2

# Vector Spaces (向量空间)

2.4

## THE FOUR FUNDAMENTAL SUBSPACES

(四个基本子空间)

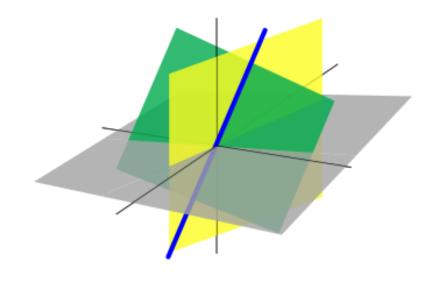
Column space

Row space

**Nullspace** 

Left nullspace

Full Rank and Rank 1





The previous sections dealt with *definitions*.

vector spaces subspaces spanned subspaces spanning set column spaces nullspaces free variables basic / pivot variables special solutions particular solution complete solution rank linearly dependent linearly independent basis dimension coordinate

special Linearly pivot basis ree dependent set **Solution** solutions basic independent **Solution** complete nullspaces spanning rank **Variable Spanned** spanning rank **Variable Spanned** vector Column **Spaces** spanned vector

#### Introduction

Subspaces can be described in *two ways*:

- 1. We may be given a set of vectors that span the space.
  - Example: The columns span the column space C(A).
  - may include useless vectors (dependent columns)
- 2. We may be told which conditions the vectors in the space must satisfy.
  - Example: The nullspace N(A) consists of all vectors that satisfy Ax = 0.
  - may include repeated conditions (dependent rows)

We know what a basis is, but <u>how to find one</u>?

We need a systematic procedure to compute an explicit basis (基的显示表达).

#### THE FOUR FUNDAMENTAL SUBSPACES

Let A be an  $(m \times n)$ -matrix.

$$m{A} = egin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \ a_{21} & a_{22} & \cdots & a_{2n} \ dots & dots & dots \ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

There are 4 vector spaces related to *A*:

C(A): column space of A
列空间

C(A<sup>T</sup>): row space of A 行空间

N(A): nullspace of A 零空间

N(A<sup>T</sup>): left nullspace of A 左零空间

## Some equivalent notations and definitions:

- C(A) or Col(A): column space of A the subspace spanned by the columns of A
- $C(A^T)$  or R(A): row space of A the subspace spanned by the rows of A It is the column space of  $A^T$ .
- N(A) or null(A): nullspace of A i.e.,  $\{x: x \in \mathbb{R}^n, Ax = 0\}$ .
- $N(A^T)$  or Lnull(A): left nullspace of AIt contains all vectors  $y \in \mathbb{R}^m$  such that  $A^Ty = 0$ , so it is the

nullspace of  $A^{T}$ , i.e.,  $\{y: y \in \mathbb{R}^{m}, A^{T}y = 0\}$ .

It can also be written as  $y^TA = 0$ , so it is called the *left* nullspace of A.

The nullspace N(A) and row space  $C(A^T)$  are subspaces of  $\mathbb{R}^n$ . The left nullspace  $N(A^T)$  and column space C(A) are subspaces of  $\mathbb{R}^m$ .

## **Example 1** For a simple matrix like

$$\boldsymbol{A} = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{vmatrix},$$

The column space C(A) is the line through  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ , and it is in  $\mathbb{R}^2$ .

The row space  $C(A^T)$  is the line through  $\begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^T$ , and it is in  $\mathbb{R}^3$ .

The nullspace is a plane in  $\mathbb{R}^3$ , N(A) contains  $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ .

The left nullspace is a line in  $\mathbb{R}^2$ ,  $N(A^T)$  contains  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ .

**Remark:** Note that all vectors here are expressed as column vectors. (Even the rows are transposed, and the row space of A is the *column* space of  $A^{T}$ .)

#### **Example 2** For a non-zero 2×4 matrix

$$\boldsymbol{A} = \begin{bmatrix} 0 & 1 & 2 & 3 \\ 1 & 2 & 3 & 4 \end{bmatrix},$$

Column space: 
$$C(\mathbf{A}) = \operatorname{Span} \left\{ \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \end{bmatrix} \right\} \subseteq \mathbf{R}^2$$
,

Row space: 
$$C(A^{T}) = \text{Span}\{(0,1,2,3)^{T},(1,2,3,4)^{T}\} \subseteq \mathbb{R}^{4}.$$

Obviously, both subspaces are of dimension equal to 2.

