

Appendix: Portfolio Management ¹

1 Lagrangian Method

1.1 Equality constraints

Let (P) be the optimisation problem under constraints

$$(P) \begin{cases} \inf_{x \in \mathbf{R}^d} f(x) \\ g_1(x) = 0 \\ \vdots \\ g_k(x) = 0 \end{cases}$$

where $f(\cdot)$ and the $g_i(\cdot)$ are differentiable functions from \mathbf{R}^d into \mathbf{R} . We note, $\mathcal{D} = \{x \in \mathbf{R}^d, g_1(x) = 0, \dots, g_k(x) = 0\}$.

Definition .1. The Lagrangian of (P) is the function from \mathbf{R}^{d+k} into \mathbf{R} defined by

$$\mathcal{L}(x, \lambda) = f(x) - \sum_{i=1}^{i=k} \lambda_i g_i(x)$$

with $\lambda = (\lambda_1, \dots, \lambda_k)'$.

The following proposition explains how the Lagrangian method transforms an optimisation problem under constraints into an optimisation problem without constraint.

Proposition .1. Solving the problem (P) is equivalent to solving

$$(Q) \inf_{x \in \mathbf{R}^d} \sup_{\lambda \in \mathbf{R}^k} \mathcal{L}(x, \lambda).$$

Proof. $x \notin \mathcal{D} \implies \exists i, g_i(x) \neq 0 \implies \sup_{\lambda \in \mathbf{R}^k} \mathcal{L}(x, \lambda) = +\infty$ as the term $-\lambda_i g_i(x)$ tends to $+\infty$ when λ_i tends to $+\infty$ or $-\infty$ (depending on the sign of $g_i(x)$). So,

$$\inf_{x \in \mathbf{R}^d} \sup_{\lambda \in \mathbf{R}^k} \mathcal{L}(x, \lambda) = \inf_{x \in \mathcal{D}} \sup_{\lambda \in \mathbf{R}^k} \mathcal{L}(x, \lambda)$$

Now,
 $x \in \mathcal{D} \implies \forall \lambda \in \mathbf{R}^k, \mathcal{L}(x, \lambda) = f(x) \implies \sup_{\lambda \in \mathbf{R}^k} \mathcal{L}(x, \lambda) = f(x).$

So,

$$\inf_{x \in \mathcal{D}} \sup_{\lambda \in \mathbf{R}^k} \mathcal{L}(x, \lambda) = \inf_{x \in \mathcal{D}} f(x)$$

which finishes the proof. □

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Definition .2. *Dual Problem*

$$(Q^*) \sup_{\lambda \in \mathbf{R}^k} \inf_{x \in \mathbf{R}^d} \mathcal{L}(x, \lambda).$$

is called the dual problem of (Q) .

Usually, the dual problem (Q^*) is easier to solve than the initial problem (Q) . In the dual problem the sup is calculated for a concave function as demonstrated below.

Property .1. *The function: $\phi : \lambda \longrightarrow \inf_{x \in \mathbf{R}^d} \mathcal{L}(x, \lambda)$ is concave*

Proof. Let $t \in [0, 1]$ and λ_1 and $\lambda_2 \in \mathbf{R}^k$.

$$\forall z \in \mathbf{R}^d, \inf_{x \in \mathbf{R}^d} \mathcal{L}(x, \lambda_1) \leq \mathcal{L}(z, \lambda_1) \text{ and } \inf_{x \in \mathbf{R}^d} \mathcal{L}(x, \lambda_2) \leq \mathcal{L}(z, \lambda_2)$$

$$\implies \forall z \in \mathbf{R}^d, t \inf_{x \in \mathbf{R}^d} \mathcal{L}(x, \lambda_1) + (1-t) \inf_{x \in \mathbf{R}^d} \mathcal{L}(x, \lambda_2) \leq t\mathcal{L}(z, \lambda_1) + (1-t)\mathcal{L}(z, \lambda_2)$$

and as $\mathcal{L}(x, \lambda)$ is an affine function of λ we get

$$\implies \forall z \in \mathbf{R}^d, t \inf_{x \in \mathbf{R}^d} \mathcal{L}(x, \lambda_1) + (1-t) \inf_{x \in \mathbf{R}^d} \mathcal{L}(x, \lambda_2) \leq \mathcal{L}(z, \lambda_1 + (1-t)\lambda_2)$$

$$\implies t \inf_{x \in \mathbf{R}^d} \mathcal{L}(x, \lambda_1) + (1-t) \inf_{x \in \mathbf{R}^d} \mathcal{L}(x, \lambda_2) \leq \inf_{z \in \mathbf{R}^d} \mathcal{L}(z, \lambda_1 + (1-t)\lambda_2)$$

$$\implies t\phi(\lambda_1) + (1-t)\phi(\lambda_2) \leq \phi(\lambda_1 + (1-t)\lambda_2)$$

which proves the concavity of ϕ . \square

The initial problem (Q) is called the primal problem. A link between the primal problem and the dual problem (Q^*) is given by the minimax theorem.

