Integer Programming ISE 418

Lecture 12

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Reading for This Lecture

- Nemhauser and Wolsey Sections II.1.1-II.1.3, II.1.6
- Wolsey Chapter 8
- CCZ Chapters 5 and 6
- "Valid Inequalities for Mixed Integer Linear Programs," G. Cornuejols.
- "Generating Disjunctive Cuts for Mixed Integer Programs," M.
 Perregaard.

Generating Cutting Planes: Two Basic Viewpoints

• There are a number of different points of view from which one can derive the standard methods used to generate cutting planes for general MILPs.

• As we have seen before, there is an *algebraic* point of view and a *geometric* point of view.

• Algebraic:

- Take combinations of the known valid inequalities.
- Use rounding to produce stronger ones.

• Geometric:

- Use a disjunction (as in branching) to generate several disjoint polyhedra whose union contains S.
- Generate inequalities valid for the convex hull of this union.
- Although these seem like very different approaches, they turn out to be very closely related.

Generating Valid Inequalities: Algebraic Viewpoint

- Consider the polyhedron $Q = \{x \in \mathbb{R}^n \mid Ax \leq b\}$.
- Valid inequalities for Q can be obtained by taking non-negative linear combinations of the rows of (A, b).
- Except for one pathological case¹, all valid inequalities for Q are either equivalent to or dominated by an inequality of the form

$$uAx \le ub, u \in \mathbb{R}_+^m$$
.

- We are taking combinations of inequalities existing in the description, so any such inequalities will be redundant for Q itself.
- Nevertheless, such redundant inequalities can be strengthened by a simple procedure when Q is the LP relaxation of an MILP.

¹The pathological case occurs when one or more variables have no explicit upper bound *and* both the primal and dual problems are infeasible.

Generating Valid Inequalities for conv(S)

As usual, we consider the MILP

$$z_{IP} = \max\{c^{\top}x \mid x \in \mathcal{S}\},\tag{MILP}$$

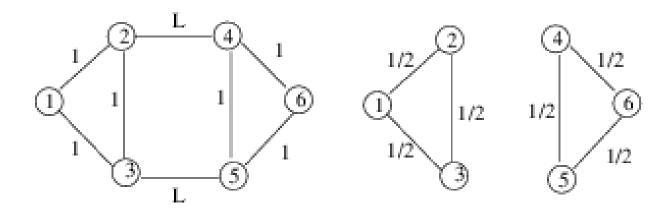
where

$$\mathcal{P} = \{ x \in \mathbb{R}^n_+ \mid Ax \le b \}$$
 (FEAS-LP)

$$S = P \cap (\mathbb{Z}_+^p \times \mathbb{R}_+^{n-p})$$
 (FEAS-MIP)

- All inequalities valid for \mathcal{P} are also valid for $\operatorname{conv}(\mathcal{S})$, but they are not cutting planes.
- We can do better.
- We need the following simple principle: if $a \le b$ and a is an integer, then $a \le |b|$.
- Believe it or not, this simple fact is all we need to generate all valid inequalities for conv(S)!

Back to the Matching Problem



Recall again the matching problem.

$$\min \sum_{e=\{i,j\} \in E} c_e x_e
s.t. \sum_{\{j | \{i,j\} \in E\}} x_{ij} = 1, \ \forall i \in N
x_e \in \{0,1\}, \ \forall e = \{i,j\} \in E.$$

Generating the Odd Cut Inequalities

Recall that each odd cutset induces a possible valid inequality.

$$\sum_{e \in \delta(S)} x_e \ge 1, S \subset N, |S| \text{ odd.}$$

- Let's derive these another way.
 - Consider an odd set of nodes U.
 - Sum the (relaxed) constraints $\sum_{\{j|\{i,j\}\in E\}} x_{i\underline{j}} \leq 1$ for $i\in U$.
 - This results in the inequality $2\sum_{e\in E(U)}x_e+\sum_{e\in\delta(U)}x_e\leq |U|$.
 - Dividing through by 2, we obtain $\sum_{e \in E(U)} x_e + \frac{1}{2} \sum_{e \in \delta(u)} x_e \leq \frac{1}{2} |U|$.
 - We can drop the second term of the sum to obtain

$$\sum_{e \in E(U)} x_e \le \frac{1}{2} |U|.$$

– What's the last step?

