# XIAOZHENG (JUDY) XU

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#### **EDUCATION**

## OLIN COLLEGE OF ENGINEERING, Needham, MA

May 2018

Robotics Engineering, GPA 3.83/4

**Relevant courses:** Computer Architecture, Computational Robotics, Data structures, Software Design, Controls, Dynamics, Fluid Dynamics, Mechanical Prototyping, Quantum Physics, Partial Differential Equations

#### EXPERIENCE

# Software Engineering Intern at Google, Mountain View, CA

June-Aug 2017

## With Davdream (Google VR):

- Worked on creating a html report for computing metrics and visualizing results
- Collected and processed data from real time measurement system
- Learned better coding practices through testing and code reviews

#### Summer Research Position in Astronomy, Toronto, ON

May-Aug 2016

## Under the direction of Prof. Ue-Li Pen at Canadian Institute for Theoretical Astrophysics:

- Researched about the emission mechanisms of the crab pulsar using its nebula as a galactic telescope.
- Used Python and Linux to process signals at different radio telescopes around the world.
- Found that the crab's enigmatic pulses might be emitted from regions separated more than 500km in the pulsar's magnetosphere.

## Localization Intern, Dassault Systems, Waltham, MA

Summer 2015

- Worked on the user interface of Solidworks in 13 different languages.
- Solved customer and QA generated service pack reports by investigating the bugs in the software. Wrote corresponding Fix-requests to translation vendor.

#### **PROJECTS**

#### **Senior Capstone in Engineering**

Fall 2017

• Research, design and implement a new type of low-weight actuator for aerospace applications.

## **Computer Architecture**

Fall 2017

• Design and implement a computer CPU in verilog.

## **IARC** competition

Fall 2017

 Research and design an autonomous drone to "shepherd" roomba robots in random motion, with extensive machine learning and algorithm implementations

# **Computational Robotics**

Spring 2017

• Implemented a working Extended Kalman Filter with Neatos Odometry and IMU data.

## Affordable Design for Entrepreneurship

Spring 2017

• Improve design, production and cost of cassava-processing machines for women in rural Ghana.

#### **Fundamental of Robotics**

Fall 2016

• Designed and coded an autonomous Bravobot to race around campus using LIDAR, camera and ROS. **Controls** Fall 2016

• Built and analyzed an inverted pendulum and magnetic levitation using circuits without sensors.

## **Software Design**

Spring 2016

• Designed and implemented an Interactive Calculus app using python and open CV.

#### **Principles of Engineering**

Fall 2015

• Designed, prototyped and fabricated Azimuth, a table top robot that fetches salt and pepper.

#### SKILLS

- Programming and software: Python, java, ROS, Matlab, Linux, Arduino, C++
- CAD and Rapid Prototyping: Solidworks CSWA-certified, 3D printing, Laser cut
- Languages: English(bilingual), Mandarin(bilingual), French (advanced)
- Machine Shop: trained on mill, lathe, drills, saws and sanders