Stochastic Gradient Hamiltonian Monte Carlo

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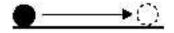
Overview

- 1 Hamiltonian Monte Carlo(HMC)
- 2 Naive Stochastic Gradient HMC(Naive SGHMC)
- 3 Stochastic Gradient HMC with friction(SGHMC)
- 4 Experiment

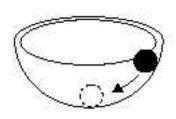
HMC: Motivation

- Random-walk approach: slow exploration.
- Explore faster?

HMC: Physical Analogy







HMC: Hamiltonian Dynamics

$$\begin{cases} d\theta &= \nabla K(r) \ dt = M^{-1}r \ dt \\ dr &= -\nabla U(\theta) \ dt \end{cases}$$

- θ : position/target variables
- r: momentum/auxiliary variables
- K(r): the kinetic energy, $\frac{1}{2}M^{-1}r^2$
- $U(\theta)$: the potential energy
- M: mass matrix

HMC: Hamiltonian Dynamics

$$\pi(\theta, r) \propto \exp(-U(\theta) - K(r))$$

 $\propto \exp(-U(\theta)) \exp(-K(r))$

• $U(\theta) = -\log(p(\theta|\mathcal{D}))$, \mathcal{D} , the observation

HMC: Discretization - Leapfrog Method

function LEAPFROG
$$(\theta_0, r_0, \epsilon, m)$$

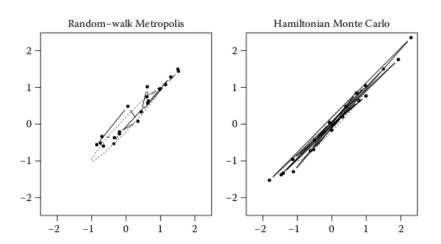
$$r_0 \leftarrow r_0 - \frac{\epsilon}{2} \nabla U(\theta_0)$$
for $i = 1$ to m do
$$\theta_i \leftarrow \theta_{i-1} + \epsilon M^{-1} r_{i-1}$$

$$r_i \leftarrow r_{i-1} - \epsilon \nabla U(\theta_i)$$
end for
$$r_m \leftarrow r_m - \frac{\epsilon}{2} \nabla U(\theta_m)$$
end function

HMC: Put Together

```
function HMC(position \theta^{(1)}, step size \epsilon, step number m)
     for t = 1, 2 \cdots do
           Resample momentum r
           r \sim \mathcal{N}(0, M)
           (\theta_0, r_0) \leftarrow (\theta^{(t)}, r)
           Simulating Hamiltonian trajectory by leapfrog
           \hat{\theta}, \hat{r} \leftarrow \mathsf{LEAPFROG}(\theta_0, r_0, \epsilon, m)
           MH correction
          if \mathcal{U}(0,1) < \min(1, \exp H(\hat{\theta}, \hat{r}) - H(\theta, r)) then
                \theta^{(t+1)} = \hat{\theta}
           else
                \theta^{(t+1)} = \theta^{(t)}
           end if
     end for
```

HMC: Comparison to Random-walk



Stochastic Gradient HMC: Problem Definition

$$p(\theta|\mathcal{D}) \propto exp(-U(\theta))$$

$$U(\theta) = -\sum_{x \in \mathcal{D}} \log p(x|\theta) - \log p(\theta)$$

Where:

- θ : target variables
- \mathcal{D} : i.i.d observations

Stochastic Gradient HMC: Motivation

$$abla U(heta) = \sum_{x \in \mathcal{D}}
abla \log p(x| heta) -
abla \log p(heta)$$
If $|\mathcal{D}| = \text{one billion}$?

Naive SGHMC: Stochastic Gradient

$$abla \widetilde{U}(\theta) = -\frac{|\mathcal{D}|}{|\widetilde{\mathcal{D}}|} \sum_{\mathbf{x} \in \widetilde{\mathcal{D}}} \nabla \log p(\mathbf{x}|\theta) - \nabla \log p(\theta), \ \widetilde{\mathcal{D}} \subset \mathcal{D}$$

Naive SGHMC: Gradient Noise Assumption

$$\nabla \widetilde{U}(\theta) = \nabla U(\theta) + \mathcal{N}(0, V(\theta))$$

Where:

• *V*: the covariance of the stochastic gradient noise

Naive SGHMC: Dynamics

$$\begin{cases} d\theta = M^{-1}r dt \\ dr = -\nabla U(\theta) dt + \mathcal{N}(0, 2B) dt \end{cases}$$

Where:

• $B = \frac{1}{2} \epsilon V$: the diffusion matrix(?)

