(7) Bayesian linear regression

ST440/540: Applied Bayesian Statistics

Spring, 2018

Bayesian linear regression

- Linear regression is by far the most common statistical model
- It includes as special cases the t-test and ANOVA
- The multiple linear regression model is

$$Y_i \sim \text{Normal}(\beta_0 + X_{i1}\beta_1 + ... + X_{ip}\beta_p, \sigma^2)$$

independently across the i = 1, ..., n observations

- ► As we'll see, Bayesian and classical linear regression are similar if *n* >> *p* and the priors are uninformative.
- However, the results can be different for challenging problems, and the interpretation is different in all cases

Review of least squares

▶ The least squares estimate of $\beta = (\beta_0, \beta_1, ..., \beta_p)^T$ is

$$\hat{\beta}_{OLS} = \underset{\beta}{\operatorname{argmin}} \sum_{i=1}^{n} (Y_i - \mu_i)^2$$

where
$$\mu_i = \beta_0 + X_{i1}\beta_1 + ... + X_{ip}\beta_p$$

- \triangleright $\hat{\beta}_{OLS}$ is unbiased even if the errors are non-Gaussian
- If the errors are Gaussian then the likelihood is proportional to

$$\prod_{i=1}^{n} \exp \left[-\frac{(Y_i - \mu_i)^2}{2\sigma^2} \right] = \exp \left[-\frac{\sum_{i=1}^{n} (Y_i - \mu_i)^2}{2\sigma^2} \right]$$

► Therefore, if the errors are Gaussian $\hat{\beta}_{OLS}$ is also the MLE

Review of least squares

- Linear regression is often simpler to describe using linear algebra notation
- Let $\mathbf{Y} = (Y_1, ..., Y_n)^T$ be the response vector and \mathbf{X} be the $n \times (p+1)$ matrix of covariates
- ▶ Then the mean of **Y** is $X\beta$ and the least squares solution is

$$\hat{\boldsymbol{\beta}}_{OLS} = \underset{\boldsymbol{\beta}}{\operatorname{argmin}} (\mathbf{Y} - \mathbf{X}\boldsymbol{\beta})^T (\mathbf{Y} - \mathbf{X}\boldsymbol{\beta}) = (\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{Y}$$

If the errors are Gaussian then the sampling distribution is

$$\hat{\boldsymbol{\beta}}_{OLS} \sim \text{Normal} \left[\boldsymbol{\beta}, \sigma^2 (\boldsymbol{X}^T \boldsymbol{X})^{-1} \right]$$

If the variance σ^2 is estimated using the mean squared residual error then the sampling distribution is multivariate t

Bayesian regression

The likelihood remains

$$Y_i \sim \text{Normal}(\beta_0 + X_{i1}\beta_1 + ... + X_{ip}\beta_p, \sigma^2)$$

independent for i = 1, ..., n observations

- As with a least squares analysis, it is crucial to verify this is appropriate using qq-plots, added variable plots, etc.
- ▶ A Bayesian analysis also requires priors for β and σ
- We will focus on prior specification since this piece is uniquely Bayesian.

Priors

- For the purpose of setting priors, it is helpful to standardize both the response and each covariate to have mean zero and variance one.
- \triangleright Many priors for β have been considered:
 - Improper priors
 - 2. Gaussian priors
 - 3. Double exponential priors
 - 4. Many, many more...

Improper priors

- ▶ The Jeffreys' prior is flat $p(\beta) = 1$
- ► This is improper, but the posterior is proper under the same conditions required by least squares
- If σ is known then

$$\boldsymbol{\beta} | \mathbf{Y} \sim \text{Normal} \left[\hat{\boldsymbol{\beta}}_{OLS}, \sigma^2 (\mathbf{X}^T \mathbf{X})^{-1} \right]$$

- ➤ See "Post beta" in http://www4.stat.ncsu.edu/ ~reich/ABA/Derivations7.pdf
- Therefore, the results should be similar to least squares
- How are they different?

Improper priors

- ▶ Of course we rarely know σ
- ► Typically the error variance follows an InvGamma(a, b) prior with a and b set to be small, say a = b = 0.01.
- In this case the posterior of β follows a multivariate t centered on $\hat{\beta}_{OLS}$
- Again, the results are similar to OLS
- ▶ The objective Bayes Jeffreys prior for $\theta = (\beta, \sigma)$ is

$$p(\beta,\sigma^2) = \frac{1}{\sigma^2}$$

which is the limit as $a, b \rightarrow 0$

Multivariate normal prior

Another common prior for is Zellner's g-prior

$$eta \sim \mathsf{Normal}\left[0, rac{\sigma^2}{g}(\mathbf{X}^T\mathbf{X})^{-1}
ight]$$

- ▶ This prior is proper assuming X is full rank
- The posterior mean is

$$\frac{1}{1+g}\hat{eta}_{OLS}$$

- This shrinks the least estimate towards zero
- g controls the amount of shrinkage
- g = 1/n is common, and called the unit information prior

Univariate Gaussian priors

- If there are many covariates or the covariates are collinear, then $\hat{\beta}_{O(S)}$ is unstable
- Independent priors can counteract collinearity

$$\beta_j \sim \text{Normal}(0, \sigma^2/g)$$

independent over j

► The posterior mode is

$$\underset{\boldsymbol{\beta}}{\operatorname{argmin}} \sum_{i=1}^{n} (Y_i - \mu_i)^2 + g \sum_{j=1}^{p} \beta_j^2$$

In classical statistics, this is known as the ridge regression solution and is used to stabilize the least squares solution

