

# Digital Signal Processing

Module 2: Discrete-time signals

# Video Introduction

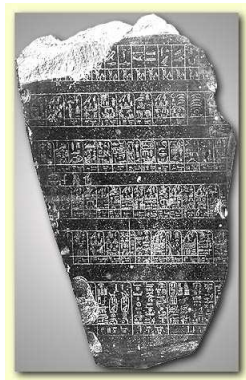
- ▶ **Module 2.1:** discrete-time signals and operators
- ▶ **Module 2.2:** the discrete-time complex exponential
- ▶ **Module 2.3:** the Karplus-Strong algorithm

# Digital Signal Processing

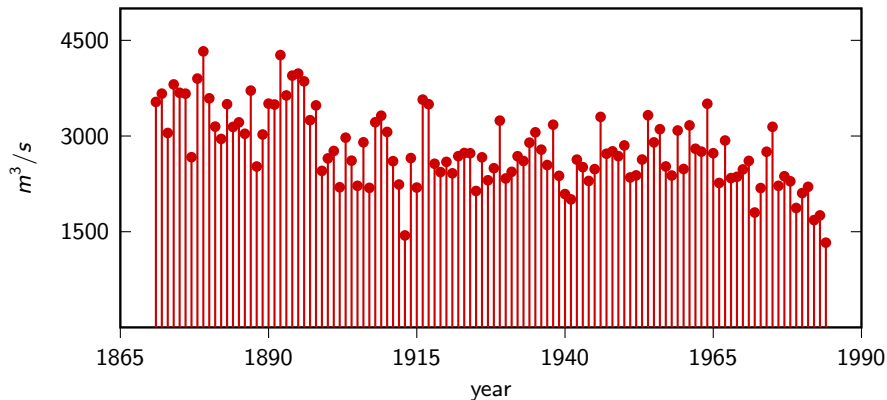
Module 2.1: Discrete-time signals

- ▶ discrete-time signals
- ▶ signal classes
- ▶ elementary operators
- ▶ shifts
- ▶ energy and power

Meteorology (limnology): the floods of the Nile

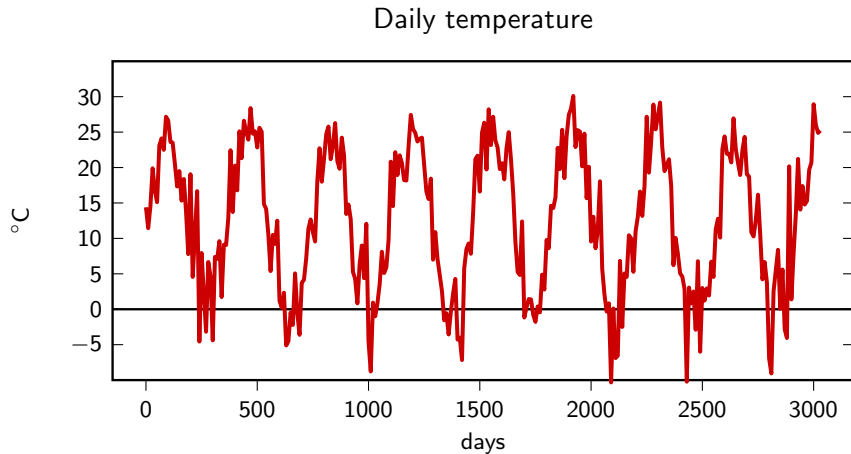


Representations of flood data: circa 2500 BC

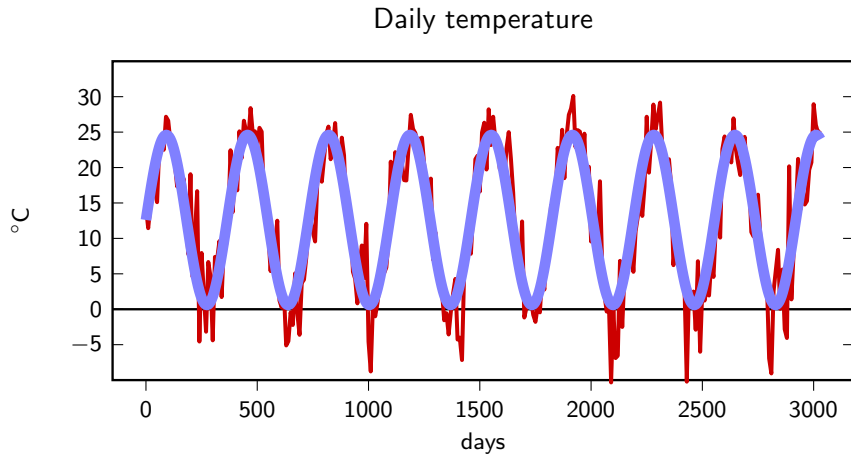


Representations of flood data: circa AD 2000

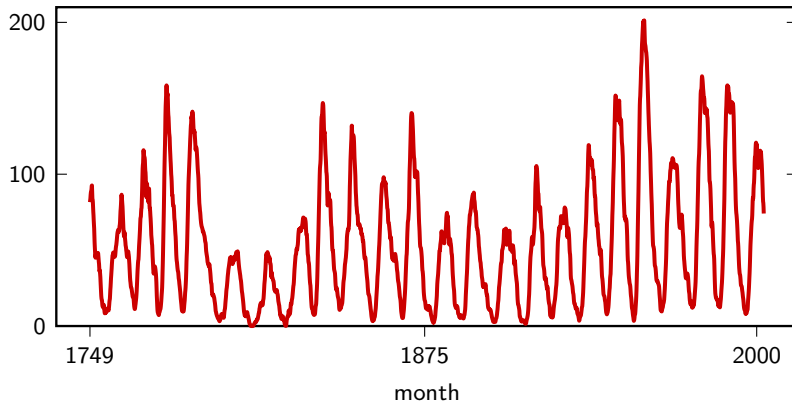
# Probably your first scientific experiment...

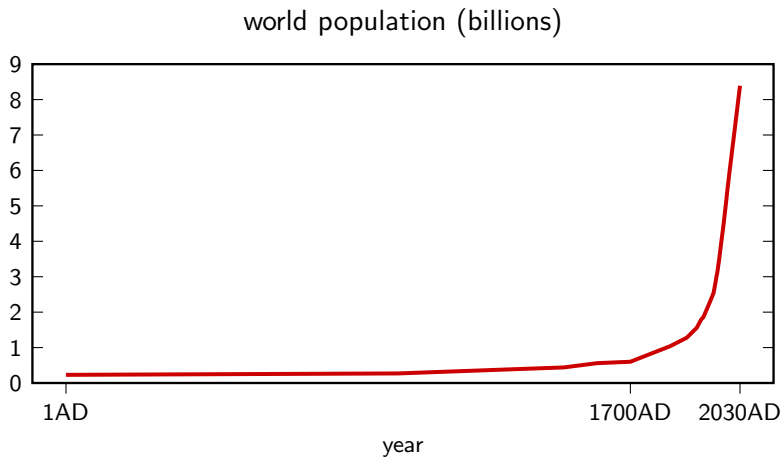




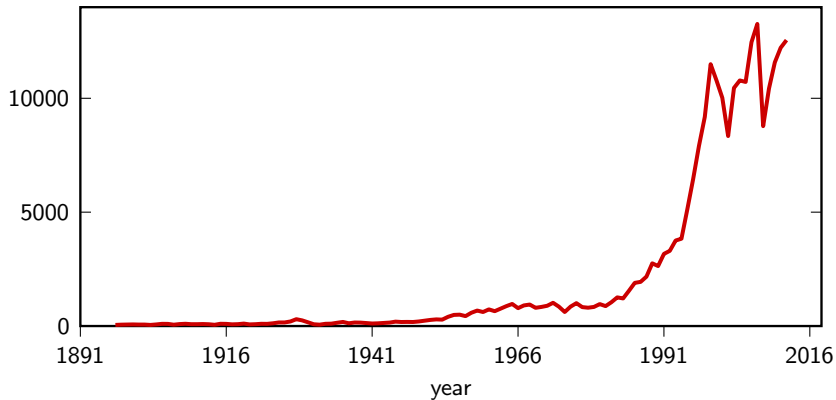


monthly solar spot activity, 1749 to 2003





a purely man-made signal: the Dow Jones industrial average



Discrete-time signal: a sequence of **complex** numbers

- ▶ one dimension (for now)
- ▶ notation:  $x[n]$
- ▶ two-sided sequences:  $x : \mathbb{Z} \rightarrow \mathbb{C}$
- ▶  $n$  is dimension-less “time”
- ▶ analysis: periodic measurement
- ▶ synthesis: stream of generated samples

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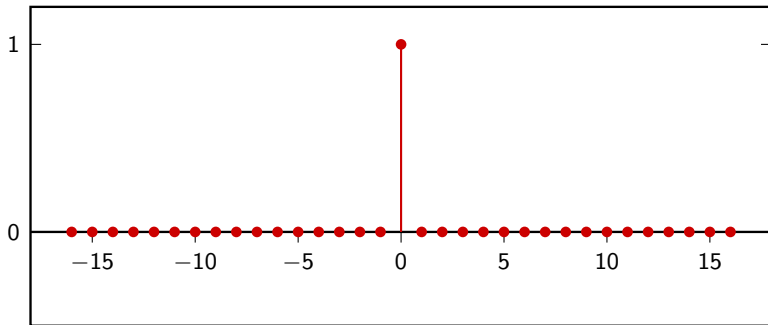
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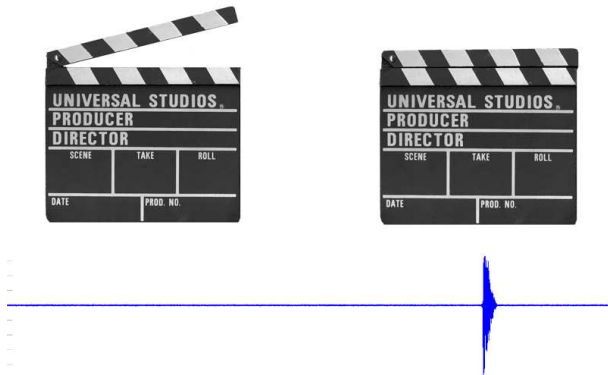
$$x[n] = \delta[n]$$



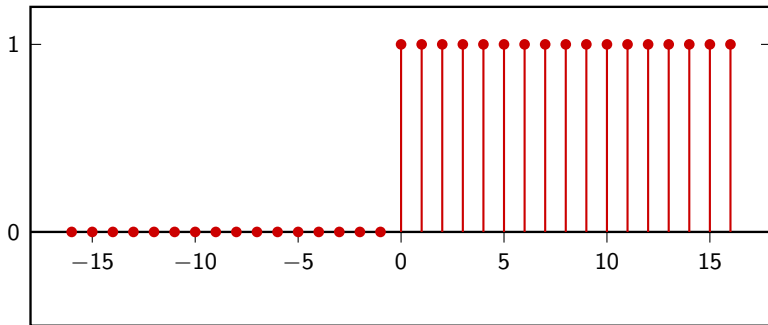
# How do you synchronize audio and video...



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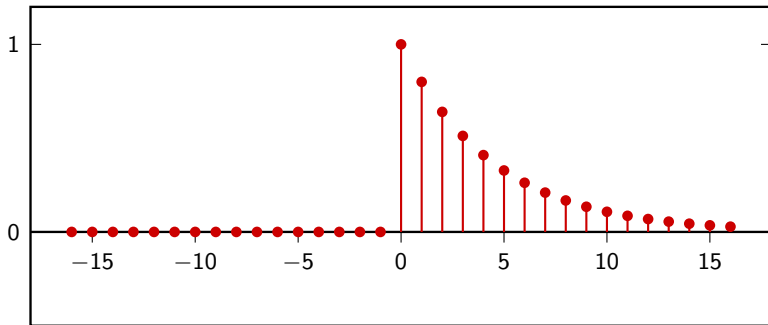
$$x[n] = u[n]$$



## The Frankenstein switch...



$$x[n] = |a|^n u[n], \quad |a| < 1$$





# How fast does your coffee get cold...



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Newton's law of cooling:

$$\frac{dT}{dt} = -c(T - T_{\text{env}})$$

$$T(t) = T_{\text{env}} + (T_0 - T_{\text{env}})e^{-ct}$$

In practice:

- ▶ must have convection only
- ▶ must have large conductivity

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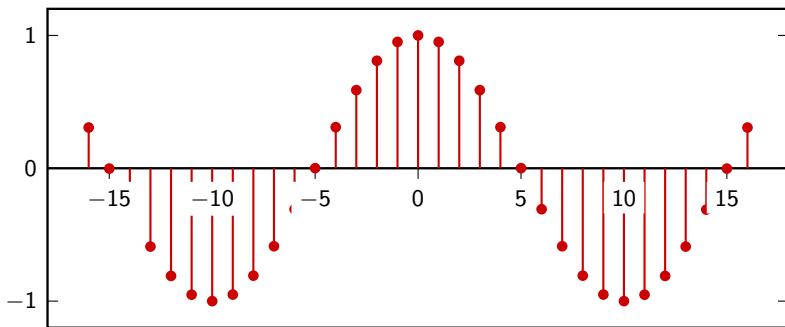
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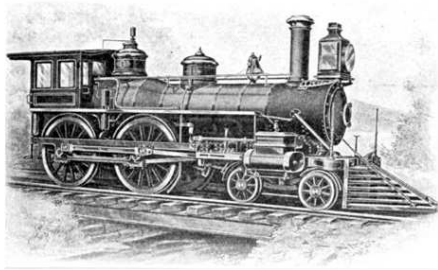
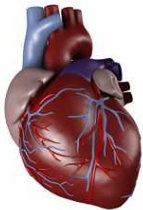
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$$x[n] = \sin(\omega_0 n + \theta)$$



# Oscillations are everywhere!



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- ▶ infinite-length
- ▶ periodic
- ▶ finite-support

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- ▶ practical entities, good for numerical packages (Matlab and the like)

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- ▶  $N$ -periodic sequence:  $\tilde{x}[n] = \tilde{x}[n + kN]$ ,  $n, k, N \in \mathbb{Z}$
- ▶ same information as finite-length of length  $N$
- ▶ “natural” bridge between finite and infinite lengths

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$$\bar{x}[n] = \begin{cases} x[n] & \text{if } 0 \leq n < N \\ 0 & \text{otherwise} \end{cases} \quad n \in \mathbb{Z}$$

