

The Stowage Stack Minimization Problem with K-Rehandle Constraint

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Abstract

The Stowage Stack Minimization Problem (SSMP) investigates a stowage planning problem when carriers have the obligation to ship all the given containers in different ports, with the objective to utilize the fewest number of stacks on the ship. This problem has realistic usefulness since it can help shipping forwarders estimate shipping space of each shippers. To our best knowledge, we propose SSMP for the first time in the academic community.

In this paper, we talk about SSMP with K -rehandle constraint. A heuristic algorithm is put forward to construct solutions. We discuss the theoretical performance guarantee of the algorithm using mathematical inequations and induction. To evaluate the actual performance of our algorithm, we conduct experiments on a set of instances with practical size and compare the results when different values of K are selected. What's more, instances with different values of ports, containers and heights have been tested to make sure the universality of our algorithm.

Key words: Containership stowage planning, stack minimization, K-rehandles, constructive heuristic

1. Introduction

International trade plays an important role in promoting the development of world economy. Maritime transport is the backbone of globalization and lies at the heart of cross-border transport networks that support supply chains and enable international trade. Nowadays, over 80% of world trade is carried by the maritime freight industry, which operates the container transportation business (Zhang & Lee, 2016). In 2015, world seaborne trade volumes surpassed 10 billion tons shown in UNCTAD (2016).

Container-shipping is a kind of modern transportation tool which has a lot of advantages in speed, security, and quality comparing with the break-bulk cargo ship. Containerization is an important driver of the global economy, and the container has become a mainstay of worldwide trade. According to World Shipping Council, around 52% of the value of world international seaborne trade today is being moved in containers. This mode is deeply accepted by shippers and carriers, and is becoming the main trend of freightage in the

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world. It has resulted in a tremendous growth of the maritime freight industry and it shows powerful vitality and promising prospects.

With the development of container-shipping, more and more containers are transported by sail. Over the past decades there has been a continuous increase in demand for cost efficient containerized transportation. Thus, it makes higher research demand. The container stowage plan is a pivotal link to containers transportation, and the objective of which is to draw a plan of loading and discharging sequence of containers for containership in Zhang et al. (2008). The most frequently used addressing notation for storage locations in a container ship is the bay-row-tier system. The cargo space of a container ship is split into several 20-ft-long areas. These areas are termed as 20-ft bays. Figure 1 reproduced from Delgado et al. (2012) shows a diagram of containership.

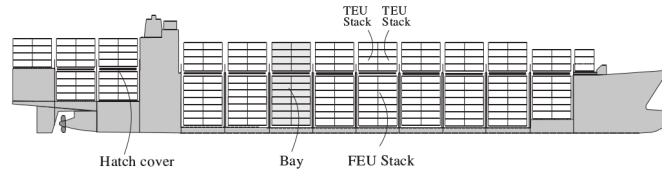


Figure 1: The arrangement of cargo space in a container vessel.

Each bay consists of container stacks placed along the width of ship. Stacks in a bay are indexed by a row number. The position for one 20-ft container in the ship is uniquely indexed by (bay, row, tier), called a slot. In addition, for some ships, two contiguous 20-ft bays form a 40-ft bay which can be used to accommodate 40-ft containers.

A ship usually calls a sequence of ports and containers are loaded and unloaded at each port by cranes in a last-in-last-out (LIFO) manner. Rehandles arise either when we want to unload containers destined for current port which however are beneath those destined for subsequent ports, or when we want to reorder the sequence of containers to prevent more rehandles in the future. Rehandles are expensive, since on one hand terminals directly charge the carriers for such operations, on the other hand, rehandles make ships dwell at terminals longer, inducing more berthing cost. Actual examples show that containership stowage plans not only influence the income of shipping company from transportation but also have direct relation to the safety of ships and freights. The problems have troubled and aroused the interests of both scholars and commercial shipping organization in many countries since 1970s (Webster & Van Dyke, 1970). Most of previous research on stowage planning focus on how to minimize the number of rehandles (Ding & Chou, 2015; Zhang & Lee, 2016; Zehendner et al., 2017).

In this paper, we investigate the problem from a new perspective. We deal with Stowage Stack Minimization Problem (SSMP) which minimizes the number of used stacks. The problem has realistic meaning.

In the real world, a carrier/forwarder may collect a few containers in a time interval and want to evaluate needed space (stacks), in order to estimate available space left. Or on the contrary, a carrier/forwarder wants to receive provisional shipment orders as many as possible while reserve enough space for regular shipment orders. Our algorithm provides them an indicator to achieve such goals.

The contribution of our paper lies in three aspects. First, to the best of our knowledge, our paper considers number of stacks used for the first time, and this is a very practical consideration. As talked before, previous research usually focus on how to reduce the rehandles or shifts. Second, we analyze SSMP and give upper and lower bounds of SSMP. The bounds pave a way for future study. Third, we propose a heuristic algorithm to solve SSMP and the algorithm has a performance guarantee.

The remainder of this paper is organized as follows: we review extant research works in Section 2. The formal definition of SSMP and its properties are provided in Section 3. In Section 4, we present our heuristic algorithm and the performance analysis. Experiments are illustrated in Section 5. Concluding remarks close the paper in Section 6.

2. Literature review

The container handling problems can be divided into two streams based on the container handling locations occurred; one is container management at terminals, and the other is containership stowage planning problems (CSP). The problem discussed in this paper belongs to the latter. Since 1970s, CSP has been studied by shipping organizations for commercial demand. Research methods of CSP can be divided into six categories: simulation methods based on probability, heuristic procedures, mathematical programming approach, decision support systems, expert systems and evolutionary computation. The following section will review relevant works.

Shields (1984) introduced a computer preplanning system (CAPS) which had been used by American President Lines. The CAPS produced stowage plans by using Monte Carlo theory. Dillingham & Perakis (1986) introduced their researches on expert system of stowage based on rules. Each of the suggested container movements was displayed graphically as the decisions were made. Wilson et al. (2001) outlined a computer system that generated good sub-optimal solutions to the stowage pre-planning problem. The methodology progressively refined the arrangement of containers within the cargo-space of a container ship until each container is specifically allocated to a stowage location.

Scott & Chen (1978) constructed a model, in which containers were sorted into ten classes based on some characteristics and then three heuristic rules were used to assign gradually each type of containers to slots of the ship by four steps, while the shifting problem had not been considered in their model. Avriel et al. (1998) presented a 0-1 binary linear programming formulation based on minimizing the number shifting in a single

bay of a ship calling at a given number of ports. Further, they showed that finding the minimum number of columns for which there was a zero shifts stowage plan is equivalent to finding the coloring number of circle graphs. Botter & Brinati (1991) created a model called complete mathematical model for the stowage plan problem, which used binary decision variables to determine the containers unloading and loading sequence for each port. However, literatures have shown that binary linear programming formulation for such problems is impracticable for real life problems due to the large number of binary variables and constraints.