To find a basis of N(A), we convert A into reduced row echelon form

$$\begin{bmatrix} 1 & 0 & -1 & -2 \\ 0 & 1 & 2 & 3 \end{bmatrix}, So \mathbf{A}\mathbf{x} = \mathbf{0} \text{ has two free variables, say}$$
$$x_3 = s \text{ and } x_4 = t.$$

Then a general solution is of the form  $(s + 2t, -2s-3t, s, t)^T$ , where  $s, t \in \mathbb{R}$ .

Thus  $(1, -2, 1, 0)^T$  and  $(2, -3, 0, 1)^T$  form a basis of N(A).

## **Example 2** For a non-zero 2×4 matrix

$$\boldsymbol{A} = \begin{bmatrix} 0 & 1 & 2 & 3 \\ 1 & 2 & 3 & 4 \end{bmatrix},$$

(Continued)

To obtain a basis of  $N(A^T)$ , we convert  $A^T$  into row echelon form

$$\mathbf{A}^{\mathrm{T}} = \begin{bmatrix} 0 & 1 \\ 1 & 2 \\ 2 & 3 \\ 3 & 4 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$$

It follows that the left nullspace  $N(A^T)$  only contains  $\theta$  (zero vector).

# I. Row Spaces

Let A be a matrix, and U the row echelon form of A. Then the row spaces of A and U are the same, i.e., R(A) = R(U).

This is because each row of U is a linear combination of the rows of A. On the other hand, since each elementary row operation is reversible, each row of A can be written as a linear combination of the rows of U.

Thus the rows of A and U span the same vector space.

This leads to a method for finding a basis of the row space of a matrix A, i.e., converting A into row echelon form U so that the non-zero rows of U form a basis of R(A), and the row space has dimension r (rank of A and U).

#### For example,

$$\mathbf{A} = \begin{bmatrix} 1 & 3 & 3 & 2 \\ 2 & 6 & 9 & 7 \\ -1 & -3 & 3 & 4 \end{bmatrix} \rightarrow \mathbf{U} = \begin{bmatrix} 1 & 3 & 3 & 2 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

# II. Nullspaces

Given an  $(m \times n)$ -matrix A with row echelon form U and reduced row echelon form R, the system of linear equations Ax = 0 has the same solutions with the system Ux = 0 and Rx = 0.

Thus the nullspace of A is the same as the nullspace of U (and R). Let r be the rank of A, i.e., the number of non-zero rows of U. Then there are n-r free variables in the system Ux=0, and the nullspace of U is of dimension n-r. We therefore obtain

**Theorem 1** (rank-nullity theorem) Let A be an  $(m \times n)$ -matrix. Then

 $\operatorname{rank}(A) + \operatorname{nullity}(A) = n.$   $\operatorname{Similarly}, \quad \operatorname{rank}(A^{\mathrm{T}}) + \operatorname{nullity}(A^{\mathrm{T}}) = m.$ 

The nullspace is also called the kernel (核) of A, and its dimension n-r is the nullity (零度) of A. nullity(A)=dimension(N(A)).

For example
$$A = \begin{bmatrix} 1 & 3 & 3 & 2 \\ 2 & 6 & 9 & 7 \\ -1 & -3 & 3 & 4 \end{bmatrix} \rightarrow U = \begin{bmatrix} 1 & 3 & 3 & 2 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\rightarrow \mathbf{R} = \begin{bmatrix} 1 & 3 & 0 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

 $\rightarrow \mathbf{R} = \begin{bmatrix} 1 & 3 & 0 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$  The "special solutions" are a basis—each free variable is given the value 1, while the other free variables are 0.

Free variables:  $x_2$ ,  $x_4$ 

Special solutions: 
$$\begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -1 \\ 1 \end{bmatrix}$$

$$n = 4$$

$$r = 2$$
The dimension of N(A) =  $n - r = 2$ 

$$n = 4$$
  
 $r = 2$ 

(nullity)

are definitely independent.

# III. Column Spaces

We notice that, in Example 2, 
$$A = \begin{bmatrix} 0 & 1 & 2 & 3 \\ 1 & 2 & 3 & 4 \end{bmatrix}$$
,

 $C(A^{T})$  and C(A) have the same dimension.



