

Digital Signal Processing

Solved HW for Day 3

Q: Derive a simple expression for the DFT of the time-reversed signal $\mathbf{x}_r = [x[N-1] \ x[N-2] \ x[1] \ x[0]]^T$ in terms of the DFT \mathbf{X} of the signal \mathbf{x} .

Hint: you may find it useful to remark that $W_N^k = W_N^{-(N-k)}$.

- ▶ Recall the DFT (analysis) formula

$$X[k] = \sum_{n=0}^{N-1} x[n] W_N^{nk}.$$

- ▶ The DFT of the time-reversed signal can be written as

$$X_r[k] = \sum_{n=0}^{N-1} x_r[n] W_N^{nk} = \sum_{n=0}^{N-1} x[N-1-n] W_N^{nk}$$

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- By replacing W_N^n with $W_N^{-(N-n)}$, we get

$$X_r[k] = \sum_{n=0}^{N-1} x[N-1-n] W_N^{-(N-n)k} = \sum_{n=0}^{N-1} x[n] W_N^{-(n+1)k}$$

- By replacing W_N^n with $W_N^{-(N-n)}$, we get

$$\begin{aligned} X_r[k] &= \sum_{n=0}^{N-1} x[N-1-n] W_N^{-(N-n)k} = \sum_{n=0}^{N-1} x[n] W_N^{-(n+1)k} \\ &= W_N^{-k} \sum_{n=0}^{N-1} x[n] W_N^{-nk} = W_N^{-k} \sum_{n=0}^{N-1} x[n] W_N^{n(N-k)} \end{aligned}$$

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$$\begin{aligned} X_r[k] &= \sum_{n=0}^{N-1} x[N-1-n] W_N^{-(N-n)k} = \sum_{n=0}^{N-1} x[n] W_N^{-(n+1)k} \\ &= W_N^{-k} \sum_{n=0}^{N-1} x[n] W_N^{-nk} = W_N^{-k} \sum_{n=0}^{N-1} x[n] W_N^{n(N-k)} \\ &= W_N^{-k} X[N-k]. \end{aligned}$$

Question 2: DFT manipulation



Consider a length- N signal $\mathbf{x} = [x[0] \ x[1] \ \dots \ x[N-1]]^T$ and the corresponding vector of DFT coefficients $\mathbf{X} = [X[0] \ X[1] \ \dots \ X[N-1]]^T$.

Consider now the length- $2N$ signal obtained by interleaving the values of \mathbf{x} with zeros:
 $\mathbf{x}_2 = [x[0] \ 0 \ x[1] \ 0 \ x[2] \ 0 \ \dots \ x[N-1] \ 0]^T$.

Q: Express \mathbf{X}_2 (the $2N$ -point DFT of \mathbf{x}_2) in terms of \mathbf{X} .

- Then, knowing that

$$W_{2N}^{2nk} = e^{-j\frac{2\pi}{2N}2nk} = e^{-j\frac{2\pi}{N}nk} = \begin{cases} W_N^{nk}, & 0 \leq k < N \\ W_N^{n(k-N)}, & N \leq k < 2N \end{cases}$$

we get

$$X_2[k] = \begin{cases} \sum_{n=0}^{N-1} x[n] W_N^{nk} & = X[k], & 0 \leq k < N \\ \sum_{n=0}^{N-1} x[n] W_N^{n(k-N)} & = X[(k-N)], & N \leq k < 2N \end{cases}$$

Compute the DFT of the length-4 real signal $\mathbf{x} = [a, b, c, d]^T$.

Q: For which values of $a, b, c, d \in \mathbb{R}$ is the DFT real?

- The DFT of the length-4 real signal $\mathbf{x} = [a, b, c, d]^T$ is

$$X[k] = a + be^{-j\frac{2\pi}{4}k} + ce^{-j\frac{2\pi}{4}2k} + de^{-j\frac{2\pi}{4}3k}$$

- The DFT of the length-4 real signal $\mathbf{x} = [a, b, c, d]^T$ is

$$\begin{aligned} X[k] &= a + be^{-j\frac{2\pi}{4}k} + ce^{-j\frac{2\pi}{4}2k} + de^{-j\frac{2\pi}{4}3k} \\ &= a + b(-j)^k + c(-j)^{2k} + d(-j)^{3k} \end{aligned}$$

- The DFT of the length-4 real signal $\mathbf{x} = [a, b, c, d]^T$ is

$$\begin{aligned} X[k] &= a + be^{-j\frac{2\pi}{4}k} + ce^{-j\frac{2\pi}{4}2k} + de^{-j\frac{2\pi}{4}3k} \\ &= a + b(-j)^k + c(-j)^{2k} + d(-j)^{3k} \\ &= \begin{cases} a + b + c + d, & k = 0 \\ a - c - j(b - d), & k = 1 \\ a - b + c - d, & k = 2 \\ a - c + j(b - d), & k = 3 \end{cases} \end{aligned}$$

Therefore, the DFT vector \mathbf{X} is real iff $b = d$.