

# Summary of jincheng1\_short\_20-bs

Run date: 2024-04-26 20:02:28.647930

Time cost: 15.24 s

## BASIC INFORMATION

Environment condition:

- temperature (°C): 26.0
- salinity (ppt): 28.0
- depth (m): 5.0
- pH: 8.0

Raw waterfall:

- frequency (kHz): 20
- slant range (m): 80.0
- sample count: 1736
- ping count: 717

NMEA:

- planned speed (knot): 4.0
- recorded speed (knot): mean=3.6, std=0.4, min=2.6, max=4.0
- raw tow fish geographic coordinates:
  - min-max longitude=120.06228-120.06396
  - min-max latitude=37.43908-37.43912
- ping direction type: cog
- raw ping direction (degree): mean=None, std=None, min=None, max=None
- smoothed ping direction(degree): mean=None, std=None, min=None, max=None

Tow fish:

- port altitude (m): mean=-2.7, std=0.2, min=-3.2, max=-2.4
- starboard altitude (m): mean=-2.7, std=0.2, min=-3.2, max=-2.4

Geocoding mosaic:

- resolution (m/pixel): 0.1
- geographic EPSG: 4490, projected EPSG: 4499
- survey line length (smoothed, m): 149.8
- flat swath (port+starboard, m): min-max=159.9-159.9
- scanning area (square meter): 23309.6

## PROCESSING PARAMETERS

TVG enhancement:

- lambda: 20.0

Bottom detection:

- gradient\_thred\_factor: 0.1
- win\_h: 10
- use\_ab\_line\_correction: 0
- peak\_factor: 0.7
- valley\_std: 5

Slant correction:

- bottom\_offset: [2, 5]

Gray enhancement:

- gray\_enhance\_method: coarse2fine
- gaussian\_kernel: 50
- gain: 10.0
- alpha: 0.05
- ratio: 0.02
- prob\_thred: 0.3

Geocoding:

- is\_ns: 1
- fish\_trajectory\_smooth\_type: bspline
- fish\_trajectory\_smooth\_factor: 80.0
- angle: cog
- angle\_smooth\_factor: 10.0