Is it always true that row space and column space have the same dimension?

Example 3 A non-zero 
$$2 \times n$$
 matrix  $A = \begin{bmatrix} a_1 & a_2 & \cdots & a_n \\ b_1 & b_2 & \cdots & b_n \end{bmatrix}$ ,

has row space and column space:

$$C(A^{T}) = \text{span}\{(a_1, a_2, ..., a_n)^{T}, (b_1, b_2, ..., b_n)^{T}\} \subseteq \mathbf{R}^n,$$

$$C(A) = \text{span}\{(a_1, b_1)^T, (a_2, b_2)^T, ..., (a_n, b_n)^T\} \subseteq \mathbb{R}^2.$$

Obviously, both are of dimension at most 2.

If  $C(A^T)$  is of dimension 1, then

$$(b_1, b_2, ..., b_n) = k(a_1, a_2, ..., a_n),$$

so  $b_i = ka_i$  for all i.

Suppose  $a_1 \neq 0$ . Then for  $a_i \neq 0$ , we have

$$\frac{b_i}{a_i} = k = \frac{b_1}{a_1}$$
 and  $\frac{b_i}{b_1} = \frac{a_i}{a_1} = k_i$ 

Thus,  $(a_i, b_i) = k_i(a_1, b_1)$  for all i,

and hence C(A) is of dimension 1.

Similarly, if C(A) is of dimension 1, then  $C(A^T)$  is also of dimension 1.

So the row space and the column space of A have the same dimension.

This is actually true in the general case.

**Theorem 2** For any matrix, its row space and column space have the same dimension, which equals the rank of the matrix.

#### For example,

$$\mathbf{A} = \begin{bmatrix} 1 & 3 & 3 & 2 \\ 2 & 6 & 9 & 7 \\ -1 & -3 & 3 & 4 \end{bmatrix} \rightarrow \mathbf{U} = \begin{bmatrix} 1 & 3 & 3 & 2 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \mathbf{R} = \begin{bmatrix} 1 & 3 & 0 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Note: the column spaces of U and A are different (just look at the matrices!)

but their dimensions are the same.

The first and third columns of U are a basis for its column space.

They are the columns with pivots.

Furthermore, the same is true of the original A—even though its columns are different.

The pivot columns of A are a basis for its column space.

#### The four fundamental subspaces

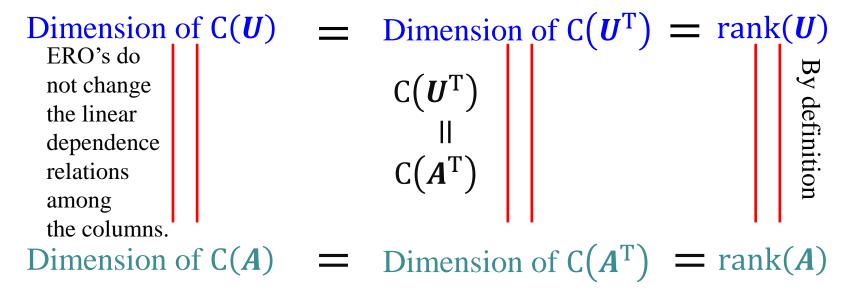
Every linear dependence Ax = 0 among the columns of A is matched by a dependence Ux = 0 (Rx = 0) among the columns of U(R), with exactly the same coefficients. (行变换不改变列之间的相关性) If a set of columns of A is independent, then so are the corresponding columns of U (and R), and vice versa.

Theorem 2 is one of the most important theorems in linear algebra. It is often abbreviated as

"row rank = column rank." (行秩=列秩)

#### For example,

• Given an  $m \times n$  matrix A with row echelon form U,



#### **Summary**

■ For any matrix, its row space and column space have the same dimension, which equals the rank of the matrix.

#### row rank= column rank

- □ For any matrix  $\mathbf{A}$ , rank( $\mathbf{A}$ ) = rank( $\mathbf{A}^{\mathrm{T}}$ ).
- □ For square matrices: If the rows of a square matrix are linearly independent, then so are the columns (and vice versa).