Avriel et al. (1998) and Avriel et al. (2000) focused on stowage planning in order to minimize the number of unproductive shifts (temporary unloading and reloading of containers at a port before their destination ports in order to access containers below them for unloading). A binary linear programming (LP) model was formulated without considering ship's stability and other real-life constraints. Due to the proven NP-hardness of the problem, a so-called "Suspensory Heuristic" — based on earlier work by Avriel & Penn (1993) — was developed in order to solve even large problem instances. The heuristic assigned slots in a bay to containers dynamically with respect to the sequence of ports in a vessel's route. Haghani & Kaisar (2001) proposed a MIP model for developing loading plans in order to minimize the time that a vessel spent at port, and the container handling cost which shifts caused by was highly influenced by the number of unproductive but necessary an unsatisfactory arrangement of containers. In Ambrosino et al. (2004) the problem of stowing containers into a containership had been faced by evaluating an exact 0-1 Linear Programming model, which was not practically useful for large cases. This had been modified by an approach proposed by the authors, consisting of heuristic preprocessing and prestowing procedures that also allow the relaxation of some constraints of the exact model. The proposed approach exhibited very good performance in terms of both solution precision and computational time. Moreover, in the performance evaluation with real size cases, it also guaranteed another very important maritime performance index, in term of handling operations/hour. In Parreno et al. (2016), they focused on the slot planning phase and presented a Constraint Programming and Integer Programming model for stowing a set of containers in a single bay section. This so-called slot planning problem was NP-hard and often involved stowing several hundred containers. Using state-of-the-art constraint solvers and modeling techniques, however, they were able to solve 90% of 236 real instances from our industrial collaborator to optimality within 1 second. Ambrosino et al. (2015) proposed a Mixed Integer Programming (MIP) heuristic aimed at determining stowage plans in circular routes for container ships so as to give support for the ship coordinator and the terminal planner.

Webster & Van Dyke (1970) first tried to solve the problem by using computer. They put forward a heuristic algorithm that could create a random stowage plan. What's more, Ding & Chou (2015) developed a heuristic algorithm which can generate stowage plans with a reasonable number of shifts for such problems. The algorithm, verified by extensive computational experimentations, performed better than the Suspensory

Heuristic Procedure (SH algorithm) in Avriel et al. (1998), which was a dynamic slot-assignment scheme that terminated with a stowage plan, and to the best of our knowledge, is one of the leading heuristic algorithms for such stowage planning problem when there are many binary variables and constraints in the formulation.

Tabu search was employed to obtain an optimal solution in Wilson et al. (2001) and his model was feasible because it can change configuration step by step until each container was assigned to specific slot. Then, Bortfeldt et al. (2003) presented a parallel tabu search algorithm for the container loading problem with a single container to be loaded. According to an extensive comparative test also including heuristics from other authors, high utilizations of the container volume are already obtained with the sequential TSA (tabu search algorithm). A slight improvement of these results could be achieved by the parallelization. The Ship Stowage Planning Problem had been addressed in Monaco et al. (2014). They first provided a detailed description of the two phases in which the decision problem is usually decomposed, along with a classification scheme and a review of the most relevant related papers. They proposed a Binary Integer Model for the minimization of the transportation times of the containers and the yard-shifts and they developed a Tabu Search Algorithm for finding sub-optimal solutions to the problem and have solved the model by CPLEX.

Algorithm of evolutionary computation came from Darwins biologic theory of evolution. There are two or three branches at present, among which genetic algorithm is used widely. The presented hybrid GA for loading a single container in Bortfeldt & Gehring (2001) was particularly suitable for strongly heterogeneous containers stowage problems. The algorithm took account of some constraints which were relevant in practice. Its good performance and superiority to comparative methods had been verified in an extensive test. The use of a time limit kept the required computing times within acceptable limits. Dubrovsky et al. (2002) used a GA for solving the stowage planning problem of minimizing the number of container movements. Search space was significantly reduced by a compact and efficient encoding scheme. Ship stability criteria were reflected by appropriate constraints. Simulation runs demonstrated the efficiency and flexibility of the GA-based approach. Kammarti et al. (2009) proposed an efficient genetic algorithm which consists on selecting two chromosomes (parent) from an initially constructed population using a roulette wheel technique. Then, the two parents were combined using a one point crossover operator. Finally, a mutation operator was performed. The variant tackled in Cohen et al. (2017) involved several constraints, inspired by real-life problems and application found in the literature. Given the complexity of the problem, which belongs to the class of NP-hard problems, a novel evolutionary metaheuristic algorithm is developed and designed. Considering the ability and flexibility of Genetic Algorithm (GA), the approach was based on a two-phase procedure, one for master planning and the other for allocation of the containers into slots. GA parameters were analyzed to achieve practical and best results. The system offered stowage allocation solutions for both phases, thus offering flexibility for a wide variety of vessels and route combinations.

Container ship stowage problem(CSSP) is combinatorial optimization problem with multiobjects and multiconstraints. In order to reduce computational difficulty, CSSP was decomposed two subproblems in Wei-Ying et al. (2005), and the first one was discussed detailed. CSSP was regarded as bin-packing problem. After being modeled the algorithm of best fit for binpacking problem was used to solve the CSSP. A case showed that the algorithm was feasible for container ship stowage problem. A multiobjective ship stowage planning problem(SSPP) was investigated by Zhang & Lee (2016), which aimed to optimize the ship stability and the number of rehandles simultaneously. They used metacentric height, list value, and trim value to measure the ship stability. Meanwhile, the number of rehandles was the sum of rehandles by yard cranes and quay cranes and all necessary rehandles at future ports. The algorithm could produce a set of nondominated solutions. Decision makers could then choose the most promising solution for practical implementation based on their experience and preferences. Extensive experiments were carried out on two groups of instances. The computational results demonstrated the effectiveness of the proposed algorithm compared to the NSGA-II and random weighted genetic algorithms, especially when it was applied in solving the six-objective SSPP.

Tierney et al. (2014) investigated the complexity of stowage planning problem and showed that the capacitated k-shift problem is solvable in polynomial time for any choice of stacks and stack capacities. Some scholars paid special attention to the process of loading and unloading, Malucelli et al. (2008) investigated stack reordering strategies aiming at minimizing the number of pop and push operations and focused on three versions of the problem in which reordering can take place in different phases: when unloading the stack, when loading it or in both phases. There are some extended problems in this field. Different problems arising in practice in the context of storage areas organized in stacks have been surveyed by Lehnfeld & Knust (2014). Different problem classes have been identified, namely loading, unloading, premarshalling and combined problems. To be able to categorize all these problems in a more abstract way, they developed a classification scheme which had been used to summarize complexity results and solution methods for all problem classes. In conclusion, many problems have already been solved by exact or heuristic methods in all four considered problem classes. Nevertheless, due to the diversity of the problems, various other versions exist. For further research, a major challenge is the development of more efficient solution algorithms integrating additional constraints coming from practical applications. As we all known, the 3D Container ship Loading Plan Problem (CLPP) is an important problem that appears in seaport container terminal operations and is well known to be NP-hard. This problem consists of determining how to organize the containers in a ship in order to minimize the number of movements necessary to load and unload the container ship and the instability of the ship in each port. In Arajo et al. (2016), the hybrid method Pareto Clustering Search (PCS) was proposed to solve the CLPP and obtain a good approximation to the Pareto Front. The PCS aimed to combine metaheuristics and local search heuristics, and the intensification was performed only in promising

regions. Computational results considering instances available in the literature were presented to show that PCS provides better solutions for the CLPP than a mono-objective Simulated Annealing.