Chvátal Inequalities

- Suppose we can find a $u \in \mathbb{R}_+^m$ such that $\pi = uA$ is integer and $\pi_0 = ub \notin \mathbb{Z}$.
- In this case, we have $\pi^{\top}x \in \mathbb{Z}$ for all $x \in \mathcal{S}$, and so $\pi^{\top}x \leq \lfloor \pi_0 \rfloor$ for all $x \in \mathcal{S}$.
- In other words, $(\pi, \lfloor \pi_0 \rfloor)$ is both a valid inequality and a split disjunction.
- In other words, it is a split disjunction for which

$$\{x \in \mathcal{P} \mid \pi^{\top} x \ge \lfloor \pi_0 \rfloor + 1\} = \emptyset \tag{1}$$

- Such an inequality is called a *Chvátal inequality*.
- Note that we have not used the non-negativity constraints in deriving this inequality.

Chvátal-Gomory Inequalities

• If we allow the non-negativity constraints to be combined with the other constraints of \mathcal{P} (with weight vector $v \in \mathbb{R}^n_+$), then integrality of π requires

$$\pi_i = uA_i - v_i \in \mathbb{Z} \text{ for } 1 \le i \le p$$

$$\pi_i = uA_i - v_i = 0 \text{ for } p + 1 \le i \le n.$$

ullet Since v_i must be non-negative, we then have that

$$v_i \ge uA_i - \lfloor uA_i \rfloor$$
 for $1 \le i \le p$
 $v_i = uA_i \ge 0$ for $p + 1 \le i \le n$

• Taking $v_i = uA_i - |uA_i|$ for $1 \le i \le p$, we then obtain that

$$\sum_{0 \le i \le p} \pi_i x_i = \sum_{0 \le i \le p} \lfloor u A_i \rfloor x_i \le \lfloor u b \rfloor = \pi_0 \tag{C-G}$$

is valid for all $u \in \mathbb{R}^m_+$ such that $uA_C \geq 0$.

- Note that validity of this cut could also be derived from first principles.
- This is the *Chvátal-Gomory Inequality*.

The Chvátal-Gomory Procedure

- 1. Choose a weight vector $u \in \mathbb{R}^m_+$ such that $uA_C \geq 0$.
- 2. Obtain the valid inequality $\sum_{0 \le i \le p} (uA_i)x_i \le ub$.
- 3. Round the coefficients down to obtain $\sum_{0 \le i \le p} (\lfloor uA_i \rfloor) x_i \le ub$.
- 4. Finally, round the right-hand side down to obtain the valid inequality

$$\sum_{0 \le i \le p} (\lfloor uA_i \rfloor) x_i \le \lfloor ub \rfloor$$

- This procedure is called the *Chvátal-Gomory* rounding procedure, or simply the *C-G procedure*.
- Surprisingly, for pure ILPs (p = n), any inequality valid for conv(S) can be produced by a finite number of applications of this procedure!
- Note that this procedure is recursive and requires exploiting inequalities derived in previous rounds to get new inequalities.
- This is not true for the general mixed case.

Assessing the Procedure

- Although it is *theoretically* possible to generate any valid inequality using the C-G procedure, this is not true in practice.
- The two biggest challenges are numerical errors and slow convergence.
- The inequalities produced may be very weak—we may not even obtain a supporting hyperplane.
- This is is because the rounding only "pushes" the inequality until it meets some point in \mathbb{Z}^n , which may or may not even be in S.
- The coefficients of the generated inequality must be relatively prime to ensure the generated hyperplane even includes an integer point!

Proposition 1. Let $S = \{x \in \mathbb{Z}^n \mid \sum_{j \in N} a_j x_j \leq b\}$, where $a_j \in \mathbb{Z}$ for $j \in N$, and let $k = \gcd\{a_1, \ldots, a_n\}$. Then $\operatorname{conv}(S) = \{x \in \mathbb{R}^n \mid \sum_{j \in N} (a_j/k) x_j \leq \lfloor b/k \rfloor \}$.

