

CSCI3160 Design and Analysis of Algorithms (2025 Fall)

SSSP with Arbitrary Weights

Instructor: Xiao Liang¹

Department of Computer Science and Engineering
The Chinese University of Hong Kong

¹These slides are primarily based on materials prepared by Prof. Yufei Tao (please refer to [Prof. Tao's version from 2024 Fall](#) for the original content). Some modifications have been made to better align with this year's teaching progress, incorporating student feedback, in-class interactions, and my own teaching style and research perspective.

What we have so far

Shortest path problem:

- ① Non-negative weights: Dijkstra's algorithm
- ② Negative weights:
 - ① negative cycles:
 - Shortest Paths are not well-defined.
 - Shortest Simple Paths are well defined. **However, this is a NP-hard problem.**
 - ② no negative cycles:
 - Shortest Paths are well-defined.
 - **But Dijkstra's algorithm does not work.**

What should we do with graphs that contain no negative cycles?

- **Bellman-Ford algorithm** (this lecture).

Problem Statement

SSSP Problem: Let $G = (V, E)$ be a directed simple graph, where function w maps every edge of E to an arbitrary integer. **It is guaranteed that G has no negative cycles.** Given a **source vertex s** in V , we want to find a shortest path from s to t for every vertex $t \in V$ reachable from s .

The output is a **shortest path tree T** :

- The vertex set of T contains all vertices reachable from s .
- The root of T is s .
- For each node $u \in V$, the root-to- u path of T is a shortest path from s to u in G .

We will learn the **the Bellman-Ford algorithm** that solves this problem in $O(|V||E|)$ time.

Note:

- We will focus on **computing $spdist(s, v)$** , namely, the shortest path distance from the source vertex s to every vertex $v \in V$.
- Constructing the shortest paths is easy and will be left to you.

Bellman-Ford Algorithm

Recalling Edge Relaxation

We begin by recalling the Edge Relaxation procedure introduced when studying Dijkstra's algorithm.

Edge Relaxation

Relaxing an edge (u, v) means:

- If $dist(v) \leq dist(u) + w(u, v)$, do nothing;
- Otherwise, reduce $dist(v)$ to $dist(u) + w(u, v)$.

Algorithm Description

The Bellman-Ford algorithm

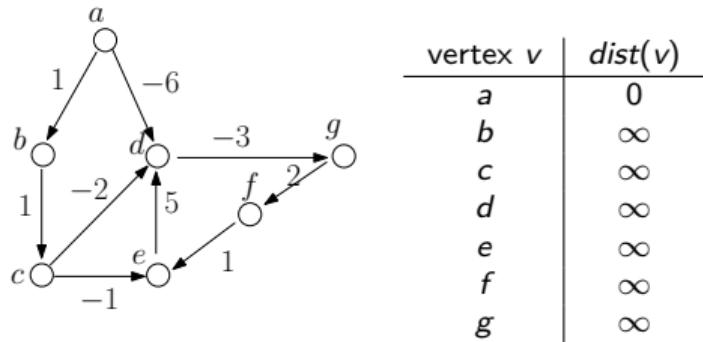
- ① Set $dist(s) \leftarrow 0$, and $dist(v) \leftarrow \infty$ for each vertex $v \in V \setminus \{s\}$
- ② Repeat the following $|V| - 1$ times
 - Relax all edges in E (the relaxation order does not matter)

Dijkstra's algorithm (for comparison):

- ① Set $dist(s) \leftarrow 0$ and $dist(v) \leftarrow \infty$ for each vertex $v \in V \setminus \{s\}$
- ② Set $S \leftarrow V$
- ③ Repeat the following until S is empty:
 - Remove from S the vertex u with the smallest $dist(u)$.
 - Relax every outgoing edge (u, v) of u .

Example

Suppose that the source vertex is a .



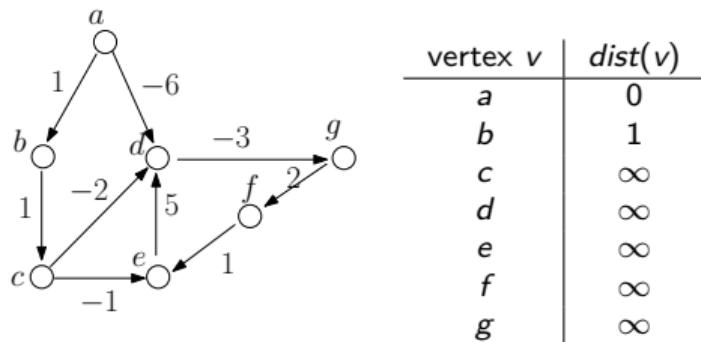
For illustration purposes, we will relax the edges in alphabetic order shown below:

$(a, b), (a, d), (b, c), (c, d), (c, e), (d, g), (e, d), (f, e), (g, f)$.