To the best of our knowledge, apart from the SSMP-ZR, only Avriel et al. (2000) and Jensen (2010) discussed the stowage stack minimization and its connection with the chromatic number of circle graphs when the stack height is unlimited. At present, the research tendency of the stowage planning problem is intelligent management system, which is a new stowage research direction. Intelligent containership stowage plan system is a technological innovation in contrast with traditional stowage method. It can improve the ability of decision-making management system of container shipping by means of artificial intelligence, information technology, communications and computer technology.

3. Problem description and properties

3.1. Problem description and notation

We put forward SSMP in this subsection. Literally speaking, SSMP is a variant of CSP. A ship starts its journey at port 1 and sequentially visits port 2, 3, ..., P . We assume the ship stops at port P . N containers are shipped along the journey. At each port, the containers destined to the current port are discharged, and the containers await on yard are loaded to the ship. We use $O(c)$ and $D(c)$ to denote the original and destination ports of container c , respectively. Accordingly, the itinerary is represented by a tuple $\{O(c), D(c)\}$. Given N containers to be shipped, the objective of SSMP is to figure out a stowage planning so as to minimize needed stacks.

If two containers $c1$ and $c2$ satisfy $O(c1) < O(c2) < D(c1) < D(c2)$, and $c2$ is placed above $c1$, then one *rehandle* occurs, as we have to move $c2$ to the yard temporally for retrieving $c1$. Besides, containers above $c2$ also have to be moved, and therefore also extra rehandles occur. In this paper, we extend SSMP with zero rehandle constraint in Wang et al. (2014), assuming that K rehandles are allowed.

Other assumptions assumed in this paper:

- Containers loaded are uniform standard 20-ft containers;
- The information of N containers are known in advance;
- The containership is large enough to accommodate all the given containers;
- Each stack can hold at most H vertically piled containers, i.e., the height limit of every stack is H ;
- The balance of the containership can be resolved by assigning container stacks and water-ballast; hence, the balance is not considered when minimizing container stacks.

If the number of containers in a non-empty stack is less than H , the stack is termed as a *partial* stack; otherwise it is a *full* stack. If rehandle occurs, containers above are called *blocking containers* and the to-be-retrieved container is called *target container*. When moving blocking containers back to the ship, there is no guarantee that they will be returned to their original slots.

A feasible solution to the SSMP is represented by a sequence of operations. Each operation indicates the number of container and the accommodating stack. Especially, the yard is term as stack 0. Moving a container c to stack 0 means that c is a blocking container and moved temporally on the yard.

3.2. Integer model

For the special case with zero rehandle, we only need to consider the loading process. For the unloading process, containers can be discharged in order without rehandles. The following IP model decides the accommodating stack of each container.

$$(IP) \quad \min \quad \sum_{s=1}^S y_s$$

$$\text{s.t.} \quad \sum_{s=1}^S x_{is} = 1, \quad \forall 1 \leq i \leq N \quad (1)$$

$$\sum_{i=1}^N x_{is} \leq M y_s, \quad \forall 1 \leq s \leq S \quad (2)$$

$$\sum_{i: O(i) \leq p \leq D(i)-1} x_{is} \leq H, \quad \forall 1 \leq s \leq S, 1 \leq p \leq P \quad (3)$$

$$x_{is} + x_{js} \leq 1, \quad \forall 1 \leq s \leq S, 1 \leq i, j \leq N, O(j) < O(i) < D(j) < D(i) \quad (4)$$

$$x_{is}, y_s \in \{0, 1\}, \quad \forall 1 \leq s \leq S, 1 \leq i, j \leq N \quad (5)$$

In the above model, M is a sufficiently large number and S is the number of stacks on the ship. x_{is} is a binary decision variable which is equal to 1 if container i is loaded to stack s , and 0 otherwise. y_s is a binary decision variable that is equal to 1 if stack s is used for stowage, and 0 otherwise. $O(i)$ and $D(i)$ indicate the shipping leg of container i . The objective minimizes the number of stacks used. Constraints (1) ensure that each container i is loaded to only one stack. Constraints (2) guarantee that containers can only be loaded to used stacks. Constraints (3) assure that at each port p , the number of containers in stack s does not exceed H . Constraints (4) avoid rehandle requiring that container i is prohibited to block container j in the same stack when $O(j) < O(i) < D(j) < D(i)$.

The IP solution can be converted into a complete loading plan: start from port $p = 1$ to port $p = P$. At port p , containers are sorted in a descending order of destination ports. Each container i is loaded to the top of its corresponding stack s^* which satisfies $x_{is^*} = 1$.

For the IP model of general SSMP, it is hard to build a model. Since there are rehandles, we have to move blocking containers on the yard and back to the ship. The stacks of blocking containers are not necessarily the original slots. If we want to model the slots of blocking containers, we have to set variable x_{ctl} that indicates the slot t of a container c at a layout l . We do not know which containers are blocking containers in advance, therefore the domain of c is the whole set of N containers. Especially, whenever we load or discharge a container, it forms a layout. In addition, we do not know the number of layouts in advance. All in all, the number of slots, containers, and layouts are numerous. Apart from other variables and constraints, the number of variable x_{ctl} alone is too large to make the model meaningful and solvable.

4. Methodology

In this section, we will talk about the heuristic algorithm to solve the SSMP as well as the performance guarantee of the algorithm. The heuristic algorithm uses a greedy rule to decide the loading and unloading operations for each container in each port along the voyage.

For the sake of description, we will use some notations presented in the following Table 1 before we begin to introduce our algorithm. If the allowed K doesn't reach when loading containers, we use arraylist S_1 to store partial stacks without rehandles occurring, arraylist S_2 to store partial stacks with rehandles occurring, arraylist S_3 to store empty stacks. The priority order of them is S_1, S_2, S_3 . If there isn't an overstockage allowed when loading containers, we use S_0 to store the feasible stacks, including the partial stacks without rehandles occurring and the empty stacks. For ease of illustration, we need to explain the definition of nearport. For example, three containers are stored in the same stack, and their destination ports are 4,5,6, respectively, then the value of nearport of this stack is 4. If a stack is empty, its nearport will be set to $P + 1$, here P is the total number of the ports along the voyage. As for other notations, we can find their meanings in this table when we need to know them.

4.1. Heuristic algorithm for the SSMP

Algorithm 1 solves instances of SSMP. Given an instance I , for each port p along the voyage, containers with $D(c) == p$ are discharged one by one. Especially, if there exist blocking containers, they are moved on the yard temporally. After containers with $D(c) == p$ are discharged, containers on yard (including containers with $O(c) == p$ and blocking containers) are sorted in order and loaded. The value of *NumofStack* will be updated when all the containers related with port p are either discharged or loaded. The algorithm finally outputs the value of *NumofStack* when all containers in an instance are processed.

The main two steps in this procedure are unloading and loading, the following context will give a detail description of the unloading and loading strategies.

