

CSCI3160 Design and Analysis of Algorithms (2025 Fall)

Dynamic Programming 2: Rod Cutting

Instructor: Xiao Liang¹

Department of Computer Science and Engineering
The Chinese University of Hong Kong

¹These slides are primarily based on materials prepared by [Prof. Yufei Tao](#) (please refer to [Prof. Tao's version from 2024 Fall](#) for the original content). Some modifications have been made to better align with this year's teaching progress, incorporating student feedback, in-class interactions, and my own teaching style and research perspective.

The Rod Cutting Problem

Input:

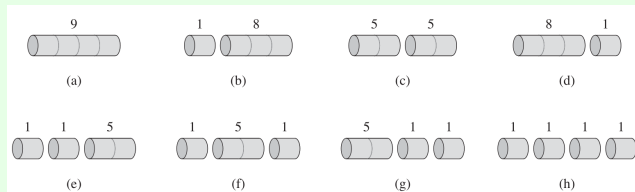
- a rod of length n
- an array P of length n where $P[i]$ is the price for a rod of length i , for each $i \in [1, n]$

Goal: Cut the rod into segments of integer lengths to maximize the revenue.

Example Consider a rod of length $n = 4$. Its price array P is given below

length i	1	2	3	4
price $P[i]$	1	5	8	9

All possible ways to cut a rod of length 4:



(by courtesy of the textbook [CLRS])

The optimal cutting method: (c), which has a revenue of 10

Subproblems! Subproblems! Subproblems!

The core trick of dynamic programming is to break the problem into subproblems that can be solved in a nice order that later subproblems can reuse the solutions of earlier subproblems.

With that in mind, when solving a problem by dynamic programming, the most crucial question is:

What are the proper subproblems?

Unfortunately, this step requires both experience and creativity. There is no universal method that guarantees you will always find the appropriate subproblems.

For our problem in hand: what are the proper subproblems for **rod cutting**?

A closer look at the earlier example

Its hardness seems to lie in that

- There are exponentially many (i.e., $O(2^n)$) possible ways to cut a rod, each with a different cost.
- So, it is hopeless to calculate the revenue for each of them to determine the best.

However, there are some crucial **structural** properties of this example:

- Despite of the exponentially many possible ways, the revenue of each way is calculated by add certain items of the price array P ; and the size of the array P is linear in n !
- In other words, the “exponentially many ways” is kind of misleading, in the sense that they are from different combinations of linearly many elements (i.e., P 's items).
- Also, certain ways of cutting are “perfectly symmetric,” and thus repetitive (e.g., (b)-(d) and (e)-(f)-(g)).

Ideas Exploiting the Structural Properties

The previous discussion of the structural properties of this problem inspires the following idea:

- We design subproblems as rod-cutting of smaller size
- It is possible that once we calculate the solution for a length i rod, we can store it so that it will contribute when we cut a length j rod with $j > i$

It turns out that this idea lead to a successful dynamic programming algorithm (subsequent slides).

Caveat: this step is indeed somewhat magical. This is the step that requires experience and creativity.

Define $opt(n)$ as the optimal revenue from cutting up a rod of length n .

Clearly, $opt(0) = 0$.

Consider now $n \geq 1$.

Let i be the length of the first segment.

- i can be any integer in $[1, n]$.

Conditioned on the first segment having length i , the highest revenue attainable is $P[i] + opt(n-i)$.

Therefore:

$$opt(n) = \max_{i=1}^n (P[i] + opt(n-i))$$

Given

$$\text{opt}(n) = \max_{i=1}^n (P[i] + \text{opt}(n - i))$$

we can compute $\text{opt}(n)$ in $O(n^2)$ time using dynamic programming (this is the problem solved in the last lecture).

Wait! We need to **generate** a cutting method to achieve revenue $\text{opt}(n)$.

This can be done by recording which subproblem yields $\text{opt}(n)$.

See the next slide.

Piggyback I

Given

$$\text{opt}(n) = \max_{i=1}^n (P[i] + \text{opt}(n-i))$$

define *bestSub*(n) = k if maximization is obtained at $i = k$ (i.e., first segment having length k).

Example

length i	1	2	3	4
price $P[i]$	1	5	8	9
$\text{opt}(i)$	1	5	8	10
$\text{bestSub}(i)$	1	2	3	2

If we have computed $\text{bestSub}(i)$ for every $i \in [1, n]$, then the best method for cutting up a rod of length n can be obtained in $O(n)$ time. (Think: how?)

Piggyback II

You can use another array to store the values of *bestSub* in the pseudo code shown in the last lecture. (Think: how?)

For each $i \in [1, n]$, computing *bestSub*(i) is no more expensive than computing *opt*(i).

We conclude that the rod cutting problem can be solved in $O(n^2)$ time.

The method of using the *bestSub* function to generate an optimal cutting is known as the **piggyback** technique.

Closing Remarks

Recall our train of thoughts when tackling the rod cutting problem:

- Distill the problem in a clean mathematically form.
- Take initial experiments/attempts with small-size toy examples (e.g., $n = 4$), trying to understand the problem better.
- Distill some structural properties of the problem from our toy examples.
 - We could try to see if the properties can be generalized. They may not always. This is a trial-error step.
- These structural properties allow us to design a dynamic programming algorithm:
 - They inspire a good definition for subproblems.
 - Subproblems can be solved in a **nice order**, leading to the solution of the original rod cutting problem.

This pattern is typical in the design of dynamic programming algorithms. In fact, it is characteristic of the entire art of algorithm design!

Our philosophy on the design and exposition of algorithms is nicely illustrated by the following analogy with an aspect of Michelangelo's art. A major part of his effort involved looking for interesting pieces of stone in the quarry and staring at them for long hours to determine the form they naturally wanted to take. The chisel work exposed, in a minimalistic manner, this form. By analogy, we would like to start with a clean, simply stated problem (perhaps a simplified version of the problem we actually want to solve in practice). Most of the algorithm design effort actually goes into understanding the algorithmically relevant combinatorial structure of the problem. The algorithm exploits this structure in a minimalistic manner. ...

— cited from the preface of the book *Aproximation Algorithms* by Vijay V. Vazirani



Figure: Michelangelo's Moses (ca. 1513–15), for the Tomb of Julius II.