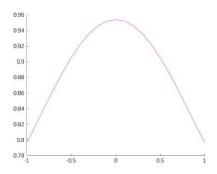
1.解 $u_t = bu_{xx}$ 的数值解,边界条件和初值条件用精确解,其精确解为

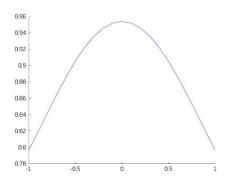
$$u(t,x) = \exp\left(\frac{-(x-y)^2}{4b(t+\tau)}\right)$$

在这里,我们取 $b=0.1, \tau=10$ ,y=0,其结果为

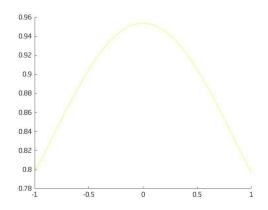
### C-N shame



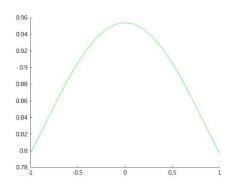
## forward-time central-space shame



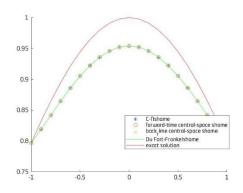
## back-time central-space shame



Du Fort-Frankel shame



将其放到一个图像中为:



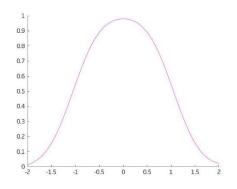
2. 画出方程 $u_t = bu_{xx}$ 的精确解

初值条件为
$$u_0(x) = \begin{cases} 1 & if |x| \le 1 \\ 0 & if |x| > 1 \end{cases}$$

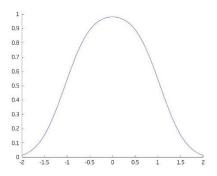
边界条件和初值条件用精确解, 其精确解为

$$u(t,x) = \frac{1}{2} \left( erf\left(\frac{a-x}{\sqrt{abt}}\right) + erf\left(\frac{a+x}{\sqrt{abt}}\right) \right)$$

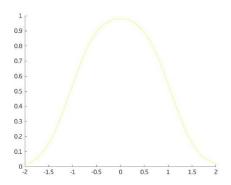
C-N shame



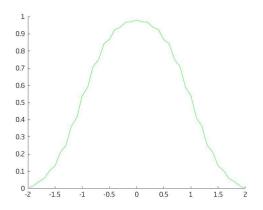
forward-time central-space shame



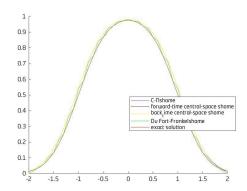
# back-time central-space shame



### Du Fort-Frankel shame



将上述四种方案与精确解放在一起,其图像为:



#### 附件 源代码

```
%%追赶法 Thomas Algorithm 解三对角矩阵
function [w] = TA(A, v, d)
%A为一个储存系数矩阵系数的矩阵,A的每一行分别代表a,b,c.
%v是一个二维向量,储存着w0和wm的值
%d代表线性方程组增广矩阵的最后一列
n=length(d);%n存储将要求解未知量的个数m-1个
p=zeros(1, n+1):
q=zeros(1, n+1);
w=zeros(1, n+2); %w0放在第一个位置, wi放在第i+1个位置
w(1) = v(1):
w(n+2)=v(2);
q(1)=v(1);%为p1,q1赋初值
for i=1:1:n %先求出pg的值
   p(i+1)=-1/(A(1)*p(i)+A(2))*A(3);
   q(i+1)=1/(A(1)*p(i)+A(2))*(d(i)-A(1)*q(i));
end
for j=n:-1:1
   w(j+1)=p(j+1)*w(j+2)+q(j+1);
end
end
%%n个未知量最后输出n+2个值
问题1的求解
clear all:
c1c
te=1:%所求的时刻
b=0.1:
tau=10;
y=0;
h=0.1;
nu=1/2:
k=nu*h*h;%%%可以修改
x=-1:h:1;
t=0:k:te:
ujingque=exp(-(x-y). ^2/(4*b*(te+tau)));%精确解
%%%%%%%%%%C—N格式
V=zeros(length(t), length(x));
V(1,:)=\exp(-(x-y).^2/(4*b*(0+tau)));%初值条件
A=ones(1,3);
A(1) = -b*nu/2;
                %存储a
A(2)= 1+b*nu ; %存储b
```

```
A(3) = -b * nu/2;
                  %存储c
d=zeros(1, length(x)-2):
for i=2:1:1ength(t)%/开始求每个时间所对应的值
v = [\exp(-(-1-y)^2/(4*b*(t(i)+tau))), \exp(-(1-y)^2/(4*b*(t(i)+tau)))]';
   for j=1:length(d)
d(j)=1/2*nu*b*V(i-1, j+2)+(1-b*nu)*V(i-1, j+1)+1/2*nu*b*V(i-1, j);
   end
   [V(i,:)]=TA(A, v, d); %%v, d在不同步骤中不同, 需要分别求
end
%%%%%%%当典显格式
V2=zeros(length(t), length(x));
V2(1,:)=\exp(-(x-y).^2/(4*b*(0+tau))):%初值条件
for i=2:1:1ength(t)%%开始求每个时间所对应的值
   V2(i, 1) = \exp(-(-1-y).^2/(4*b*(t(i)+tau)));
   V2(i, length(x)) = (exp(-(1-y).^2/(4*b*(t(i)+tau))));
   for i=2:1ength(x)-1
       V2(i, j) = (1-2*b*nu)*V2(i-1, j)+b*nu*(V2(i-1, j-1)+V2(i-1, j+1));
   end
end
%%%%%%%%%%%back time central-space格式
V3=zeros(length(t), length(x));
V3(1,:)=\exp(-(x-y).^2/(4*b*(0+tau)));%初值条件
A = ones(1, 3):
A(1) = -b*nu;
                  %存储a
A(2)= 1+2*b*nu ; %存储b
A(3) = -b*nu:
                %存储c
d=zeros(1, length(x)-2);
for i=2:1:1ength(t)%%开始求每个时间所对应的值
v = [\exp(-(-1-y)^2/(4*b*(t(i)+tau))), \exp(-(1-y)^2/(4*b*(t(i)+tau)))]';
   for j=1:length(d)
       d(j)=V(i-1, j+1);
   end
   [V3(i,:)]=TA(A, v, d): %%v, d在不同步骤中不同, 需要分别求
end
%%%%DFF格式
V4=zeros(length(t), length(x));
V4(1,:)=exp(-(x-y).^2/(4*b*(0+tau)));%初值条件
V4(2, :) = \exp(-(x-y).^2/(4*b*(k+tau)));%初值条件
for i=3:1:1ength(t)%%开始求每个时间所对应的值
   V4(i, 1) = \exp(-(-1-y)^2/(4*b*(t(i)+tau)));
   V4(i, length(x)) = (exp(-(1-v)^2/(4*b*(t(i)+tau)))):
```

```
for j=2:1ength(x)-1
V4(i, j)=1/(1+2*b*nu)*(2*b*nu*(V4(i-1, j+1)+V4(i-1, j-1))+(1-2*b*nu)*V4(i, j)=1/(1+2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*
i-2, j));
               end
end
hold on;
plot(x, (V(length(t), :))', '*');
plot(x, (V2(length(t), :))', 'o');
plot(x, (V3(length(t), :))', 'x');
plot(x, (V4(length(t), :))', 'g');
plot(x, ujingque, 'r');
legend('C-Nshame', 'forward-time central-space shame', 'back_time