# Waterfall after each processing step

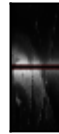
Raw waterfall



TVG enhanced waterfall



Waterfall with bottom line



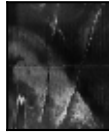
Slant corrected waterfall



Gray enhanced waterfall



Speed corrected waterfall

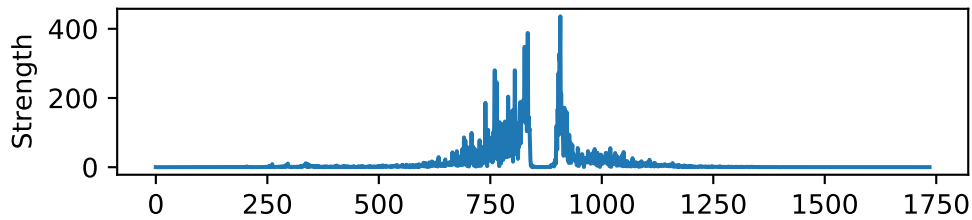


Geocoded sidescan image

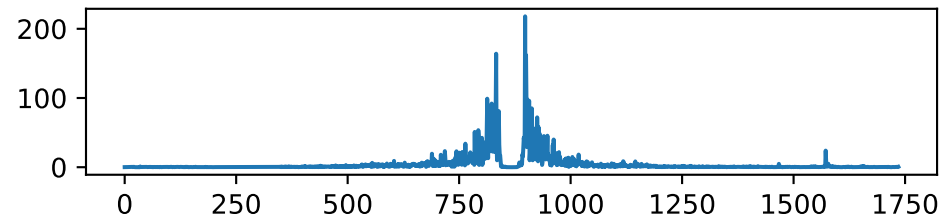


