

# Weekly Report

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# Faster Rcn 家族

## R-CNN

1. 用**计算**的方式找 ROIs
2. 对每个 ROI 卷积, 得到 bbox 和 class

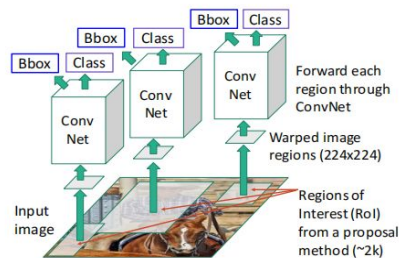
## Fast R-CNN

1. 先**卷积**, 得到 feature 空间, 再用**计算**的方式找 ROIs
2. 对每个 ROI 卷积, 得到 bbox 和 class

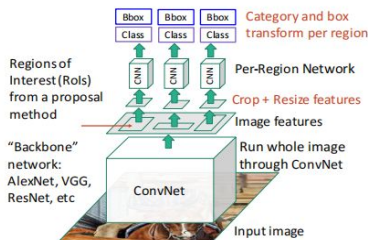
## Faster R-CNN

1. Region Proposal Network(**RPN**)直接对图片进行卷积, 得到 ROIs
2. 对每个 ROI 卷积, 得到 bbox 和 class

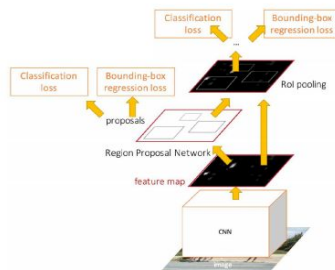
**“Slow” R-CNN:** Run CNN independently for each region



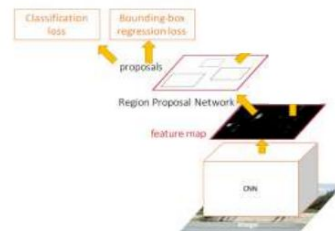
**Fast R-CNN:** Apply differentiable cropping to shared image features



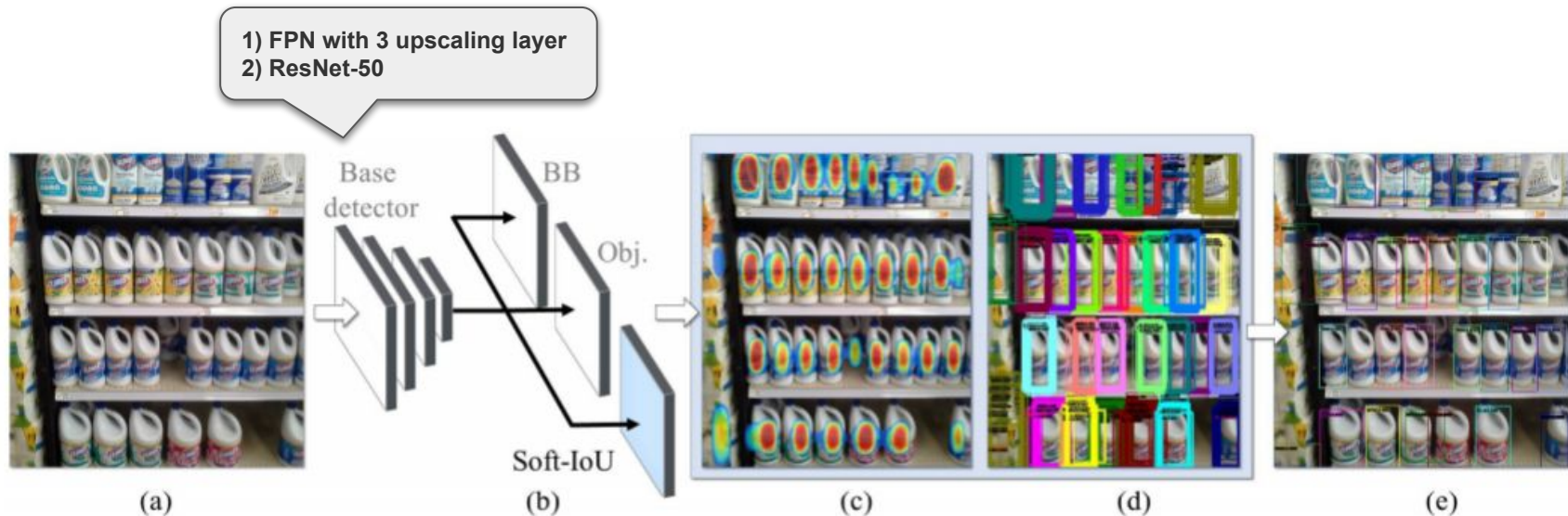
**Faster R-CNN:** Compute proposals with CNN



**Single-Stage:** Fully convolutional detector



# Precise Detection in Densely Packed Scenes



$$\mathcal{L}_{\text{sIoU}} = -\frac{1}{n} \sum_{i=1}^n [IoU_i \log(c_i^{\text{iou}}) + (1 - IoU_i) \log(1 - c_i^{\text{iou}})], \quad (2)$$

$$\mathcal{L} = \mathcal{L}_{\text{Classification}} + \mathcal{L}_{\text{Regression}} + \mathcal{L}_{\text{sIoU}}. \quad (3)$$

## EM-Merger:

1. converts **Soft-IoU to Gaussians**
2. **EM-approach**, minimize overall **KL** distance, to resolve best  $K$  gaussians
3. Produce one single detection per object, totally

$$K = \text{size}(\mathbf{I}) / (\mu_w \mu_h),$$

# Futher Reading

- **Focal loss** for dense object detection.
- A Solution to Product detection in Densely Packed Scenes.  
([Cascade R-CNN](#))(which performs No.1 on SKU-110K, better than [Soft-IoU + EM-Merger unit](#))
- [RetinaNet](#)
- Mask R-CNN
- KL distance

Dense Object Detection on SKU-110K