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- ▶ scaling:

$$y[n] = \alpha x[n]$$

- ▶ sum:

$$y[n] = x[n] + z[n]$$

- ▶ product:

$$y[n] = x[n] \cdot z[n]$$

- ▶ shift by  $k$  (delay):

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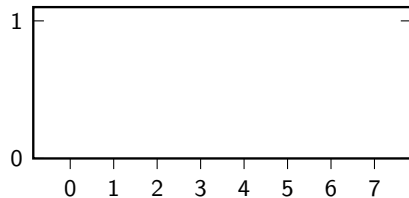
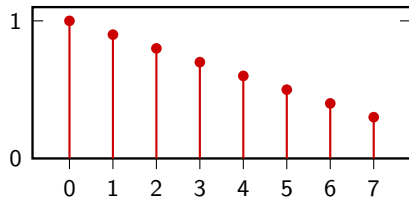
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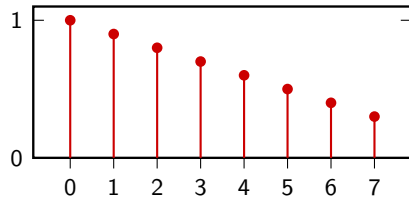
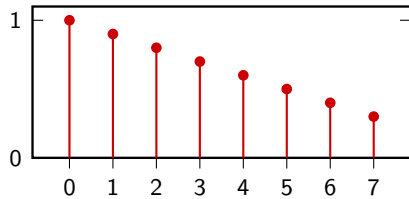


$$[x_0 \ x_1 \ x_2 \ x_3 \ x_4 \ x_5 \ x_6 \ x_7]$$



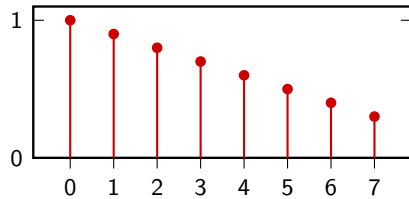
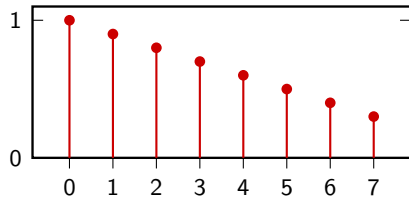
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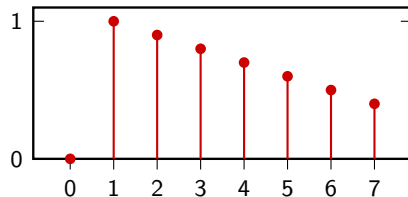
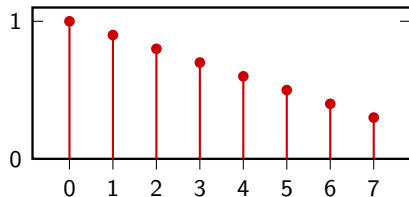
$$\bar{x}[n]$$

... 0 0 0  $x_0$   $x_1$   $x_2$   $x_3$   $x_4$   $x_5$   $x_6$   $x_7$  0 0 0 ...



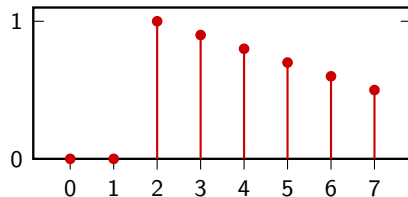
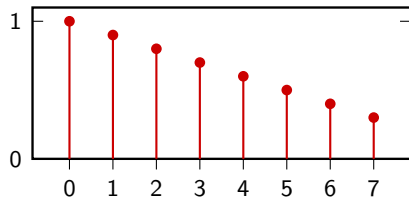
$$\bar{x}[n-1]$$

... 0 0 0 0  $x_0$   $x_1$   $x_2$   $x_3$   $x_4$   $x_5$   $x_6$   $x_7$  0 0 ...



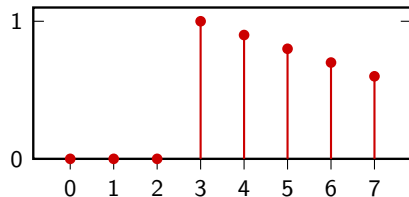
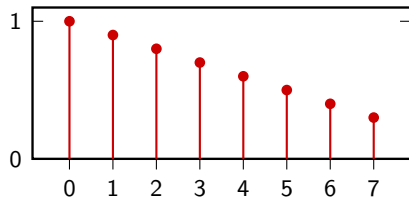
$$\bar{x}[n-2]$$

... 0 0 0 0 0  $x_0$   $x_1$   $x_2$   $x_3$   $x_4$   $x_5$   $x_6$   $x_7$  0 ...



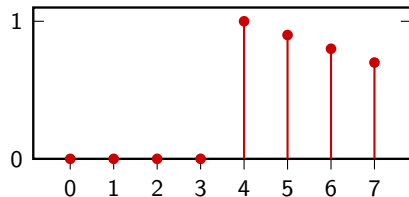
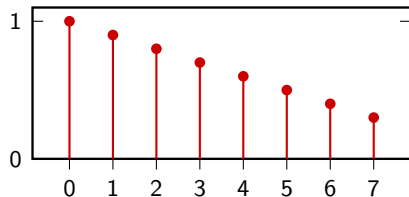
$$\bar{x}[n-3]$$

... 0 0 0 0 0 0 0  $x_0$   $x_1$   $x_2$   $x_3$   $x_4$   $x_5$   $x_6$   $x_7$  ...

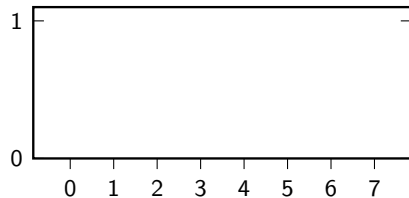
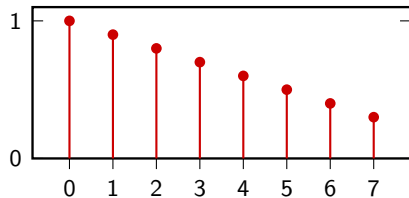


$$\bar{x}[n-4]$$

... 0 0 0 0 0  $x_0$   $x_1$   $x_2$   $x_3$   $x_4$   $x_5$   $x_6$  ...



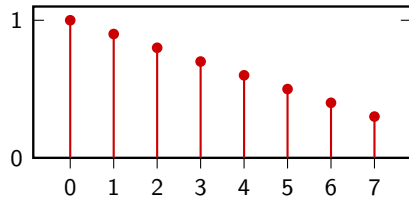
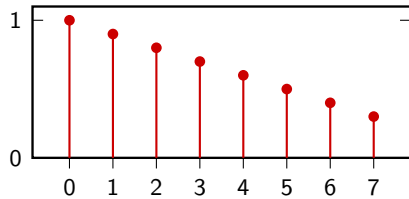
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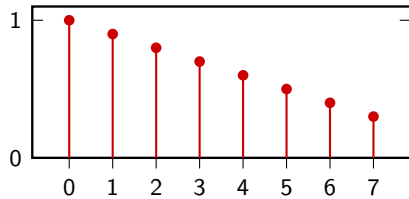
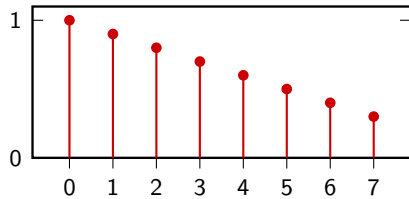
$x[n]$

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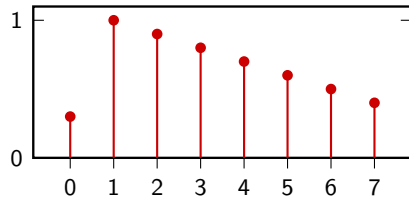
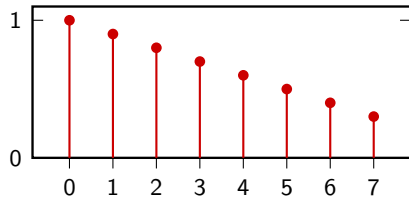
$$\tilde{x}[n]$$

...  $x_5$   $x_6$   $x_7$   $x_0$   $x_1$   $x_2$   $x_3$   $x_4$   $x_5$   $x_6$   $x_7$   $x_0$   $x_1$   $x_2$  ...



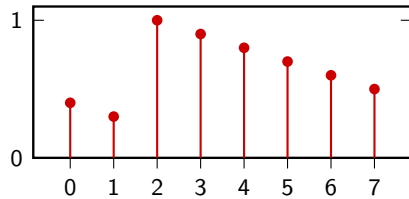
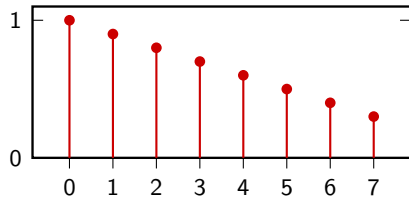
$$\tilde{x}[n-1]$$

...  $x_4$   $x_5$   $x_6$   $x_7$   $x_0$   $x_1$   $x_2$   $x_3$   $x_4$   $x_5$   $x_6$   $x_7$   $x_0$   $x_1$  ...



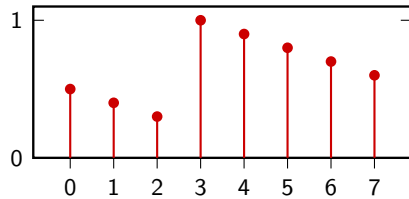
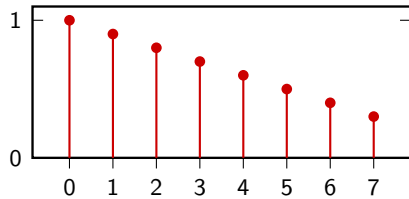
$$\tilde{x}[n-2]$$

...  $x_3$   $x_4$   $x_5$   $x_6$   $x_7$   $x_0$   $x_1$   $x_2$   $x_3$   $x_4$   $x_5$   $x_6$   $x_7$   $x_0$  ...



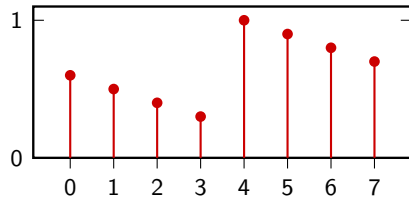
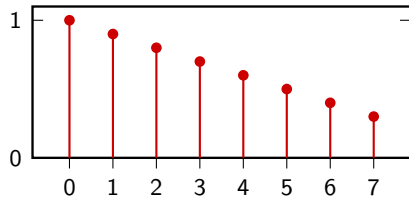
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$$E_x = \sum_{n=-\infty}^{\infty} |x[n]|^2$$

$$P_x = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |x[n]|^2$$

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$$E_{\tilde{x}} = \infty$$

$$P_{\tilde{x}} \equiv \frac{1}{N} \sum_{n=0}^{N-1} |\tilde{x}[n]|^2$$

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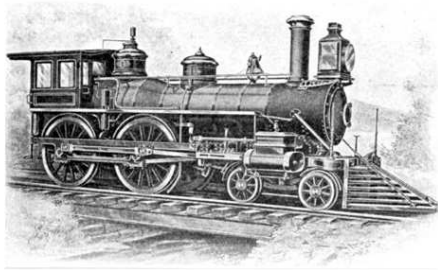
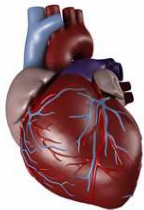
END OF MODULE 2.1

## Digital Signal Processing

Module 2.2: the complex exponential

- ▶ the complex exponential
- ▶ periodicity
- ▶ wagonwheel effect and maximum “speed”
- ▶ digital and real-world frequency

# Oscillations are everywhere



## Ingredients:

- ▶ a frequency  $\omega$  (units: radians)
- ▶ an initial phase  $\phi$  (units: radians)
- ▶ an amplitude  $A$  (units depending on underlying measurement)
- ▶ a trigonometric function

e.g.  $x[n] = A \cos(\omega n + \phi)$

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$$\text{e.g. } x[n] = A \cos(\omega n + \phi)$$

the trigonometric function of choice in DSP is the complex exponential:

$$\begin{aligned}x[n] &= Ae^{j(\omega n + \phi)} \\&= A[\cos(\omega n + \phi) + j \sin(\omega n + \phi)]\end{aligned}$$

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- ▶ simpler math: trigonometry becomes algebra
- ▶ we can use complex numbers in digital systems

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Example: change the phase of a pure cosine

$$\cos(\omega n + \phi) = a \cos(\omega n) + b \sin(\omega n), \quad a = \cos \phi, \quad b = -\sin \phi$$

- ▶ each sinusoid is always a sum of sine and cosine
- ▶ we have to remember complex trigonometric formulas
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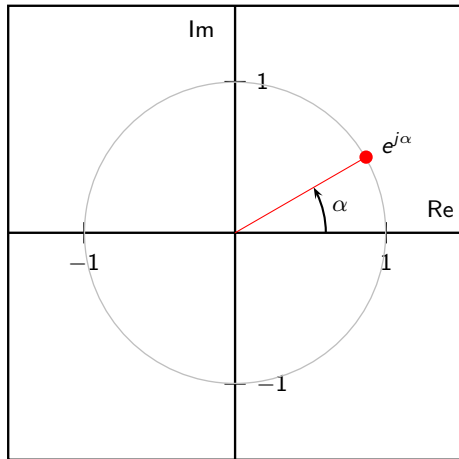
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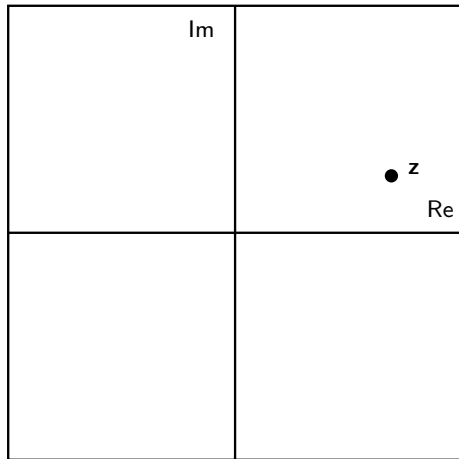
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$$e^{j\alpha} = \cos \alpha + j \sin \alpha$$