# Backscatters of two random pings in each processing step

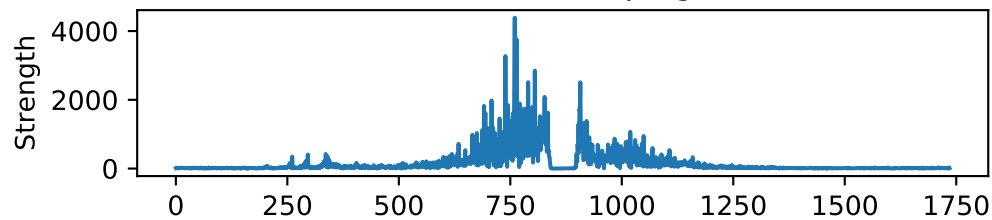
Raw ping 77



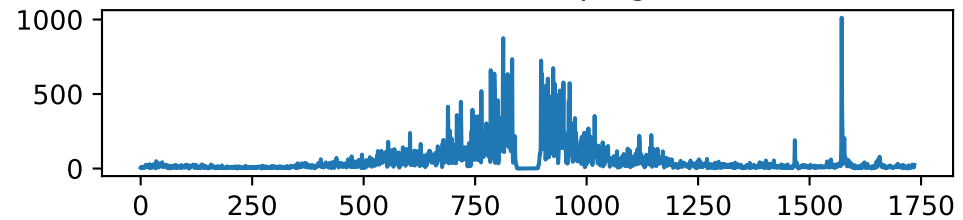
Raw ping 610



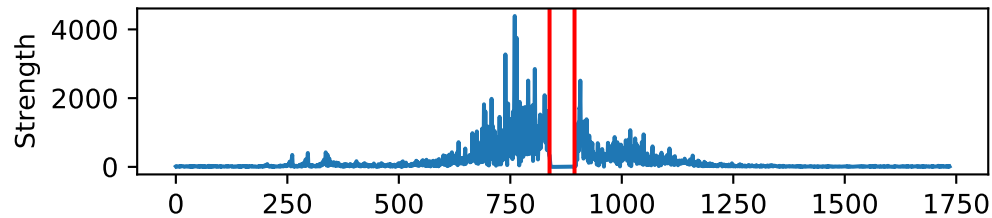
TVG enhanced ping 77



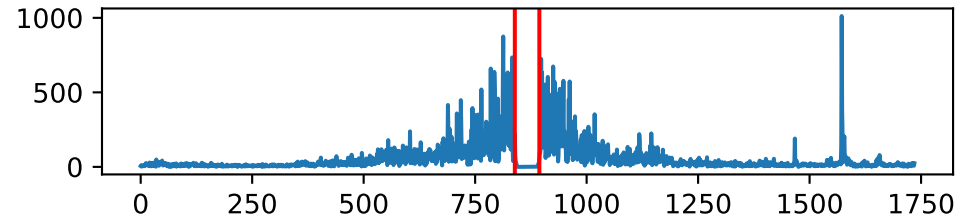
TVG enhanced ping 610



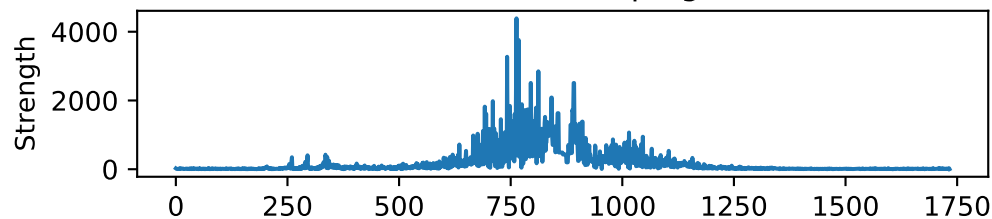