Table 1: constants, sets, variables and methods in the algorithm

P	the number of total ports
N	the number of total containers to be transported
H	the limited height of stacks in the vessel
K	the number of allowed rehandles
k	a variable to record how many rehandles have been used
S_0	stack index set to store feasible stacks when there isn't an rehandle allowed
S_1	stack index set to store partial stacks without rehandles when K doesn't reach
S_2	stack index set to store partial stacks with rehandles when K doesn't reach
S_3	stack index set to store empty stacks when K doesn't reach
$height$	a one-dimension array, represents the current height of each stack
$Numofstack$	the cumulative number of used stacks
$nearport$	a one-dimension array to store the nearest port in all containers for each stack
ac	an arraylist to ordinally store the information of each container including the origin port and the destination port
$Container$	a Class to record the information of each container
$heuristic()$	the main method to complete the container stowage planning along the voyage

Algorithm 1 A heuristic procedure for the SSMP

HEURISTIC(I)

- 1 **for** each port $p = 1, 2, \dots, P$
 - 2 Unload containers with $D(c) == p$.
 - 3 Sort containers with $O(c) == p$ by the decreasing order of their destinations.
 - 4 **for** each container c with $O(c) == p$ at port p
 - 5 **if** $k == K$
 - 6 execute method $loading_equalK(c, nearport)$.
 - 7 **else** If $k < K$
 - 8 execute method $loading_lessK(c, nearport)$.
 - 9 Update the value of $NumofStack$ at port p .
 - 10 Output the value of $NumofStack$ in instance I.
-

When discharging containers at each port, we just need to unload containers from top to bottom one by one when $D(c) == p$ if there isn't a rehandle in the stacks. when rehandles happen, we have to unload the blocking containers before discharging those target containers. As for blocking containers, we will reset their origin ports as current port after unloading them and their destination ports remain unchanged. That's to say, the outbound containers at the current port increase.

The key point in our algorithm is how to load container into the optimal stack to make sure we can minimize the needed stacks. When loading containers at each port, we adopt two different methods to choose stack for the target containers according to whether a rehandle can be produced. They are *loading_equalK(c, nearport)* and *loading_lessK(c, nearport)*, respectively.

We firstly talk about the simple condition that the allowed rehandles run out and the procedure of method *loading_equalK(c, nearport)* is given in Algorithm 2. When traversing all the stacks to choose the optimal one for each container, we add non-full stacks whose nearest port is no smaller than the current loading container into arraylist S_0 . For all the feasible stacks in S_0 , we choose the one with the smallest value of nearport. If there isn't only one stack with the smallest value of nearport, we choose the first one we traverse. It's worth mentioning that s_{min} in the pseudo code represents the first stack with the smallest value of nearport according to the traversing sequence.

Algorithm 2 The procedure for the method *loading_equalK(c, nearport)*

LOADING METHOD($K==K$)

- 1 S_0 =currently non-full stacks whose nearport is greater than or equal to $D(c)$.
 - 2 **if** $S_0 \neq \emptyset$
 - 3 $s_{min} = \arg \min_{s \in S_0} nearport[s]$.
 - 4 Clear the arraylist S_0 .
 - 5 Load container c to stack s_{min} .
 - 6 Update the value of nearport of stack s_{min} .
 - 7 Update the height of stack s_{min} .
-

Afterwards, we talk about the complex condition that the rehandles are allowed and the procedure of method *loading_lessK(c, nearport)* is given in Algorithm 3. Undoubtedly, its procedure to load containers is not as easy as the simple condition. Under this condition, S_1 have the highest priority. If S_1 is null, we choose the stack from arraylist S_2 which is used to store partial stacks whose value of nearport is smaller than the current loading container. Both in S_1 and S_2 , we choose the stack whose value of nearport is smallest. If there isn't only one stack with the smallest value of nearport, we choose the first one we traverse, which is

indexed by s_{min} . If S_2 is null, we choose the first stack when we traverse the S_3 , which is used to store empty stacks.

Algorithm 3 The procedure for the method *loading_lessK(c, nearport)*

LOADING METHOD($K < K$)

- 1 S_1 = currently partial stacks whose nearport is greater than or equal to $D(c)$.
 - 2 S_2 = currently partial stacks whose nearport is smaller than $D(c)$.
 - 3 S_3 = currently empty stacks.
 - 4 **if** $S_1 \neq \emptyset$
 - 5 $s_{min} = \arg \min_{s \in S_1} nearport[s]$.
 - 6 Clear the arraylist S_1 .
 - 7 Load container c to stack s_{min} .
 - 8 **else if** $S_2 \neq \emptyset$
 - 9 $s_{min} = \arg \min_{s \in S_2} nearport[s]$.
 - 10 Clear the arraylist S_2 .
 - 11 Update the value of k .
 - 12 Load container c to stack s_{min} .
 - 13 **else**
 - 14 Clear the arraylist S_3 .
 - 15 Load container c to the first empty stack in S_3 , which is also indexed by s_{min} .
 - 16 Update the value of nearport of stack s_{min} .
 - 17 Update the height of stack s_{min} .
-

From the Algorithm 2 and 3, we can see that we will clear the arraylist once we have chosen the stack for the target container and we will update the value of k if there is a rehandle. After loading the target container into the chosen stack, the value of nearport and height of the stack need to be updated.

Considering the length of pseudo code, some details are omitted. For example, the method to record the loading and unloading information. In a word, a lot of variables and methods of the concrete unloading and loading strategies have been involved, we don't give the complete pseudo here for the sake of context length. What is identical for the two steps is that they choose the optimal operation for each container during the unloading and loading process according to the greedy rules made by our algorithm. As is explained in the heading of this section, we divide the loading strategy into two methods on the basis of the number of allowed rehandles. Similarly, the unloading strategy are divided into two conditions depending on whether there are

rehandles and specific steps are a little different from each other between the two circumstances.

Our algorithm can give the detailed location changes of each container and output the layout status in the vessel at arbitrary time. In other words, we can predict the real-time container stowage process before the voyage as long as we know some information in advance. Therefore, our algorithm makes a little difference and makes some sense in the reality application.

4.2. Performance Guarantee of the Algorithms

In order to simplify the problem, we show that the heuristic algorithms have a performance guarantee whether the value of K is zero or not and we regard the port number P as a fixed number in our voyage. For ease of exposition, we first give some related notations.

- C^* : the optimal solution to the SSMP instances.
- C : the solution to the SSMP instances by the algorithm.
- N_p : the number of containers on the ship before its departure from port p .
- V_p : the number of loading ports that the ship has visited before it departs from port p .

A port is called a loading port if there exists at least one container to be loaded. Clearly, $V_p \leq p$, $\forall p = 1, \dots, P$.

Proposition 1. *The SSMP instance has a lower bound:*

$$\max_{p=1, \dots, P} (\lceil \frac{N_p}{H} \rceil) \leq C^*$$

Proof. $\lceil \frac{N_p}{H} \rceil$ is the least number of stacks to accommodate all the containers at port p , and thus, $\max_p (\lceil \frac{N_p}{H} \rceil)$ is the least number of stacks needed throughout the journey. \square

The lower bound can be a reference to check the optimality of solutions obtained by our heuristic. If the solution is close to the lower bound, we can conclude that the solution is close to optimal.