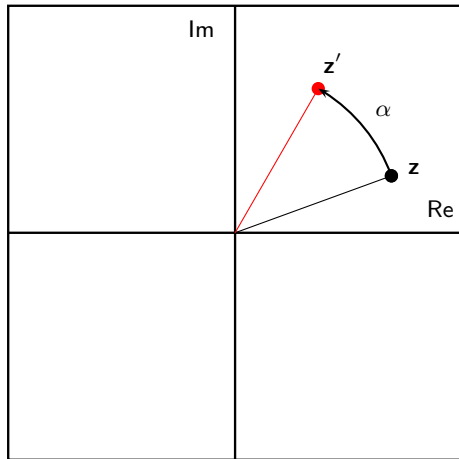




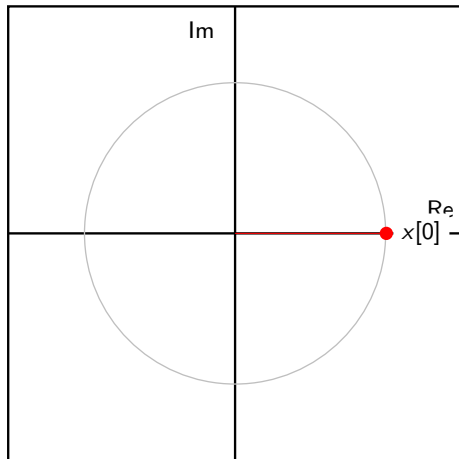
$z$ : point on the complex plane



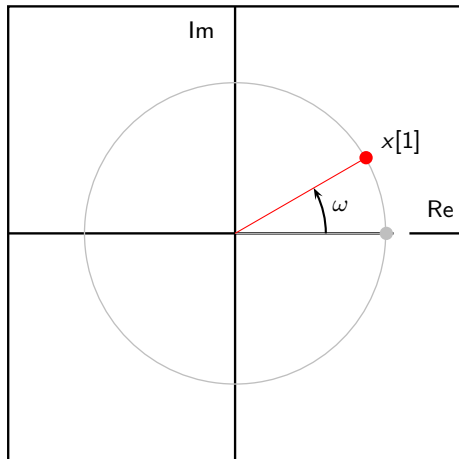
rotation:  $z' = z e^{j\alpha}$



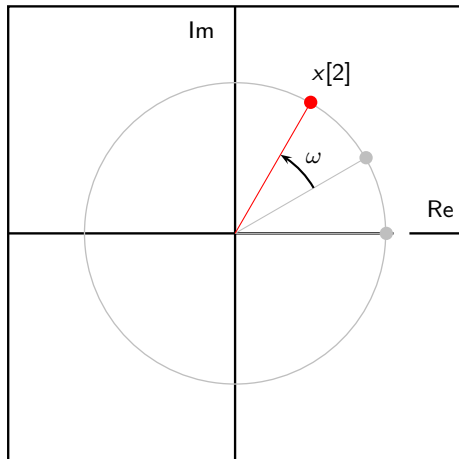
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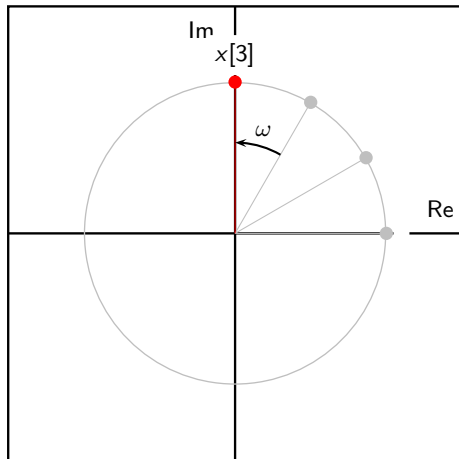
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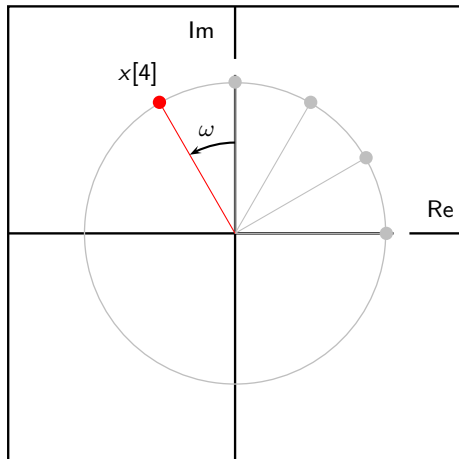
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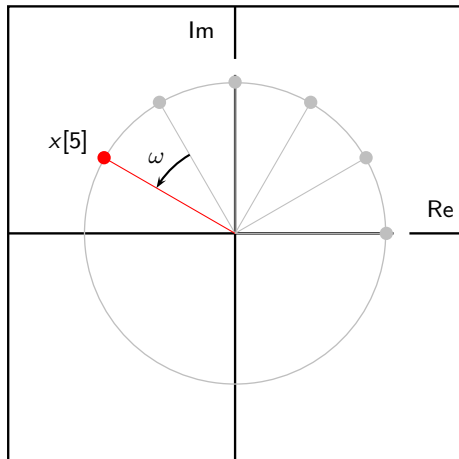
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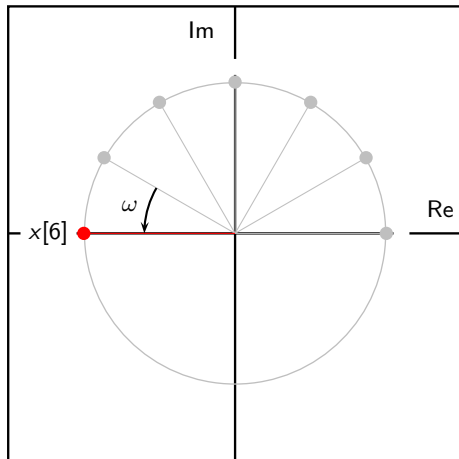


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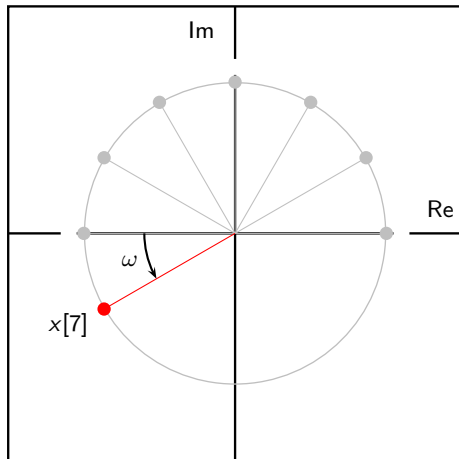




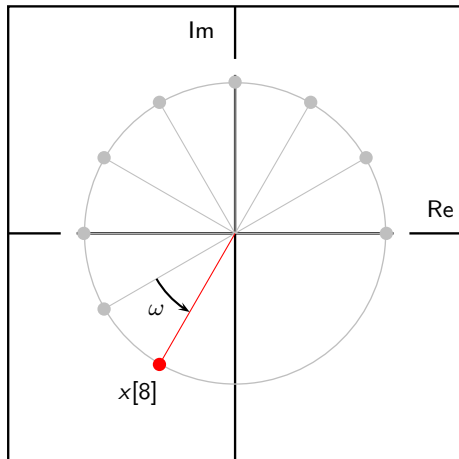
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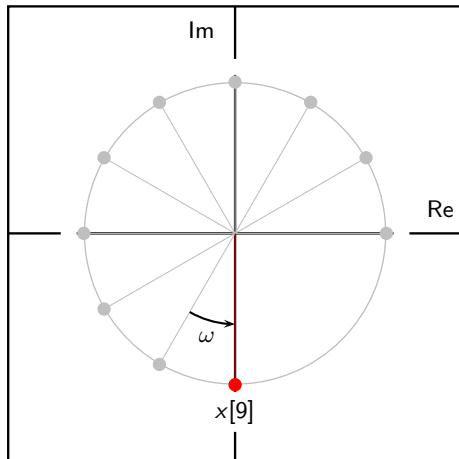
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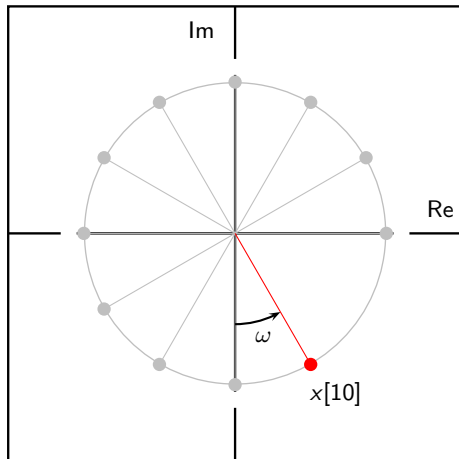
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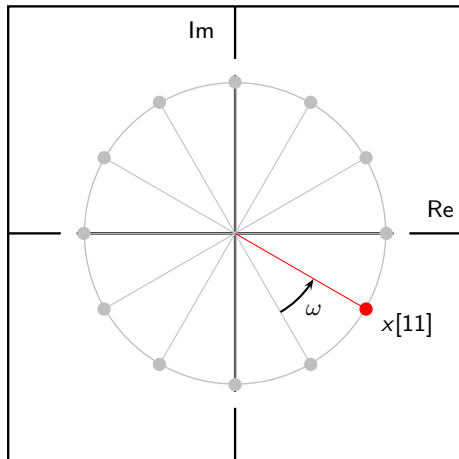
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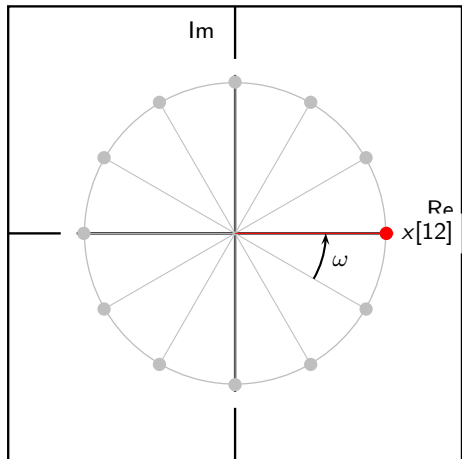
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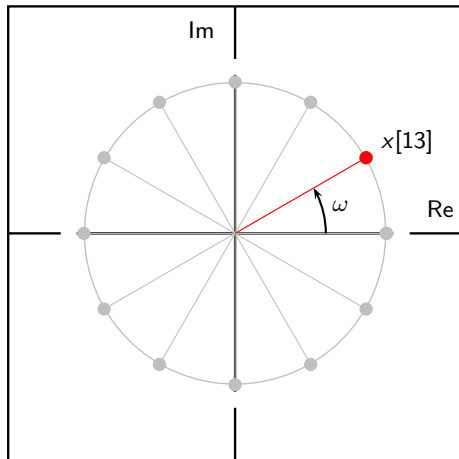
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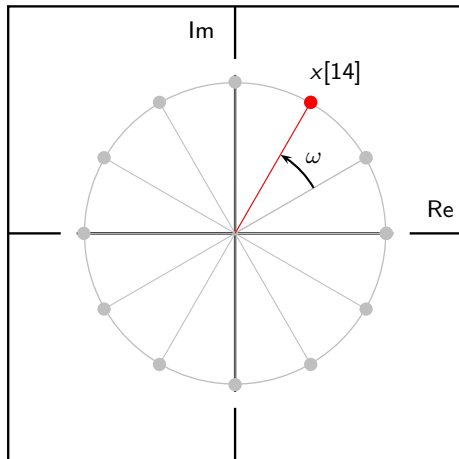


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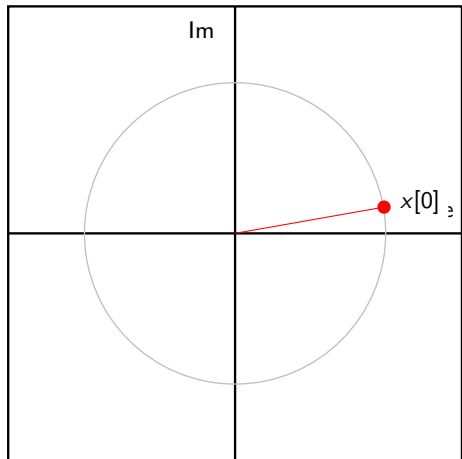




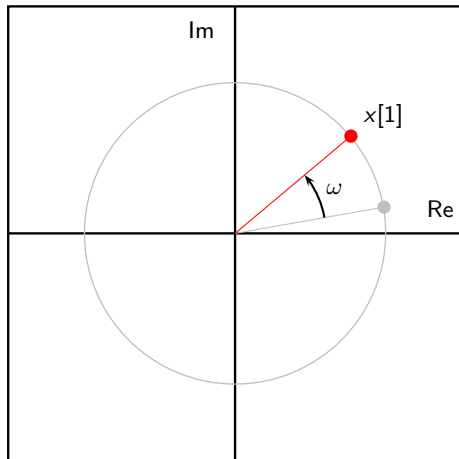
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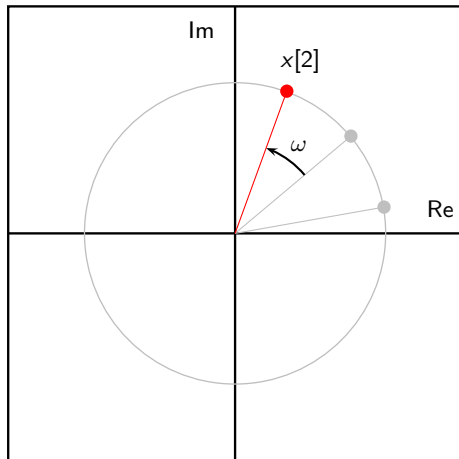
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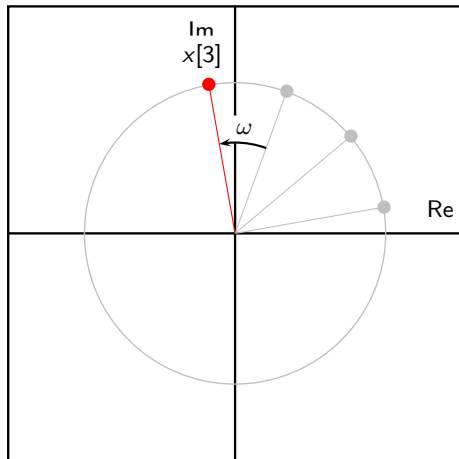
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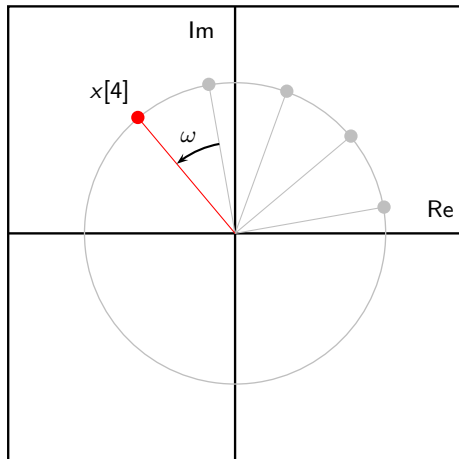
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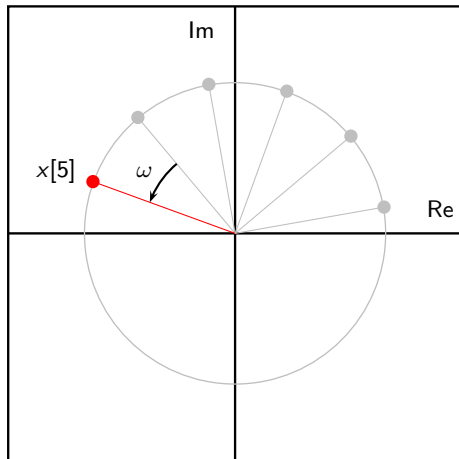
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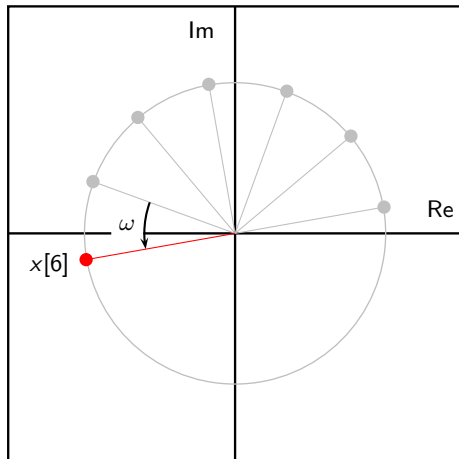
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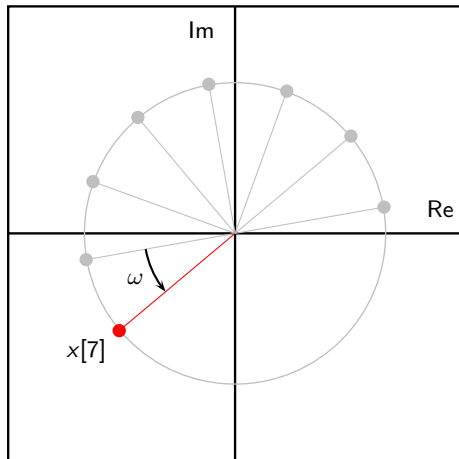