Bottom line on TVG enhanced ping 77



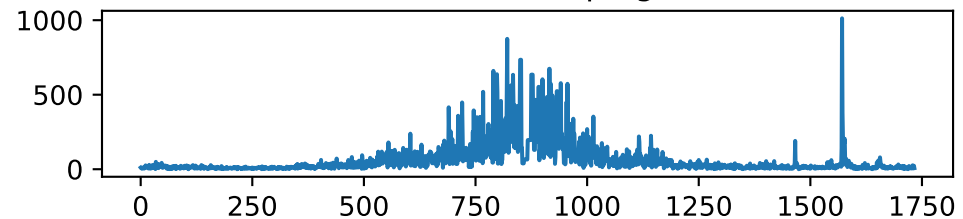
Bottom line on TVG enhanced ping 610



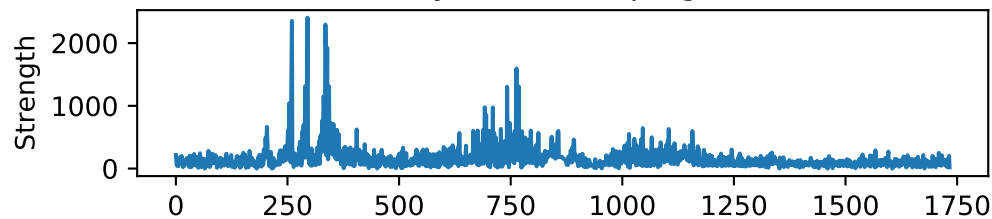
Slant corrected ping 77



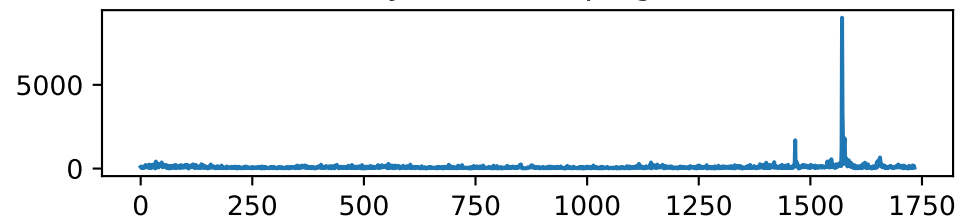
Slant corrected ping 610



Gray enhanced ping 77



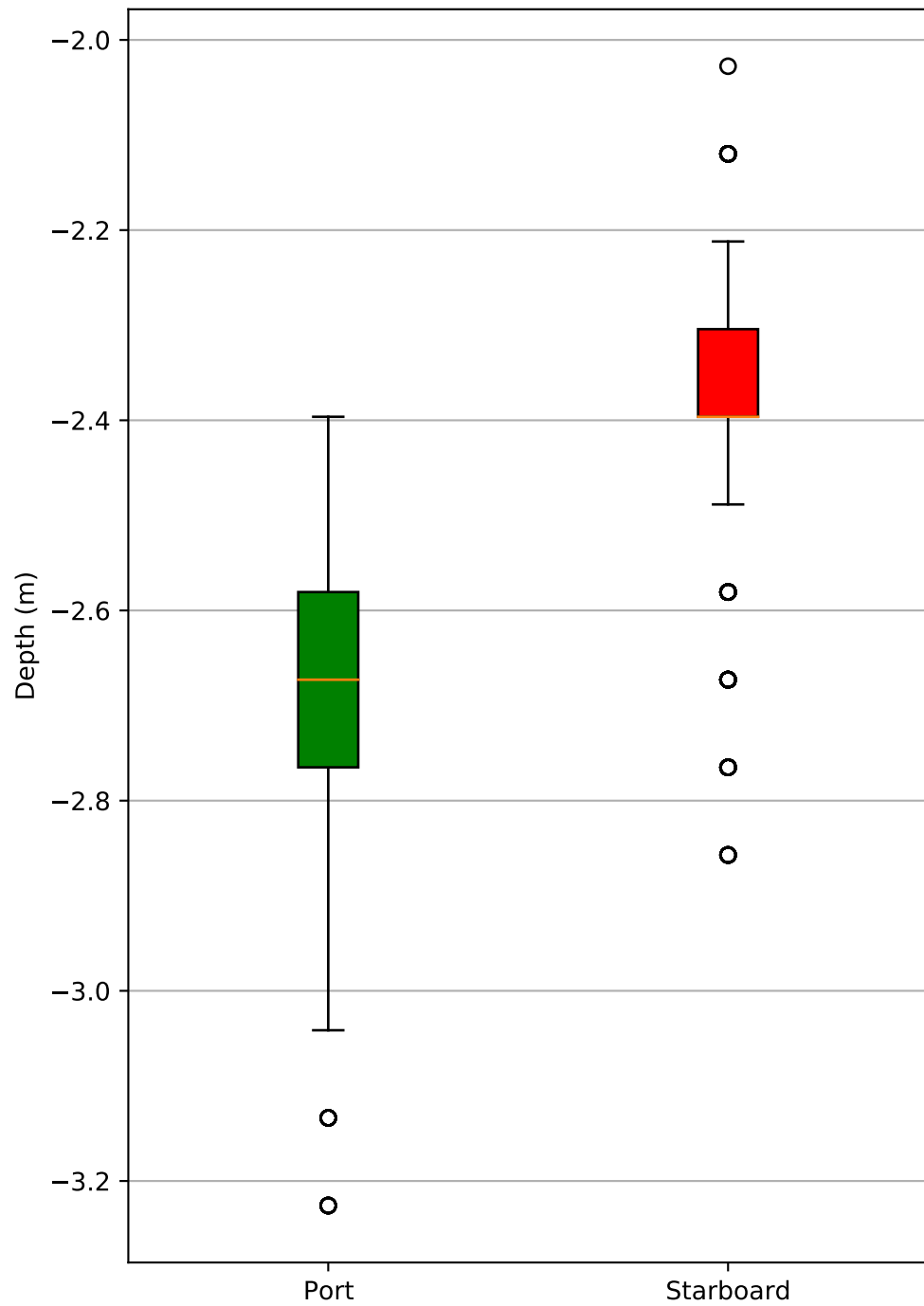
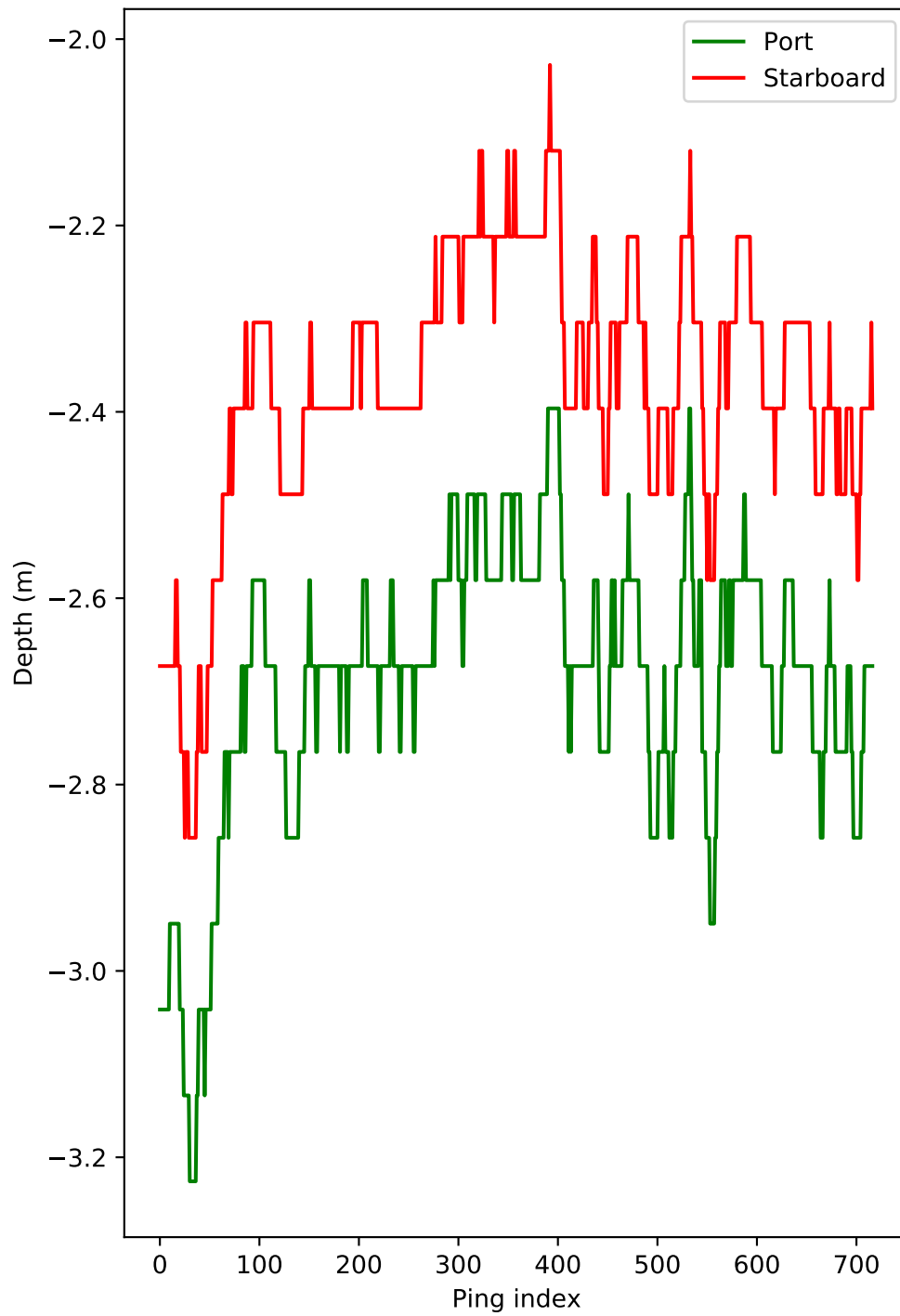
Gray enhanced ping 610