Gomory Inequalities

 \bullet Let's consider T, the set of solutions to a pure ILP with one equation:

$$T = \left\{ x \in \mathbb{Z}_+^n \mid \sum_{j=1}^n a_j x_j = a_0 \right\}$$

ullet For each j, let $f_j = a_j - \lfloor a_j \rfloor$. Then equivalently

$$T = \left\{ x \in \mathbb{Z}_+^n \mid \sum_{j=1}^n f_j x_j = f_0 + k \text{ for some integer } k \right\}$$

• Since $\sum_{j=1}^n f_j x_j \geq 0$ and $f_0 < 1$, then we must have $k \geq 0$ and so

$$\sum_{j=1}^{n} f_j x_j \ge f_0$$

is a valid inequality for S called a *Gomory inequality*.

Gomory Cuts from the Tableau

 Gomory cutting planes can also be derived directly from the tableau while solving an LP relaxation.

- ullet We assume for now that A has integral coefficients so that the slack variables also have integer values implicitly.
- Consider the set

$$\left\{ (x,s) \in \mathbb{Z}_+^{n+m} \mid Ax + Is = b \right\}$$

in which the LP relaxation of an ILP is put in standard form.

ullet The tableau corresponding to basis matrix B is

$$B^{-1}Ax + B^{-1}s = B^{-1}b$$

- Each row of this tableau corresponds to a weighted combination of the original constraints.
- The weight vectors are the rows of B^{-1} .

Gomory Cuts from the Tableau (cont.)

• A row of the tableau is obtained by combining the equations in the standard representation with weight vector $\lambda = B_i^{-1}$ to obtain

$$\sum_{j=1}^{n} (\lambda A_j) x_j + \sum_{i=1}^{m} \lambda_i s_i = \lambda b,$$

where A_j is the j^{th} column of A and λ is a row of B^{-1} .

Applying the previous procedure, we can obtain the valid inequality

$$\sum_{i=1}^{n} (\lambda A_j - \lfloor \lambda A_j \rfloor) x_j + \sum_{i=1}^{m} (\lambda_i - \lfloor \lambda_i \rfloor) s_i \ge \lambda b - \lfloor \lambda b \rfloor.$$

• We will show that this Gomory cut is equivalent to the C-G inequality with weights $u_i = \lambda_i - |\lambda_i|$.

Gomory Versus C-G

• To show the Gomory cut is a C-G cut, we first apply the C-G procedure directly to the tableau row, resulting in the inequality

$$\sum_{j=1}^{n} \lfloor \lambda A_j \rfloor x_j + \sum_{i=1}^{m} \lfloor \lambda_i \rfloor s_i \le \lfloor \lambda b \rfloor.$$

- Note that we can relax the equality to an inequality because of nonnegativity.
- We could have also obtained this inequality by summing the associated Gomory cut and the original tableau row.
- Now, we substitute out the slack variables using the equation

$$s = b - Ax$$
.

to obtain

$$\sum_{j=1}^{n} \left(\lfloor \lambda A_j \rfloor - \sum_{i=1}^{m} \lfloor \lambda_i \rfloor a_{ij} \right) x_j \le \lfloor \lambda b \rfloor - \sum_{i=1}^{m} \lfloor \lambda_i \rfloor b_i,$$

Gomory Versus C-G (cont.)

• The final inequality from the previous slide can be re-written as

$$\sum_{j=1}^{n} \left(\sum_{i=1}^{m} (\lambda_i - \lfloor \lambda_i \rfloor) a_{ij} \right) x_j \le \sum_{i=1}^{m} (\lambda_i - \lfloor \lambda_i \rfloor) b_i,$$

which is a C-G inequality.

- The substitution of slack variables is more than just a textbook procedure to show the Gomory cut is a C-G cut.
- In practice, the slack variables are substituted out in this fashion in order to derive a cut in terms of the original variables.

Strength of Gomory Cuts from the Tableau

 Consider a row of the tableau in which the value of the basic variable is not an integer.