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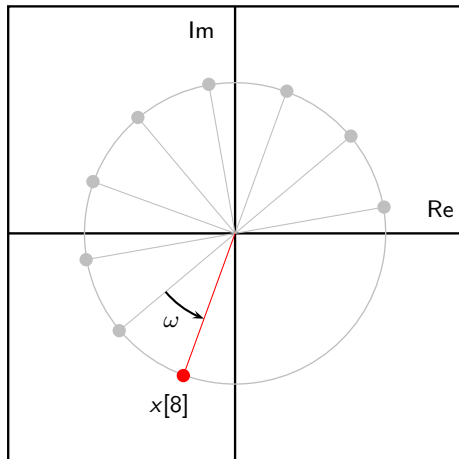




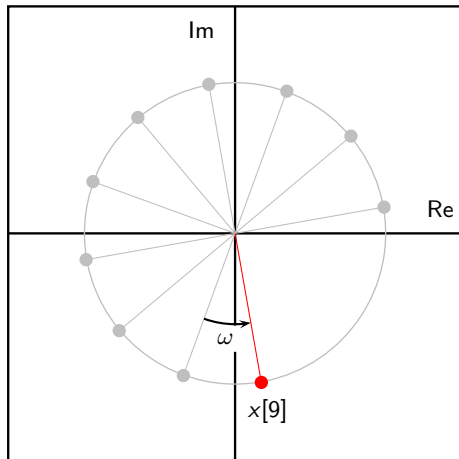
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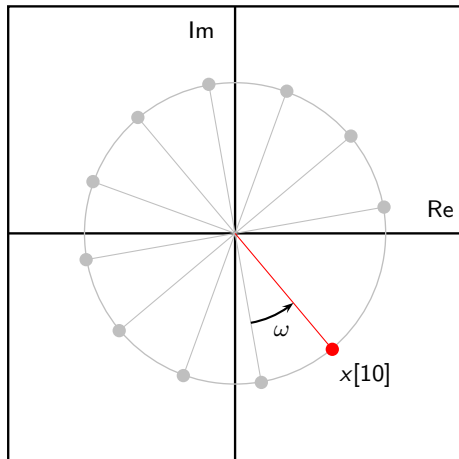
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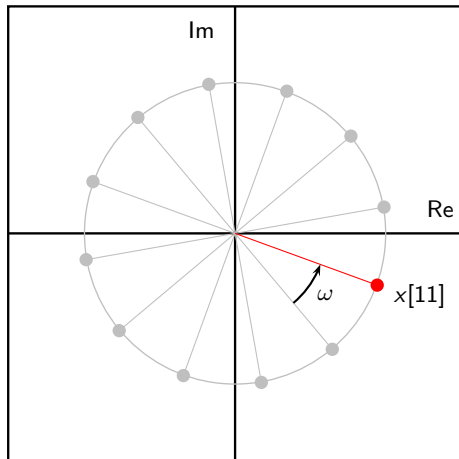
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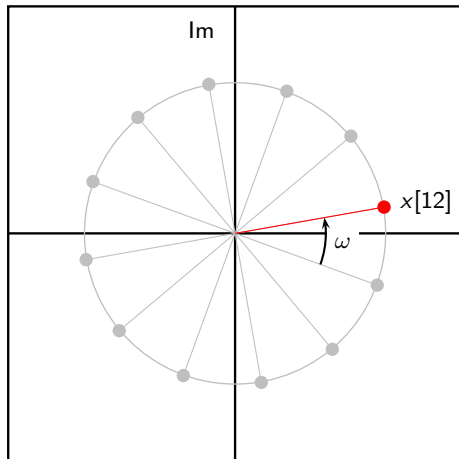
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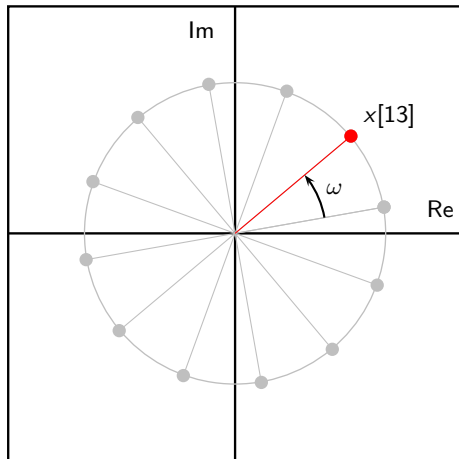
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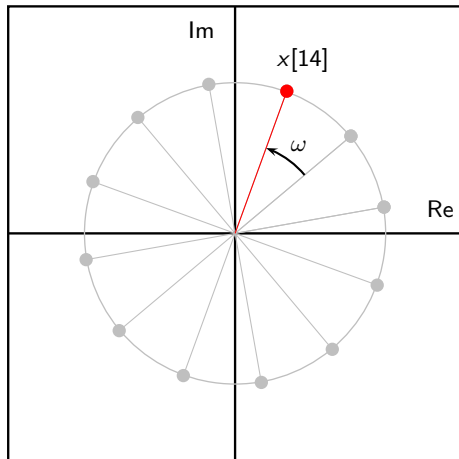
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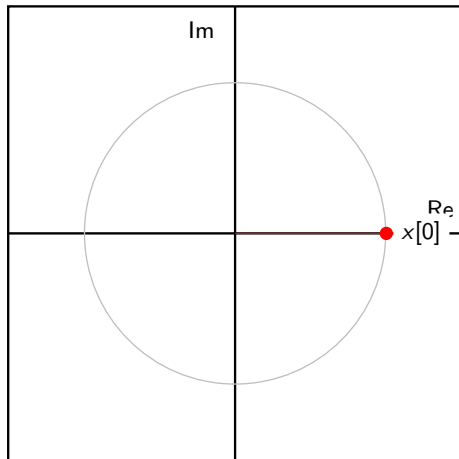
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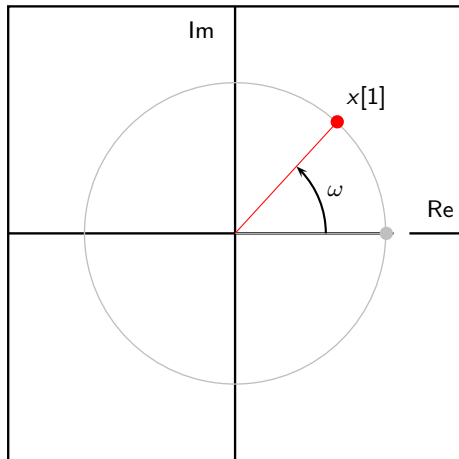


## Careful: not every sinusoid is periodic in discrete time

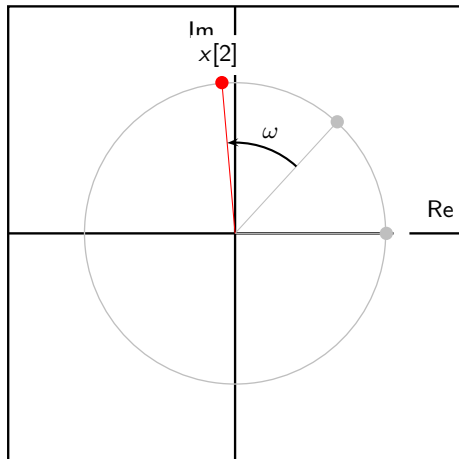
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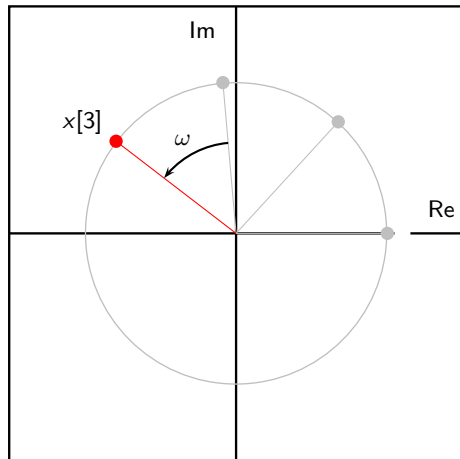


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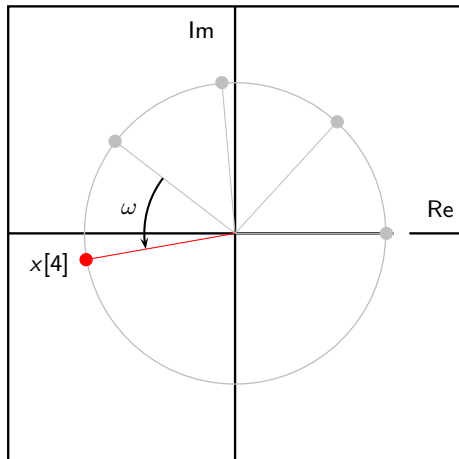
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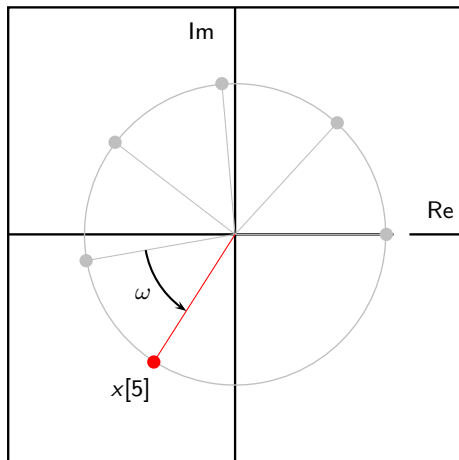


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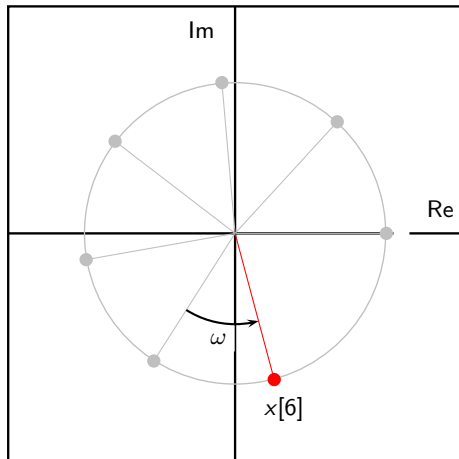
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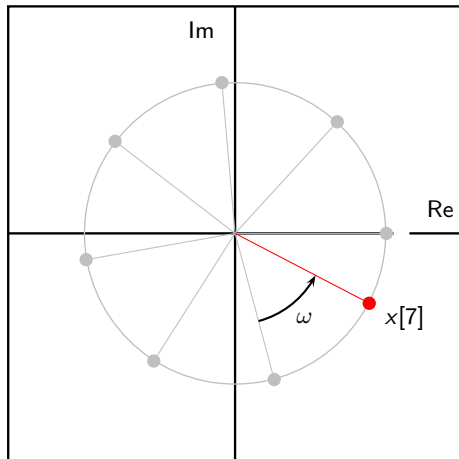
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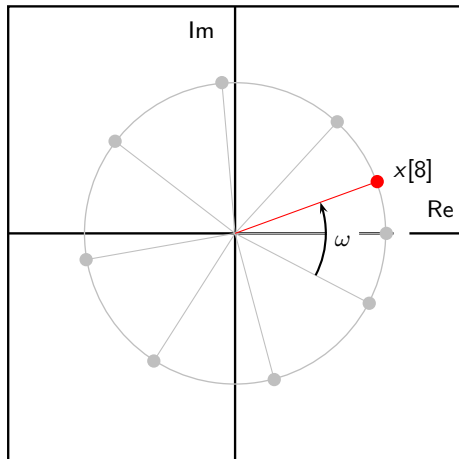
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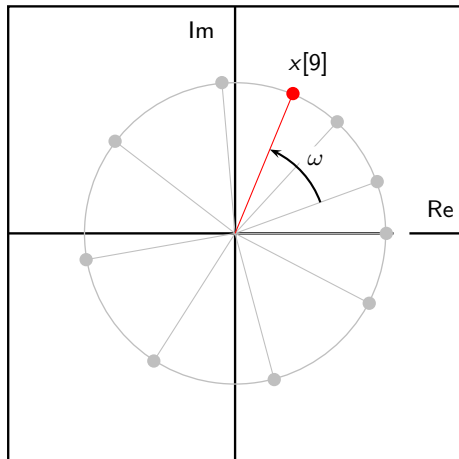