Backscatter samples

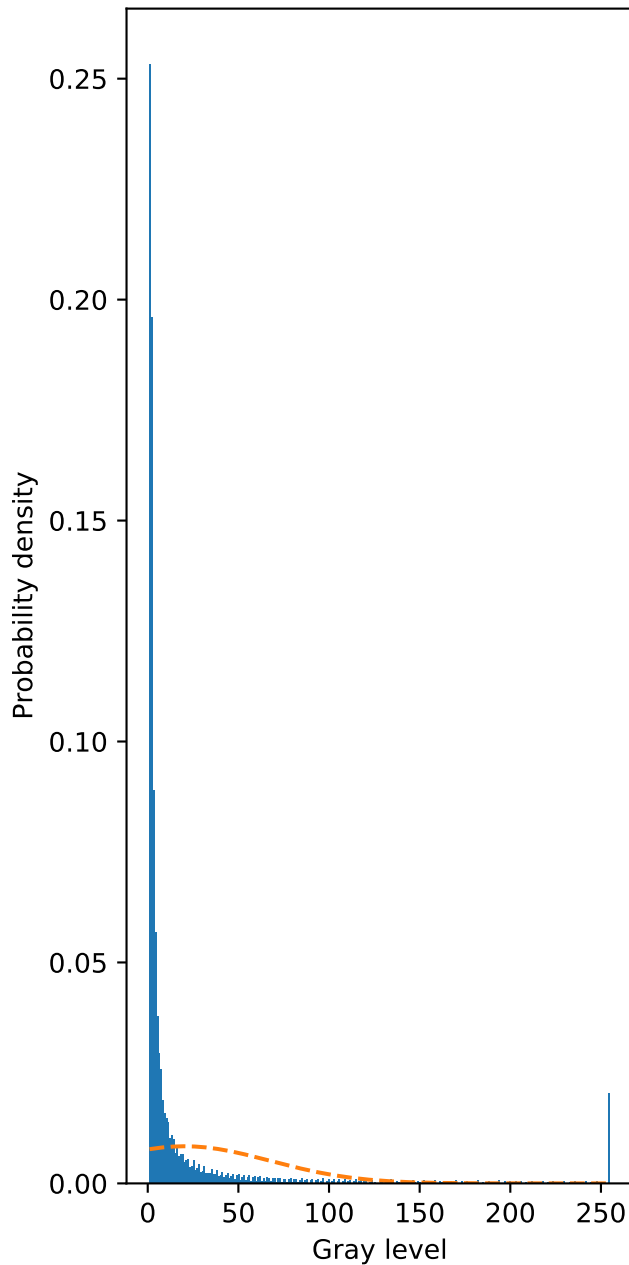
Backscatter samples

# Bottom depth distribution

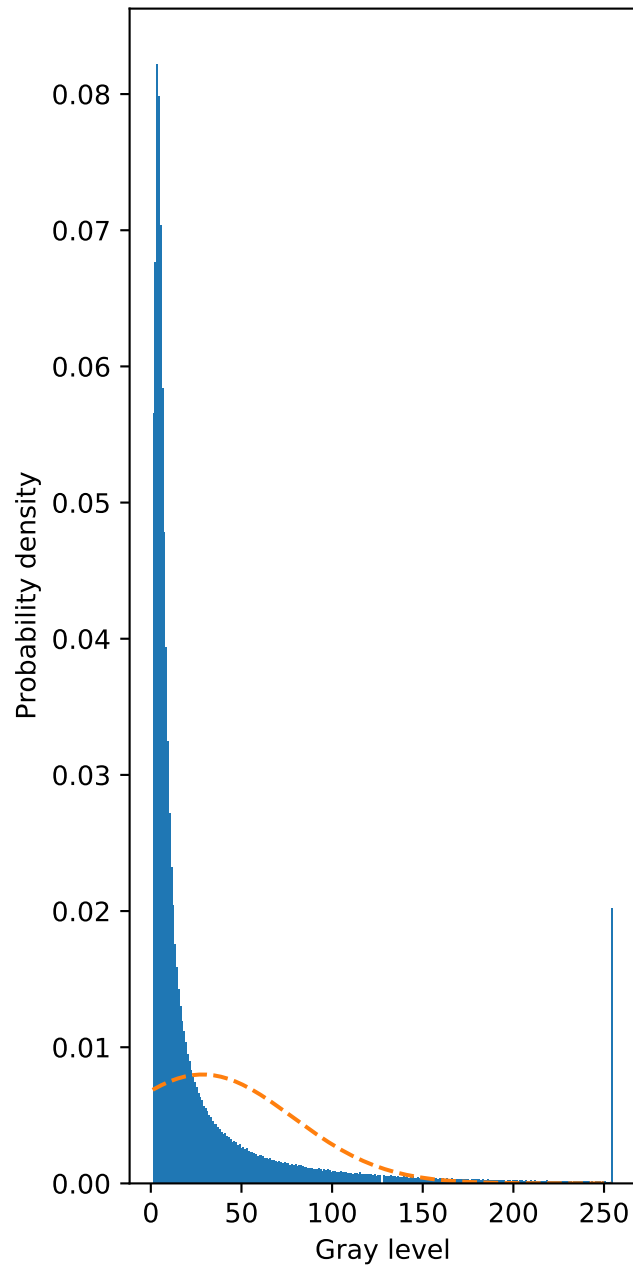


