

Full-fledged Postulates

of (complex-number) \mathcal{H}

Postulate 1: An isolated quantum system is completely described by its vector of state, which is -a unit vector in a Hilbert space.

| Vector space (Real
Complex)
| inner-product space
| complete.

"mathematically correct" approach
to Linear Algebra!!!

$$\vec{u} = \begin{bmatrix} a \\ b \\ c \end{bmatrix} \quad \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$
$$\vec{v} \cdot \vec{w}$$

Modern Math is all about structure.

More basic Math structure?

- scale.
- numbers

=  Sets

What is a set? 



= sets: a collection of things

having a common property.

$$R = \{ s \mid s \in S \}$$

$$R \in R$$

{ Barber only cuts hairs for the

| people who don't cut hairs for
| themselves !

- Sir. Bertrand Russell.

Russell Paradox.

— (1901)

“axiomat set theories.”

- Zermelo-Fraenkel set theory
(ZF)

- Type Theory:

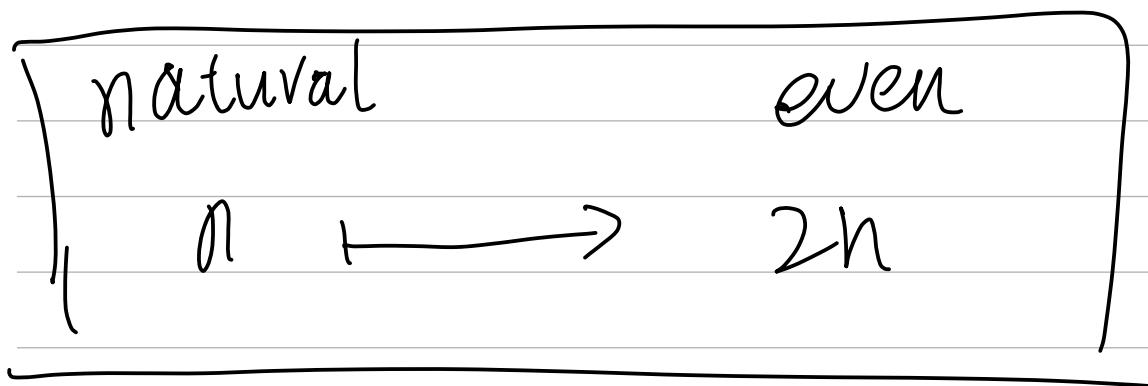
Countability:

① How do you compare
the # of even numbers v.s.

of odd numbers ?

② # even numbers v.s.

natural numbers ?



③ # natural numbers v.s.

rational numbers ?

④ # Naturals v.s.

Reals ?

" diagonalization "

Gödel's incompleteness theorems

L Undecidability.

- Alan Turing.

Magma:

$(M, "+")$

Set binary operation

I. (Closure)

$\forall a, b \in M, a + b \in M$

Semigroup:

$(M, "+")$

I. (closure)

2. (Associativity)

$\forall a, b, c \in M,$

$$(a+b)+c = a+(b+c)$$

Monoid: $(M, "+")$

① it's a semigroup

3. Identity Element:

$\exists e \in M$ s.t.

$$\forall a \in M \quad \underline{a+e = e+a = a}$$

Group: $(G, "+")$

1. Closure: - - - -

2. Associativity: - - -

3. Identity: $a + e = e + a = a$

4. Inverse element:

$\forall a \in G, \exists -a \in G,$

$$a + (-a) = (-a) + a = e$$

5. Commutativity:

$\forall a, b \in G$

$$a + b = b + a$$

L(optional). If satisfied

Abelian Group.

$G = \{ \text{Apple}, \text{Banana} \}$

"A"

"B"

Diagram illustrating a function or operation mapping elements from a domain to a codomain.

The domain is represented by the set $G = \{ \text{Apple}, \text{Banana} \}$.

The codomain is represented by the set $\{ A, B \}$.

