

# *Using automatic program verifier Dafny*

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# What is Dafny?

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Language and program verifier

- Static verification
- Imperative
- Object-based
- Automatic
- Based on Boogie
- SMT solver at the backend

Microsoft Research product

Part of Boogie distribution

Good for beginners

# How does it work?

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Write a program in Dafny

- Dafny translates it to Boogie
  - Boogie tries to prove it
    - SMT solver (Z3)
  - Boogie gives some response
- Dafny processes Boogie output

Outcome

- Success → *C#* code
- Fail → reasonable feedback

# How to use

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Write a program with specification

Prove

- Possible design-time feedback
  - MS Visual Studio integration

Debug

- Asserts
- Print Boogie code

Execute

- Automatic generation of *C#* code

# If you know Boogie...

## Boogie

```
function fib(n: int) returns (int)  
{  
    if n < 2 then n else fib(n - 1) + fib(n - 2)  
}
```

```
procedure Fibonacci(n: int) returns (m: int)  
    requires n >= 0;  
    ensures m == fib(n);  
{  
    var p, next, tmp : int;  
    p, m, next := 0, 0, 1;  
    while (p < n)  
        invariant p <= n;  
        invariant m == fib(p);  
        invariant next == fib(p + 1);  
    {  
        tmp := m + next;  
        m := next;  
        next := tmp;  
        p := p + 1;  
    }  
}
```

## Dafny

```
function fib(n: int) : int  
{  
    if n < 2 then n else fib(n - 1) + fib(n - 2)  
}
```

```
method Fibonacci(n: int) returns (m: int)  
    requires n >= 0;  
    ensures m == fib(n);  
{  
    var p, next, tmp : int;  
    p, m, next := 0, 0, 1;  
    while (p < n)  
        invariant p <= n;  
        invariant m == fib(p);  
        invariant next == fib(p + 1);  
    {  
        tmp := m + next;  
        m := next;  
        next := tmp;  
        p := p + 1;  
    }  
}
```

# Difference with Boogie

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High-level

Syntax sugar

Cares much about the heap

Generates executable code

# Program in Dafny

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## Classes

- Generics
- No inheritance, interfaces, etc.

## Methods

- Contain the code
- Translated to *C#* code

## Functions

- Differ from methods
- Special notation
- Ghost by default

# Specification

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## Contracts

- Pre- and postconditions
- No class invariants

## Assertions

- Debugging
- Hints for proving backend

## Ghost variables and methods

- Specification
- Lemmas and theorems



# Specification (cont.)

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## Functions

- Specification
- Pure
- Ghost by default

## Termination metrics

- No infinite loops
- Integers, tuples, sets...

## Dynamic frames

- At the object grain
- Set of objects method can modify
- Set of objects function can read

# Types

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## Primitive

- Booleans
- Integers
  - mathematical

## Classes

- Default class
- Arrays
- User-defined
- No subtyping
  - `object`

## Datatypes

- Recursively defined datastructures
- No subtyping
  - `datatype`

## Sequences

- Functional specification

## Sets

- Dynamic frames

# Classes

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Any class is subtype of `object`

Arrays

- `array<T>`
- `array2<T>`
- ...

User-defined

- `class C {...}`
- `class C<T> {...}`

Top-level methods are in the `_default` class

# Methods

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```
method M(a: A, b: B, c: C) returns (x: X, y: Y, z: Y)
  requires Precondition;
  modifies Frame;
  ensures Postcondition;
  decreases Rank;
{
  Body
}
```

Modular verification: method body is unknown outside its definition.

# Example

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```
method MultyRet(x: int, y: int) returns (more: int, less: int)
  requires 0 < y;
  ensures less < x < more;
{
  more := x + y;
  less := x - y;
}
```

# Functions

---

```
function F(a: A, b: B, c: C): T
  requires Pre;
  reads Frame;
  ensures Post;
  decreases Rank;
{
  Body
}
```

Non-ghost function: **method function**

Functions could be used in predicates

Function body is known by Dafny

# Example

---

```
function fib(n: int): int
  requires 0 <= n;
  decreases n;
{
  if n < 2 then n else fib(n-1) + fib(n - 2)
}
```

Note absence of semicolon

# Example

---

```
method Fibonacci(n: int) returns (m: int)
  requires n >= 0;
  ensures m == fib(n);
{
  var i, next := 0, 1;
  m := 0;
  while (i < n)
    invariant i <= n;
    invariant m == fib(i);
    invariant next == fib(i + 1);
    {
      var tmp := m + next;
      m, next, i := next, tmp, i + 1;
    }
}
```



# Frames

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## Definition

- Frame denotes a set of objects whose fields may be updated by the method

```
class MyClass {  
  ghost var Repr: set<object>;  
  method SomeMethod()  
    modifies Repr;  
  {...}  
  function SomeFunction(): Something  
    reads Repr;  
  {...}  
}
```

# Sequences

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## Definition

- `var s: seq<int>`
- Length:  $|s|$
- Element:  $s[0]$
- Subsequence:  $s[a..b]$
- Tail:  $s[1..]$
- Concatenation  $s1+s2$

