15.094J: Robust Modeling, Optimization, Computation

Lecture 5: Robust Mixed Integer Optimization

Outline

- RMIO: Tractability
- 2 RMIO: Probabilistic Guarantees
- 3 Robust 0-1 Optimization
- Robust Network Flows

Row-wise Polyhedral Uncertainty

- Primitives: Uncertainty sets U_i , i = 1, ..., m, b, c (known, WLOG).
- RLO with row-wise uncertainty:

max
$$c'x$$

s.t. $a'_ix \leq b_i$. $\forall a_i \in U_i, i = 1, ..., m$,
 $x \geq 0, x_i \in \mathcal{Z}, i = 1, ..., k$.

- $U_i = \{a_i | D_i a_i \leq d_i\}, D_i : k_i \times n.$
- RC

$$\max_{\mathbf{x}, \mathbf{p}_{i}} \quad \mathbf{c}' \mathbf{x}$$
s.t.
$$\mathbf{p}'_{i} \mathbf{d}_{i} \leq b_{i}, \quad i = 1, \dots, m,$$

$$\mathbf{p}'_{i} \mathbf{D}_{i} = \mathbf{x}', \quad i = 1, \dots, m,$$

$$\mathbf{p}_{i} \geq \mathbf{0}, \quad i = 1, \dots, m,$$

$$\mathbf{x} > \mathbf{0}, \quad x_{i} \in \mathcal{Z}, \quad i = 1, \dots, k.$$

- RMIO reduces to MIO.
- Same even if uncertainty is not row-wise.

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Row-wise Ellipsoidal uncertainty

RO:

$$\begin{aligned} \max \quad & \boldsymbol{c}' \boldsymbol{x} \\ \text{s.t.} \quad & \max_{\boldsymbol{a}_i \in U_i} \boldsymbol{a}_i' \boldsymbol{x} \leq b_i. \\ & \boldsymbol{x} \geq \boldsymbol{0}, \ x_i \in \mathcal{Z}, \ i = 1, \dots, k. \end{aligned}$$

- $U_i = \{ \boldsymbol{a}_i | \boldsymbol{a}_i = \overline{\boldsymbol{a}}_i + \boldsymbol{\Delta}_i' \boldsymbol{u}_i, ||\boldsymbol{u}_i||_2 \leq \rho \}, \boldsymbol{\Delta}_i : k_i \times n, \boldsymbol{u}_i : k_i \times 1.$
- RC:

max
$$\mathbf{c}'\mathbf{x}$$

s.t. $\mathbf{\overline{a}}_{i}'\mathbf{x} + \rho||\mathbf{\Delta}_{i}\mathbf{x}||_{2} \leq b_{i}, \quad i = 1, \dots, m.$
 $\mathbf{x} \geq \mathbf{0}, \ x_{i} \in \mathcal{Z}, \ i = 1, \dots, k.$

- RMIO reduces to Mixed Integer Second order cone problem.
- Current versions of CPLEX and Gurobi support it, but more difficult than MIO.



Row-wise Budget of Uncertainty

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- Uncertainty for matrix A: a_{ij} , $j \in J_i$ is independent, symmetric and bounded random variable (but with unknown distribution) \tilde{a}_{ij} , $j \in J_i$ that takes values in $[a_{ij} \hat{a}_{ii}, a_{ij} + \hat{a}_{ii}]$.
- Uncertainty for cost vector c: c_j , $j \in J_0$ takes values in $[c_j, c_j + d_j]$.

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Budget of Uncertainty

- Consider an integer $\Gamma_i \in [0, |J_i|]$, $i = 0, 1, \dots, m$.
- Γ_i adjusts the robustness of the proposed method against the level of conservativeness of the solution.
- Unlikely that all of the a_{ij} , $j \in J_i$ will change. We want to be protected against all cases that up to Γ_i of the a_{ij} 's are allowed to change.
- Nature will be restricted in its behavior, in that only a subset of the coefficients will change in order to adversely affect the solution.
- We will guarantee that if nature behaves like this then the robust solution will be feasible deterministically. Even if more than Γ_i change, then the robust solution will be feasible with very high probability.

