

1. Background

- Net load fluctuations, defined as difference between demand and power output of DERs, causes uncertainty on nodal power injections.

2. AC-CCOPF in radial distribution networks

2.1 Definition of radial distribution system (using LinDistFlow model)

$$\begin{cases}
 \text{nodes : active/reactive power demand } d_i^p \text{ and } d_i^q; \text{ voltage magnitude } v_i \in [v_i^{\min}, v_i^{\max}] \\
 \begin{cases}
 \text{root node } 0; \text{ non-root nodes } N^+ := N \setminus \{0\}, \text{ edges } i \in \mathcal{E} \text{ are indexed by } N^+ \\
 \text{substation/DER nodes : active/reactive power generation } g_i^p \in [g_i^{p,\min}, g_i^{p,\max}] \text{ and } g_i^q \in [g_i^{q,\min}, g_i^{q,\max}] \\
 \text{ancestor node } A_i : |A_i| = 1, \forall i \in N^+
 \end{cases} \\
 \text{edges : resistance } R_i; \text{ reactance } X_i; \text{ apparent power flow limit } S_i^{\max}, i \in \mathcal{E}; \\
 \begin{cases}
 \text{active/reactive power flows } f_i^p \text{ and } f_i^q, i \in \mathcal{E} \text{ is the index of downstream node of edge } i. \\
 \text{LinDistFlow approximation : } \begin{cases}
 (d_i^p - g_i^p) + \sum_{j \in \mathcal{G}_i} f_j^p = f_i^p, p \in \{P, Q\}, \forall i \in N^+ \\
 u_{A_i} - 2(f_i^p R_i + f_i^q X_i) = u_i, \forall i \in N^+ \\
 u_i^{\min} \leq u_i \leq u_i^{\max}, \forall i \in N; \quad (f_i^p)^2 + (f_i^q)^2 \leq (S_i^{\max})^2, \forall i \in \mathcal{E}
 \end{cases}
 \end{cases}
 \end{cases}$$

2.2 Chance Constraint OPF for LinDistFlow

$$\begin{cases}
 \text{Define the uncertain net load injections as } d_i = \bar{d}_i + \epsilon_i, \text{ given forecast + normally distributed forecast error.} \\
 \epsilon_i : \text{mean } \mathbb{E}(\epsilon_i) = u_i = 0, \text{ standard-deviation } \sigma_i, \text{ variance } \text{Var}(\epsilon_i) = \sigma_i^2 \Rightarrow \mathbb{E}(d_i) = \bar{d}_i; \epsilon_i^p \text{ and } \epsilon_i^q \\
 \text{generators compensate for load deviations using affine control: } g_i^p = \bar{g}_i^p + \alpha_i \tilde{\epsilon}^p; g_i^q = \bar{g}_i^q + \alpha_i \tilde{\epsilon}^q, i \in \mathcal{G}; \tilde{\epsilon}^p = \sum_{i \in \mathcal{G}} \epsilon_i^p; \sum_{i \in \mathcal{G}} \alpha_i = 1 \\
 \text{power transmission distribution factors (PTDF) } A : a_{ij} = 1 \text{ if line } i \text{ is part of the path from root to bus } j. \\
 \text{uncertain edge power flow : } f_i^p = \bar{f}_i^p + d_{i*} (\epsilon^p - \alpha \tilde{\epsilon}^p); f_i^q = \bar{f}_i^q + d_{i*} (\epsilon^q - \alpha \tilde{\epsilon}^q) \\
 \text{uncertain voltage magnitude squared : } u_i = u_{A_i} - 2(R_i f_i^p + X_i f_i^q) = \bar{u}_i - 2a_{i*}^T (R \circ A (\epsilon^p - \alpha \tilde{\epsilon}^p) + X \circ A (\epsilon^q - \alpha \tilde{\epsilon}^q))
 \end{cases}$$

$$\text{Complete model: } \min_{(\bar{g}, \alpha, \bar{f}, \bar{u})} \mathbb{E}[f(\bar{g}^p, \bar{g}^q, \epsilon^p, \epsilon^q)]$$

$$\text{s.t. } \sum_{i \in \mathcal{G}} \alpha_i = 1$$

$$\text{Deterministic LinDistFlow} \begin{cases} (d_i^p - \bar{g}_i^p) + \sum_{j \in \mathcal{G}_i} \bar{f}_j^p = \bar{f}_i^p, p \in \{P, Q\}, \forall i \in \mathcal{E}. \\ \bar{u}_{A_i} - 2(\bar{f}_i^p R_i + \bar{f}_i^q X_i) = \bar{u}_i, \forall i \in N^+ \end{cases}$$

$$\text{Chance Constraints} \begin{cases} P(g_i^{p,\min} \leq g_i^p \leq g_i^{p,\max}) \geq (1-2\eta_g), \forall i \in \mathcal{G}_c \\ P(g_i^{q,\min} \leq g_i^q \leq g_i^{q,\max}) \geq (1-2\eta_g), \\ P(u_i^{\min} \leq u_i \leq u_i^{\max}) \geq (1-2\eta_v), \forall i \in N \end{cases} \left. \begin{matrix} \eta_g \text{ and } \eta_v \text{ are confidence level.} \end{matrix} \right\}$$