Proposition 2. *For the heuristic solution to the SSMP instance, it holds*

$$C^* \leq C \leq \max_{p=1, \dots, P} (\lfloor \frac{N_p}{H} \rfloor + V_p) \leq C^* + V_P$$

Proof. The first inequality obviously holds.

For the second inequality, $C = \max_p C_p$. Noted that C_p is the number of stacks in port p obtained from our algorithm. We divide the stack used in the port into two parts: full stacks and partial stacks. For the full stacks, the number of full stacks in port p is no greater than $\lfloor \frac{N_p}{H} \rfloor$. For the partial stacks, we define the number of partial stacks in port p as $P(p)$.

Proposition 3. *The partial stacks in port p is no greater than V_p :*

$$P(p) \leq V_p$$

Proof. We use an inductive proof.

Basis: For $p = 1$, without loss of generality, we assume that port 1 is a loading port, and therefore $V(p = 1) = 1$. In addition, $P(1) = 0$ or 1 , i.e. $P(1) \leq 1$. Hence, $P(p) \leq V_p$ holds. For $p = 2$, there isn't any blocking containers when discharging the containers from the ship, $P(2) \leq 1$ still holds. If there are containers to be loaded at port 2, then $V(p = 2) = 2$, $P(2)$ will add one at most whether there will be rehandles or not. That's to say, $P(2) \leq V(p = 2)$. If no containers is loaded at port 2, then $V(p = 2) = 1$, $P(2) \leq 1 = V(p = 2)$ still holds.

Inductive step: Suppose that the partial stacks in port p is no greater than V_p . Upon the ship arrives at port $p + 1$, it first unloads the containers from the ship. This process does not increase the number of partial stacks comparing with the former port whether there are blocking containers or not.

(1) If there are containers to be loaded at port $p + 1$, then $V_{p+1} = V_p + 1$, $P(p+1) \leq P(p) + 1$ whether we allow the rehandle or not in port $p + 1$.

(2) If there is no containers to be loaded at port $p + 1$, $V_{p+1} = V_p$, $P(p+1) \leq P(p)$. Hence, $P(p+1) \leq P(p) \leq V_p = V_{p+1}$.

Based on the above two steps, we have $P(p) \leq V_p, \forall p = 1, \dots, P$. □

Therefore, the second inequality holds.

For the third inequality, $\lfloor \frac{N_p}{H} \rfloor \leq \lceil \frac{N_p}{H} \rceil$, and $\lceil \frac{N_p}{H} \rceil$ is the lower bound of the number of stacks used at port p by Proposition 1. Thus, $\lfloor \frac{N_p}{H} \rfloor \leq C_p^*$. It then holds $\max_p (\lfloor \frac{N_p}{H} \rfloor + V_p) \leq \max_p (C_p^* + V_p) = C^* + V_P$. □

The above propositions show that our heuristic algorithm has a constant performance guarantee. In the real shipping transportation, the number of ports is generally much smaller than the number of used stacks. Therefore, the difference between the optimal solution and our heuristic solution is relatively small, which indicates that our heuristic algorithms can generate promising solutions.

Due to page limit, we omit the details here. Interested readers are welcome to contact the authors for details.

5. Experiments and Analysis

This paper uses the test data from the existing literature (Wang et al. (2014)) and we add an extra parameters K into the primary instances in order to meet the demands of research. K means the number of allowed rehandles and it is selected from $\{0, 10, 20, 50, 100\}$. Particular, instances with $K = 0$ represent the benchmark instances comparing with the same instances with different values of K . In fact, the problem becomes SSMP-ZR when $K = 0$. There are 360 sets of instances, or 1800 instances in total, which are categorized by three parameters: the number of ports P , which is selected from $\{5, 10, 20, 30\}$; the number of containers N , which is selected from $\{50, 100, 200, 500, 1000, 5000\}$; and the height limit H is selected from $\{4, 8, 12\}$. Each set consists of 5 instances generated by different random seeds. In each instance, the origin $O(i)$ and the destination $D(i)$ of a container i are generated from a uniform distribution on the integers $1, 2, \dots, P$ satisfying that $O(i) < D(i)$. For the convenience of comparison, we only show the average value of "Numofstack" when $K = 0, K = 10, K = 20, K = 50, K = 100$, respectively.

In this section, we will showcase the performance of our heuristic algorithms on a number of test instances. The heuristic was implemented in Java and the experiments were conducted on a computer with Intel Core processor clocked at 2.30 GHz and 8 GB RAM. The operating system of the computer is Windows 10.

The experimental results are shown in Table 2 and Table 3. Considering the size of table, the results of instances with 5000 containers are not listed.

Table 2 summarizes the results of those easy instances with small number of ports, i.e. $P \in \{5, 10\}$. For each given P, N and H , we work out the value of LB, UB of our heuristic algorithm and the average numbers of *Numofstack* of our heuristic algorithm and random algorithm in different instances when K selects different values. The LB and UB are used to test the rationality of heuristic algorithm and the average *Numofstack* of instances with different values of K by using heuristic and random algorithms are used to compare with each other.

Table 3 summarizes that the results of those difficult instances with large number of ports, i.e. $P \in \{20, 30\}$. The columns in this table are similarly defined as those of Table 1 and so is the conclusion we can get from Table 1.

Most of instances provide the evidence that it works better when K isn't equal to zero comparing the condition where K is equal to zero. However, the results between the easy instances and difficult instances have some differences. Comparing with the significant influence of different K in the difficult instances, the influence of different K in the easy instances isn't obvious. The same conclusion can be drawn if we focus on