# Histogram before and after gray enhancement

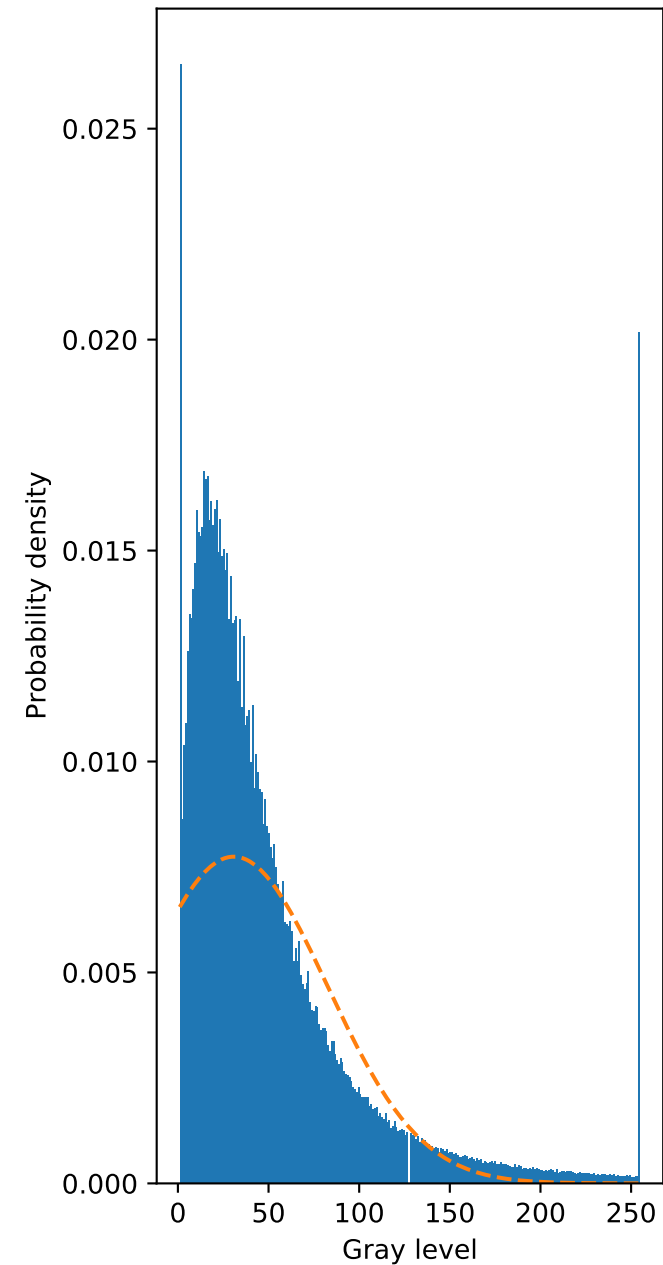
Raw waterfall:  
 $\mu=20$ ,  $\sigma=47$ ,  
difference=1.0768