Theorem .1. *mini-max theorem*

For any domains \mathcal{Y} and \mathcal{Z} and real function g defined on $\mathcal{Y} \times \mathcal{Z}$:

$$\sup_{z \in \mathcal{Z}} \left[\inf_{y \in \mathcal{Y}} g(y, z) \right] \leq \inf_{y \in \mathcal{Y}} \left[\sup_{z \in \mathcal{Z}} g(y, z) \right]$$

$$\text{Proof. } \inf_{y \in \mathcal{Y}} g(y, z) \leq g(y, z) \Rightarrow \sup_{z \in \mathcal{Z}} \left[\inf_{y \in \mathcal{Y}} g(y, z) \right] \leq \sup_{z \in \mathcal{Z}} g(y, z) \quad (1)$$

As (1) is true for all y , the inequality stands for the inf of the right term of (1).

$$\text{So, } \sup_{z \in \mathcal{Z}} \left[\inf_{y \in \mathcal{Y}} g(y, z) \right] \leq \inf_{y \in \mathcal{Y}} \left[\sup_{z \in \mathcal{Z}} g(y, z) \right] \quad \text{Q.E.D.}$$

\square

Definition .3. *Duality*

The difference between $\inf_{y \in \mathcal{Y}} \left[\sup_{z \in \mathcal{Z}} g(y, z) \right]$ and $\sup_{z \in \mathcal{Z}} \left[\inf_{y \in \mathcal{Y}} g(y, z) \right]$ is called the duality gap. When the **duality gap** is zero, we say that there is **strong duality** or **no duality gap**.

There are some mathematical conditions which guarantee that the duality gap is zero (Slater's conditions and non-empty interior condition).

Remark .1. *Example with duality gap.*

In this example:

$g(y, z)$	$y=1$	$y=2$	$y=3$
$z=3$	3	3	1
$z=2$	2	1	3
$z=1$	1	2	3

$$\sup_{z \in \mathcal{Z}} \left[\inf_{y \in \mathcal{Y}} g(y, z) \right] = 1$$

$$\inf_{y \in \mathcal{Y}} \left[\sup_{z \in \mathcal{Z}} g(y, z) \right] = 3 \text{ and the duality gap is 2.}$$

Here, with our notations we can write

$$(\text{dual problem}) \ d^* = \sup_{\lambda \in \mathbf{R}^k} \inf_{x \in \mathbf{R}^d} \mathcal{L}(x, \lambda) \leq \inf_{x \in \mathbf{R}^d} \sup_{\lambda \in \mathbf{R}^k} \mathcal{L}(x, \lambda) = p^* \text{ (primal problem)}$$

To solve $\sup_{\lambda \in \mathbf{R}^k} \inf_{x \in \mathbf{R}^k} \mathcal{L}(x, \lambda)$ we can consider the following approach:

- solve $\inf_{x \in \mathbf{R}^k} \mathcal{L}(x, \lambda)$ and for this solve $\frac{\partial \mathcal{L}}{\partial x}(x, \lambda) = 0$ and find a solution $x^*(\lambda)$ dependent on λ then,
- solve $\sup_{\lambda \in \mathbf{R}^k} \mathcal{L}(x^*(\lambda), \lambda)$, and for this solve $\frac{\partial \mathcal{L}}{\partial \lambda}(x^*(\lambda), \lambda) = 0$ to obtain λ^* .
- from this get the solution $x^*(\lambda^*)$.

In practice, instead of solving $\frac{\partial \mathcal{L}}{\partial \lambda}(x^*(\lambda), \lambda) = 0$ we solve

$$\forall i \in \llbracket 1, k \rrbracket, g(x^*(\lambda)) = 0$$

the two being equivalent, as demonstrated in the following proposition which assumes some differentiability properties for $x^*(\lambda)$.

