Lecture 22: Support vector classifier

Reading: Sections 9.1-9.2

STATS 202: Data mining and analysis

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- ▶ An (affine) hyperplane *H* is an affine space which separates the space into two regions.
- It is determined by a normal vector $\beta=(\beta_1,\ldots,\beta_p)$, is a unit vector $\sum_{j=1}^p \beta_j^2=1$ which is perpendicular to the hyperplane and an "intercept" β_0

$$H = \left\{ x : \sum_{j=1}^{p} x_j \beta_j + \beta_0 = 0 \right\}.$$

▶ If the hyperplane goes through the origin $(\beta_0 = 0)$, the deviation between a point (x_1, \ldots, x_p) and the hyperplane is the dot product:

$$x \cdot \beta = x_1 \beta_1 + \dots + x_p \beta_p.$$

▶ If the hyperplane goes through a point $-\beta_0\beta$, i.e. it is displaced from the origin by $-\beta_0$ along the normal vector (β_1,\ldots,β_p) , the deviation of a point (x_1,\ldots,x_p) from the hyperplane is:

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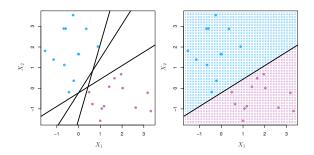
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- The sign of the dot product tells us on which side of the hyperplane the point lies.
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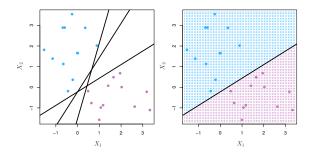
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Suppose we have a classification problem with response Y = -1 or Y = 1.

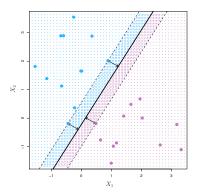


- Suppose we have a classification problem with response Y = -1 or Y = 1.
- ► If the classes can be separated, most likely, there will be an infinite number of hyperplanes separating the classes.



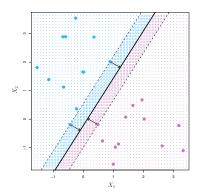
Idea:

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- ▶ Draw the largest possible empty margin around the hyperplane.
- ▶ Out of all possible hyperplanes that separate the 2 classes, choose the one with the widest margin.



This can be written as an optimization problem:

$$\begin{aligned} \max_{\beta_0,\beta_1,\dots,\beta_p} & M \\ \text{subject to } \sum_{j=1}^p \beta_j^2 = 1, \\ & \underbrace{y_i(\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip})}_{\text{How far is } x_i \text{ from the hyperplane}} \geq M \quad \text{ for all } i = 1,\dots,n. \end{aligned}$$

M is simply the width of the margin in either direction.

We can reformulate the problem by defining a vector $w = (w_1, \dots, w_p) = \beta/M$:

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This is a quadratic optimization problem. Having found $(\hat{\beta}_0, \hat{w})$ we can recover $\hat{\beta} = \hat{w}/\|\hat{w}\|_2, M = 1/\|\hat{w}\|_2$.

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Introducing Karush-Kuhn-Tucker multipliers, $\alpha_1, \ldots, \alpha_n$, this is equivalent to:

$$\max_{\alpha} \min_{\beta_0, w} \frac{1}{2} \|w\|^2 - \sum_{i=1}^n \alpha_i [y_i(\beta_0 + w \cdot x_i) - 1]$$
 subject to $\alpha_i \ge 0$.

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▶ Setting the partial derivatives with respect to w and β_0 to 0, we get:

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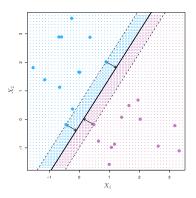
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$$\hat{w} = \sum_{i=1}^{n} \alpha_i y_i x_i, \quad \sum_{i=1}^{n} \alpha_i y_i = 0$$

Furthermore, one of the KKT conditions yields $\alpha_i > 0$ if and only if $y_i(\beta_0 + w \cdot x_i) = 1$, that is, if x_i falls on the margin.

Support vectors

The vectors that fall on the margin and determine the solution are called **support vectors**:



$$\max_{\alpha} \min_{\beta_0, w} \frac{1}{2} \|w\|^2 - \sum_{i=1}^n \alpha_i [y_i (\beta_0 + w \cdot x_i) - 1]$$
 subject to $\alpha_i \ge 0$.