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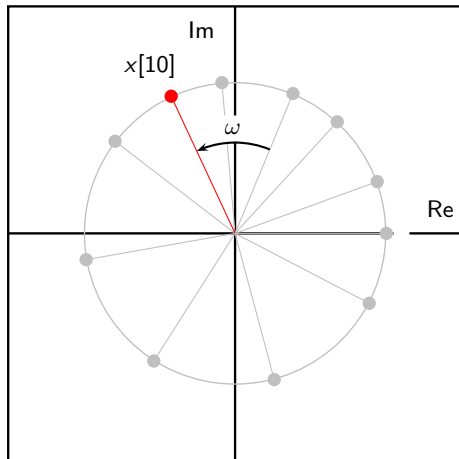
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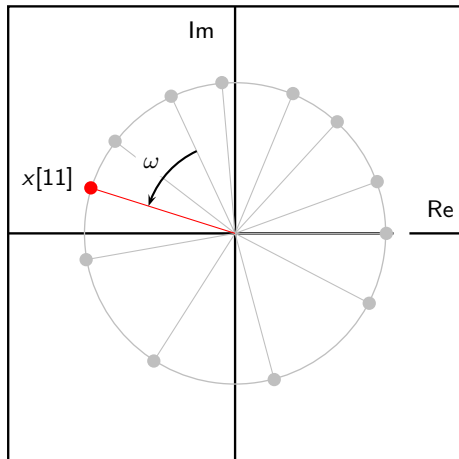


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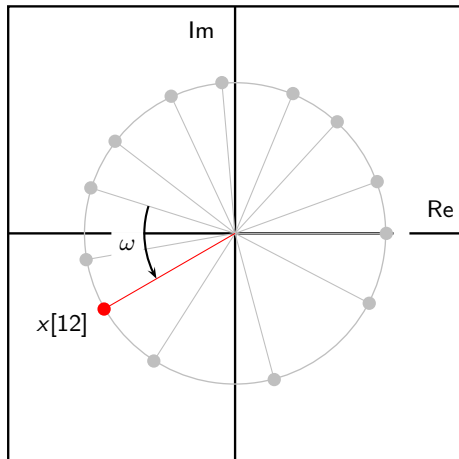
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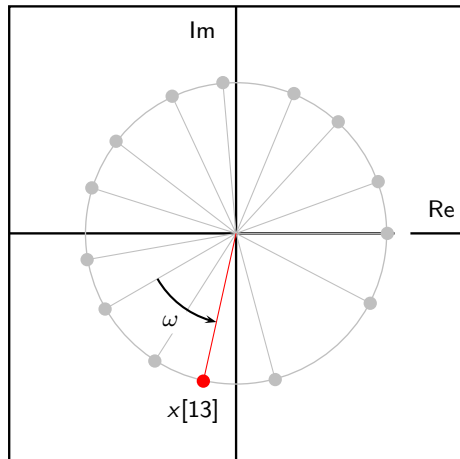
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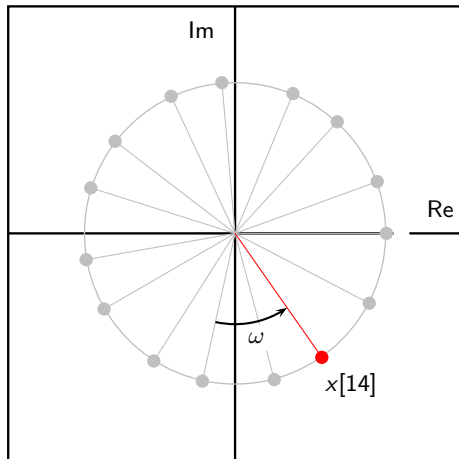
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$$e^{j\omega n} \text{ periodic} \iff \omega = \frac{M}{N}2\pi, M, N \in \mathbb{N}$$

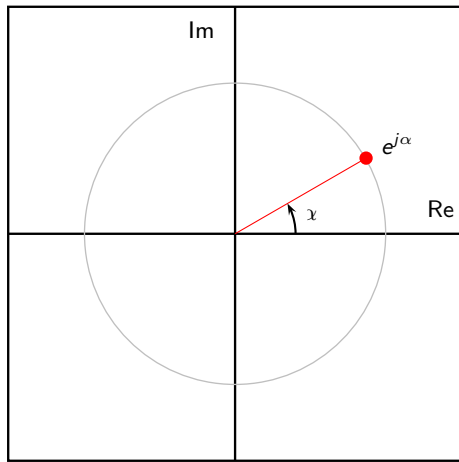
$$e^{j\omega} = e^{j(\omega+2k\pi)} \quad \forall k \in \mathbb{N}$$



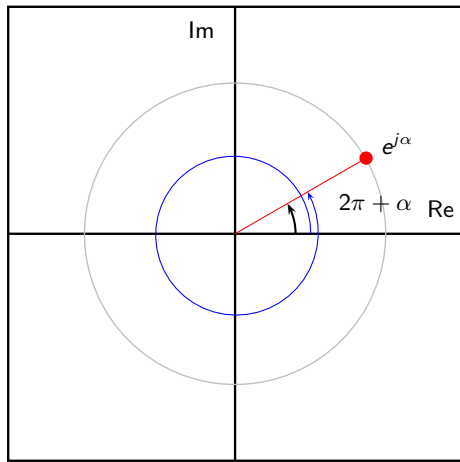
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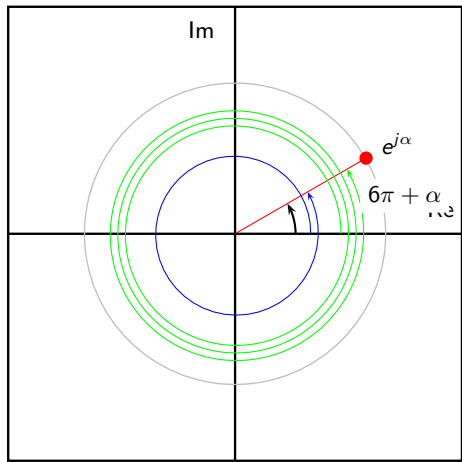
# One point, many names



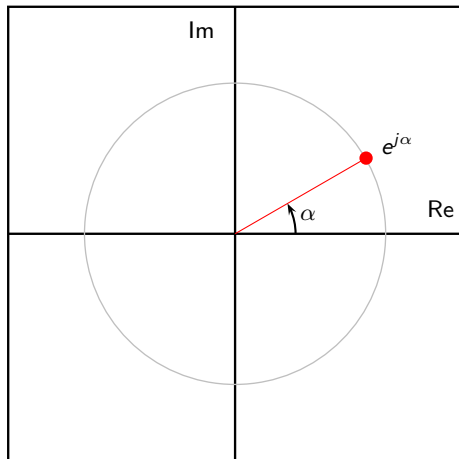
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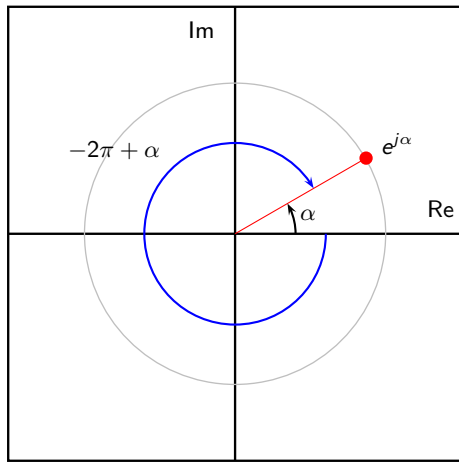
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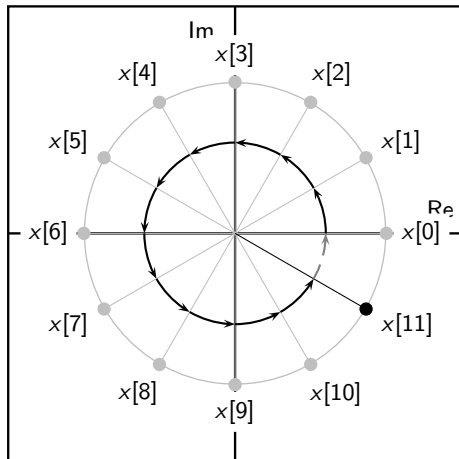


How “fast” can we go?



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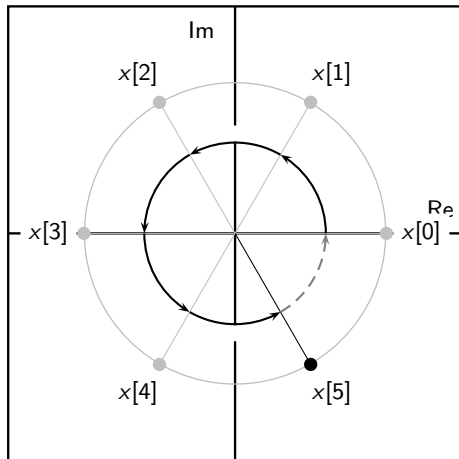
$$\omega = 2\pi/12$$





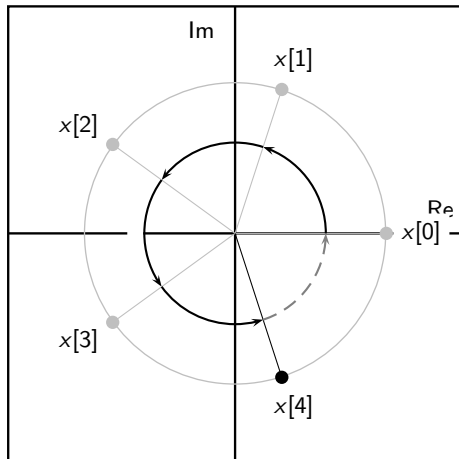
# How “fast” can we go?

$$\omega = 2\pi/6$$



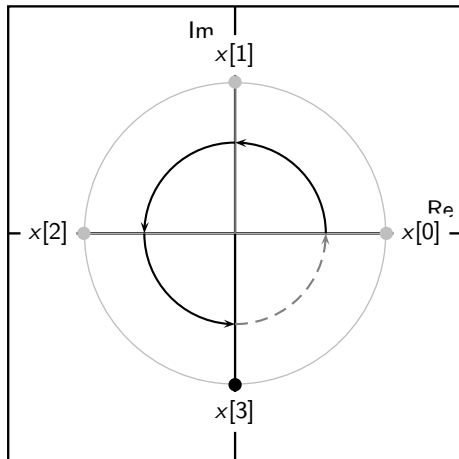
# How “fast” can we go?

$$\omega = 2\pi/5$$



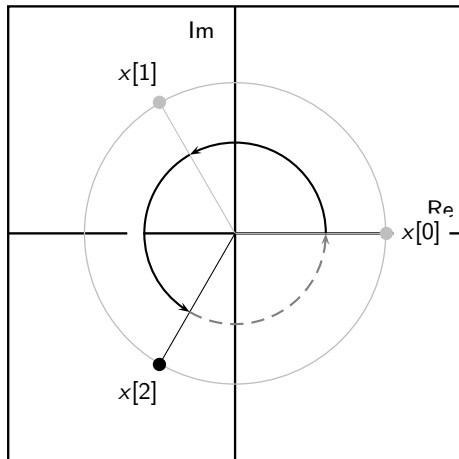
# How “fast” can we go?

$$\omega = 2\pi/4$$



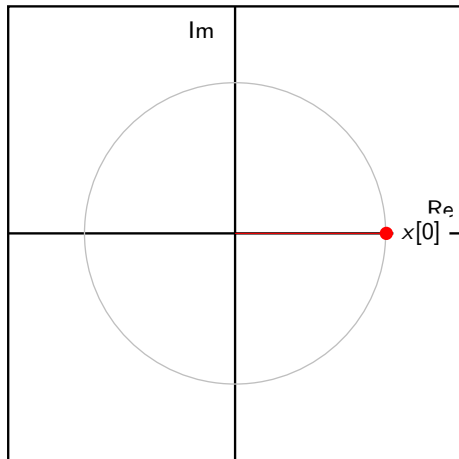
# How “fast” can we go?

$$\omega = 2\pi/3$$



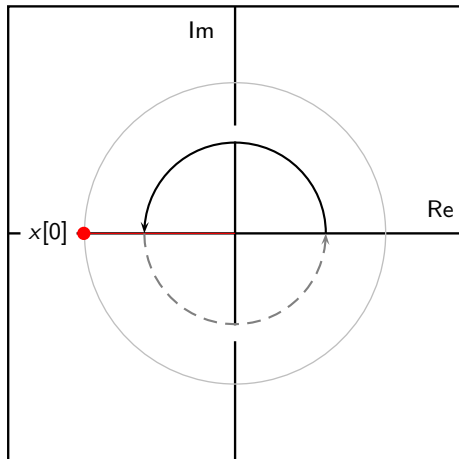
# How “fast” can we go?

$$\omega = 2\pi/2 = \pi$$



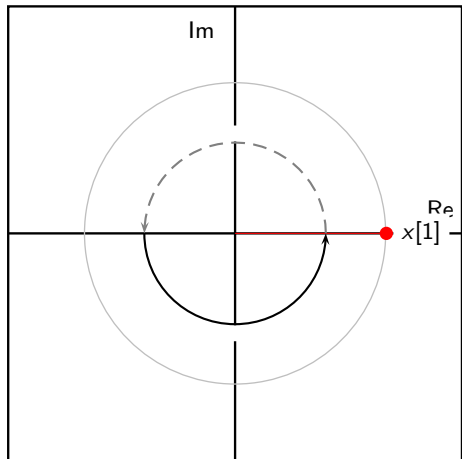
## How “fast” can we go?

$$\omega = 2\pi/2 = \pi$$



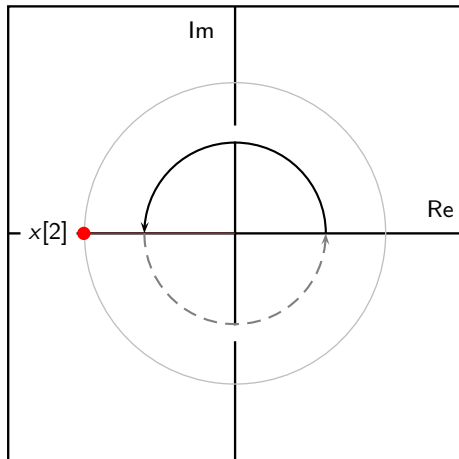
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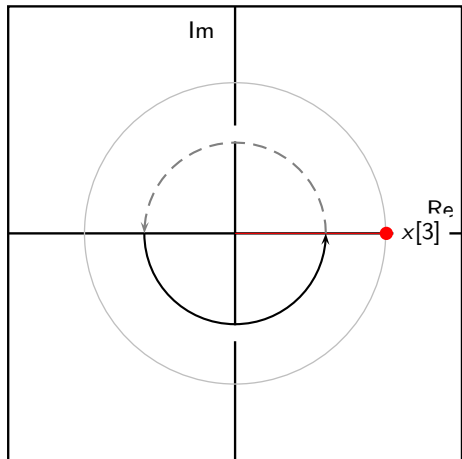
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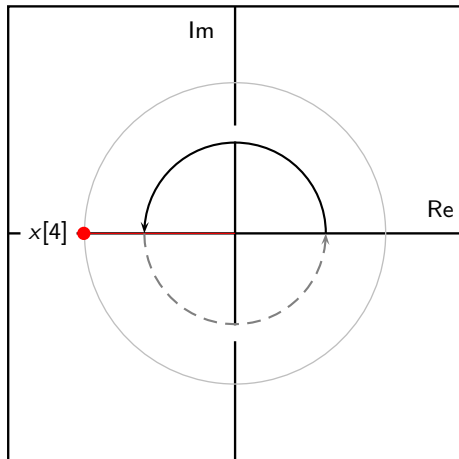
## How “fast” can we go?