 Applying the procedure from the last slide, the resulting inequality will only involve nonbasic variables and will be of the form

$$\sum_{j \in NB} f_j x_j \ge f_0$$

where $0 \le f_j < 1$ and $0 < f_0 < 1$.

- The left-hand side of this cut has value zero with respect to the solution to the current LP relaxation.
- We can conclude that the generated inequality will be violated by the current solution to the LP relaxation.

Example: Gomory Cuts

Consider the polyhedron \mathcal{P} described by the constraints

$$4x_1 + x_2 \le 28 \tag{2}$$

$$x_1 + 4x_2 \le 27 \tag{3}$$

$$x_1 - x_2 \le 1 \tag{4}$$

$$x_1, x_2 \ge 0 \tag{5}$$

Graphically, it can be easily determined that the facet-inducing valid inequalities describing $\operatorname{conv}(\mathcal{S} = \mathcal{P} \cap \mathbb{Z}^2)$ are

$$x_1 + 2x_2 \le 15 \tag{6}$$

$$x_1 - x_2 \le 1 \tag{7}$$

$$x_1 \le 5 \tag{8}$$

$$x_2 \le 6 \tag{9}$$

$$x_1 \ge 0 \tag{10}$$

$$x_2 \ge 0 \tag{11}$$

Example: Gomory Cuts (cont.)

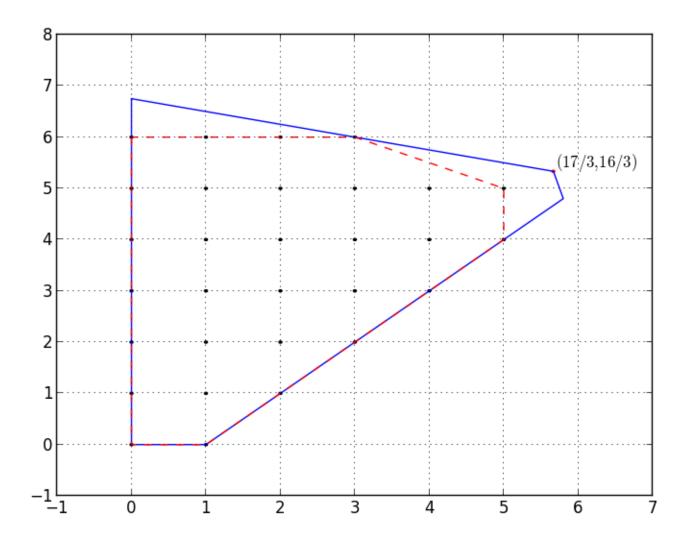


Figure 1: Convex hull of ${\mathcal S}$

Example: Gomory Cuts (cont.)

Consider the optimal tableau of the LP relaxation of the ILP

$$\max\{2x_1 + 5x_2 \mid x \in \mathcal{S}\},\$$

shown in Table 1.

| Basic var. | x_1 | x_2 | s_1 | s_2 | s_3 | RHS |
|------------------|-------|-------|-------|-------|-------|------|
| $\overline{x_2}$ | 0 | 1 | -2/30 | 8/30 | 0 | 16/3 |
| s_3 | 0 | 0 | -1/3 | 1/3 | 1 | 2/3 |
| x_1 | 1 | 0 | 8/30 | -2/30 | 0 | 17/3 |

Table 1: Optimal tableau of the LP relaxation

The associated optimal solution to the LP relaxation is also shown in Figure 1.

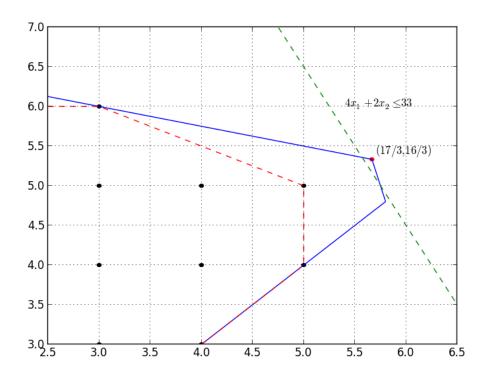
Example: Gomory Cuts (cont.)