The solution is $\hat{w} = \sum_{i=1}^{n} \alpha_i y_i x_i$, and $\sum_{i=1}^{n} \alpha_i y_i = 0$ so we can plug this in above to obtain the dual problem:

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$$\max_{\alpha} \sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i=1}^{n} \sum_{i'=1}^{n} \alpha_{i} \alpha_{i'} y_{i} y_{i'} (x_{i} \cdot x_{i'})$$
subject to $\alpha_{i} \geq 0$, $\sum_{i} \alpha_{i} y_{i} = 0$.

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subject to $\alpha_{i} \geq 0$, $\sum_{i} \alpha_{i} y_{i} = 0$.

This only depends on the training sample inputs through the inner products $x_i \cdot x_j$ for every pair i, j.

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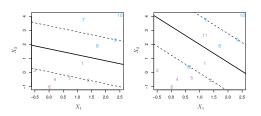
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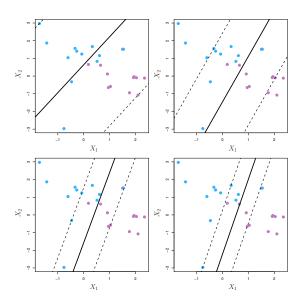


This can be written as an optimization problem:

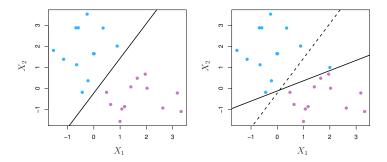
$$\begin{aligned} \max_{\beta_0,\beta,\epsilon} \ M \\ \text{subject to} \ \sum_{j=1}^p \beta_j^2 &= 1, \\ \underbrace{y_i(\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip})}_{\text{How far is } x_i \text{ from the hyperplane}} \geq M(1 - \epsilon_i) \quad \text{ for all } i = 1,\dots,n \\ \epsilon_i \geq 0 \text{ for all } i = 1,\dots,n, \quad \sum_{i=1}^n \epsilon_i \leq C. \end{aligned}$$

M is the width of the margin in either direction. $\epsilon=(\epsilon_1,\ldots,\epsilon_n)$ are called *slack* variables. C is called the *budget*.

Tuning the budget, C (high to low)



If the budget is too low, we tend to overfit



Maximal margin classifier, C=0. Adding one observation dramatically changes the classifier.

We can reformulate the problem by defining a vector $w = (w_1, \dots, w_p) = \beta/M$:

$$\begin{split} \min_{\beta_0, w, \epsilon} & \ \frac{1}{2} \|w\|^2 + D \sum_{i=1}^n \epsilon_i \\ \text{subject to} \\ y_i(\beta_0 + w \cdot x_i) & \geq (1 - \epsilon_i) \quad \text{ for all } i = 1, \dots, n, \\ \epsilon_i & \geq 0 \quad \text{for all } i = 1, \dots, n. \end{split}$$

The penalty $D \ge 0$ serves a function similar to the budget C, but is inversely related to it.

$$\begin{split} & \min_{\beta_0, w, \epsilon} \ \frac{1}{2} \|w\|^2 + D \sum_{i=1}^n \epsilon_i \\ & \text{subject to} \\ & y_i(\beta_0 + w \cdot x_i) \geq (1 - \epsilon_i) \quad \text{ for all } i = 1, \dots, n. \\ & \epsilon_i > 0 \quad \text{for all } i = 1, \dots, n. \end{split}$$

Introducing Karush-Kuhn-Tucker multipliers, α_i and μ_i , this is equivalent to:

$$\max_{\alpha,\mu} \min_{\beta_0,w,\epsilon} \frac{1}{2} \|w\|^2 - \sum_{i=1}^n \alpha_i [y_i(\beta_0 + w \cdot x_i) - 1 + \epsilon_i] + \sum_{i=1}^n (D - \mu_i) \epsilon_i$$
 subject to $\alpha_i \geq 0, \mu_i \geq 0$, for all $i = 1, \dots, n$.

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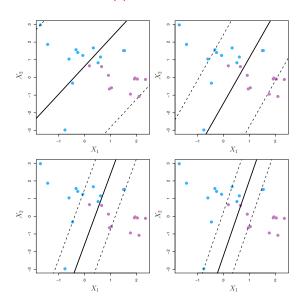
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