central-space shame', 'Du Fort-Frankelshame', 'exact solution');
问题 2 的求解
clear all;
c1c
te=1;%所求的时刻
b=0.1;
tau=10;
y=0;
h=0.1;
nu=1/2;
k=nu*h*h;%%%可以修改
x=-2:h:2;
t=0:k:te;
ujingque=1/2*(erf((1-x)/sqrt(4*b*te))+erf((1+x)/sqrt(4*b*te)));%精确
%%%%初值条件
u0=zeros(1, length(x));
for i=(1/h+1):1:(3/h+1)
               u0(i)=1;
end
%%%%%%%%%%C—N格式
V=zeros(length(t), length(x));
V(1,:)=u0;%初值条件
```

```
A = ones(1, 3);
A(1) = -b*nu/2:
                     %存储a
A(2)= 1+b*nu ; %存储b
A(3) = -b * nu/2;
                   %存储c
d=zeros(1, length(x)-2);
for i=2:1:1ength(t)%%开始求每个时间所对应的值
v=[1/2*(erf((1-x)/sqrt(4*b*t(i)))+erf((1+x)/sqrt(4*b*t(i)))), 1/2*(erf((1-x)/sqrt(4*b*t(i))))]
((1-x)/sqrt(4*b*t(i)))+erf((1+x)/sqrt(4*b*t(i))));
    for j=1:length(d)
d(j)=1/2*nu*b*V(i-1, j+2)+(1-b*nu)*V(i-1, j+1)+1/2*nu*b*V(i-1, j);
   [V(i,:)]=TA(A, v, d); %%v, d在不同步骤中不同, 需要分别求
end
%%%%%%%******古典显格式
V2=zeros(length(t), length(x));
V2(1,:)=u0:%初值条件
for i=2:1:1ength(t)%/开始求每个时间所对应的值
V2(i, 1)=1/2*(erf((1-(-2))/sqrt(4*b*t(i)))+erf((1+(-2))/sqrt(4*b*t(i)))
);
V2(i, length(x)) = 1/2*(erf((1-2)/sqrt(4*b*t(i))) + erf((1+2)/sqrt(4*b*t(i)))
)));
    for j=2:1ength(x)-1
        V2(i, j) = (1-2*b*nu)*V2(i-1, j)+b*nu*(V2(i-1, j-1)+V2(i-1, j+1));
    end
end
%%%%%%%%%%%back time central-space格式
V3=zeros(length(t), length(x));
V3(1,:)=u0;%初值条件
A = ones(1, 3);
A(1) = -b*nu;
                   %存储a
A(2)= 1+2*b*nu ; %存储b
A(3) = -b*nu;
                 %存储c
d=zeros(1, length(x)-2);
for i=2:1:1ength(t)%/开始求每个时间所对应的值
v=[1/2*(erf((1-x)/sqrt(4*b*t(i)))+erf((1+x)/sqrt(4*b*t(i)))), 1/2*(erf((1-x)/sqrt(4*b*t(i))))]
((1-x)/sqrt(4*b*t(i)))+erf((1+x)/sqrt(4*b*t(i))));
    for j=1:length(d)
        d(j)=V(i-1, j+1);
    end
```

```
[V3(i,:)]=TA(A, v, d); %%v, d在不同步骤中不同, 需要分别求
end
%%%%DFF格式
V4=zeros(length(t), length(x));
V4(1,:)=u0;%初值条件
V4(2,:)=1/2*(erf((1-x)/sqrt(4*b*t(2)))+erf((1+x)/sqrt(4*b*t(2))));%初
值条件
for i=3:1:length(t)%%开始求每个时间所对应的值
V2(i, 1)=1/2*(erf((1-(-2))/sqrt(4*b*t(i)))+erf((1+(-2))/sqrt(4*b*t(i)))
);
V2(i, length(x)) = 1/2*(erf((1-2)/sqrt(4*b*t(i))) + erf((1+2)/sqrt(4*b*t(i)))
)));
              for j=2:1ength(x)-1
V4(i, j)=1/(1+2*b*nu)*(2*b*nu*(V4(i-1, j+1)+V4(i-1, j-1))+(1-2*b*nu)*V4(i, j)=1/(1+2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*(2*b*nu)*
i-2, j));
              end
end
hold on;
plot(x, (V(length(t), :))', 'm');
   plot(x, (V2(length(t), :))', 'b');
plot(x, (V3(length(t), :))', 'y');
   plot(x, (V4(length(t), :))', 'g');
plot(x, ujingque, 'r');
legend ('C-Nshame', 'forward-time central-space shame', 'back time
central-space shame', 'Du Fort-Frankelshame', 'exact solution');
```