# IV. Left Nullspaces

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In Theorem 1 Let A be an (m \times n)-matrix. Then
                       rank(A) + nullity(A) = n.
                       rank(A^{T}) + nullity(A^{T}) = m.
Similarly,
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Now that  $rank(A) = rank(A^T)$  (Theorem 2), we have  $\text{nullity}(A^{\mathrm{T}}) = \text{dimension}(N(A^{\mathrm{T}})) = m - r$ .

$$C(A) =$$
column space of  $A$ ; dimension  $r$ .

$$N(A)$$
 = nullspace of  $A$ ; dimension  $n-r$ .

$$C(A^{\mathrm{T}})$$
 = row space of A; dimension r.

$$C(A) = \text{column space of } A; \text{ dimension } r.$$
 $N(A) = \text{nullspace of } A; \text{ dimension } n-r.$ 
 $C(A^{T}) = \text{row space of } A; \text{ dimension } r.$ 
 $N(A^{T}) = \text{left nullspace of } A; \text{ dimension } m-r.$ 

Fundamental Theorem of Linear Algebra (Part I)

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix},$$

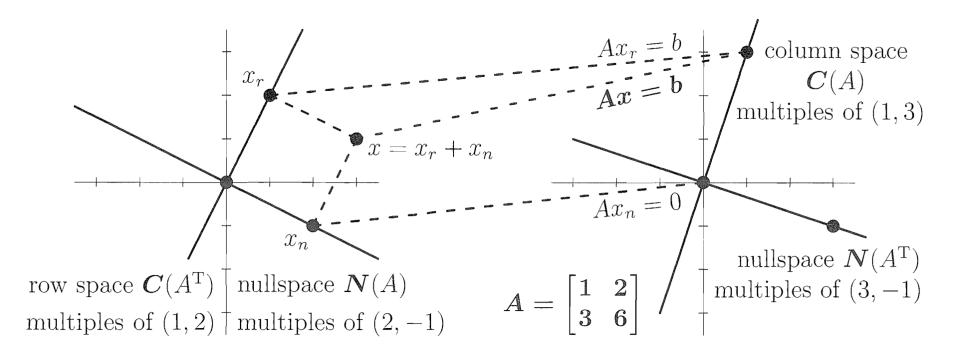
$$m = n = 2$$
, Singular matrix  $r = 1$ .

Column space: Span
$$\{\begin{bmatrix} 1\\3 \end{bmatrix}\}$$

Nullspace: Span
$$\{\begin{bmatrix} 2 \\ -1 \end{bmatrix}\}$$

Row space: Span
$$\{\begin{bmatrix} 1\\2 \end{bmatrix}\}$$

Left nullspace: 
$$Span\{\begin{bmatrix} 3 \\ -1 \end{bmatrix}\}$$



$$\boldsymbol{B} = \begin{vmatrix} 1 & 2 \\ 3 & 7 \end{vmatrix},$$

Example 4 What if -- 
$$B = \begin{bmatrix} 1 & 2 \\ 3 & 7 \end{bmatrix}$$
,  $m = n = 2$ , Invertible matrix  $r = 2$ .

Column space: 
$$Span\{\begin{bmatrix} 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 7 \end{bmatrix}\}$$
  
= $\mathbb{R}^2$ 

Nullspace: 
$$\left\{\begin{bmatrix} 0\\0 \end{bmatrix}\right\}$$

Row space: 
$$Span \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 7 \end{bmatrix} \right\}$$
 Left nullspace:  $\left\{ \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right\}$ 

$$= \mathbb{R}^2$$

## V. Full Rank Matrices (满秩矩阵: extreme case)

We now consider some extremal cases. Let A be an  $(m \times n)$ -matrix.

- If rank(A) = m, then A is said to have full row rank (行满秩).
- If rank(A) = n, then A is said to have full column rank (列满秩).

## For example,

The following matrix *A* has full row rank, and *B* has full column rank.

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 1 & 2 \\ 0 & 2 & 2 & 5 \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 6 \\ 2 & 7 & 3 \\ 1 & 2 & 3 \end{bmatrix}.$$

#### **Definition 1** Let A be an $(m \times n)$ -matrix.

- If there exists a matrix C such that  $AC = I_m$ , then we say A has right-inverse (右逆) C.
- If there exists a matrix B such that  $BA = I_n$ , then we say A has left-inverse (左逆) B.