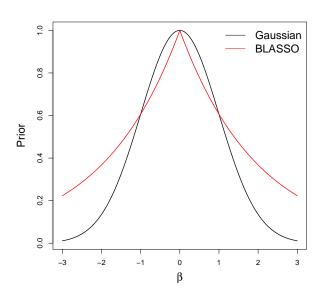
BLASSO

- An increasingly-popular prior is the double exponential or Bayesian LASSO prior
- ▶ The prior is $\beta_i \sim \mathsf{DE}(\tau)$ which has PDF

$$f(eta) \propto \exp\left(-rac{|eta|}{ au}
ight)$$

- The square in the Gaussian prior is replaced with an absolute value
- The shape of the PDF is thus more peaked at zero (next slide)
- ► The BLASSO prior favors settings where there are many β_j near zero and a few large β_j
- ► That is, p is large but most of the covariates are noise

BLASSO



BLASSO

The posterior mode is

$$\underset{\boldsymbol{\beta}}{\operatorname{argmin}} \sum_{i=1}^{n} (Y_i - \mu_i)^2 + g \sum_{j=1}^{p} |\beta_j|$$

- ► In classical statistics, this is known as the LASSO solution
- It is popular because it adds stability by shrinking estimates towards zero, and also sets some coefficients to zero
- Covariates with coefficients set to zero can be removed
- Therefore, LASSO performs variables selection and estimation simultaneously

Computing

- With flat or Gaussian (with fixed prior variance) priors the posterior is available in closed-form and Monte Carlo sampling is not needed
- With normal priors all full conditionals are Gaussian or inverse gamma, and so Gibbs sampling is simple and fast
- JAGS works well, but there are R (and SAS and others) packages dedicated just to Bayesian linear regression that are preferred for big/hard problems
- BLR is probably the most common
- http://www4.stat.ncsu.edu/~reich/ABA/code/ regJAGS

Computing for the BLASSO

- For the BLASSO prior the full conditionals are more complicated
- There is a trick to make all full conditional conjugate so that Gibbs sampling can be used
- Metropolis sampling works fine too
- BLR works well for BLASSO and is super fast
- JAGS can handle this as well,
- http: //www4.stat.ncsu.edu/~reich/ABA/code/BLASSO

Summarizing the results

- ▶ The standard summary is a table with marginal means and 95% intervals for each β_i
- This becomes unwieldy for large p
- Picking a subset of covariates is a crucial step in a linear regression analysis.
- We will discuss this later in the course.
- Common methods include cross-validation, information criteria, and stochastic search.

Logistic regression

- Other forms of regression follow naturally from linear regression
- ► For example, for binary responses $Y_i \in \{0, 1\}$ we might use logistic regression

logit[Prob(
$$Y_i = 1$$
)] = $\eta_i = \beta_0 + \beta_1 X_{i1} + ... + \beta_p X_{ip}$

- ▶ The logit link is the log-odd logit(x) = log[x/(1-x)]
- ▶ Then β_j represents the increase in the log odds of an event corresponding to a one-unit increase in covariate j
- ► The expit transformation expit(x) = exp(x)/[1 + exp(x)] is the inverse, and

$$\mathsf{Prob}(Y_i = 1) = \mathsf{expit}(\eta_i) \in [0, 1]$$

Logistic regression

- ▶ Bayesian logistic regression requires a prior for β
- All of the prior we have discussed for linear regression (Zellner, BLASSO, etc) apply
- Computationally the full conditional distributions are no longer conjugate and so we must use Metropolis sampling
- ► The R function MCMClogit does this efficiently
- It is fast in JAGS too, for example http: //www4.stat.ncsu.edu/~reich/ABA/code/GLM

Predictions

- ► Say we have a new covariate vector X_{new} and we would like to predict the corresponding response Y_{new}
- ▶ A plug-in approach would fix β and σ at their posterior means $\hat{\beta}$ and $\hat{\sigma}$ to make predictions

$$Y_{new}|\hat{\boldsymbol{\beta}},\hat{\sigma}\sim \mathsf{Normal}(\mathbf{X}_{new}\hat{\boldsymbol{\beta}},\hat{\sigma}^2)$$

- ▶ However this plug-in approach suppresses uncertainty about β and σ
- ► Therefore these prediction intervals will be slightly too narrow leading to undercoverage

Posterior predicitive distribution (PPD)

- We should really account for all uncertainty when making predictions, including our uncertainty about β and σ
- We really want the PPD

$$p(Y_{new}|\mathbf{Y}) = \int f(Y_{new}, \beta, \sigma|\mathbf{Y}) d\beta d\sigma$$
$$= \int f(Y_{new}|\beta, \sigma) f(\beta, \sigma|\mathbf{Y}) d\beta d\sigma$$

- Marginalizing over the model parameters accounts for their uncertainty
- ► The concept of the PPD applies generally (e.g., logistic regression) and means the distribution of the predicted value marginally over model parameters

Posterior predicitive distribution (PPD)

- MCMC naturally gives draws from Y_{new}'s PPD
 - For MCMC iteration t we have $\beta^{(t)}$ and $\sigma^{(t)}$
 - ► For MCMC iteration *t* we sample

$$Y_{new}^{(t)} \sim \text{Normal}(\mathbf{X}\boldsymbol{\beta}^{(t)}, {\sigma^{(t)}}^2)$$

- $Y_{new}^{(1)},...,Y_{new}^{(S)}$ are samples from the PPD
- ► This is an example of the claim that "Bayesian methods naturally quantify uncertainty"
- http://www4.stat.ncsu.edu/~reich/ABA/code/ Predict