2.3 Expected Cost

$$\mathbb{E}[f_p(\bar{g}^p, \epsilon^p)] = \sum_{i \in \mathcal{G}} [c_{i2} \alpha_i^2 \text{Var}(\tilde{\epsilon}^p) + c_{i1} \bar{g}_i^p]$$

2.4 Conic Reformulation of Chance Constraints

For normally distributed random variable $X \sim \text{Norm}(\mu, \sigma^2)$, $\mathbb{P}(X \leq x^{\max}) > \eta$ holds if and

only if $x^{\max} \geq \mu + z_\eta \sigma$; $z_\eta = \Phi^{-1}(1-\eta)$ is $(1-\eta)$ -quantile of standard normal distribution

$$\begin{cases} g_i^{p, \max} \geq \mathbb{E}(g_i^p) + z_{\eta_g} \sqrt{\text{Var}(g_i^p)} = \bar{g}_i^p + z_{\eta_g} \alpha_i \sqrt{\sum_{j=1}^b \text{Var}(\epsilon_j^p)}, p \in \{P, Q\}; -g_i^{p, \min} \geq -\bar{g}_i^p + z_{\eta_g} \alpha_i \sqrt{\sum_{j=1}^b \text{Var}(\epsilon_j^p)} \\ u_i^{\max} \geq \bar{u}_i + z_{\eta_v} \sqrt{\text{Var}(u_i)}; -u_i^{\min} \geq -\bar{u}_i + z_{\eta_v} \sqrt{\text{Var}(u_i)} \\ \text{Var}(u_i) = 4 \sum_{k=1}^l a_{ki} \left[(R_k^2 \sum_{j=1}^b a_{kj} (\text{Var}(\epsilon_j^p) + \alpha_j^2 \text{Var}(\tilde{\epsilon}^p)) + (X_k^2 \sum_{j=1}^b a_{kj} (\text{Var}(\epsilon_j^Q) + \alpha_j^2 \text{Var}(\tilde{\epsilon}^Q))) \right] \quad (\text{电压平方的方差}) \end{cases}$$

3. Data-Driven DR-AC-CCOPF: 在 AC-CCOPF 基础上加上考虑矩不确定性的 DRO

The above formulations are under the assumption of perfect knowledge of the distribution of random variable (mean and variance). In this chapter, true distribution cannot be known. We can only inform by finite observations.

Redefine the AC-CCOPF obj: $\min_x \max_{\epsilon \in \mathcal{U}} \mathbb{E}_\epsilon[f(x, \epsilon)]$. minimize the worst-case expectation based on the distributional uncertainty set.

3.1 Definition of Uncertainty Set

- $H(\epsilon_i) = \{\hat{\epsilon}_{i,t}\}_{t \leq N}$, $i \in \mathcal{N}$ is the set of N observed realizations of forecast error at bus i .
 - Zero-mean, normally distributed \Rightarrow distribution defined by sample variance: $\hat{\sigma}_i^2 = \frac{1}{N} \sum_{t \leq N} \hat{\epsilon}_{i,t}^2$, $i \in \mathcal{N}$
 - The sample variance follows a Chi-Square (χ^2) distribution \Rightarrow define uncertainty set $\mathcal{U}_{\hat{\sigma}_i^2} = [\hat{\epsilon}_{i,l}, \hat{\epsilon}_{i,h}]$
- where: $\hat{\epsilon}_{i,l} = \frac{N \hat{\sigma}_i^2}{\chi_{N-1, (1-\epsilon)/2}^2}$, $\hat{\epsilon}_{i,h} = \frac{N \hat{\sigma}_i^2}{\chi_{N-1, \epsilon/2}^2}$. $\chi_{N-1, \epsilon}^2$ is the ϵ -quantile of χ^2 -distribution (not symmetric)