The mapping is shown in the following table:

1st Operand	2nd	Result
A	B	B
A	A	A
B	A	A
B	B	B

$$(A \oplus A) \oplus B = A \oplus (A \oplus B)$$

Abelian Group

$$\boxed{\mathbb{Z}_7 = \{0, 1, 2, 3, \dots, 6\}}$$

"+": addition mod 7

(-2): by def:

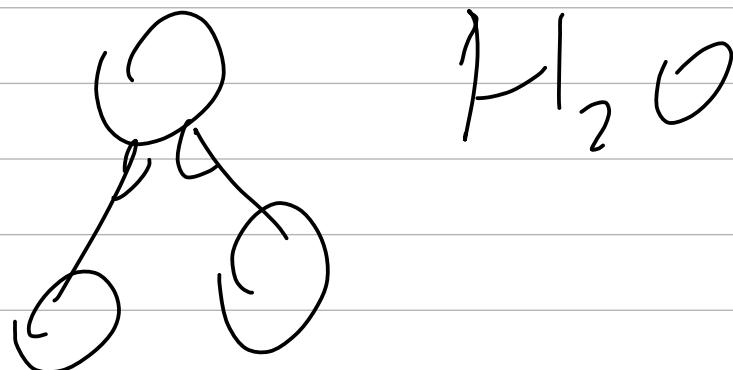
$$2 + \underbrace{(-2)}_5 = 0 \quad \text{mod } 7$$

Non-abelian Group:

↪ All 2×2 matrices over \mathbb{R} [$\det \neq 0$] under

standard matrix mult.

Groups are important:



Ring:

see (R , "+", ".")

- R is a abelian group

under "+"

- R is a monoid under "·".

$$- \left\{ \begin{aligned} a \cdot (b+c) &= a \cdot b + a \cdot c \\ (b+c) \cdot a &= b \cdot a + c \cdot a \end{aligned} \right.$$

L distributivfig:

" + "

$$R = \{a, b, c, \dots\}$$

$$\underline{R[x]} \neq \{a, b, c, \dots\} \cup \{x\}$$

$$\cup \{a+x\}$$

$$\cup \{a+bx\}$$

$$\cup \{ax, ax^2, ax^3, \dots\}$$

$$ax^2 + bx$$

Field: $(\mathbb{F}, +, \cdot)$

1. \mathbb{F} is abelian group " $+$ "

2. $\mathbb{F} \setminus \{\underline{e}\}$ is abelian group

under " \cdot "

3. " \cdot " is distributive w.r.t.

" $+$ "

$$a \cdot (b+c) = ab + ac$$

$$(b+c) \cdot a = b \cdot a + c \cdot a$$

$$a/b = a \cdot (b^{-1})$$

$$b \cdot b^{-1} = 1$$

$$x+b=c$$

$$ax^2+bx+c=0$$

T Galois' theorem

No closed-form formula

for eq. of degree ≥ 5

Modules: ~~R-module~~

T (R, M, +, ·)

2. $(M, +)$ is an abelian group

1.5 R is a ring under " \cdot "

$$2. \frac{a \cdot b = c}{P \quad P \quad P}$$

R M M

$\cdot : R \times M \rightarrow M$

$\forall r, s \in R, m, n \in M$

(a) $\underline{(r+s)} \cdot m = r \cdot m + s \cdot m$

(b) $(r \cdot s) \cdot m = r \cdot (s \cdot m)$

(c) $r \cdot \underline{(m+n)} = r \cdot m + r \cdot n$

(d) $\exists 1 \text{ (unity)}$

$1 \cdot m = m$.

Vector Space

Let \mathbb{F} be a field.

$\mathbb{C}\{\mathbb{R}, \mathbb{C}\}$

Let V be a set -

If \exists " $+$ ", " \cdot " s.t.

~~($\mathbb{F}, V, +, \cdot$)~~

form a module, then

$(V, +, \cdot)$ is called a vector space over \mathbb{F} .