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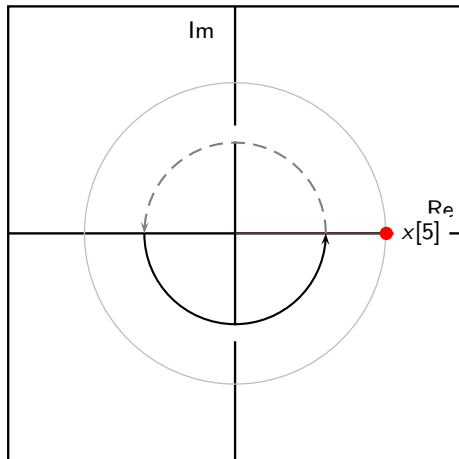
## How “fast” can we go?

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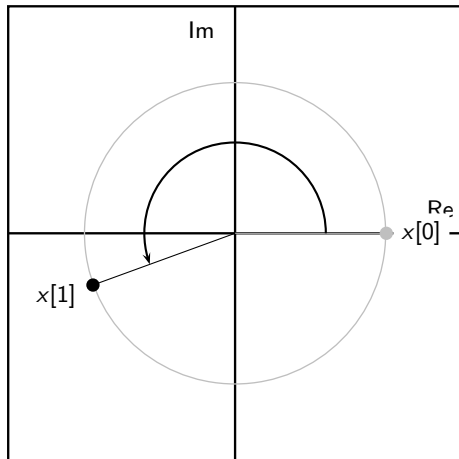
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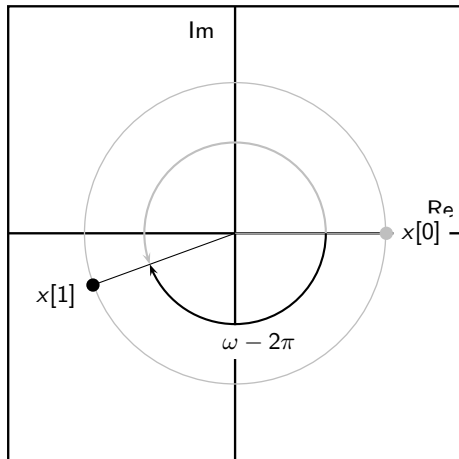
## What if we go “faster”?

$$\pi < \omega < 2\pi$$

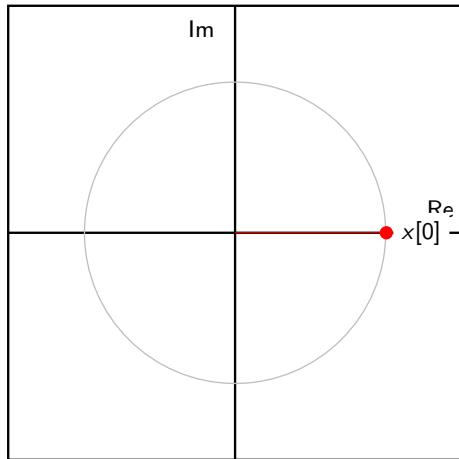


## What if we go “faster”?

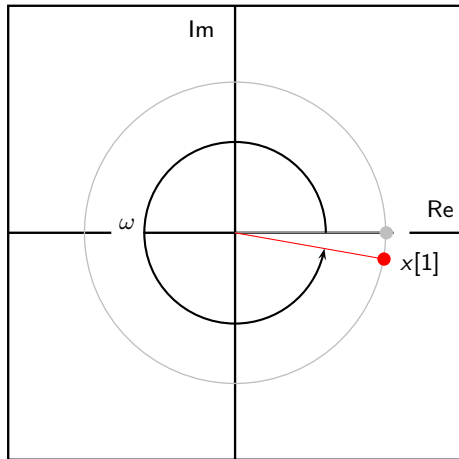
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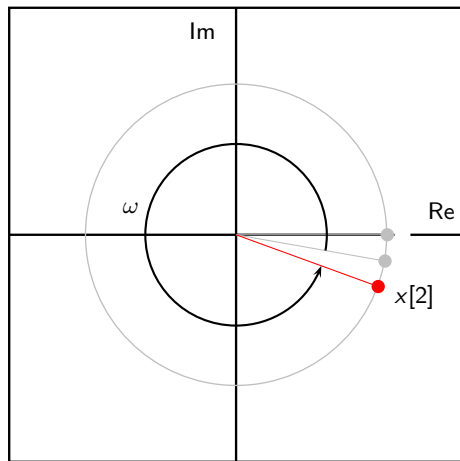
$$\omega = 2\pi - \alpha, \quad \alpha \text{ small}$$



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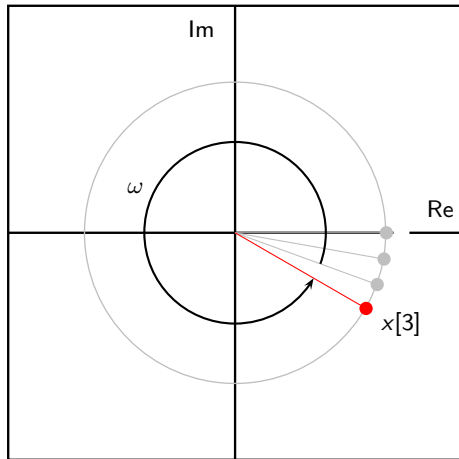


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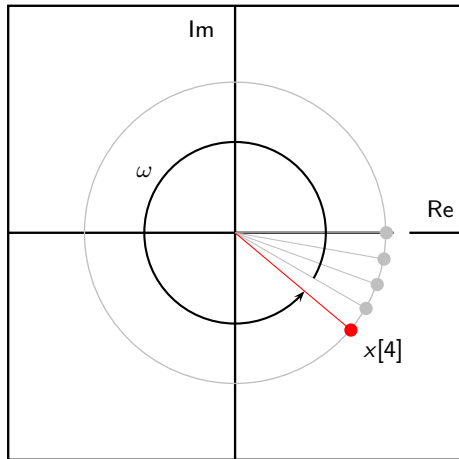




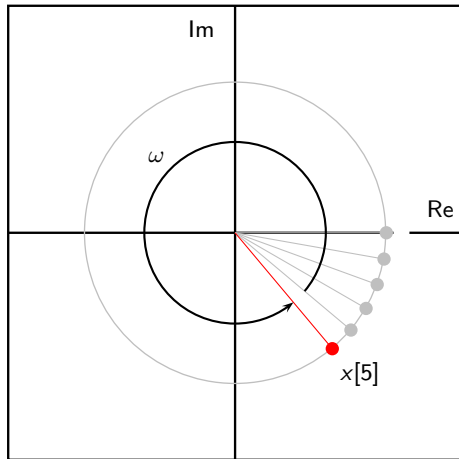
$$\omega = 2\pi - \alpha, \quad \alpha \text{ small}$$



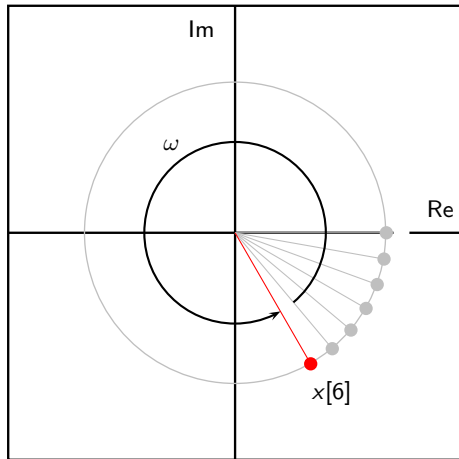
$$\omega = 2\pi - \alpha, \quad \alpha \text{ small}$$



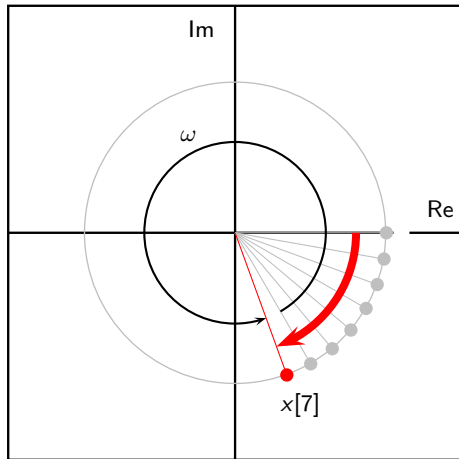
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## ► Discrete time:

- $n$ : no physical dimension (just a counter)
- periodicity: how many samples before pattern repeats

## ► “Real world”:

- periodicity: how many *seconds* before pattern repeats
- frequency measured in Hz ( $s^{-1}$ )

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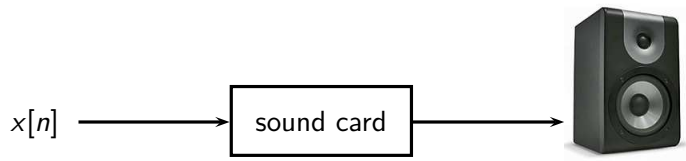


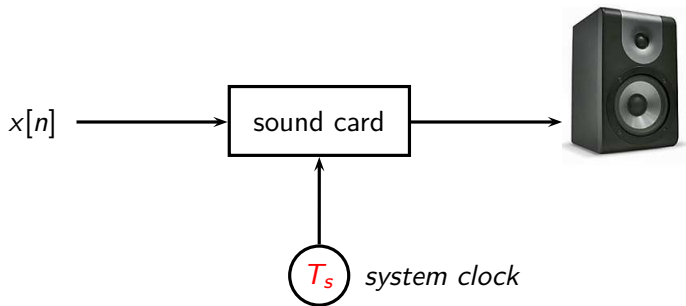
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- ▶ set  $T_s$ , time in seconds between samples
- ▶ periodicity of  $M$  samples  $\longrightarrow$  periodicity of  $MT_s$  seconds
- ▶ real world frequency:

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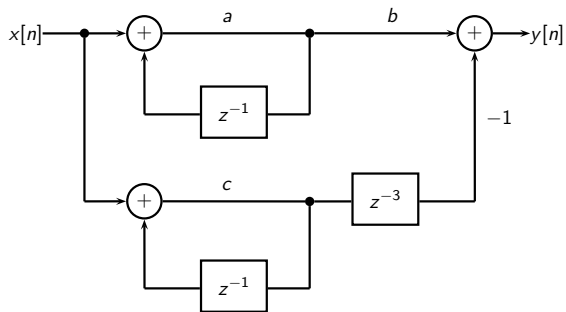
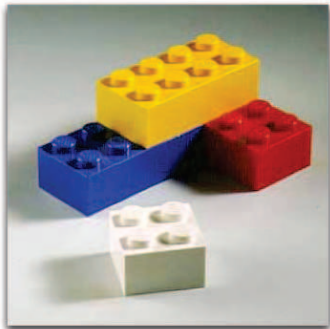
END OF MODULE 2.2

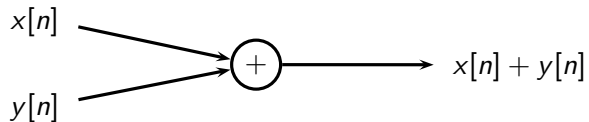
## Digital Signal Processing

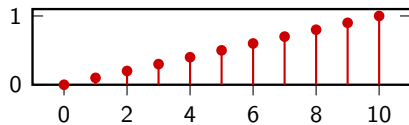
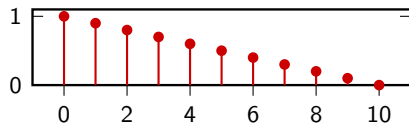
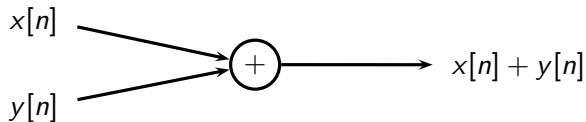
Module 2.3: the Karplus-Strong algorithm

- ▶ DSP building blocks
- ▶ moving averages and simple feedback loops
- ▶ a sound synthesizer

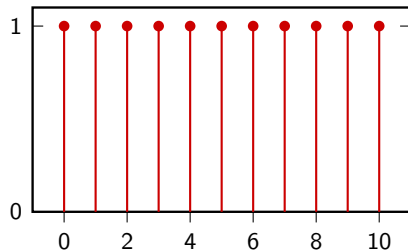
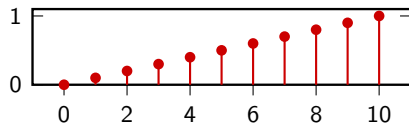
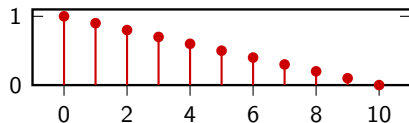
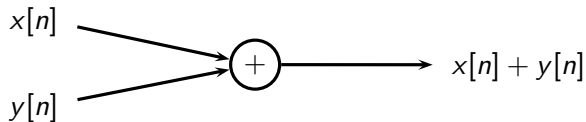
- ▶ DSP as Lego: The fundamental building blocks
- ▶ Averages and moving averages
- ▶ Recursion: Revisiting your bank account
- ▶ Building a simple recursive synthesizer
- ▶ Examples of sounds