#### The four fundamental subspaces

- If A has a left-inverse (BA = I) and a right-inverse (AC = I), then the two inverses are equal: B = B(AC) = (BA)C = C.
- The rank always satisfies  $r \leq \min(m, n)$ .
- Existence and Uniqueness of solution to Ax=b
- **EXISTENCE:** Full row rank r = m. (possible only if  $m \le n$ )

Ax = b has at least one solution x for every b if and only if the columns span  $\mathbb{R}^m$ .

Then *A* has an *n* by *m* right-inverse *C* such that  $AC = I_m$  (*m* by *m*).

• UNIQUENESS: Full column rank r = n. (possible only if  $m \ge n$ )

Ax = b has at most one solution x for every b if and only if the columns are linearly independent.

Then *A* has an *n* by *m left-inverse B* such that  $BA = I_n(n \text{ by } n)$ .

• Only a square matrix can have both r = m and r = n, and therefore—Only a square matrix can achieve both existence and uniqueness of solution to Ax=b. Only a square matrix has a two-sided inverse.

How can we find a left-inverse, or a right-inverse for a matrix?

#### Lemma

Let *A* be an  $(m \times n)$ -matrix.

(1) If A has full row rank, and the first m columns are linearly independent, then, writing

$$A = [A_0 \mid X],$$

the matrix

$$oldsymbol{C} = \left[ rac{oldsymbol{A}_0^{-1}}{oldsymbol{ heta}} 
ight]$$

is a right-inverse of A.

(2) If *A* has full column rank, and the first *n* rows are linearly independent, then, writing

$$A = \left| \frac{A_0}{Y} \right|,$$

the matrix

$$\boldsymbol{B} = \left[ \boldsymbol{A}_0^{-1} \mid \boldsymbol{\theta} \right]$$

is a left-inverse of A.

Example 5 Using this lemma to the matrices A, B, it is easy to find a right-inverse of A, and a left-inverse of B.

$$A = \begin{bmatrix} 1 & 0 & 1 & 2 \\ 0 & 2 & 2 & 5 \end{bmatrix}, \qquad B = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 6 \\ 2 & 7 & 3 \\ 1 & 2 & 3 \end{bmatrix}.$$

**Remark:** Generally, if  $AA^{T}$  is invertible, then a right-inverse of A is

$$C = A^{\mathrm{T}} (AA^{\mathrm{T}})^{-1},$$

while if  $A^{T}A$  is invertible, then a left-inverse of A is

$$\boldsymbol{B} = (\boldsymbol{A}^{\mathrm{T}}\boldsymbol{A})^{-1}\boldsymbol{A}^{\mathrm{T}}.$$

We shall study this stuff further later.

# VI. Matrices of Rank 1(秩为1的矩阵: simplest case)

Finally, we make a simple observation about matrices of rank 1. (The rank is as small as possible, except for the zero matrix.) Let A be an  $(m \times n)$ -matrix of rank 1.

For example,

$$\mathbf{A} = \begin{bmatrix} 2 & 1 & 1 \\ 4 & 2 & 2 \\ 8 & 4 & 4 \\ -2 & -1 & -1 \end{bmatrix}, \text{ has rank}(\mathbf{A}) = 1.$$

Then

$$A = uv^{\mathrm{T}}$$
,

where u is a column vector (i.e.,  $(m \times 1)$ -matrix), and  $v^{T}$  is a row vector ( $(1 \times n)$ -matrix).

This is because

- the rows are all multiples of the same row  $v^{T}$ , and
- the columns are all multiples of the same column u.

$$\mathbf{A} = \begin{bmatrix} 2 & 1 & 1 \\ 4 & 2 & 2 \\ 8 & 4 & 4 \\ -2 & -1 & -1 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 4 \\ -1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \\ 8 \\ -2 \end{bmatrix} \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{2} \end{bmatrix}.$$

Every matrix of rank 1 has the simple form

 $A = uv^{T} = column \ times \ row.$ 

The row space and column space are lines—the easiest case.

We remark that if  $A = uv^T$ , then  $A = (cu)(c^{-1}v^T)$ , where c is a non-zero number.

#### **Key words:**

row space, column space, nullspace, left nullspace, rank, full rank

## Homework

#### See Blackboard

Note: In Ex. 35, u,v,w,z are column vectors.