TVG enhanced waterfall:  
 $\mu=28$ ,  $\sigma=50$ ,  
difference=0.9076



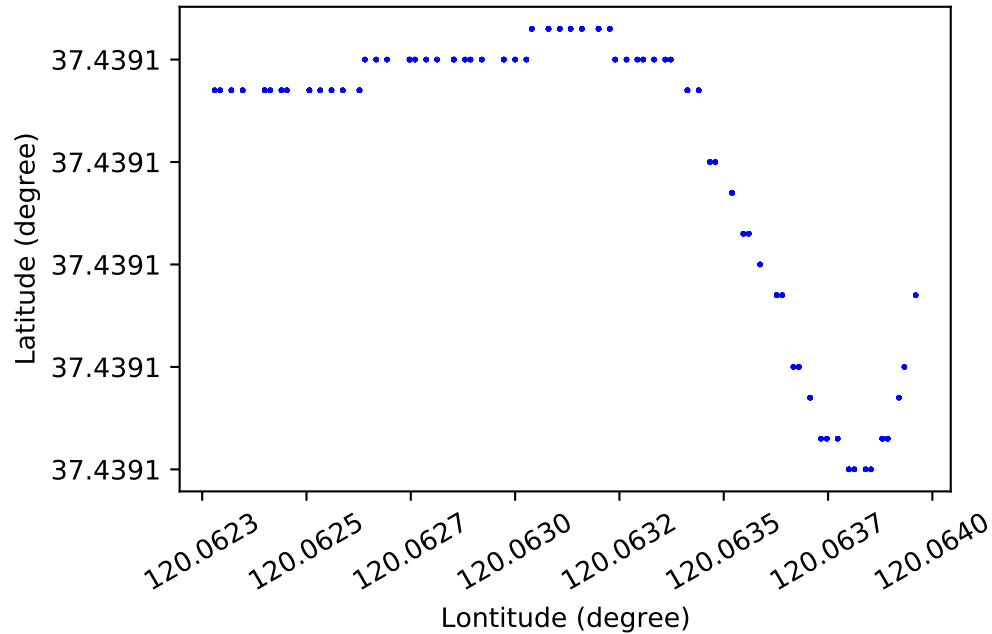
Gray enhanced waterfall:  
 $\mu=51$ ,  $\sigma=52$ ,  
difference=0.4051



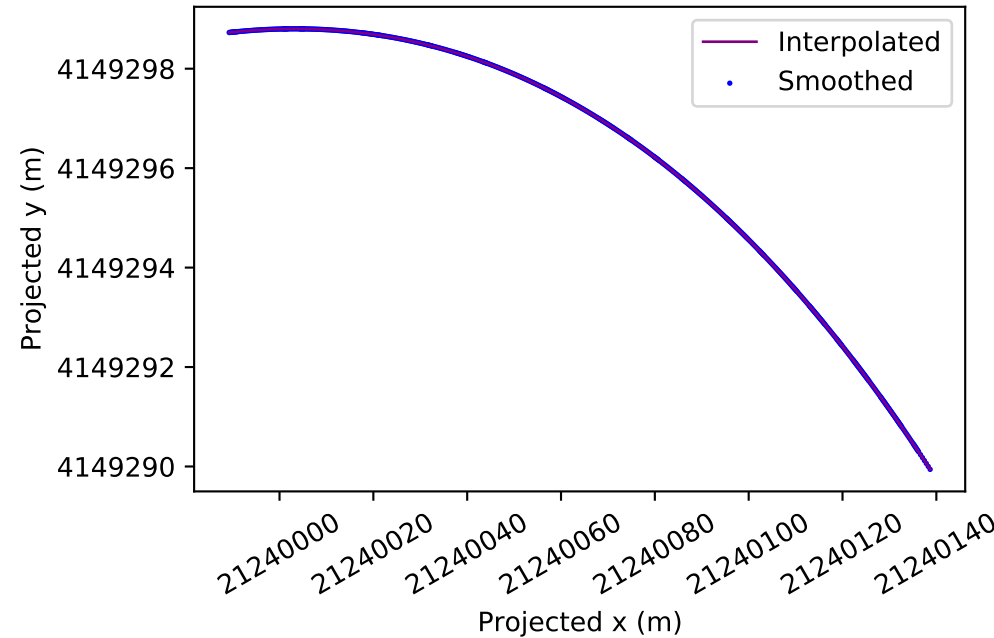
- Note: difference: absolute difference between histogram and normal distribution