Property .2. .

$$\{\lambda \in \mathbf{R}^k, \frac{\partial \mathcal{L}}{\partial \lambda}(x^*(\lambda), \lambda) = 0\} = \{\lambda \in \mathbf{R}^k \text{ such that } \forall i \in \llbracket 1, k \rrbracket, g_i(x^*(\lambda)) = 0\}.$$

Proof. $\frac{\partial \mathcal{L}}{\partial \lambda}(x^*(\lambda), \lambda) = 0$

$$\iff \forall j \in \llbracket 1, k \rrbracket,$$

$$\sum_{i=1}^{i=d} \frac{\partial f}{\partial x_i}(x^*(\lambda)) \frac{\partial x_i^*}{\partial \lambda_j}(\lambda) - g_j(x^*(\lambda)) - \sum_{l=1}^k \left[\lambda_l \sum_{i=1}^{i=d} \frac{\partial g_l}{\partial x_i}(x^*(\lambda)) \frac{\partial x_i^*}{\partial \lambda_j}(\lambda) \right] = 0$$

$$\Longleftrightarrow \forall j \in \llbracket 1, k \rrbracket,$$

$$\sum_{i=1}^{i=d} \frac{\partial f}{\partial x_i}(x^*(\lambda)) \frac{\partial x_i^*}{\partial \lambda_j}(\lambda) - g_j(x^*(\lambda)) - \sum_{i=1}^{i=d} \left[\sum_{l=1}^k \lambda_l \frac{\partial g_l}{\partial x_i}(x^*(\lambda)) \frac{\partial x_i^*}{\partial \lambda_j}(\lambda) \right] = 0$$

$$\Longleftrightarrow \forall j \in \llbracket 1, k \rrbracket,$$

$$\sum_{i=1}^{i=d} \left[\frac{\partial f}{\partial x_i}(x^*(\lambda)) - \sum_{l=1}^k \lambda_l \frac{\partial g_l}{\partial x_i}(x^*(\lambda)) \right] \frac{\partial x_i^*}{\partial \lambda_j}(\lambda) - g_j(x^*(\lambda)) = 0$$

but $x^*(\lambda)$, solves $\frac{\partial \mathcal{L}}{\partial x}(x^*(\lambda), \lambda) = 0$ and so for the first term in bracket above

$$\forall i \in \llbracket 1, d \rrbracket, \frac{\partial f}{\partial x_i}(x^*(\lambda)) - \sum_{l=1}^k \lambda_l \frac{\partial g_l}{\partial x_i}(x^*(\lambda)) = 0$$

Therefore, $\frac{\partial \mathcal{L}}{\partial \lambda}(x^*(\lambda), \lambda) = 0 \Longleftrightarrow \forall j \in \llbracket 1, k \rrbracket, g_j(x^*(\lambda)) = 0$. Q.E.D. □

So, in practice to solve (P) first we solve in x the equation $\frac{\partial \mathcal{L}}{\partial x}(x, \lambda) = 0$ which gives a solution $x^*(\lambda)$ dependent on λ . Then we solve in λ the equations $g_i(x^*(\lambda)) = 0$ which gives the solution $x^*(\lambda^*)$ for which the optimum is reached. The next section illustrates the method.

1.2 Solution of the Markowitz problem

We solve,

$$(P) \begin{cases} \inf_{\pi \in \mathbb{R}^d} \pi' \Sigma \pi \\ \pi' M = m \\ \pi' 1_d = 1 \end{cases} \text{ where } 1_d \text{ is the vector of } \mathbb{R}^d \text{ with components equal to 1}$$

The Lagrangian is, $\mathcal{L}(\pi, \lambda) = \pi' \Sigma \pi - \lambda_1(\pi' M - m) - \lambda_2(\pi' 1_d - 1)$

We solve,

$$\begin{aligned} \frac{\partial \mathcal{L}}{\partial \pi}(\pi, \lambda) &= 0 \\ \Longleftrightarrow 2\Sigma\pi - \lambda_1 M - \lambda_2 1_d &= 0 \\ \Longleftrightarrow \pi &= \frac{\lambda_1}{2} \Sigma^{-1} M + \frac{\lambda_2}{2} \Sigma^{-1} 1_d \end{aligned}$$

to satisfy the second constraint we get,

$$\pi' 1_d = 1 \Longleftrightarrow \frac{\lambda_1}{2} b + \frac{\lambda_2}{2} a = 1$$

so, $\pi = \frac{\lambda_1}{2} \Sigma^{-1} M + (\frac{1}{a} - \frac{\lambda_1}{2} \frac{b}{a}) \Sigma^{-1} 1_d = \frac{1}{a} \Sigma^{-1} 1_d + \frac{\lambda_1}{2} \Sigma^{-1} (M - \frac{b}{a} 1_d)$

The second constraint $\pi' M = m$ determines λ_1 and the portfolio in a unique way as a function of m ,

$$\pi' M = m \Longleftrightarrow \frac{1}{a} b + \frac{\lambda_1}{2} \|M - \frac{b}{a} 1_d\|_{\Sigma^{-1}}^2 = m$$

$$\iff \frac{\lambda_1}{2} = \frac{m - \frac{b}{a}}{\|M - \frac{b}{a}1_d\|_{\Sigma^{-1}}^2}$$