Example

Relaxing all edges for the **first time**.

Here is what happens after relaxing (a, b) :



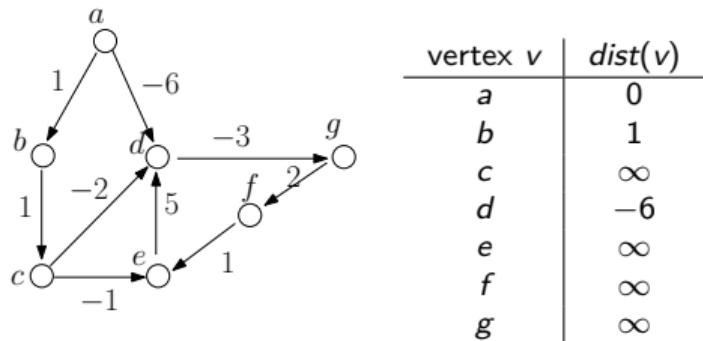
Alphabetic order of the edges in the graph:

$$(a, b), (a, d), (b, c), (c, d), (c, e), (d, g), (e, d), (f, e), (g, f).$$

Example

Relaxing all edges for the **first time**.

Here is what happens after relaxing (a, d) :



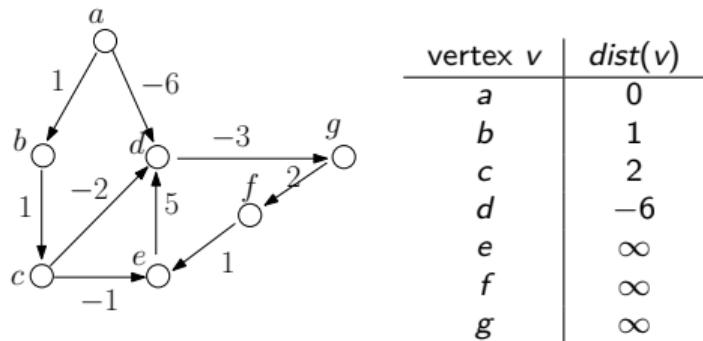
Alphabetic order of the edges in the graph:

$$(a, b), (a, d), (b, c), (c, d), (c, e), (d, g), (e, d), (f, e), (g, f).$$

Example

Relaxing all edges for the **first time**.

Here is what happens after relaxing (b, c) :



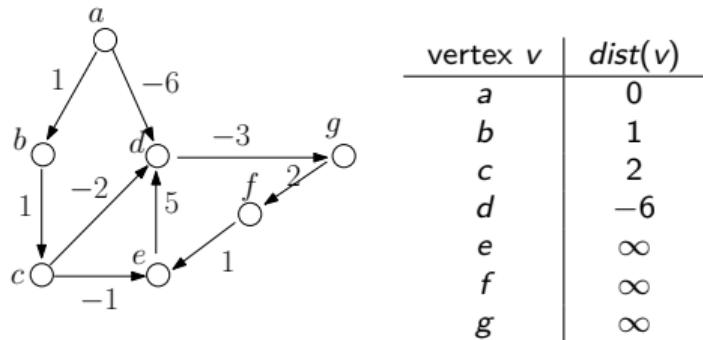
Alphabetic order of the edges in the graph:

$$(a, b), (a, d), (b, c), (c, d), (c, e), (d, g), (e, d), (f, e), (g, f).$$

Example

Relaxing all edges for the **first time**.

Here is what happens after relaxing (c, d) :



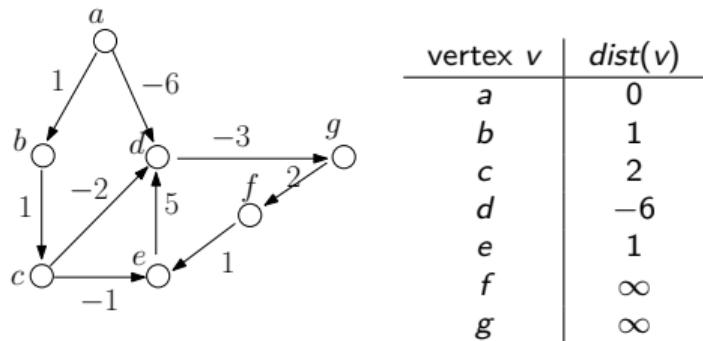
Alphabetic order of the edges in the graph:

$$(a, b), (a, d), (b, c), (c, d), (c, e), (d, g), (e, d), (f, e), (g, f).$$

Example

Relaxing all edges for the **first time**.

