Homework & Tutorial Problems

- Tutorial
 - Property of DTFT: 5.24
 - ▶ Difference equation of LTI systems: 5.36
- Homework
 - **5.23**, **5.29**, **5.33**





Convolution Property & LTI Systems (1/2)

- Let h[n] be the impulse response of certain LTI system
- The output y[n] of input x[n] is given by y[n] = x[n] * h[n]
- For input signal $x[n] = e^{j\omega n}$,

$$y[n] = \sum_{k=-\infty}^{\infty} h[k]e^{j\omega(n-k)} = e^{j\omega n} \sum_{k=-\infty}^{\infty} h[k]e^{-j\omega k}$$
Frequency Response $H(e^{j\omega})$

• For periodic input signal $x[n] = \sum_{k=<N>} a_k e^{jk(\frac{2\pi}{N})n}$:

$$y[n] = \sum_{k=< N>} a_k H(e^{jk(\frac{2\pi}{N})}) e^{jk(\frac{2\pi}{N})n}$$

$$b_k = a_k H(e^{jk(\frac{2\pi}{N})})$$





Convolution Property & LTI Systems (2/2)

Convolution Property

If
$$y[n] = x_1[n] * x_2[n]$$
, then

$$Y(e^{j\omega}) = X_1(e^{j\omega})X_2(e^{j\omega})$$

• For general input signal x[n]:

$$y[n] = x[n] * h[n] \longleftrightarrow Y(e^{j\omega}) = X(e^{j\omega})H(e^{j\omega})$$

- Observation: It's easier to evaluate LTI systems in frequency domain
- Drawback: Not every LTI system has frequency response
 - $h[n] = a^n u[n] \ (a > 1)$
 - Stable LTI system has frequency response, because

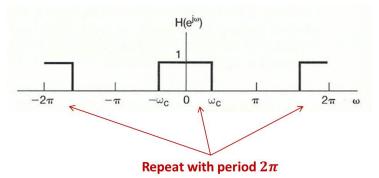
$$\sum_{n=-\infty}^{\infty} |h[n]| < \infty$$





Example: Ideal Low-Pass Filter (1/2)

- What's ideal low-pass filter?
- Perfectly maintain the low-frequency component
- Perfectly cancel the high-frequency component

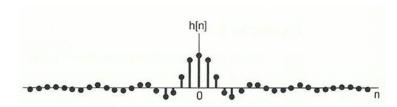




Example: Ideal Low-Pass Filter (2/2)

• Impulse response:

$$h[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} H(e^{j\omega}) e^{j\omega n} d\omega = \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} e^{j\omega n} d\omega = \frac{\sin \omega_c n}{\pi n}$$

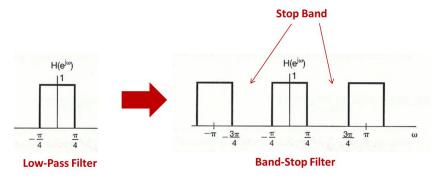


- Pros: no distortion in frequency domain
- Cons: non-causal
- See textbook, Example 5.12



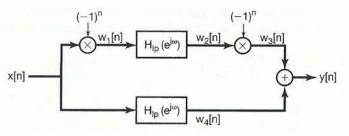
Example: Band-Stop Filter (1/2)

• Given low-pass filter $H_{lp}(e^{j\omega})$, how to generate band-stop effect from low-pass filter?



Example: Band-Stop Filter (2/2)

Two branches: low-pass + high-pass



$$\bullet (-1)^n = e^{j\pi n} \Rightarrow W_1(e^{j\omega}) = X(e^{j(\omega-\pi)})$$

$$\Rightarrow W_2(e^{j\omega}) = H_{lp}(e^{j\omega})X(e^{j(\omega-\pi)})$$

$$\Rightarrow W_3(e^{j\omega}) = H_{lp}(e^{j(\omega-\pi)})X(e^{j(\omega-2\pi)}) = H_{lp}(e^{j(\omega-\pi)})X(e^{j\omega})$$

See textbook, Example 5.14



4 D > 4 P > 4 E > 4 E > 9 Q P

Multiplication Property

Multiplication Property

Let $y[n] = x_1[n]x_2[n]$, then

$$Y(e^{j\omega}) = \frac{1}{2\pi} \int_{2\pi} X_1(e^{j\theta}) X_2(e^{j(\omega-\theta)}) d\theta,$$

which is periodic convolution of $X_1(e^{j\omega})$ and $X_2(e^{j\omega})$

• Comparison: Multiplication of periodic signals

$$x_1[n] \longleftrightarrow a_k$$
 and $x_2[n] \longleftrightarrow b_k$

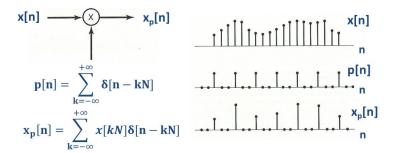
$$\Rightarrow x_1[n]x_2[n] \longleftrightarrow \sum_{k=< N>} a_k b_{n-k}$$
 discrete-time periodic convolution