In a vector space:

- What you can:

Span, linear indep.

$$\text{span}\{u, v\} = \{a \cdot u + b \cdot v \mid a, b \in F\}$$

basis, dimension,

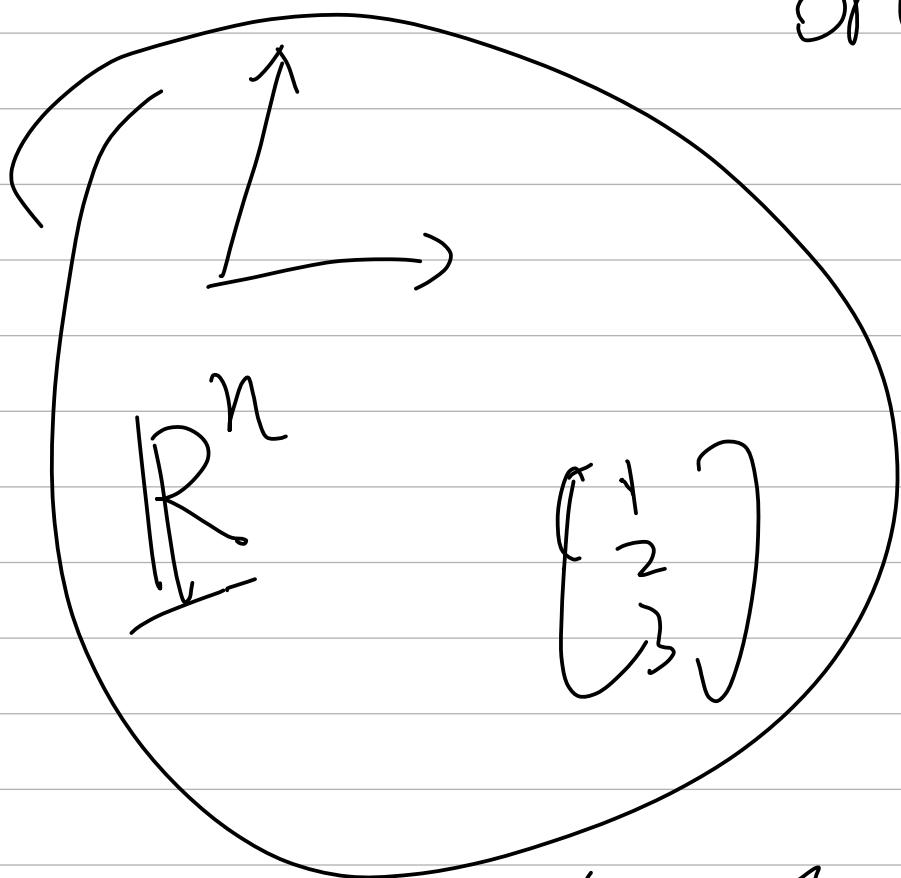
eigenvalues / vectors.

Linear operator.

- What you cannot:

Any geometry.

length, distance, degree,
orthogonality.



Vanilla Vec Space:

(without obvious
geometry)

Space $C[a, b]$:

| all continuous functions
| over interval $[a, b] \subset \mathbb{R}$

$f, g \in \underline{C(\bar{a}, b)}^T$ $a \in \underline{\mathbb{F}}$
 $\{\mathbb{R}, \mathbb{C}\}$

$$\left\{ \begin{array}{l} (f+g)(x) = f(x) + g(x) \\ (af)(x) = a \cdot f(x) \end{array} \right.$$

- IS A VEC SPAC \bar{E} .

Linear Operators:

Let V, W be two

vec. spaces (over $\mathbb{F} = \mathbb{C}$)

A linear operator/map/transform

is a function $T: \bar{V} \rightarrow W$

satisfying :

① Additivity: $\forall u, v \in \bar{V}$

$$T(u+v) = T(u) + T(v)$$

② Homogeneity:

$\forall v \in \bar{V}, \alpha \in F$

$$T(\alpha v) = \alpha \cdot T(v)$$

$$\bar{V} = \text{span } \{ \underline{v_1, \dots, v_n} \}$$

$$W = \text{span } \{ \underline{w_1, \dots, w_m} \}$$

$\forall k \in \{1 \dots n\}$

$$T(v_k) = a_{1k} \cdot w_1 + \dots + a_{mk} w_m$$

$\begin{matrix} \cap \\ W \end{matrix}$

$$T = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix}$$

Eigenvalue decom

tool to characterize

Square matrices

$T: V \rightarrow W$

of same dim.

$$T_{\vec{v}} = \lambda \cdot \vec{v} \quad \lambda \in \mathbb{F}$$

Def: (Diagonalizable)

Eigenvalue comp)

a $n \times n$ matrix A : over a field

\mathbb{F} . If \exists invertible matrix

P s.t. $\underline{(P^{-1} \cdot A \cdot P)}$ is

a diagonal matrix, then

A is diagonalizable.

$$\Lambda = P^{-1} A P = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$$

$$\Rightarrow A = P \Lambda P^{-1}$$

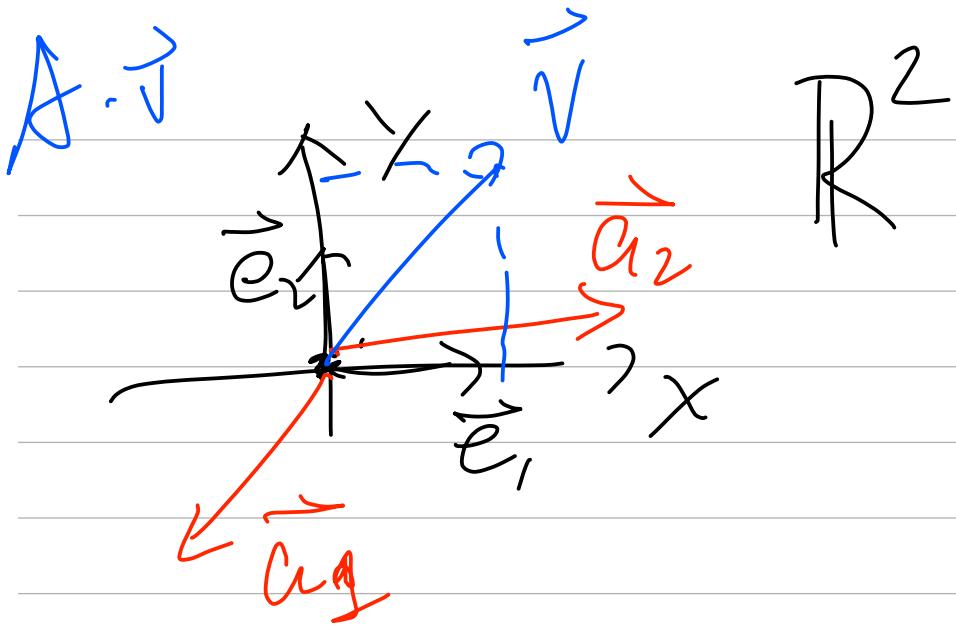
λ_i 's are eigenvalues
columns are eigenvectors of A .

$$\underline{A \vec{v} = (P \Lambda P^{-1}) \cdot \vec{v}}$$

$$= (P^{-1} \vec{v})$$

\uparrow
 Λ
 \uparrow
 P \rightarrow back to
 Original space

$$\vec{v} \in \mathcal{V} = \text{span } \{v_1, \dots, v_n\}$$



$$\vec{v} = \alpha_1 \cdot \vec{e}_1 + \alpha_2 \cdot \vec{e}_2$$

$$= (\beta_1 \cdot \vec{a}_1 + \beta_2 \cdot \vec{a}_2)$$

$$(P \cdot P^{-1})\vec{v}$$

$$A \cdot \vec{v} = P \Delta P^{-1} \vec{v} \Delta = [\beta_1 \quad \beta_2]$$

Only one rule to determine if A is

Diagonalizable:

- check # of linearly independent eigenvectors
- = $\dim(T)$

- T linear independent
is the most we can say
about a diagonalizable
A. the eigenvectors

They may not be
orthogonal to
each other.