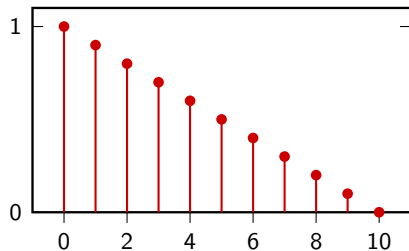




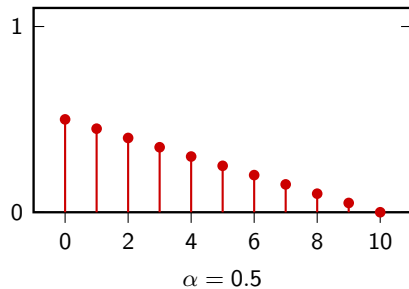
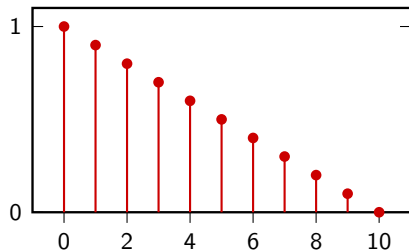


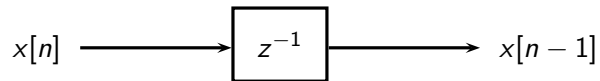
$$x[n] \xrightarrow{\alpha} \alpha x[n]$$

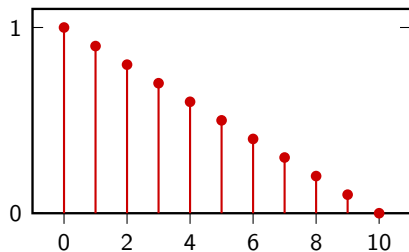
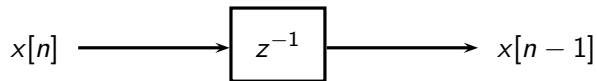
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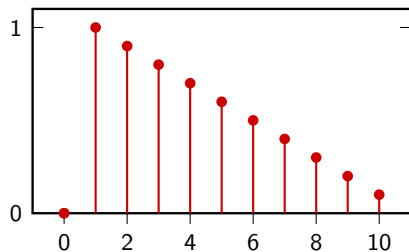
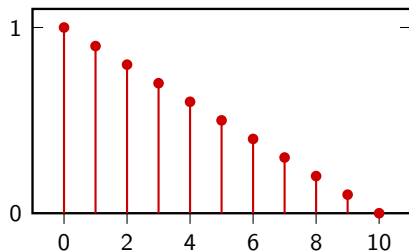
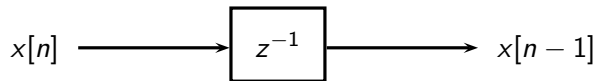


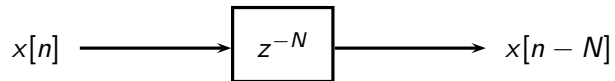
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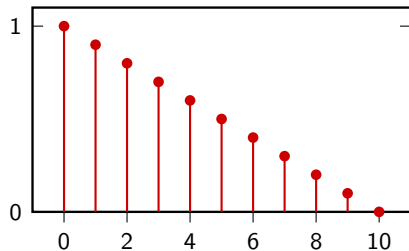
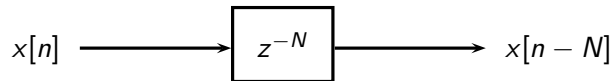


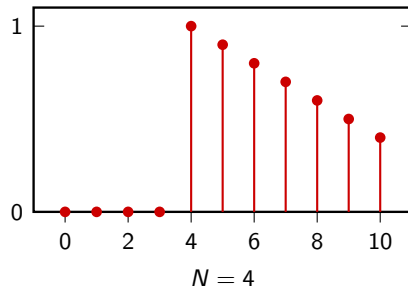
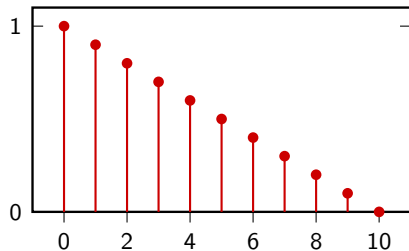
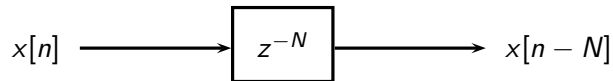












- ▶ simple average:

$$m = \frac{a + b}{2}$$

- ▶ moving average: take a “local” average

$$y[n] = \frac{x[n] + x[n - 1]}{2}$$

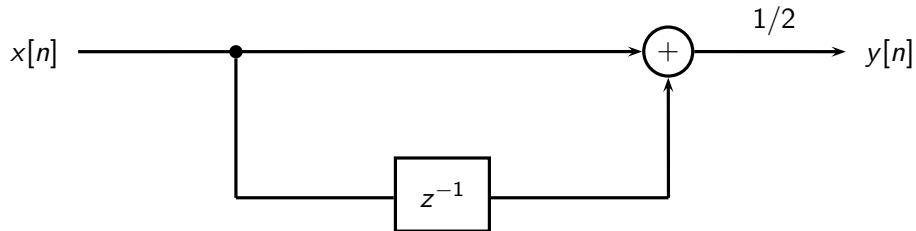
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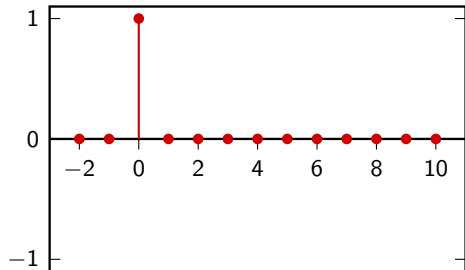
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## The 2-point Moving Average Using Lego



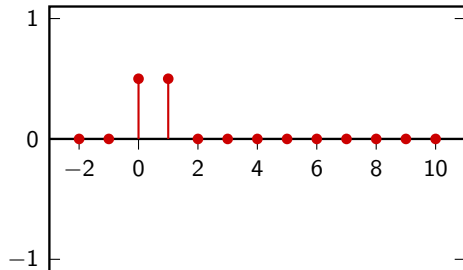
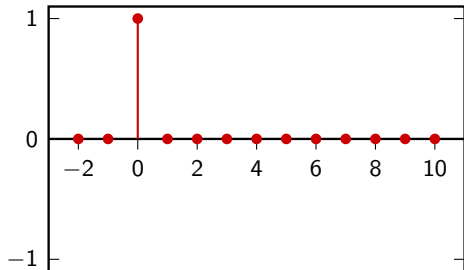
Let's average...

$$x[n] = \delta[n]$$



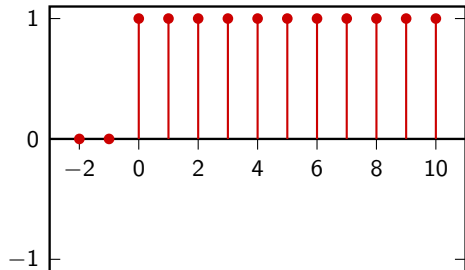
Let's average...

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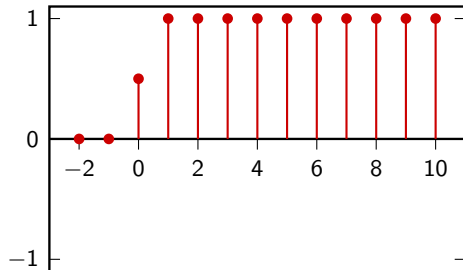
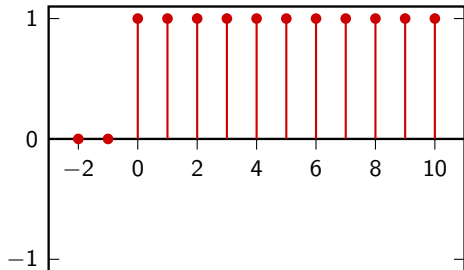
$$x[n] = u[n]$$





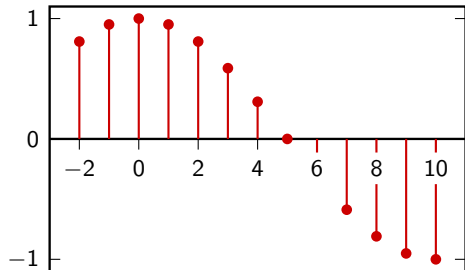
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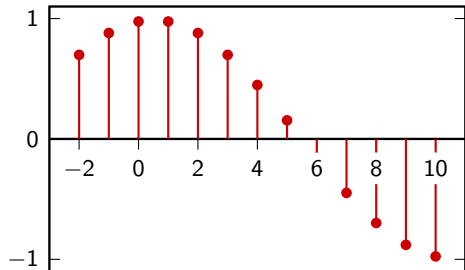
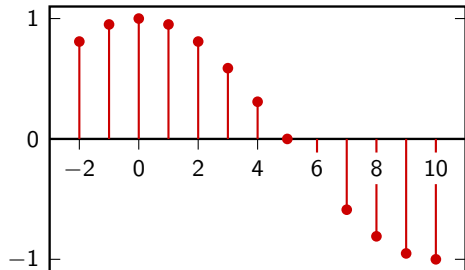
Let's average...

$$x[n] = \cos(\omega n), \quad \omega = \pi/10$$



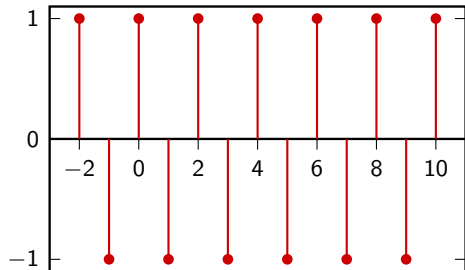
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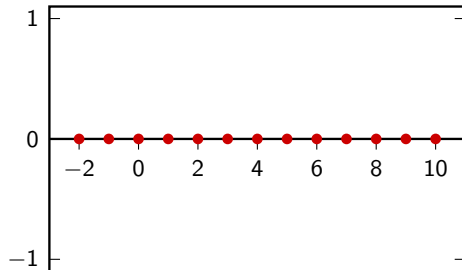
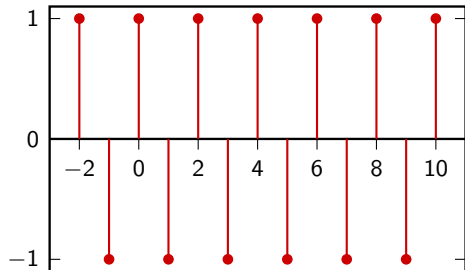
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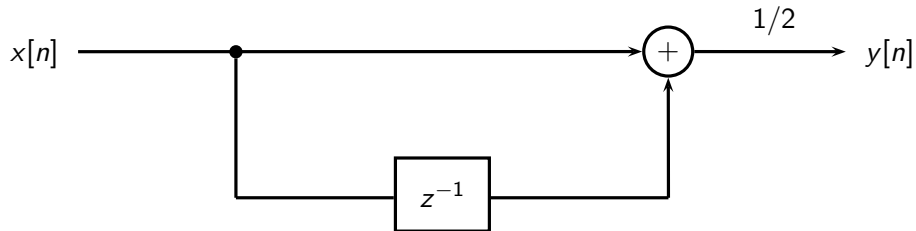


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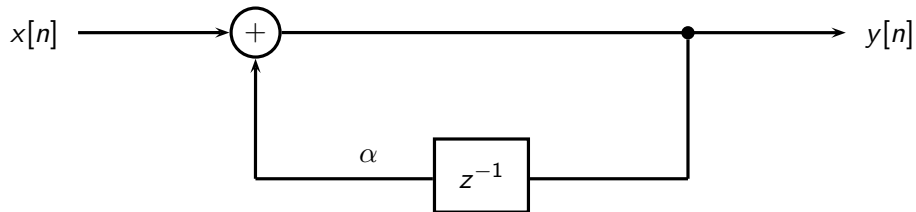
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## What if we reverse the loop?



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A simple equation to describe compound interest:

- ▶ constant interest/borrowing rate of 5% per year
- ▶ interest accrues on Dec 31
- ▶ deposits/withdrawals during year  $n$ :  $x[n]$
- ▶ balance at year  $n$ :

$$y[n] = 1.05 y[n-1] + x[n]$$



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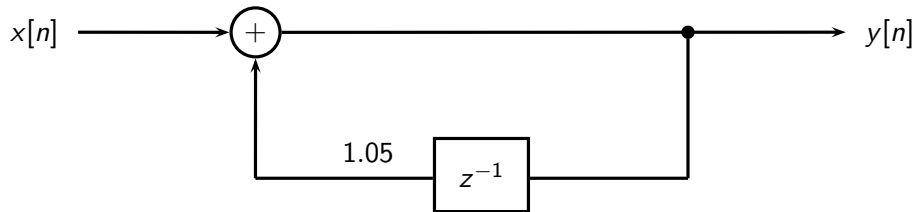
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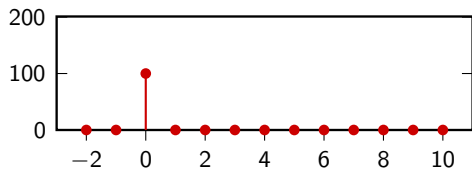


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## Example: the one-time investment

$$x[n] = 100 \delta[n]$$

- ▶  $y[0] = 100$
- ▶  $y[1] = 105$
- ▶  $y[2] = 110.25$ ,  $y[3] = 115.7625$  etc.
- ▶ In general:  $y[n] = (1.05)^n 100 u[n]$



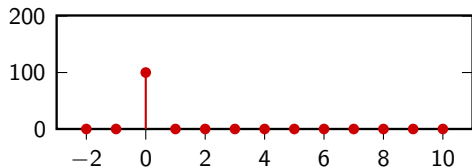
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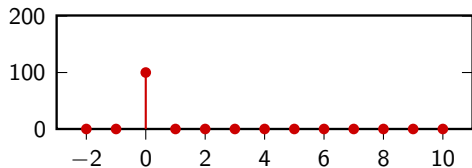
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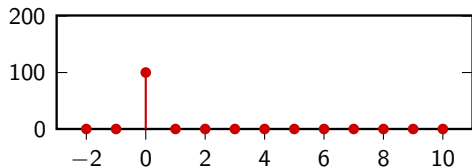
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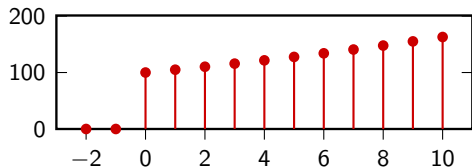
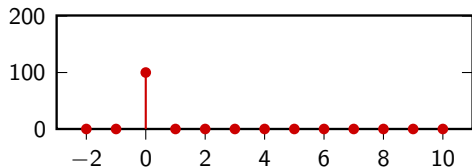
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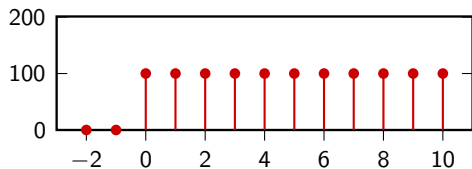
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$$x[n] = 100 u[n]$$