RMIO

$$\begin{aligned} RMIO: & \text{minimize} & \quad \boldsymbol{c'x} + \max_{\{S_{\mathbf{0}} \mid S_{\mathbf{0}} \subseteq J_{\mathbf{0}}, |S_{\mathbf{0}}| \leq \Gamma_{\mathbf{0}}\}} \left\{ \sum_{j \in S_{\mathbf{0}}} d_{j} |x_{j}| \right\} \\ & \text{subject to} & \quad \sum_{j} a_{ij} x_{j} + \max_{\{S_{i} \mid S_{i} \subseteq J_{i}, |S_{i}| \leq \Gamma_{i}\}} \left\{ \sum_{j \in S_{i}} \hat{a}_{ij} |x_{j}| \right\} \leq b_{i}, & \forall i \\ & \quad \boldsymbol{x} \geq \boldsymbol{0}, & \quad x_{i} \in \mathcal{Z}, & i = 1, \dots, k. \end{aligned}$$

Proof

• Given a vector x*, we define:

$$\beta_i(\boldsymbol{x^*}) = \max_{\{S_i | S_i \subseteq J_i, |S_i| = \Gamma_i\}} \left\{ \sum_{j \in S_i} \hat{a}_{ij} |x_j^*| \right\}.$$

This equals to:

$$\beta_{i}(\mathbf{x}^{*}) = \max \sum_{j \in J_{i}} \hat{a}_{ij} |x_{j}^{*}| z_{ij}$$
s.t.
$$\sum_{j \in J_{i}} z_{ij} \leq \Gamma_{i}$$

$$0 < z_{ii} < 1 \quad \forall i, j \in J_{i}.$$

• Dual:

$$\beta_{i}(\boldsymbol{x}^{*}) = \min \sum_{j \in J_{i}} p_{ij} + \Gamma_{i} z_{i}$$
s.t.
$$z_{i} + p_{ij} \geq \hat{a}_{ij} |x_{j}^{*}| \quad \forall j \in J_{i}$$

$$p_{ij} \geq 0 \qquad \forall j \in J_{i}$$

$$z_{i} \geq 0 \qquad \forall i.$$

Size

- Original Problem has n variables and m constraints
- RC has 2n + m + l variables, where $l = \sum_{i=0}^{m} |J_i|$ is the number of uncertain coefficients, and 2n + m + l constraints.
- Sparsity is preserved, attractive!



Probabilistic Guarantees

- x* an optimal solution of RMIO.
- $\tilde{a}_{ij}, j \in J_i$ independent, symmetric and bounded random variables, support $[a_{ij} \hat{a}_{ij}, a_{ij} + \hat{a}_{ij}]$.

$$\Pr\left(\sum_{j} \tilde{a}_{ij} x_{j}^{*} > b_{i}\right) \leq \frac{1}{2^{n}} \left\{ (1 - \mu) \sum_{l = \lfloor \nu \rfloor}^{n} \binom{n}{l} + \mu \sum_{l = \lfloor \nu \rfloor + 1}^{n} \binom{n}{l} \right\},$$

 $n = |J_i|$, $\nu = \frac{\Gamma_i + n}{2}$ and $\mu = \nu - \lfloor \nu \rfloor$; bound is tight.

• As $n \to \infty$

$$\frac{1}{2^n}\left\{(1-\mu)\sum_{l=\lfloor\nu\rfloor}^n\binom{n}{l}+\mu\sum_{l=\lfloor\nu\rfloor+1}^n\binom{n}{l}\right\}\sim 1-\Phi\left(\frac{\Gamma_i-1}{\sqrt{n}}\right).$$

$ J_i $	Γį
5	5
10	8.3565
100	24.263
200	33.899

Experimental Results

Knapsack Problem

maximize
$$\sum_{i \in N} c_i x_i$$
subject to
$$\sum_{i \in N} w_i x_i \le b$$
$$\mathbf{x} \in \{0, 1\}^n.$$

- \tilde{w}_i independently distributed and follow symmetric distributions in $[w_i \delta_i, w_i + \delta_i]$;
- c is not subject to data uncertainty.
- |N| = 200, b = 4000,
- w_i randomly chosen from $\{20, 21, \ldots, 29\}$.
- c_i randomly chosen from $\{16, 17, \ldots, 77\}$.
- $\delta_i = 0.1 w_i$.



Experimental Results. continued

Г	Violation Probability	Optimal Value	Reduction
0	0.5	5592	0%
2.8	0.449	5585	0.13%
36.8	5.71×10^{-3}	5506	1.54%
82.0	5.04×10^{-9}	5408	3.29%
200	0	5283	5.50%

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Robust 0-1 Optimization

• Nominal 0-1 optimization:

minimize
$$c'x$$

subject to $x \in X \subset \{0,1\}^n$.