Naive SGHMC: Not Invariant Anymore

$$t\uparrow \Longrightarrow h(p_t)\uparrow p_t \to \text{uniform}$$

- $p_t(\theta, r)$: the distribution of (θ, r) at t.
- $h(p_t)$: entropy of p_t

Naive SGHMC: The Dilemma

- **1** With MH correction, calculating $U(\theta)$ is expensive
- **②** Without MH correction, far from the target $\pi(\theta,t)$

Naive SGHMC: Fixing It

- Do MH using subset of data
- Eliminate/reduce the gradient noise

SGHMC: Dynamics

$$\begin{cases} d\theta = M^{-1}r dt \\ dr = -\nabla U(\theta) dt - BM^{-1}r dt + \mathcal{N}(0, 2B) dt \end{cases}$$

- $BM^{-1}r$: the friction term
- Commonly referred to as second-order Langevin dynamics

SGHMC: Invariance

It can be proved that:

$$\partial_t p_t(\theta, r) = 0$$

SGHMC: in Practice

- B is unknown but can be estimated
- Beneficial to use friction constant term C(user-specified)

SGHMC: in Practice

$$\begin{cases} d\theta = M^{-1}r dt \\ dr = -\nabla U(\theta) dt - CM^{-1}r dt \\ +\mathcal{N}(0, 2(C - \hat{B})) dt + \mathcal{N}(0, 2B) dt \end{cases}$$

• \hat{B} : estimated B

SGHMC: in Practice

- As $\epsilon \to 0$, $B = \frac{1}{2}\epsilon V \to 0$.
- Assume $\hat{B} = 0$ for simplicity and goodness.

$$\begin{cases} d\theta = M^{-1}r dt \\ dr = -\nabla U(\theta)dt - CM^{-1}rdt + \mathcal{N}(0, 2C))dt \end{cases}$$

Invariant again.

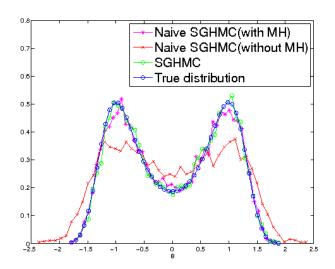
Algorithm

```
function STOCHASTIC-GRADIENT-HMC(\theta^{(1)}, \epsilon_t, m)
     for t = 1, 2 \cdots do
          Optionally resample momentum r
          r \sim \mathcal{N}(0, M)
          (\theta_0, r_0) \leftarrow (\theta^{(t)}, r)
          Simulate noisy Hamiltonian trajectory
          for i = 1 to m do
               \theta_i \leftarrow \theta_{i-1} + \epsilon_t M^{-1} r_{i-1}
               r_i \leftarrow r_{i-1} - \epsilon_t \nabla \widetilde{U}(\theta_i) - \epsilon_t CM^{-1} r_{i-1} + \epsilon_t \mathcal{N}(0, 2(C - \hat{B}))
          end for
          No MH correction
          (\theta^{(t+1)}, r^{(t+1)}) = (\theta_m, r_m)
     end for
end function
```

•
$$U(\theta) = -2\theta^2 + \theta^4$$

•
$$\nabla \widetilde{U}(\theta) = \nabla U(\theta) + \mathcal{N}(0,4)$$

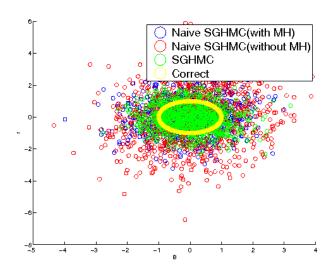
- $\epsilon = 0.1, m = 10$
- C = 1
- Sampled 10000 data points



METHOD	ACCEPTANCE RATE
Naive SGHMC(with MH)	0.62
Naive SGHMC(without MH)	1.0
SGHMC(with MH)	0.76

•
$$U(\theta) = \frac{1}{2}\theta^2$$

- $\nabla \widetilde{U}(\theta) = \nabla U(\theta) + \mathcal{N}(0,4)$
- $\epsilon = 0.1, m = 10$
- C = 2
- Sampled 1000 data points



SGHMC: Connection to SGLD

When the friction is large, SGHMC reduces to *Stochastic Gradient Langevin Dynamics*.

Illustration:

- **1** suppose $BM^{-1} = \frac{1}{dt}$.
- ② r converges to $\mathcal{N}(MB^{-1}\nabla U(\theta), M)$ fast.
- **1** dynamics for θ becomes:

$$d\theta = -M^{-1}\nabla U(\theta)dt^2 + \mathcal{N}(0, 2M^{-1}dt^2)$$

where:

• M^{-1} , the preconditioning matrix in SGLD

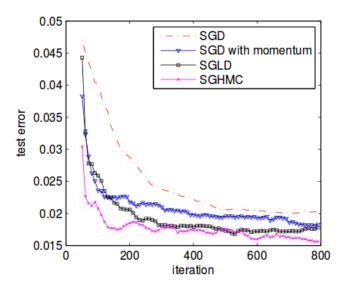
Bayesian Neural Networks for Classification: Data

- Handwritten digit classification
- MNIST dataset
- 60,000 instances for training and 10,000 for testing

Bayesian Neural Networks for Classification: Model

- 2-layer Bayesian neural network
- 100 hidden variables using sigmoid unit
- Output layer using softmax

Bayesian Neural Networks for Classification: Result



Online Bayesian Probabilistic Matrix Factorization

- Recommend movies to users
- ullet 1 million ratings of pprox 4000 movies by pprox 6000 users

Online Bayesian Probabilistic Matrix Factorization

METHOD	RMSE
SGD	0.8538 ± 0.0009
SGD with momentum	0.8539 ± 0.0009
SGLD	0.8412 ± 0.0009
SGHMC	0.8411 ± 0.0011

Thank you!