3.2 Worst-Case Expectation

$$\sup_{\substack{\bar{g}, \alpha, \bar{f}, \bar{u} \\ \bar{g}_i^p \in \mathcal{U}_{\hat{\sigma}_i^2}, i \in \mathcal{N}}} \mathbb{E}[f_p(\bar{g}^p, \epsilon^p)] = \sup_{\substack{\bar{g}_i^p \in \mathcal{U}_{\hat{\sigma}_i^2}, i \in \mathcal{N}}} \sum_{i \in \mathcal{G}} [c_{i2} (\alpha_i^2 \sum_{i \in \mathcal{N}} \hat{\epsilon}_{i,h} + (\bar{g}_i^p)^2) + c_{i1} \bar{g}_i^p + c_{i0}] = \sum_{i \in \mathcal{G}} [c_{i2} (\alpha_i^2 \sum_{i \in \mathcal{N}} \hat{\epsilon}_{i,h} + (\bar{g}_i^p)^2) + c_{i1} \bar{g}_i^p + c_{i0}]$$

3.3 DR-AC-CCOPF model

$$\min_{\bar{g}, \alpha, \bar{f}, \bar{u}} \sum_{i \in \mathcal{G}} \left[c_{i2} \left(\alpha_i^2 \sum_{i \in \mathcal{N}} \hat{\epsilon}_{i,h}^p + (\bar{g}_i^p)^2 \right) + c_{i1} \bar{g}_i^p + c_{i0} \right] \quad \text{最小化由误差引起的成本} \quad (22a)$$

$$\sum_{i \in \mathcal{G}} \alpha_i = 1 \quad \text{有功预测误差在总功率上归一化} \quad (22b)$$

$$(\bar{d}_i^p - \bar{g}_i^p) + \sum_{j \in \mathcal{C}_i} \bar{f}_j^p = \bar{f}_i^p \quad \forall i \in \mathcal{E}, p \in \{P, Q\} \quad \text{负荷平衡约束} \quad (22c)$$

$$\bar{u}_{A_i} - 2(\bar{f}_i^p R_i + \bar{f}_i^Q X_i) = \bar{u}_i \quad \forall i \in \mathcal{N}^+ \quad \text{电压约束} \quad (22d)$$

$$\bar{g}_i^{p, \max} \geq \bar{g}_i^p + z_{\eta_g} \alpha_i \sqrt{\sum_{k=1}^b \hat{\epsilon}_{i,h}^p} \quad \forall i \in \mathcal{G}, p \in \{P, Q\} \quad \text{发电机功率分布约束} \quad (22e)$$

$$-\bar{g}_i^{p, \min} \geq -\bar{g}_i^p + z_{\eta_g} \alpha_i \sqrt{\sum_{k=1}^b \hat{\epsilon}_{i,h}^p} \quad \forall i \in \mathcal{G}, p \in \{P, Q\} \quad (22f)$$

$$u_i^{\max} \geq \bar{u}_i + z_{\eta_v} 2\sqrt{h_i(\alpha)} \quad \forall i \in \mathcal{N} \quad (22g)$$

$$-u_i^{\min} \geq -\bar{u}_i + z_{\eta_v} 2\sqrt{h_i(\alpha)} \quad \forall i \in \mathcal{N} \quad (22h)$$

$$h_i(\alpha) = \sum_{k=1}^l a_{ki} \left[\left(R_k^2 \sum_{j=1}^b a_{kj} (\hat{\epsilon}_{j,h}^p + \alpha_j^2 \sum_{m=1}^b \hat{\epsilon}_{m,h}^p) \right) + \left(X_k^2 \sum_{j=1}^b a_{kj} (\hat{\epsilon}_{j,h}^Q + \alpha_j^2 \sum_{m=1}^b \hat{\epsilon}_{m,h}^Q) \right) \right] \quad (22i)$$

4.1 Case Study

4.1 Uncertainty interval derivation: use true distribution to obtain $N=100$ error samples

Change χ^2 -distribution quantile $\bar{\varepsilon}$ and obtain different uncertainty intervals and possible distributions.

4.2 In-Sample Evaluation: use true distribution to generate 750 random samples

Change η_v , obtain different probabilities of voltage constraint violations and costs (trade-off)

4.3 Out-of-Sample Performance: use newly parameterized distributions supported by initial sample data to generate 750 samples

→ new value of σ^2 , changed by parameter δ : $\sigma^2+0.2\delta$, $\sigma^2+0.5\delta$, $\sigma^2+0.8\delta$.

Change η_v and $\bar{\varepsilon}$, get different probabilities of voltage violations

Increase of δ will lead to larger distance between DOS distribution and true distribution, which will increase probability of voltage violations