Table 2: Results of the instances with $P \in \{5, 10\}$

P	N	H	Heu					Ran					K=50	K=100
			LB	UB	K=0	K=10	K=20	K=50	K=100	K=0	K=10	K=20		
5	50	4	8	9.6	8	8	8	8	8	12.2	9.6	10.4	9.6	9.6
5	50	8	4	6	4.6	4	4	4	4	10	8.4	8	9.6	7.8
5	50	12	3	5	3.2	3.2	3	3	3	9.2	9.2	7	8.6	7.6
5	100	4	15	16.8	15	15	15	15	15	18.4	16.2	16.2	16.6	16.6
5	100	8	7.6	9.6	7.6	7.6	7.6	7.6	7.6	14.2	14.8	12.8	12	13.2
5	100	12	5.4	7.6	5.4	5.6	5.4	5.4	5.4	14.2	14.4	12.6	13.2	12
5	200	4	30.6	32.2	30.6	30.6	30.6	30.6	30.6	32.8	32.4	32.4	32	33
5	200	8	15.6	17.4	15.6	15.6	15.6	15.6	15.6	23.6	24.6	22.4	19.4	20.4
5	200	12	10.4	12.4	10.4	10.4	10.4	10.4	10.4	21.8	22.8	20.4	19.2	16.2
5	500	4	76.6	78	76.6	76.6	76.6	76.6	76.6	78.6	78.6	78	77.8	79
5	500	8	38.6	40	38.6	38.6	38.6	38.6	38.6	46	44.4	45	42.8	42
5	500	12	26	27.4	26	26	26	26	26	38	36.2	39.8	37.6	33.8
5	1000	4	152.2	153.8	152.2	152.2	152.2	152.2	152.2	153.6	153.6	154.2	154.2	153.4
5	1000	8	76.6	78.2	76.6	76.6	76.6	76.6	76.6	82.2	81.8	81.4	80.2	79.6
5	1000	12	51	52.8	51	51	51	51	51	61.4	60.8	60.4	63	60.4
10	50	4	7.8	12.6	9	8	7.8	7.8	7.8	12.4	11	10.2	9.8	9.6
10	50	8	4	10	6	6	5	4	4	10.8	10.8	10.4	8.8	8.8
10	50	12	3	9.4	5.6	4.6	4.4	3.2	3	12	11.4	9	8.8	8.6
10	100	4	14.8	19.6	15.8	15.6	15	14.8	14.8	20.4	20.2	20.2	16.8	17.4
10	100	8	7.6	12.6	9.2	9.8	9.6	7.8	7.6	20	18.4	17	13.6	13.6
10	100	12	5.2	10.4	7	7	7.2	6.4	5.2	18.4	17.8	17.6	13.8	14.2
10	200	4	28.6	33.2	29.6	29.6	28.6	28.6	28.6	35.4	36	34.4	31.4	30.6
10	200	8	14.4	19.2	16.4	16.6	16.2	14.8	14.4	28.6	29.2	25.6	27.4	23
10	200	12	9.8	15	12	12	11.8	11.4	9.8	26.4	27.2	26.8	24.2	24
10	500	4	69.8	74.2	69.8	69.8	69.8	69.8	69.8	78	75.4	74.6	74.2	71.2
10	500	8	35	39.4	35.6	35	35.2	35	35	52.8	49.4	52.6	51.4	52.6
10	500	12	23.6	28	25.2	24.8	24.8	24	23.6	50.2	48.4	50	47.4	47.6
10	1000	4	137.6	141.8	137.6	137.6	137.6	137.6	137.6	143.2	143.8	143.4	141.8	140.2
10	1000	8	69	73.2	69.2	69	69.2	69	69	87.8	84.8	85.8	86	85.2
10	1000	12	46.2	50.4	46.6	46.8	46.8	46.6	46.2	77.2	78	74.4	76.4	74.8

Table 3: Results of the instances with $P \in \{20, 30\}$

P	N	H	Heu					Ran					K=50	K=100
			LB	UB	K=0	K=10	K=20	K=50	K=100	K=0	K=10	K=20		
20	50	4	7.2	19.6	9	9	8	7.2	7.2	13	12.2	10.8	10.2	9.6
20	50	8	3.8	19	7.8	7	6.6	5.4	3.8	12.8	13	10.8	8.8	8.8
20	50	12	2.8	19	7.8	6.6	5.6	4	2.8	13.6	12.4	11	8	8
20	100	4	14.2	25	16	16	16	14.2	14.2	21	21.8	22.2	17.8	16
20	100	8	7.4	19.6	10.8	11	10.8	10.2	7.6	20.6	19.4	19.4	17.4	13.4
20	100	12	5	19.2	10.2	9.8	9	9	7.6	21.2	21.4	20	18.4	13
20	200	4	27.6	37.6	29.8	30.2	29.8	28.8	27.6	39.6	37	37.2	36.4	31.8
20	200	8	14.2	25.2	17.6	18	18	17.4	17.4	33.4	35.4	32	31.8	28.6
20	200	12	9.4	21.6	13.8	13	13.8	13.2	13.4	33.8	31.6	31.8	30.2	30.8
20	500	4	67.6	77.2	70.2	70.4	70	70.4	67.6	80	81	80.8	80.4	77.8
20	500	8	34	43.6	38	37.6	37.8	38	38	64.2	64.6	62.6	61.4	61
20	500	12	22.8	33.2	27	27.2	27.2	27.2	27.2	60.8	61.6	62.4	59.8	58
20	1000	4	134.4	143.6	135.8	135.8	136.2	136	134.4	148	146	148.6	148.4	147.4
20	1000	8	67.6	76.8	70.6	71	70.4	70.4	70.6	102.2	101.6	101	100.2	100.8
20	1000	12	45.2	54.4	48.8	49.8	49.2	49.2	48.8	93.8	97.4	97.4	94.8	91.6
30	50	4	8	29.8	10	9.8	9.4	8	8	15.8	13.4	11	10.6	10.6
30	50	8	4.2	29	8.2	7.8	7.6	5.2	4.2	15.8	13.2	11.6	10	9.6
30	50	12	3	29	8	7.4	6.8	5.2	3.4	14.6	14.4	12.8	9	8.8
30	100	4	13.8	33.4	16.8	16.6	16.2	15.6	13.8	22.4	22.8	22.8	19.6	16.6
30	100	8	7.2	29.6	12	11.4	11.8	10.8	9.8	22	21.8	20.8	19	15
30	100	12	5	29	10.8	10.4	10.2	9.8	8.2	21.8	21.8	20.4	19.8	15.2
30	200	4	27.6	43.8	30.4	31	31.6	31.2	28	40.6	39.8	41.2	38.6	34
30	200	8	14	32.2	18.6	18.8	19	19.4	19.8	36.4	36.2	36.2	36.8	32.8
30	200	12	9.6	29.8	17	16.6	16.2	16.2	16.2	35.6	36	37	34.8	33.4
30	500	4	64.8	80.4	69.6	69.6	69.6	69.4	69.2	83.2	82.2	82.8	82	81.8
30	500	8	32.6	49	38.4	38.6	38.6	38.2	37.8	68.8	66	68.6	70.6	66.4
30	500	12	22.2	39.2	29	29	28.6	28.6	28.8	69.2	67.4	66.2	66.6	66
30	1000	4	128.8	144	133.6	133.6	133.6	133.8	133.6	149	150.8	150	147.8	150.6
30	1000	8	64.8	80.4	71.4	70.6	71	70.6	70.6	111.2	112.8	111.8	110.6	110
30	1000	12	43.2	59.4	50.8	50.6	50.8	50.8	50.8	107.6	108.8	108.6	107	101.2

one specific variable or factor while keeping other variables unchanged.

As far as we are concerned, we think it is the density and sparseness of stacks that cause this consequence. In other words, the smaller value of each variable is, the same kind of containers that have the identical origin port and destination port have more chance to be placed in the same stack and less rehandles will arise. We call this kind of stack with high density, and the high sparseness in contrast.

For the instance with the same P , N and H , we call it benchmark instance when K is equal to zero. If the number of used stacks is larger than the benchmark instance when K isn't equal to zero, we call it an exceptional instance. There are few exceptions when we analyze the result through a large amount of experiments. Comparing with the zero rehandles, the number of needed stack is even larger when the allowed rehandle K isn't equal to zero, though the deviation is not great.