Reformulation:

$$Z^* = \text{minimize} \quad \boldsymbol{c'x} + \max_{\{S \mid S \subseteq J, |S| \le \Gamma\}} \sum_{j \in S} d_j x_j$$
 subject to $\boldsymbol{x} \in X$,

Contrast

• Other approaches to robustness are hard. Scenario based uncertainty:

minimize
$$\max(c'_1x, c'_2x)$$
 subject to $x \in X$.

is NP-hard for the shortest path problem.

• $d_1 > d_2 > \ldots > d_n$. Optimal robust solution is

$$Z^* = \min_{l=1,...,n+1} d_l \Gamma + \min_{x \in X} \sum_{j=1}^n c_j x_j + \sum_{j=1}^l (d_j - d_l) x_j.$$

• Thus, if nominal problem is polynomially solvable the robust problem is also.

Proof

Primal :
$$Z^* = \min_{\mathbf{x} \in X} \mathbf{c'x} + \max \sum_{j} d_j x_j u_j$$

s.t. $0 \le u_j \le 1$, $\forall j$

$$\sum_{j} u_j \le \Gamma$$
Dual : $Z^* = \min_{\mathbf{x} \in X} \mathbf{c'x} + \min \quad \theta \Gamma + \sum_{j} y_j$
s.t. $y_j + \theta \ge d_j x_j$, $\forall j$
 $y_j, \theta \ge 0$

Proof, continued

• Solution: $y_j = \max(d_j x_j - \theta, 0)$

$$Z^* = \min_{\mathbf{x} \in X, \theta \geq 0} \theta \Gamma + \sum_j \left(c_j x_j + \max(d_j x_j - \theta, 0) \right)$$

• Since $X \subset \{0,1\}^n$,

$$\max(d_j x_j - \theta, 0) = \max(d_j - \theta, 0) x_j$$

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$$Z^* = \min_{\mathbf{x} \in X, \theta \ge 0} \theta \Gamma + \sum_{j} (c_j + \max(d_j - \theta, 0)) x_j$$



Proof, continued

- $d_1 \geq d_2 \geq \ldots \geq d_n \geq d_{n+1} = 0$.
- For $d_l \geq \theta \geq d_{l+1}$,

$$\min_{\mathbf{x}\in X, d_i\geq \theta\geq d_{i+1}}\theta\Gamma+\sum_{j=1}^n c_jx_j+\sum_{j=1}^l (d_j-\theta)x_j=$$

$$d_{l}\Gamma + \min_{\mathbf{x} \in X} \sum_{j=1}^{n} c_{j}x_{j} + \sum_{j=1}^{l} (d_{j} - d_{l})x_{j} = Z_{l}$$

$$Z^* = \min_{l=1,...,n+1} d_l \Gamma + \min_{\mathbf{x} \in X} \sum_{j=1}^n c_j x_j + \sum_{j=1}^l (d_j - d_l) x_j.$$

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Algorithm A

- Input: Vectors $c, d \in \Re_+^n$, an integer Γ , and a polynomial time algorithm that solves the problem $Z = \min c'x$ subject to $x \in X \subseteq \{0,1\}^n$ for all $c \ge 0$.
- Output: A solution $x^* \in X$ such that $x^* = \operatorname{argmin} \left(c'x + \max_{\{S \mid S \subseteq J, |S| = \Gamma\}} \sum_{j \in S} d_j x_j \right).$

Algorithm A, continued

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1 : x^1 \leftarrow \arg \min\{c'x : x \in X\}
2 : FOR l \in 2, ..., r
3 : IF d_l < d_{l-1}
4 : \mathbf{x}^{I} \leftarrow \arg\min\{\mathbf{c}^{\prime}\mathbf{x} + \sum_{j=1}^{I} (d_{j} - d_{l})x_{j} : x \in X\}

