

# 3WC-GBNRS++: A novel three-way classifier with granular-ball neighborhood rough sets based on uncertainty

## (Supplementary materials)

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This is the supplementary file for the paper entitled 3WC-GBNRS++: A novel three-way classifier with granular-ball neighborhood rough sets based on uncertainty in IEEE Transactions on Fuzzy Systems.

### S1 THE ORIGINAL GRANULAR-BALLS GENERATION METHOD

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**Algorithm S1:** The original granular-balls generation method [1]

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**Input:** Dataset  $\mathbb{D}$ , purity threshold  $p$ ;  
**Output:** The set of granular balls  $GB\_list$ .

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1 Initialize  $GB\_list = \{\}$ ;
2 Function Split_GB( $GB$ ):
3   if the purity of  $GB > p$  then
4     Add  $GB$  to the  $GB\_list$ ;
5   end
6   else
7      $GB_1, GB_2 \leftarrow GB$  is subdivided into two
       granular-balls by 2-means clustering algorithm;
8     Split_GB( $GB_1$ );
9     Split_GB( $GB_2$ );
10  end
11 return
12 Function Main( $\mathbb{D}$ ):
13   Turn  $\mathbb{D}$  to a granular ball  $GB$ ;
14   Split_GB( $GB$ );
15   return  $GB\_list$ ;
16 return

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In the process of generating granular-balls, Algorithm S1 introduces a purity threshold as a parameter to control the granularity. The purity threshold plays a crucial role in controlling the degree of granularity in the division of these granular-balls. The purity of a granular-ball can be determined by calculating the proportion of the majority label. If the purity of a granular-ball falls below the purity threshold, it will be divided again. Therefore, the higher the purity threshold, the higher the purity of the final generated granular-balls.

The process of threshold acquisition is shown in Algorithm S2. First, the quality index of each granular-ball in GBNRS++ is computed. Subsequently, the average fuzziness of  $\mathbb{X}_{\mathbb{R}}^J$  is determined. Next, based on the objective function, we calculate  $H_{\psi(\mathbb{X}_{\mathbb{R}}^J)}$  and  $|\bar{H}_{\psi(\mathbb{X}_{\mathbb{R}}^J)} - \bar{H}_{\mathbb{X}_{\mathbb{R}}^J}|$  under varying thresholds by ad-

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**Algorithm S2:** The process of threshold acquisition

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**Input:**  $DBGB\_list$ , step size  $L$   
**Output:** The decision thresholds  $\alpha^*$  and  $\beta^*$

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1 for  $GB \in DBGB\_list$  do
2   Compute the quality index  $m(GB)$ ;
3 end
4 Computing  $H_{\mathbb{X}_{\mathbb{R}}^J} = \frac{1}{|U|} \sum_{GB \in DBGB\_list} \xi(GB)$ , where
    $\xi(GB) = 4m(GB)(1 - m(GB))$ ;
5 Assuming  $\beta = 1 - \alpha$  and  $Min = H_{\mathbb{X}_{\mathbb{R}}^J}$ ;
6 for  $\beta = 0$  to  $0.5$  do
7    $\alpha = 1 - \beta$ ;
8   Computing  $H_{\psi(\mathbb{X}_{\mathbb{R}}^J)}$  and  $|\bar{H}_{\psi(\mathbb{X}_{\mathbb{R}}^J)} - \bar{H}_{\mathbb{X}_{\mathbb{R}}^J}|$ ;
9   if  $|\bar{H}_{\psi(\mathbb{X}_{\mathbb{R}}^J)} - \bar{H}_{\mathbb{X}_{\mathbb{R}}^J}| < Min$  then
10     $Min = |\bar{H}_{\psi(\mathbb{X}_{\mathbb{R}}^J)} - \bar{H}_{\mathbb{X}_{\mathbb{R}}^J}|$ ;
11     $\beta^* = \beta$ ;
12     $\alpha^* = 1 - \beta^*$ ;
13  end
14   $\beta = \beta + L$ ;
15 end
16 return  $\alpha^*$  and  $\beta^*$ ;

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justing the step size. When the minimum value is achieved, the optimal thresholds are obtained. The main steps in Algorithm 2, from step 6 to step 14, involve searching for optimal thresholds ( $\beta^*$ ,  $\alpha^*$ ) by exploring all possible thresholds.

Algorithm S3 gives the details of choosing the turning point. To compute the set  $DIS$ , all GBs must be traversed, resulting in a time complexity of  $O(N)$ . To compute  $dV$  and  $AllMaxDiff$  each takes  $O(N)$  time since it involves traversing the elements of  $DIS$ . The time complexity of this loop over  $i$  can be considered as  $O(N)$ .

### REFERENCES

- [1] M. Ester, H. Kriegel, J. Sander, and X. Xu, "A density-based algorithm for discovering clusters in large spatial databases with noise," in *Proc. 2nd Int. Conf. Knowledge Discovery and Data Mining (KDD'96)*, 1996, p. 226–231.

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**Algorithm S3:** Construction of adaptive granular-ball neighborhood
 

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**Input:**  $DBGB\_list$ , parameters  $LocalR$  and  $GlobalR$ , predicted object  $x_{test}$ .

**Output:** The  $\delta_R^*(x_{test})$  of  $x_{test}$ .

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1 Compute the set  $DIS = \{\gamma_1, \gamma_2, \gamma_3, \dots, \gamma_n\}$ ;
2  $Len = \text{length}(DIS)$ ;
3  $dV = \{\gamma_i - \gamma_{i+1}\}_{i=1}^{Len-1}$ ;
4  $AllMaxDiff = \max(dV)$ ;
5  $FitLen = 20$ ;
6 for  $i = Len - FitLen; i \geq 2; i = i - 1$  do
7    $CV = \{\gamma_j\}_{j=i+1}^{i+FitLen}$ ;
8    $Index = \{i + 1, \dots, i + FitLen\}$ ;
9    $[a, b] = \text{LinearFit}(Index, CV)$ ;
10   $PredictV = a \times i + b$ ;
11   $CDiff = \gamma_i - PredictV$ ;
12   $dCV = \{CV_j - CV_{j+1}\}_{j=1}^{FitLen-1}$ ;
13   $CAllMaxDiff = \max(dCV)$ ;
14  if  $CDiff > LocalR \times CAllMaxDiff$  and
     $CDiff > GlobalR \times AllMaxDiff$  then
15    break;
16  end
17 end
18  $\delta_R^*(x_{test}) = \{\gamma \text{ values less than } \gamma_i\}$  return  $\delta_R^*(x_{test})$ ;
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## S2 THE BIOGRAPHIES OF AUTHORS



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