## Properties

- Immutable

# Sets

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## Definition

- `var s: set<int>`
- `e in s`
- `e !in s`
- `s1 < s2`
- `s1 <= s2`
- `s1 !! s2`

## Properties

- Finite
- Could be used as termination metric
  - `decreases s;`

# Datatypes

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**datatype** Tree<T> = Empty | Node(Tree<T>, T, Tree<T>);

Useful for datastructure definitions

No need to care about the heap

Easy termination proof

Special notations:

```
match (Expr) {  
  case Empty => ...  
  case Node(l, d, r) => ...  
}
```

# *EXAMPLES*

# Maximum over array

```
method Max(a: array<int>) returns (m: int)
  requires a != null;
  requires a.Length > 0;
  ensures forall k :: 0 <= k < a.Length ==> a[k] <= m;
  ensures exists k :: 0 <= k < a.Length ==> a[k] == m;
{
  m := a[0];
  var p := 1;
  while (p < a.Length)
    invariant p <= a.Length;
    invariant forall k :: 0 <= k < p ==> a[k] <= m;
    invariant exists k :: 0 <= k < p ==> a[k] == m;
    {
      if (a[p] > m) {
        m := a[p];
      }
      p := p + 1;
    }
}
```

# Maximum over array

---

```
{
  m := a[0];
  ghost var mi := 0;          //!
  var p := 1;
  while (p < a.Length)
    invariant p <= a.Length;
    invariant 0 <= mi < a.Length; //!
    invariant m == a[mi];         //!
    invariant forall k :: 0 <= k < p ==> a[k] <= m;
    invariant exists k :: 0 <= k < p ==> a[k] == m;
    {
      if (a[p] > m) {
        m := a[p];
        mi := p;          //!
      }
      p := p + 1;
    }
}
```

# Two-way maximum

method Max(a: array<int>) returns (mi: int)

requires a != null;

requires a.Length > 0;

ensures 0 <= mi < a.Length;

ensures forall k :: 0 <= k < a.Length ==> a[k] <= a[mi];

{

var i, j := 0, a.Length - 1;

while (i < j)

invariant 0 <= i <= j < a.Length;

invariant (forall k :: 0 <= k <= i ==> a[k] <= a[j] || a[k] <= a[i]);

invariant (forall k :: j <= k < a.Length ==> a[k] <= a[j] || a[k] <= a[i]);

{

if (a[i] > a[j]) {

j := j - 1;

} else {

i := i + 1;

}

}

mi := i;

}



# Infinite loop

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```
method hail(n: nat)
{
  var i := n;
  while (1 < i)
    decreases *;
  {
    i := if i % 2 == 0 then i / 2 else 3 * i + 1;
  }
}
```

# Ackerman

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```
function Ack(m: nat, n: nat): nat
  decreases m, n;
{
  if m == 0 then n + 1
  else if n == 0 then Ack(m - 1, 1)
  else Ack(m - 1, Ack(m, n - 1))
}
```

# List reversal

---

```
class Data {}
```

```
class Node {  
  ghost var heap: set<Node>;  
  var value: Data;  
  var right: Node;  
  
  function isValid(): bool  
    reads this, heap;  
    decreases heap;  
  {  
    if right == null then  
      heap == {this}  
    else  
      this in heap &&  
      right in heap &&  
      right.heap == heap - {this} &&  
      right.isValid()  
    }  
  }  
}
```

# List reversal

---

```
function getHeap(n: Node): set<Node>
  reads n;
{
  if n == null then {} else n.heap
}
```

```
function integralRight(n: Node): seq<Node>
  reads n, n.heap;
  requires n != null ==> n.isValid();
  decreases getHeap(n);
{
  if n == null then [] else [n] + integralRight(n.right)
}
```

```
function minus(s: seq<Node>): seq<Node>
{
  if |s| == 0 then [] else minus(s[1..]) + [s[0]]
}
```

# List reversal

---

```
method set_right(n: Node, right: Node)
  requires n != null;
  requires n !in getHeap(right);
  requires right != null ==> right.isValid();
  modifies n;
  ensures n.isValid();
  ensures integralRight(n) == [n] + old(integralRight(right));
{
  n.right := right;
  n.heap := {n} + getHeap(right);
}
```

# List reversal

```
method reverse(first: Node) returns (result: Node)
  requires first != null ==> first.isValid();
  modifies first, first.heap;
  ensures result != null ==> result.isValid();
  ensures minus(integralRight(result)) == old(integralRight(first));
{
  if (first == null) {
    result := null;
    return;
  }
  var previous: Node, next: Node := null, first;
  while (next != null)
    decreases getHeap(next);
    invariant next != null ==> next.isValid() && previous != null ==> previous.isValid();
    invariant getHeap(next) <= old(first.heap) && getHeap(previous) !! getHeap(next);

    invariant minus(integralRight(previous)) + integralRight(next) ==
                                                         old(integralRight(first));
    {
      var temp := previous;
      previous, next := next, next.right;
      set_right(previous, temp);
    }
    result := previous;
}
```

# Links

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## Dafny

- <http://research.microsoft.com/dafny>
- <http://rise4fun.com/Dafny/tutorial/Guide>
- <http://research.microsoft.com/dafny/reference.aspx>

## Rise4Fun

- <http://rise4fun.com/Dafny>

## Verification corner

- <http://research.microsoft.com/verificationcorner>