So, the solution (investment) portfolio solution of (P) is

$$\pi^* = \frac{1}{a}\Sigma^{-1}1_d + \frac{m - \frac{b}{a}}{\|M - \frac{b}{a}1_d\|_{\Sigma^{-1}}^2}\Sigma^{-1}(M - \frac{b}{a}1_d)$$

1.3 Inequality constraints

Let (P) be the optimisation problem under constraints

$$(P) \left\{ \begin{array}{l} \inf_{x \in \mathbf{R}^d} f(x) \\ g_1(x) = 0 \\ \vdots \\ g_k(x) = 0 \\ h_1(x) \geq 0 \\ \vdots \\ h_m(x) \geq 0 \end{array} \right.$$

where $f(\cdot)$ the $g_i(\cdot)$ and the $h_j(\cdot)$ are differentiable functions from \mathbf{R}^d into \mathbf{R} . We note, $\mathcal{D} = \{x \in \mathbf{R}^d, g_1(x) = 0, \dots, g_k(x) = 0, h_1(x) = 0, \dots, h_m(x) = 0\}$.

Definition .4. The Lagrangian of (P) is the function from \mathbf{R}^{d+k} into \mathbf{R} defined by

$$\mathcal{L}(x, \lambda, \mu) = f(x) - \sum_{i=1}^k \lambda_i g_i(x) - \sum_{j=1}^m \mu_j h_j(x)$$

with $\lambda = (\lambda_1, \dots, \lambda_k)'$ and $\mu = (\mu_1, \dots, \mu_m)'$.

The following proposition explains how the Lagrangian method transforms an optimisation problem under constraints into an optimisation problem without constraint.

Proposition .2. Solving the problem (P) is equivalent to solving

$$(Q) \inf_{x \in \mathbf{R}^d} \sup_{\lambda \in \mathbf{R}^k, \mu \in (\mathbf{R}^+)^m} \mathcal{L}(x, \lambda, \mu)$$

Proof. Let $x \notin \mathcal{D}$,

if $\exists i, g_i(x) \neq 0$ then, $\sup_{\lambda \in \mathbf{R}^k} \mathcal{L}(x, \lambda) = +\infty$ as the term $-\lambda_i g_i(x)$ tends to $+\infty$

when λ_i tends to $+\infty$ or $-\infty$ (depending on the sign of $g_i(x)$).

if $\exists j, h_j(x) < 0$ then, $\sup_{\lambda \in \mathbf{R}^k} \mathcal{L}(x, \lambda) = +\infty$ as the term $-\lambda_j h_j(x)$ tends to $+\infty$

when μ_j tends to $+\infty$.

Now, if $x \in \mathcal{D}$, $\sup_{\lambda \in \mathbf{R}^k, \mu \in (\mathbf{R}^+)^m} \mathcal{L}(x, \lambda, \mu)$ is obtained for $\mu = 0$

Therefore,

$$\begin{aligned}
& \inf_{x \in \mathbf{R}^d} \sup_{\lambda \in \mathbf{R}^k, \mu \in (\mathbf{R}^+)^m} \mathcal{L}(x, \lambda, \mu) \\
&= \inf_{x \in \mathcal{D}} \sup_{\lambda \in \mathbf{R}^k, \mu \in (\mathbf{R}^+)^m} \mathcal{L}(x, \lambda, \mu) \\
&= \inf_{x \in \mathcal{D}} f(x)
\end{aligned}$$

□

and as before we solve the dual problem.

Remark .2. We do not need the equality constraints $g_i(x) = 0$ to describe the general case as such constraints can be expressed as $-g_i(x) \geq 0$ and $g_i(x) \geq 0$.

Property .3. *Complementary Slackness*

If we assume that,

- $d^* = p^*$ (no duality gap)
- $\exists x^* \in \mathcal{D}, p^* = f(x^*)$ (there is an optimal point for the primal problem)
- $\exists \mu^* \in (\mathbf{R}^+)^m, \sup_{\mu \in (\mathbf{R}^+)^m} \inf_{x \in \mathbf{R}^d} \mathcal{L}(x, \mu) = \inf_{x \in \mathbf{R}^d} \mathcal{L}(x, \mu^*)$ (there is an optimal point for the dual problem).

Then, $\forall i \in \llbracket 1, m \rrbracket, \mu_i^* h_i(x^*) = 0$.

Proof. $f(x^*) = \inf_{x \in \mathbf{R}^d} \mathcal{L}(x, \mu^*) \implies f(x^*) \leq \mathcal{L}(x^*, \mu^*)$

$$\implies f(x^*) \leq f(x^*) - \sum_{i=1}^{i=m} \mu_i^* h_i(x^*)$$

but all the terms $-\mu_i^* h_i(x^*)$ are negative so equality can be obtained only iff all these terms are zero. Q.E.D. □