The Gomory cut from the first row is

$$\frac{28}{30}s_1 + \frac{8}{30}s_2 \ge \frac{1}{3},$$

In terms of x_1 and x_2 , we have

$$4x_1 + 2x_2 \le 33,$$
 (G-C1)



Note this inquality can be trivially strengthened by dividing by 2.

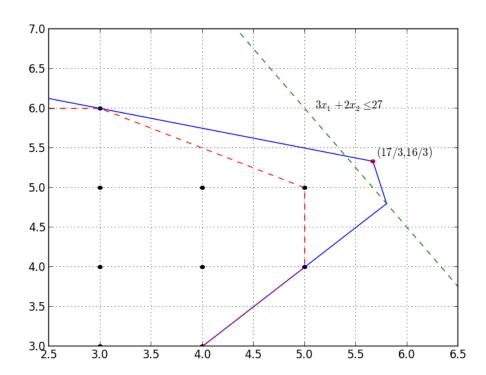
Example: Gomory Cuts (cont.)

The Gomory cut from the second row is

$$\frac{2}{3}s_1 + \frac{1}{3}s_2 \ge \frac{2}{3},$$

In terms of x_1 and x_2 , we have

$$3x_1 + 2x_2 \le 27,$$
 (G-C2)



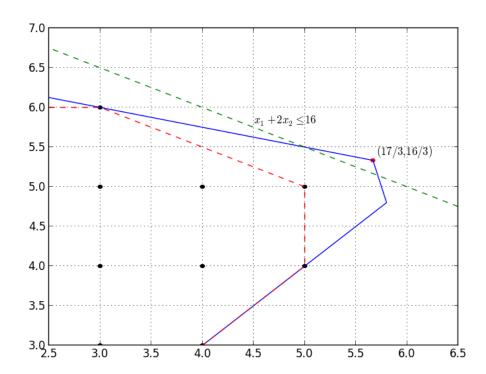
Example: Gomory Cuts (cont.)

The Gomory cut from the third row is

$$\frac{8}{30}s_1 + \frac{28}{30}s_2 \ge \frac{2}{3},$$

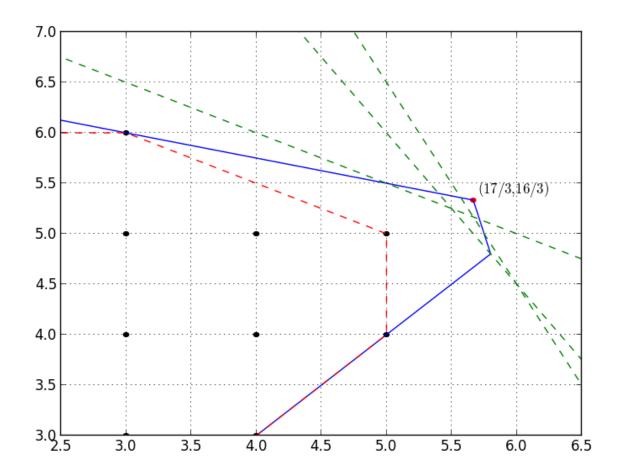
In terms of x_1 and x_2 , we have

$$x_1 + 2x_2 \le 16,$$
 (G-C3)



Example: Gomory Cuts (cont.)

This picture shows the effect of adding all Gomory cuts in the first round.



Applying the Procedure Recursively

- This procedure can be applied recursively by adding the generated inequalities to the formulation and performing the same steps again.
- Any inequality that can be obtained by recursive application of the C-G procedure (or is dominated by such an inequality) is a C-G inequality.
- For pure ILPs, all valid inequalities are C-G inequalities.
 - **Theorem 1.** Let $(\pi, \pi_0) \in \mathbb{Z}^{n+1}$ be a valid inequality for $S = \{x \in \mathbb{Z}_+^n \mid Ax \leq b\} \neq \emptyset$. Then (π, π_0) is a C-G inequality for S.
- Roughly speaking, the *rank* of an inequality is the minimum number of recursive applications of the procedure required to produce the inequality.