Example: Sampling on Discrete-Time Signals

- In digital signal processing, we may sample the discrete-time signals
- Example: image, audio, video compression
- Its mathematical model is give below:



Review: Discrete-Time Impulse Chain

- What's the Fourier transform of $x[n] = \sum_{k=0}^{+\infty} \delta[n kN]$?
- First of all, we calculate the Fourier series:

$$a_k = \frac{1}{N} \sum_{n=} x[n] e^{-jk\frac{2\pi}{N}n}$$

$$= \frac{1}{N} \sum_{n=} \sum_{k=-\infty}^{+\infty} \delta[n-kN] e^{-jk\frac{2\pi}{N}n}$$

$$= \frac{1}{N} \sum_{n=} \delta[n] e^{-jk\frac{2\pi}{N}n} = \frac{1}{N}$$

• Then, we have

$$X(e^{j\omega}) = \sum_{l=-\infty}^{\infty} \sum_{k=0}^{N-1} \frac{2\pi}{N} \delta(\omega - k(2\pi/N) - 2\pi I) = \frac{2\pi}{N} \sum_{k=-\infty}^{\infty} \delta(\omega - \frac{2\pi k}{N})$$

• Time domain period × Frequency domain period = ?



Example: Frequency Analysis

$$P(e^{j\omega}) = \frac{2\pi}{N} \sum_{k=-\infty}^{\infty} \delta(\omega - k\omega_s) \text{ where } \omega_s = 2\pi/N$$

$$X_p(e^{j\omega}) = \frac{1}{2\pi} \int_{2\pi} P(e^{j\theta}) X(e^{j(\omega-\theta)}) d\theta = \frac{1}{N} \sum_{k=0}^{N-1} X(e^{j(\omega-k\omega_s)})$$

$$\frac{1}{2\pi} \sum_{k=0}^{N-1} X(e^{j(\omega-k\omega_s)}) \sum_{k=0}^{N-1} X(e^{j(\omega-k\omega_s)})$$

$$\frac{1}{2\pi} \sum_{k=0}^{N} X_p(e^{j\omega}) \sum_{k=0}^{N-1} X_p(e^{j\omega})$$



Duality in DTFS

Analysis and synthesis equations of DTFS share a similar form:

$$x[n] = \sum_{k=} a_k e^{jk(2\pi/N)n}$$

$$a_k = \frac{1}{N} \sum_{k=} x[n] e^{-jk(2\pi/N)n}$$
(1)

- Every of DTFS has a dual (See Table 3.2)
 - Time shift v.s. Frequency shift
 - ► Time multiplication v.s. Frequency multiplication
- If $g[n] \longleftrightarrow f[k]$, then $f[n] \longleftrightarrow \frac{1}{N}g[-k]$



Dualtiy Between CTFS and DTFT

DTFT transform pair is given by

$$x[n] = \frac{1}{2\pi} \int_{2\pi} X(e^{j\omega}) e^{j\omega n} d\omega$$
$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$$

CTFS transform pair is given by

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$$

$$a_k = \frac{1}{T} \int_T x(t) e^{-jk\omega_0 t} dt$$

- Frequency Domain of DTFT ⇔ Time Domain of CTFS
- Frequency Domain of CTFS
 ⇔ Time Domain of DTFT
- Discrete-Time Low-pass Filter v.s. Continuous-Time Square Wave



Summary of Duality

	Continuous time		Discrete time	
	Time domain	Frequency domain	Time domain	Frequency domain
Fourier Series	$x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t}$	$a_k = \frac{1}{T_0} \int_{T_0} x(t)e^{-jk\omega_0 t}$	$x[n] = \sum_{k=\langle N \rangle} a_k e^{jk(2\pi/N)n}$	$a_k = \frac{1}{N} \sum_{k=\langle N \rangle} x[n] e^{-jk(2\pi i N)n}$
	continuous time periodic in time	discrete frequency aperiodic in frequency	discrete time duality	discrete frequency periodic in frequency
Fourier Transform	$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\omega) e^{j\omega t} d\omega$	$X(j\omega) = \int_{-\infty}^{+\infty} x(t)e^{-j\omega t}dt$	$x[n] = \frac{1}{2\pi} \int_{2\pi} X(e^{j\omega}) e^{j\omega n} d\omega$	$X(e^{j\omega}) = \sum_{n=-\infty}^{+\infty} x[n]e^{-j\omega n}$
	continuous time aperiodic in time duality	continuous frequency aperiodic in frequency	discrete time aperiodic in time	continuous frequency periodic in frequency

• See textbook, Table 5.3



LTI by Difference Equation

 A number of DT LTI systems can be written as the following linear constant-coefficient difference equation

$$\sum_{k=0}^{N} a_k y[n-k] = \sum_{k=0}^{M} b_k x[n-k]$$

What's the frequency response?