# Survey line and ping direction

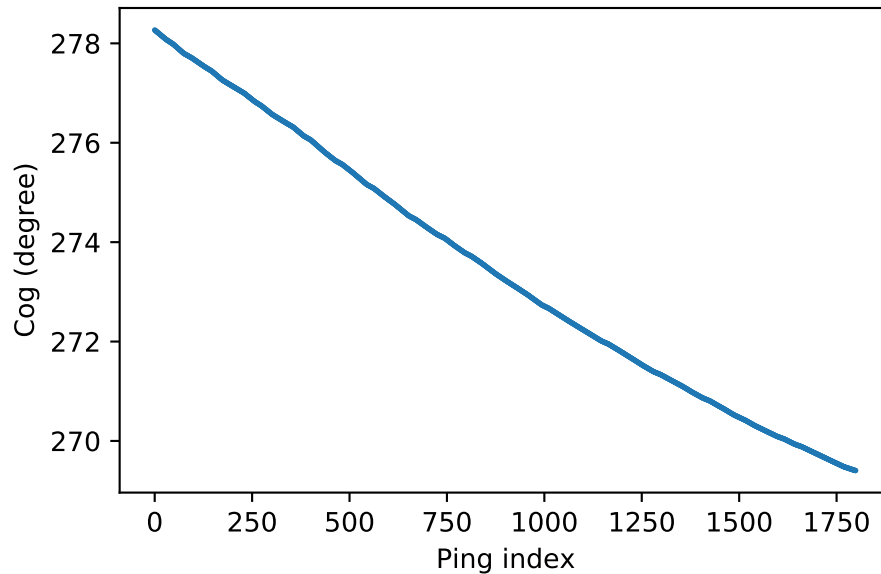
Raw survey line in geographic coordinates system



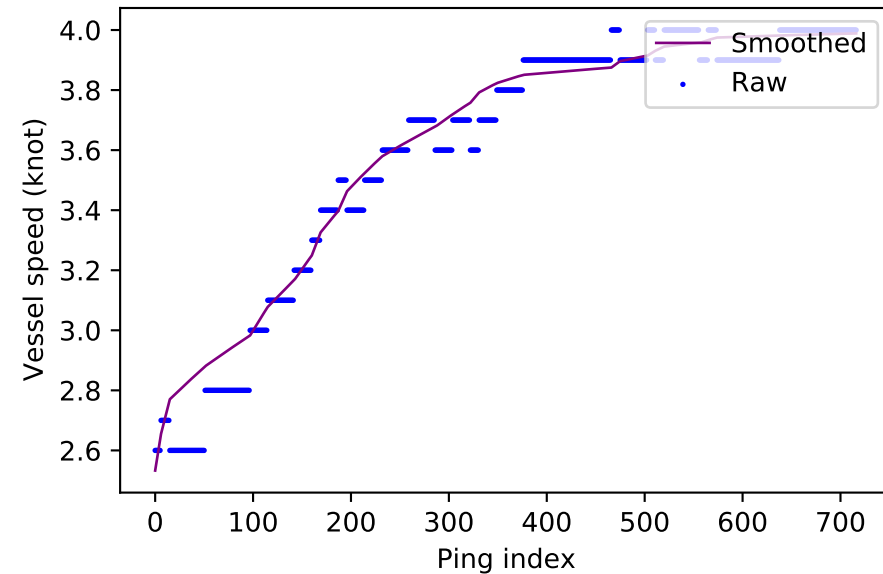
Survey line in projected coordinates system



Ping direction along survey line



Vessel speed along survey line



- The survey line is smoothed using a cubic spline curve with a smoothing factor of 80.0. The length of survey line is 149.8 m after smoothing.
- Cog (course over ground) is calculated from smoothed fish projected coordinates.
- Vessel speed is obtained from satellite navigation sensor and is smoothed using a cubic spline curve with a smoothing factor: 10.0.