5 : Z_{l} \leftarrow \mathbf{c}^{\prime}\mathbf{x}^{I} + \max_{\{S \mid S \subseteq J, |S| = \Gamma\}} \sum_{j \in S} d_{j}x_{j}^{I}
6 : ELSE
7 : x^{l} \leftarrow x^{l-1}
8 : Z_{l} \leftarrow Z_{l-1}
9 : END IF
  10 : END FOR
```

Algorithm A, continued

11 :
$$\mathbf{x}^{r+1} \leftarrow \arg\min\{\mathbf{c}'\mathbf{x} + \sum_{j \in J} d_j x_j : x \in X\}$$

12 : $Z_{r+1} \leftarrow \mathbf{c}'\mathbf{x}^{r+1} + \max_{\{S \mid S \subseteq J, |S| = \Gamma\}} \sum_{j \in S} d_j x_j^{r+1}$
13 : $\pi \leftarrow \arg\min\{Z_j : j \in J \cup \{r+1\}\}$
14 : $Z^* = Z_{\pi} : \mathbf{x}^* = \mathbf{x}^{\pi}$.

Theorem

- Algorithm A correctly solves the robust 0-1 optimization problem.
- It requires at most |J|+1 solutions of nominal problems. Thus, If the nominal problem is polynomially time solvable, then the robust 0-1 counterpart is also polynomially solvable.
- Robust minimum spanning tree, minimum assignment, minimum matching, shortest path and matroid intersection, are polynomially solvable.

Robust Approximation Algorithms

- If the nominal problem is α -approximable, is the robust counterpart also α -approximable?
- Use an α -approximate solution to

$$\min_{\mathbf{x} \in X} \sum_{j=1}^{n} c_j x_j + \sum_{j=1}^{l} (d_j - d_l) x_j.$$

• Theorem: Overall algorithm is α -approximate.

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Ellipsoidal Uncertainty

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$$\min_{\mathbf{x} \in X} \mathbf{c'x} + \max_{\tilde{\mathbf{s}} \in D} \tilde{\mathbf{s'}x}$$

- $D = \{ s : \| \Sigma^{-1/2} s \|_2 \le \Omega \}$
- Equivalent to:

$$\min_{\mathbf{x} \in X} \mathbf{c'x} + \Omega \sqrt{\mathbf{x'} \mathbf{\Sigma} \mathbf{x}}$$

- Σ is the covariance matrix of the random cost coefficients: NP-hard
- D a polyhedron: NP-hard.

Uncorrelated uncertainty

• For $\Sigma = diag(d_1^2, \dots, d_n^2)$,

$$Z^* = \min_{\mathbf{x} \in X} \mathbf{c'x} + \Omega \sqrt{\mathbf{d'x}}$$

Complexity Open.

• Theorem: For $d_1 = \ldots = d_n = \sigma$,

$$Z^* = \min_{w=0,1,\ldots,n} Z(w),$$

$$Z(w) = \begin{cases} \min_{\mathbf{x} \in X} & \left(\mathbf{c} + \frac{\Omega \sigma}{2\sqrt{w}} \mathbf{e}\right)' \mathbf{x} + \frac{\Omega \sigma \sqrt{w}}{2} & w = 1, \dots, n \\ \min_{\mathbf{x} \in X} & \left(\mathbf{c} + \Omega \sigma \mathbf{e}\right)' \mathbf{x} & w = 0. \end{cases}$$

Practical algorithm

- Until $\|x^{k+1} x^k\| \le \epsilon$, set $x^{k+1} := \arg\min_{y \in X} (c + \frac{\Omega}{2\sqrt{d'x^k}}d)'y$
- Output x^{k+1}
- Experimented on Shortest Path Problems, Uniform Matroid and Knapsack Problems, under randomly generated cost vectors in dimensions from 200 to 20,000.
- In 998 out of 1000 instances, optimal solution is found in solving less than 6 nominal problems!

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Robust Network Flows

Nominal

$$\begin{aligned} & \min & & \sum_{(i,j) \in \mathcal{A}} c_{ij} x_{ij} \\ & \text{s.t.} & & \sum_{\{j: (i,j) \in \mathcal{A}\}} x_{ij} - \sum_{\{j: (j,i) \in \mathcal{A}\}} x_{ji} = b_i & \forall i \in \mathcal{N} \\ & & 0 \leq x_{ij} \leq u_{ij} & \forall (i,j) \in \mathcal{A}. \end{aligned}$$

- X set of feasible solutions flows.
- Robust

$$Z^* = \min \quad \boldsymbol{c'x} + \max_{\{S \mid S \subseteq \mathcal{A}, |S| \le \Gamma\}} \sum_{(i,j) \in S} d_{ij} x_{ij}$$
 subject to $\boldsymbol{x} \in X$.



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Theorem

For any fixed $\Gamma \leq |\mathcal{A}|$ and every $\epsilon > 0$, we can find a solution $\hat{\mathbf{x}} \in X$:

$$\hat{Z} = \boldsymbol{c}'\hat{\boldsymbol{x}} + \max_{\{S \mid S \subseteq \mathcal{A}, |S| \le \Gamma\}} \sum_{(i,j) \in S} d_{ij}\hat{x}_{ij}$$

such that

$$Z^* \leq \hat{Z} \leq (1+\epsilon)Z^*$$

by solving $2\lceil \log_2(|\mathcal{A}|\overline{\theta}/\epsilon) \rceil + 3$ network flow problems, where $\overline{\theta} = \max\{u_{ij}d_{ij} : (i,j) \in \mathcal{A}\}.$