We then find out those exceptional instances and compare the stowage planning with the same instances under the zero rehandle constraint, and we think it's the distribution status of previous containers to be blamed. The allowed rehandles delay the production of new stacks but not to reduce them, that's why the problem happens. Actually, it's the unloading strategy for blocking containers that causes this exceptional condition. Because we reset the origin port of blocking containers, the loading containers in current port increases and meanwhile the allowed rehandles run out. In the end, the new stacks are needed under the coincidence. In order to prove it, we output the layout of the exceptional instances and the corresponding benchmark instances. By comparing the exceptional instances with the corresponding benchmark instances, we get the conclusion that both the distribution of containers and the algorithm are blamed for this kind of abnormal condition. In our heuristic algorithm, we reset the blocking containers' origin ports as the current port, and it enlarges the number of containers to be loaded. Meanwhile, the allowed rehandles run out and thus new stacks are needed to stow those new outbound containers.

However, it doesn't mean that our algorithm isn't universal because the probability of causing exceptional instances is very low and it hardly happens in our practical operations. Therefore, our heuristics algorithm is feasible for most of the instances and has a good performance as well. The following tables and figures can be used to illustrate the good performance of our algorithm.

We then analyze the average result of all instances to get some conclusions. Table 4 and Figure 2 give the average results of heuristic and random algorithm when the allowed rehandle K has different values. It's not difficult to draw the conclusion that the number of used stacks gets smaller as the allowed rehandle becomes larger for both heuristic algorithm and random algorithm. Another conclusion is, comparing with random algorithm, our heuristic algorithm has a fairly good performance to work out the solution to the SSMP. It's noteworthy that the average results in Table 4 include the instances with $N = 5000$.

There is a simple example to elaborate why a certain number of allowed rehandles can improve the uti-

Table 4: average results of the instances with different K for two algorithms

K	0	10	20	50	100
<i>Numofstack</i> of Heu	99.3	99.21944	99.08333	98.73889	98.35
<i>Numofstack</i> of Ran	114.62778	114.31667	114.21448	112.86111	111.9

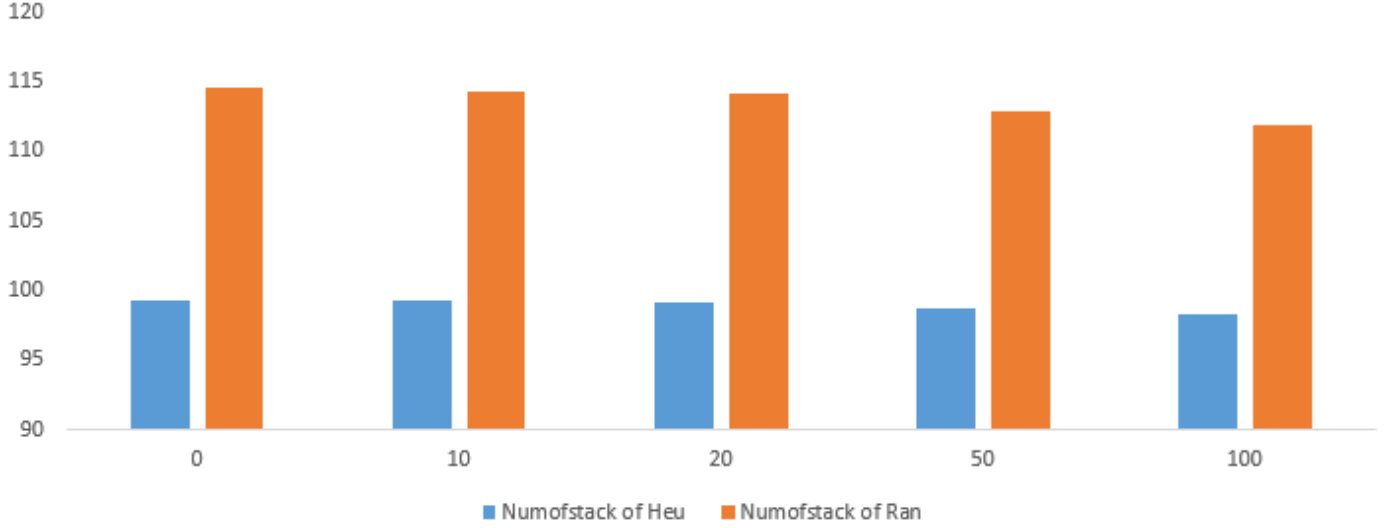


Figure 2: Numofstack of Heu and Ran with different K.

lization of containership comparing with the zero rehandle. Assuming that there are thirteen containers to be transported along the voyage with six ports. We let $C(i,j)$ denote index container whose origin port is i and destination port j . The following is the way to denote those containers: four containers are $C(1,3)$, one is $C(2,4)$, one is $C(2,6)$, four are $C(3,5)$, one is $C(4,6)$ and two are $C(5,6)$.

If they are loaded without any rehandles, the loading sequence and layout will be the following Figure 3.

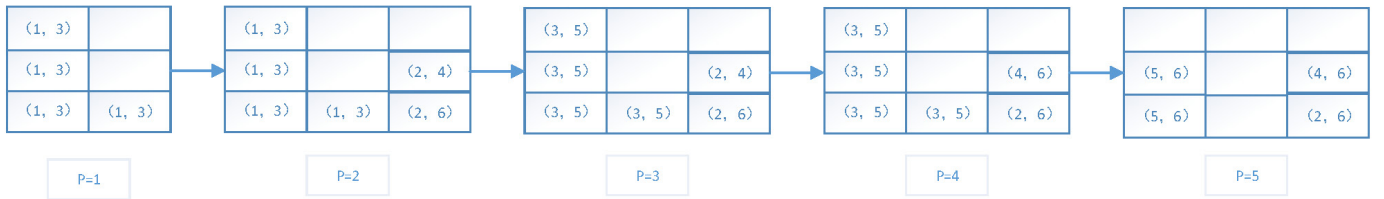


Figure 3: stowage plan without rehandle.

If they are loaded with rehandles, the loading sequence and layout will be the following Figure 4.

From the above figures, we can draw the conclusion that allowing a certain number of rehandles will reduce the number of stacks used to store containers in a vessel compared with zero rehandle. That's to say, the utilization of containership can be improved if some rehandles are allowed.

In fact, we have tried a related algorithm named $P\&H$ algorithm before adopting our current heuristic algorithm to get the stowage planning. This algorithm is actually a process of parameter tuning, our original

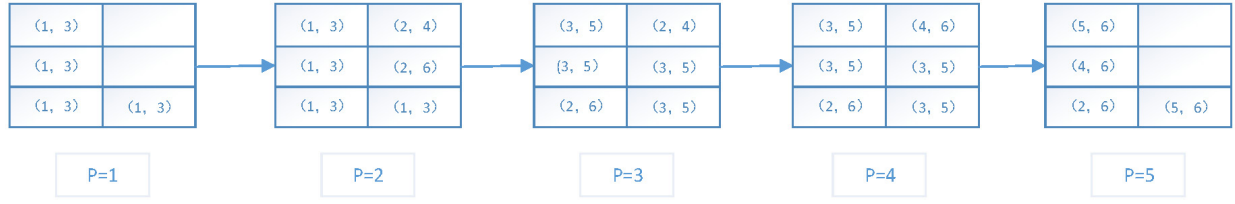


Figure 4: stowage plan with rehandle.

intention is attempting to find out better solution to stow containers. Nevertheless, the result through this algorithm isn't as good as the heuristic algorithm and it doesn't work well as we expected if the value of K is small. From another point of view, it just shows the good performance of our heuristic algorithm.