Here is what happens after relaxing (c, e) :



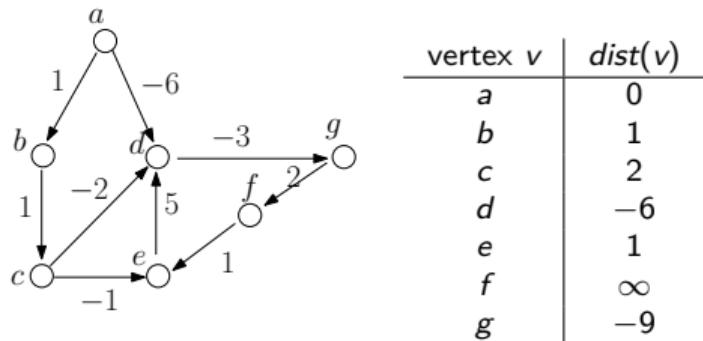
Alphabetic order of the edges in the graph:

$$(a, b), (a, d), (b, c), (c, d), (c, e), (d, g), (e, d), (f, e), (g, f).$$

Example

Relaxing all edges for the **first time**.

Here is what happens after relaxing (d, g) :



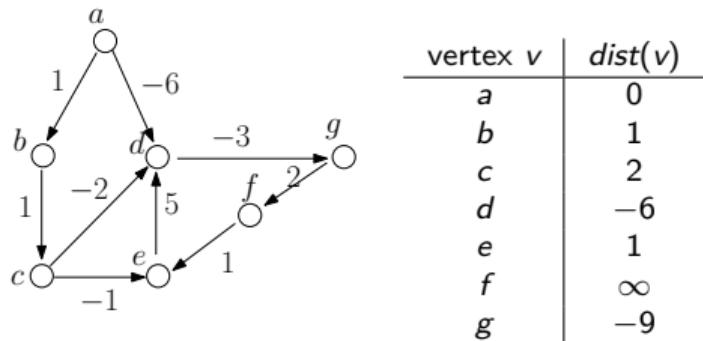
Alphabetic order of the edges in the graph:

$$(a, b), (a, d), (b, c), (c, d), (c, e), (d, g), (e, d), (f, e), (g, f).$$

Example

Relaxing all edges for the **first time**.

Here is what happens after relaxing (e, d) :



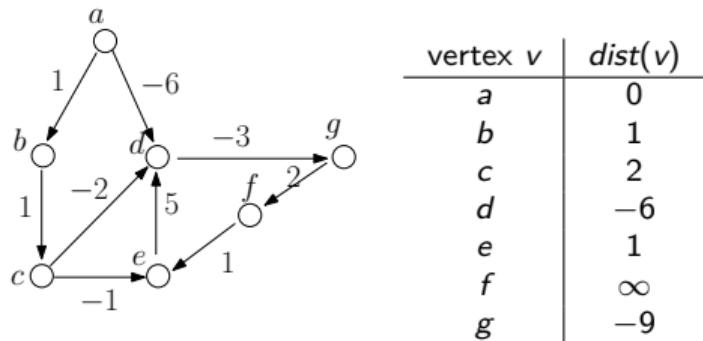
Alphabetic order of the edges in the graph:

$$(a, b), (a, d), (b, c), (c, d), (c, e), (d, g), (e, d), (f, e), (g, f).$$

Example

Relaxing all edges for the **first time**.

Here is what happens after relaxing (f, e) :



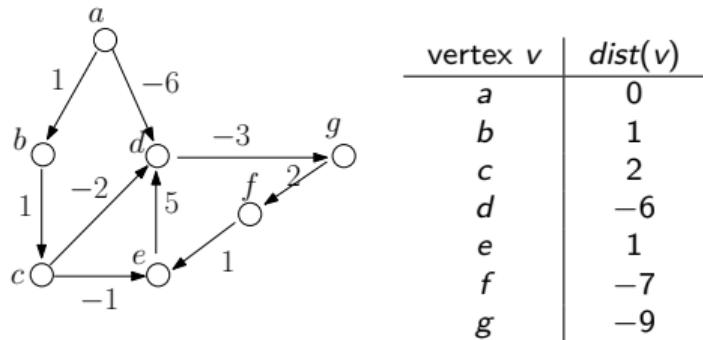
Alphabetic order of the edges in the graph:

$$(a, b), (a, d), (b, c), (c, d), (c, e), (d, g), (e, d), (f, e), (g, f).$$

Example

Relaxing all edges for the **first time**.