Taking Fourier transform on both side, we have

$$\sum_{k=0}^{N} a_k e^{-jk\omega} Y(e^{j\omega}) = \sum_{k=0}^{M} b_k e^{-jk\omega} X(e^{j\omega})$$

$$\Rightarrow H(e^{j\omega}) = \frac{Y(e^{j\omega})}{X(e^{j\omega})} = \frac{\sum_{k=0}^{N} b_k e^{-jk\omega}}{\sum_{k=0}^{N} a_k e^{-jk\omega}}$$

What's the impulse response?



Example: Difference Equation

Please calculate the frequency and impulse response of the following LTI systems

$$y[n] - \frac{3}{4}y[n-1] + \frac{1}{8}y[n-2] = 2x[n].$$

Solution

According to the last slide,

$$H(e^{j\omega}) = \frac{2}{1 - \frac{3}{4}e^{-j\omega} + \frac{1}{8}e^{-2j\omega}}.$$

Moreover, by partial fraction expansion

$$H(e^{j\omega}) = \frac{4}{1 - \frac{1}{2}e^{-j\omega}} - \frac{2}{1 - \frac{1}{4}e^{-j\omega}} \Rightarrow h[n] = 4(\frac{1}{2})^n u[n] - 2(\frac{1}{4})^n u[n]$$

Discrete Fourier Transform (DFT)

- In practice, there is a huge demand on processing finite duration signals
- ullet Given a finite duration signal $\{x[0],x[1],...,x[N-1]\}$, its Fourier transform is

$$X(e^{j\omega}) = \sum_{n=0}^{N-1} x[n]e^{-j\omega n}$$

- Drawback: The spectrum of DTFT is continuous ⇒ Cannot be handle by computer.
- Discrete Fourier Transfrom (DFT) is developed for digital processing of finite duration signals

$$\widetilde{X}[k] = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-jk(2\pi/N)n} \quad k = < N >$$

• DFT: frequency sampling of DTFT

$$\widetilde{X}[k] = \frac{1}{N}X(e^{j2k\pi/N})$$
 $k = < N >$



Inverse DFT

Equation system of DFT:

$$\begin{pmatrix} \tilde{X}[0] \\ \tilde{X}[1] \\ \dots \\ \tilde{X}[N-1] \end{pmatrix} = \underbrace{\frac{1}{N}} \begin{pmatrix} e^{-j0} & e^{-j0} & \dots & e^{-j0} \\ e^{-j0} & e^{-j2\pi/N} & \dots & e^{-j2(N-1)\pi/N} \\ \dots & \dots & \dots \\ e^{-j0} & e^{-j2(N-1)\pi/N} & \dots & e^{-j2(N-1)\pi/N} \end{pmatrix} \underbrace{\begin{pmatrix} \times [0] \\ \times [1] \\ \dots \\ \times [N-1] \end{pmatrix}}_{K[N-1]}$$

- Transform matrix F is full rank.
- Observation: $\{\widetilde{X}[k]|k=< N>\}$ maintains all the information of $\{x[0],x[1],...,x[N-1]\}$
- Inverse DFT is feasible:

$$x[n] = \sum_{k=0}^{N-1} \widetilde{X}[k] e^{jk(2\pi/N)n} \quad n = 0, 1, ..., N-1$$





DFT and DTFS

- DFT is for finite duration signals; DTFS is for periodic signals
- Define $\widetilde{x}[n]$ as the periodic extension of x[n]: Repeat x[n] with period N
- Fourier series of $\widetilde{x}[n]$:

$$\frac{1}{N} \sum_{n=0}^{N-1} \widetilde{x}[n] e^{-jk(2\pi/N)n} = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-jk(2\pi/N)n} \implies \mathsf{DFT} \; \mathsf{of} \; x[n]$$

- DFT of a finite-duration signal = DTFS of its periodic extension
- Reference on DFT:
 - Textbook: Problem 5.53, 5.54
 - http://en.wikipedia.org/wiki/Discrete_Fourier_transform



Comparison **Finite Duration Signals Discrete Spectrum DFT** Sample the spectrum Same via periodic extension DT Signal **DTFS Periodic Signals General Signals Discrete Spectrum**



Continuous Spectrum

Periodic Convolution of Finite Duration Signals

Periodic Convolution

Let x and y be two finite duration signals with duration N, \tilde{x} and \tilde{y} be the associated periodic extension, then the periodic convolution of finite duration signals is defined as

$$x[n] \circledast y[n] := \widetilde{x}[n] \circledast \widetilde{y}[n] = \sum_{k=< N>} \widetilde{x}[k] \widetilde{y}[n-k] \quad n = 0, 1, 2..., N-1$$

Convoluation Property of DFT

Time domain periodic convolution is equivalent to frequency domain multiplication, thus,

•
$$x[n] \circledast y[n] \longleftrightarrow N\widetilde{X}[k]\widetilde{Y}[k]$$