In our $P\&H$ algorithm, we give some restrictions on the height and the destination port of current loading container when choosing stack for each container. All the parameters in $P\&H$ value between 0 and 1, the former is not included. The former parameter represents the ratio of the loading container's destination port and the farthest port P . If their values are equal, the value of parameter is 1. The latter parameter represents the ratio of stack's height and the limited height H . The main idea of $P\&H$ algorithm is to take the destination port of loading container and the limit height of stack into consideration. The purpose of this algorithm is to load those containers with farther destination port into the bottom of stack and the computational result will be listed in the Table 5.

Table 5: average results of the instances with $P\&H$ algorithm

$P\&H$	0	10	20	50	100
0.75&0.75	99.32222	99.24167	99.08056	98.725	98.29167
0.75&0.80	99.32222	99.24167	99.08056	98.725	98.29167
0.80&0.75	99.30833	99.225	99.05556	98.71111	98.31389
0.80&0.80	99.30833	99.225	99.05556	98.71111	98.31389

Table 5 shows the result with "P&H" algorithm, which is firstly designed to improve the original algorithm and eventually it is used to prove the good performance of our original algorithm. It's noteworthy that the average results in Table 5 include the instances with $N = 5000$. Both the values of two parameters of the algorithm are selected from $\{0.75, 0.8\}$. It's clear that the result shows the allowed rehandles will decrease the number of used stacks as the above results in Table 4. We can draw a conclusion that the first parameter has a significant influence on the result while the second parameter makes no difference if we compare the result in each line. I suppose that it happens as a result of the value set of H . Comparing with the results shown in Table 4, we could find that original algorithm we propose works better when the value of K is small while the "P&H" algorithm gets the similar results when the value of K is large.

To find the relationship between the related parameters and the result of our heuristic. We use some data from our results obtained from heuristic algorithm to produce the Figure 5 to make it visual.

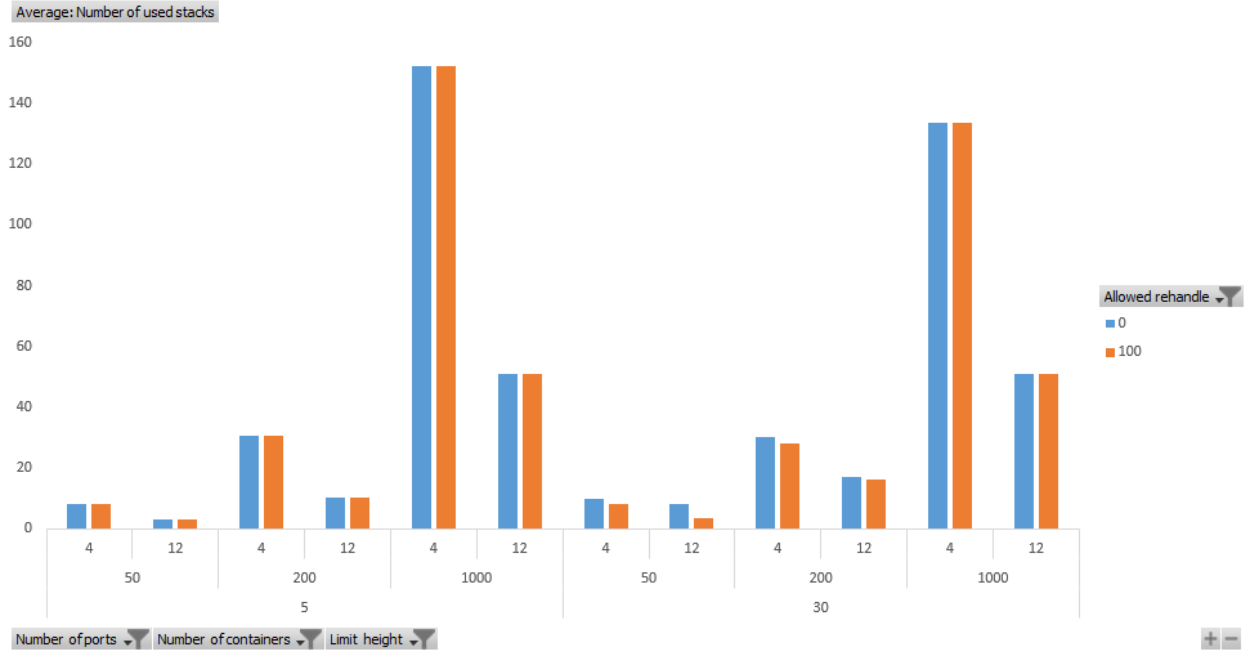


Figure 5: comprehensive analysis.

Seeing from Figure 5, we can get the following relationships. On one hand, the more ports, the more containers and the higher the limit height will result in the more needed stacks if we only change the factor we want to analyze. On the other hand, the difference in the results between zero rehandle and some allowed rehandles become obvious as the number of port gets larger, the limit height gets higher and the number of container gets smaller.

In short, the rationality and good performance of our heuristic have been confirmed through the above tables and figures.

6. Conclusion

The stowage stack minimization problem with K-rehandle constraint (SSMP-KR) is aimed to find out a stowage plan that fewest stacks on a containership are required to accommodate given containers throughout a voyage by subject to K-rehandles.

In this paper, we analyze the structure of this two-dimensional bin-packing optimization problem and its relationship with the SSMP-ZR problem proposed in Wang et al. (2014).

We can regard the stowage stack minimization problem with zero rehandle as an particular case when we choose the value of K as zero. Hence, the problem proposed in this paper is a generalized and extended problem of SSMP-ZR considering the existence of K-rehandle.

On the one hand, the stowage planning problems in cyclic navigation path is converted into linear navigation path using the specific method. On the other hand, the result is equivalent to each other whether we convert or not.

In this paper, we presented the integer programming model for the SSMP-ZR and presented a simple IP model for the SSMP-KR.

A heuristic approach is proposed to construct near-optimal solutions to the SSMP-KR problem in a very short computational time. Since there are different status in the process of handling containers, different methods in our algorithm are thought to cope with the corresponding conditions.

The experimental results show that our heuristic approaches generate very promising solutions on a variety of instances. Comparing with the stowage stack minimum problem with zero constraint, our problem with K rehandle constraint can offer a certain flexibility for the actual problem. The results show the problem we put forward is of practical significance and it can improve the utilization of containership. Our algorithm uses greedy rules to find the best slot for each container, hence the results may be the near-optimal rather than global optimal. As we all know, it is difficult to get the global optimal for this kind of problem. Applying this algorithm into the real shipping management can enhance the hull space utilization and reduce some spending in the case of improving the utilization of containership. The novelty and practicality show the importance of this paper and it can give a reference to the future study.

Furthermore, the rehandles are unavoidable in the actual port operation, which indicates the problem we propose in this paper does make some sense and the solution we work out using our heuristic algorithm can provide a preliminary assessment for forwarders to arrange linear shipping company for transportation.

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