- ▶  $y[0] = 100$
- ▶  $y[1] = 205$
- ▶  $y[2] = 315.25$ ,  $y[3] = 431.0125$  etc.
- ▶ In general:  $y[n] = 2000 ((1.05)^{n+1} - 1) u[n]$



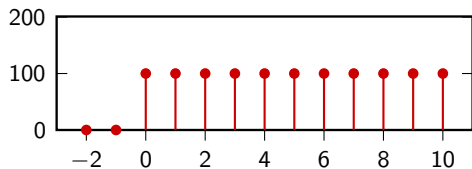
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► In general:  $y[n] = 2000 ((1.05)^{n+1} - 1) u[n]$



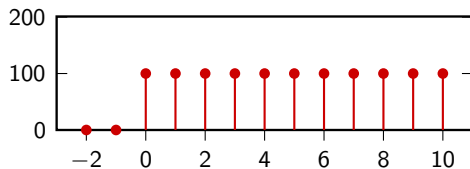
$$x[n] = 100 u[n]$$

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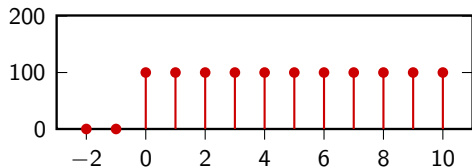
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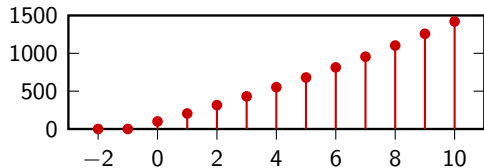
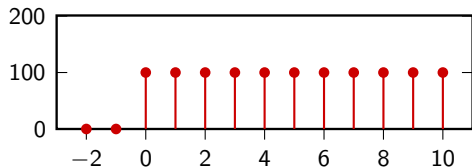
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## Example: The independently wealthy



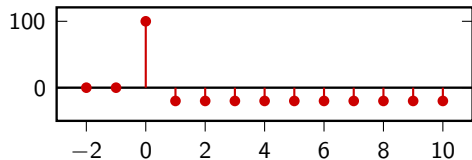
$$x[n] = 100 \delta[n] - 5 u[n - 1]$$

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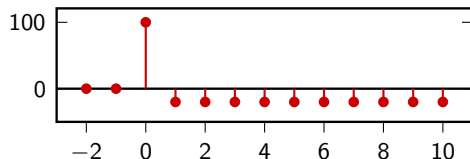
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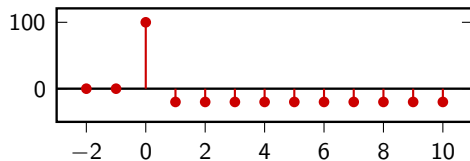
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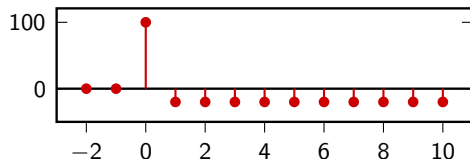
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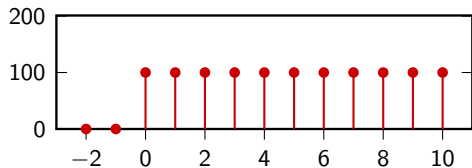
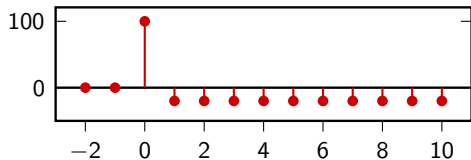


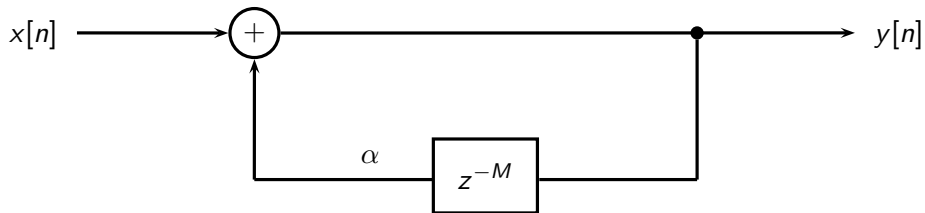
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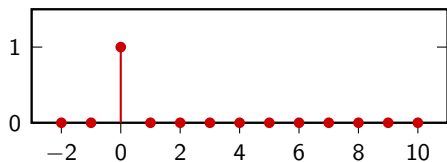




$$y[n] = \alpha y[n - M] + x[n]$$

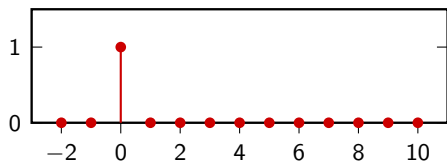
$$M = 3, \alpha = 0.7, x[n] = \delta[n]$$

- ▶  $y[0] = 1, y[1] = 0, y[2] = 0$
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- ▶  $y[6] = 0.7^2, y[7] = 0, y[8] = 0$ , etc.



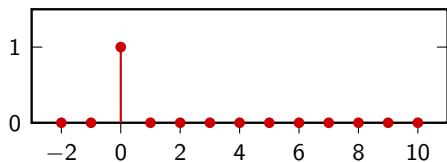
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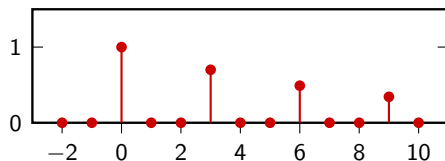
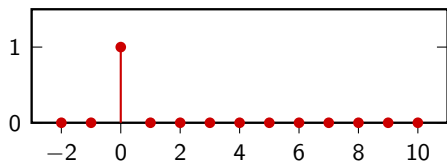
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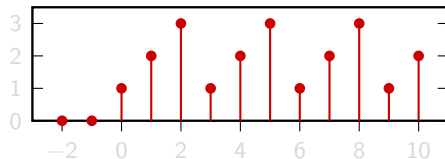
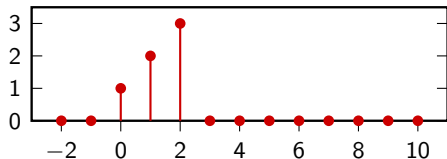
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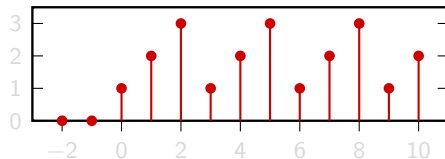
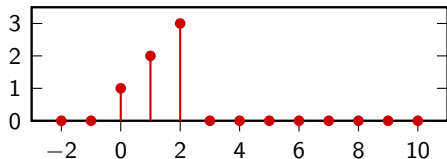
$$M = 3, \alpha = 1, x[n] = \delta[n] + 2\delta[n-1] + 3\delta[n-2]$$

- ▶  $y[0] = 1, y[1] = 2, y[2] = 3$
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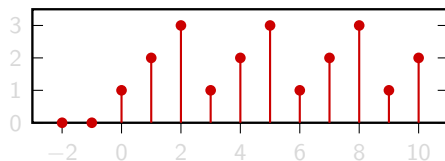
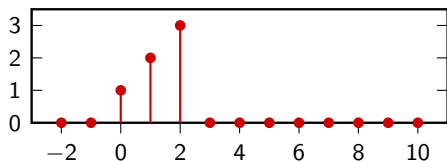
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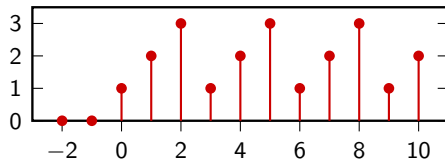
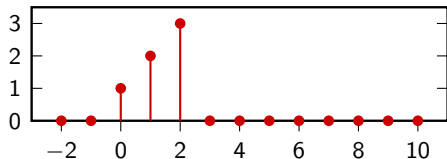
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- ▶ choose a signal  $\bar{x}[n]$  that is nonzero only for  $0 \leq n < M$
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- ▶ input  $\bar{x}[n]$  to the system
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- ▶  $M$ -tap delay  $\rightarrow$   $M$ -sample “periodicity”

- ▶ associate time  $T$  to sample interval

- ▶ periodic signal of frequency

$$f = \frac{1}{MT} \text{Hz}$$

- ▶ example:  $T = 22.7\mu\text{s}$ ,  $M = 100$

$$f \approx 440\text{Hz}$$

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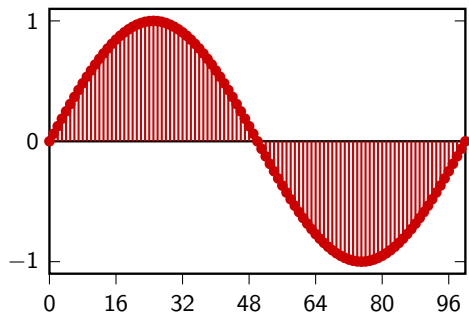
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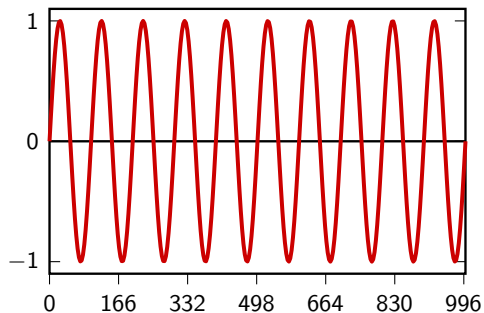
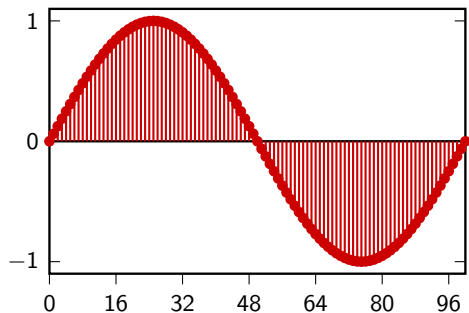
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$M = 100$ ,  $\alpha = 1$ ,  $\bar{x}[n] = \sin(2\pi n/100)$  for  $0 \leq n < 100$  and zero elsewhere



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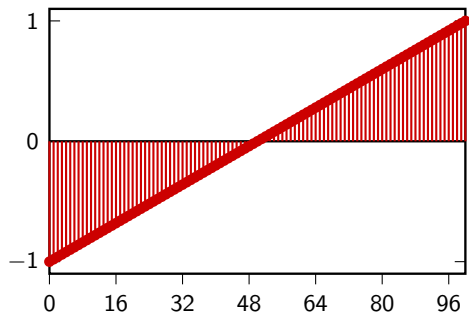
- ▶  $M$  controls frequency (pitch)
- ▶  $\alpha$  controls envelope (decay)
- ▶  $\bar{x}[n]$  controls color (timbre)



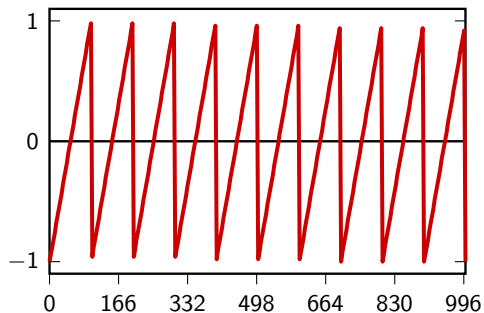
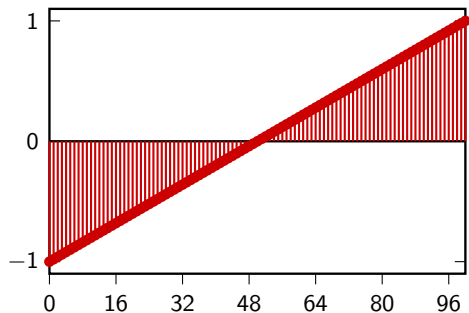
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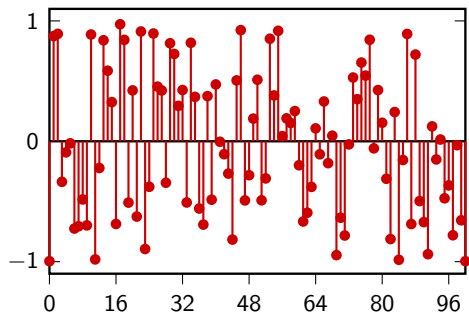
$M = 100$ ,  $\alpha = 0.95$ ,  $\bar{x}[n]$ : zero-mean sawtooth wave between 0 and 99, zero elsewhere



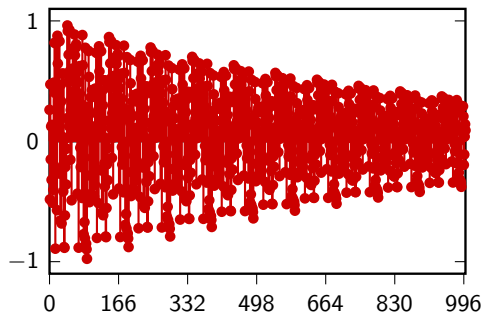
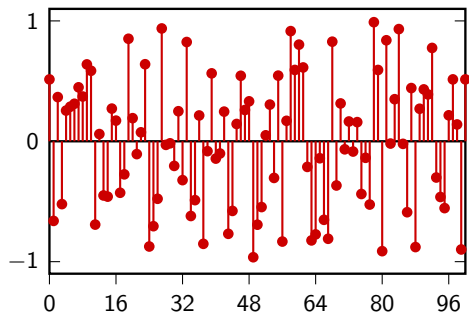
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$M = 100$ ,  $\alpha = 0.9$ ,  $\bar{x}[n]$ : 100 random values between 0 and 99, zero elsewhere



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- ▶ We have seen basic elements:
  - adders
  - multipliers
  - delays
- ▶ We have seen two systems
  - moving averages
  - recursive systems
- ▶ We were able to build simple systems with interesting properties
- ▶ to understand all of this in more details we need a mathematical framework!

END OF MODULE 2.3



END OF MODULE 2