                                                        type = array(8, int)
③ L \rightarrow id [E] \mid L_1[E]
                                                                                        offset = i_1 \times 160 + i_2 \times 32
                                                                     array = a
                                                                                                                                id
                                                                    type = array(5, array(8, int)) [F]
base + i_1 \times w_1 + i_2 \times w_2 + ... + i_k \times w_k
                                                                                                                                 (i_3)
                                                                                         [ E ]
                                                                                                             (i_2)
                                                             (a)
                                                                    15
```

Translation of Array References (cont.)

• $A[i_1][i_2][i_3]$, type(a) = array(3, array(5, array(8, int)))

```
① S \rightarrow id = E; | L = E; { gen(L.array.base'['L.addr']' '=' E.addr); }
② E \rightarrow E_1 + E_2 \mid -E_1 \mid (E_1) \mid id \mid L \{ E.addr = newtemp(); \}
                   gen(E.addr'='L.array.base'['L.addr']'); }
(3) L -> id [E] { L.array = lookup(id.lexeme); if !L.array then error;
                 L.type = L.array.type.elem;
                 L.offset = newtemp();
                 gen(L.addr '=' E.addr '*' L.type.width); }
    |L_1[E] \{ L.array = L_1.array;
             L.type = L_1.type.elem;
             t = newtemp();
             gen(t '=' E.addr '*' L.type.width);
             L.addr = newtemp();
             gen(L.addr '=' L<sub>1</sub>.addr '+' t; }
```

```
t_1 = i_1 * 160

t_2 = i_2 * 32

t_3 = t_1 + t_2

t_4 = i_3 * 4

t_5 = t_3 + t_4

c = a[t_5]
```



CodeGen: Boolean Expressions

- Boolean expression: a op b
 - where op can be <, <=, = !=, > or >=, &&, | |, ...
- Short-circuit evaluation[短路计算]: to skip evaluation of the rest of a boolean expression once a boolean value is known
 - Given following C code: if (flag | | foo()) { bar(); };
 - If flag is true, foo() never executes
 - = Equivalent to: if (flag) { bar(); } else if (foo()) { bar(); };
 - Given following C code: if (flag && foo()) { bar(); };
 - □ If *flag* is false, *foo()* never executes
 - Equivalent to: if (!flag) { } else if (foo()) { bar(); };
 - Used to alter control flow, or compute logical values
 - Examples: if (x < 5) x = 1; x = true; x = a < b
 - □ For control flow, boolean operators translate to *jump* statements





Boolean Exprs (w/o Short-Circuiting)

Computed just like any other arithmetic expression

$$E \rightarrow (a < b) \text{ or } (c < d \text{ and } e < f)$$

$$t_1 = a < b$$
 $t_2 = c < d$
 $t_3 = e < f$
 $t_4 = t_2 && t_3$
 $t_5 = t_1 || t_4$

- Then, used in control-flow statements
 - S.next: label for code generated after S