Here is what happens after relaxing (g, f) :



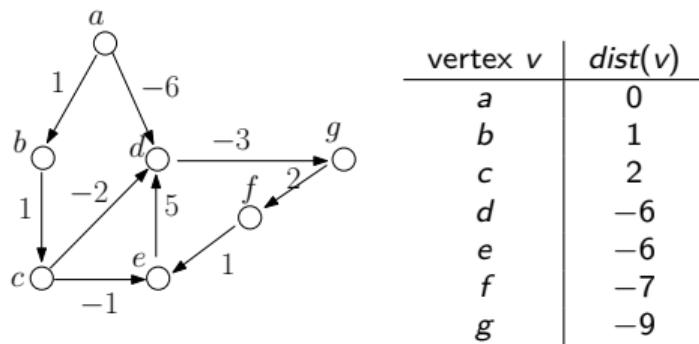
Alphabetic order of the edges in the graph:

$$(a, b), (a, d), (b, c), (c, d), (c, e), (d, g), (e, d), (f, e), (g, f).$$

Example

In the same fashion, relax all edges for a **second time**.

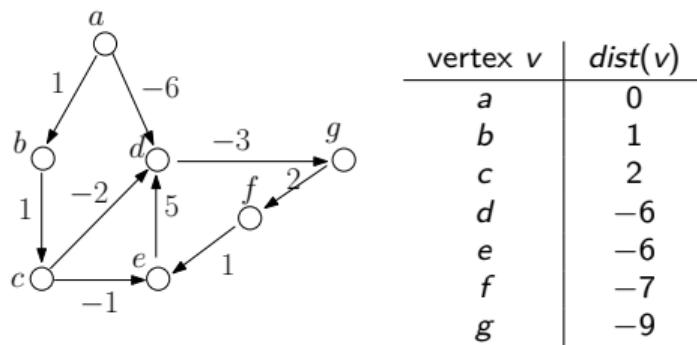
Here is the content of the table at the end of this relaxation round:



Example

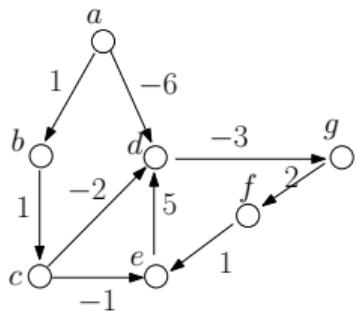
In the same fashion, relax all edges for a **third time**.

Here is the content of the table at the end of this relaxation round (no changes from the previous round):



Example

In the same fashion, relax all edges for a **fourth time**, **fifth time**, and then a **sixth time**. No more changes to the table:



vertex v	$dist(v)$
a	0
b	1
c	2
d	-6
e	-6
f	-7
g	-9

The algorithm then terminates here with the above values as the final shortest path distances.

Remark: We did 6 rounds only to follow the algorithm description faithfully. As a heuristic, we can stop as soon as no changes are made to the table after some round.

Time

The running time is clearly $O(|V||E|)$.

Proof of Correctness

Correctness

Lemma: For every vertex $v \in V$ such that $v \neq s$, at least one shortest path from s to v is a **simple path**, namely, a path where no vertex appears twice.

The proof is left to you — note that you must use the condition that no negative cycles are present.

Corollary: For every vertex $v \in V$, there is a shortest path from s to v having at most $|V| - 1$ edges.

Correctness

Theorem: Consider any vertex v ; suppose that there is a shortest path from s to v that has ℓ edges. Then, after ℓ rounds of edge relaxations, it must hold that $dist(v) = spdist(v)$.

Convince yourself that this theorem (with the previous corollary) establishes the correctness of Bellman-Ford.

Proof:

We will prove the theorem by induction on ℓ . If $\ell = 0$, then $v = s$, in which case the theorem is obviously correct. Next, assuming the statement's correctness for $\ell < i$ where i is an integer at least 1, we will prove it holds for $\ell = i$ as well.

Denote by π the shortest path from s to v , namely, π has i edges.

Let p be the vertex right before v on π .

By the inductive assumption, we know that $dist(p)$ was already equal to $spdist(p)$ after the $(i - 1)$ -th round of edge relaxations.

In the i -th round, by relaxing edge (p, v) , we make sure:

$$\begin{aligned} dist(v) &\leq dist(p) + w(p, v) \\ &= spdist(p) + w(p, v) \\ &= spdist(v). \end{aligned}$$

In the above:

- The first “=”: $dist(p)$ is already the shortest path after the $(i - 1)$ -th round.
 - Note that the shortest path from s to p must coincide with π (**Think: why?**)
- The second “=”: by the definition of π and p .