C-G Inequalities of Rank 1

 The *elementary closure* of polyhedron P is the intersection of half-spaces defined by inequalities in the set

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e(\mathcal{P}) = \{(\pi, \pi_0) \mid \pi_j = \lfloor ua_j \rfloor \text{ for } j \in \mathbb{N}, \pi_0 = \lfloor ub \rfloor \text{ for some } u \in \mathbb{R}_+^m \}
```

- The elementary closure is described by all of the nondominated C-G inequalities obtained by combining inequalities in the original formulation.
- Although it is not obvious, one can show that the elementary closure is a polyhedron.
- Optimizing over this polyhedron is difficult (\mathcal{NP} -hard) in general.
- Inequalities valid for $e(\mathcal{P})$ but not for \mathcal{P} have C-G rank 1 (inequalities valid for \mathcal{P} have rank 0).

C-G Inequalities of Higher Rank

- The rank k closure \mathcal{P}^k of \mathcal{P} is defined recursively as follows.
 - The rank 1 closure of \mathcal{P} is $\mathcal{P}^1 = e(\mathcal{P})$.
 - The rank k closure $\mathcal{P}^k=e(\mathcal{P}^{k-1})$ is the elementary closure of the \mathcal{P}^{k-1} .
 - An inequality is rank k if it is valid for the rank k closure \mathcal{P}^k and not for \mathcal{P}^{k-1} .
- The *C-G rank* of \mathcal{P} is the maximum rank of any facet-defining inequality of $\operatorname{conv}(\mathcal{S})$.

A Finite Cutting Plane Procedure

• Under mild assumptions on the algorithm used to solve the LP, this yields a general algorithm for solving (pure) ILPs.

• The details are contained in Section 5.2.5 of CCZ.

Determining the C-G Rank

• By solving an LP, it can be determined whether a given inequality has maximum rank 1.

Proposition 2. If $(\pi, \pi_0) \in e(\mathcal{P})$, then $\pi_0 \geq \lfloor \pi_0^{LP} \rfloor$, where $\pi_0^{LP} = \max_{x \in \mathcal{P}} \pi^\top x$

- Alternatively, if $\pi \in \mathbb{Z}^n$, the inequality $(\pi, |\pi_0^{LP}|)$ is rank 1.
- Further, any valid inequality (π, π_0) for which $\pi_0 < \lfloor \pi_0^{LP} \rfloor$ has rank at least 2.
- This tells us that the effectiveness of the C-G procedure is strongly tied to the strength of our original formulation.
- In general it is difficult to determine the rank of any inequality that is not rank 1.

Example: C-G Rank

• Let's consider the C-G rank of the inequality

$$x_1 + 2x_2 \le 15,$$

which is facet-defining for conv(S) in our example.

We have

$$\max_{x \in \mathcal{P}} x_1 + 2x_2 = 49/3. \tag{12}$$

- Since $\lfloor 49/3 \rfloor = 16$, we conclude that this is not a rank 1 cut.
- Note that the dual solution to the LP (12) gives us weights with which to combine the original inequalities to get a C-G cut.
- This is the strongest possible C-G cut of rank 1 with those coefficients.

Bounding The C-G Rank of a Polyhedron

• For most classes of MILPs, the rank of the associated polyhedron is an unbounded function of the dimension.

• Example:

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- \mathcal{P} = \{x \in \mathbb{R}^n_+ \mid x_i + x_j \le 1 \text{ for } i, j \in N, i \ne j\} \text{ and } S = \mathcal{P}^n \cap \mathbb{Z}^n- \operatorname{conv}(\mathcal{S}) = \{x \in \mathbb{R}^n_+ \mid \sum_{j \in N} x_j \le 1\}.- \operatorname{rank}(\mathcal{P}) = O(\log n).
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- For a family of polyhedra with bounded rank, there is a certificate for the validity of any given inequality.
- This leads to a certificate of optimality for the associated optimization problem.
- Hence, it is unlikely that the problem of optimizing over any family of MILPs formulated by polyhedra with bounded rank is in NP-hard².
- Conversely, for any family of MILPs that is in NP-hard, the associated family of polyhedra is likely to have unbounded rank.

²More on what this means later