

Dimension Reduction using PCA and SVD

Plan of Class

- Starting the machine Learning part of the course.
- Based on Linear Algebra.
- If your linear algebra is rusty, check out the pages on “Resources/Linear Algebra”
- This class will all be theory.
- Next class will be on doing PCA in Spark.
- HW3 will open on friday, be due the following friday.

Dimensionality reduction

Why reduce the number of features in a data set?

- ① It reduces storage and computation time.
- ② High-dimensional data often has a lot of redundancy.
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$28 \times 28 = 784$ pixels. A vector $\vec{x} \in \mathbb{R}^{784}$



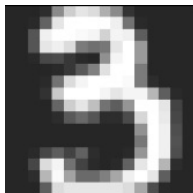
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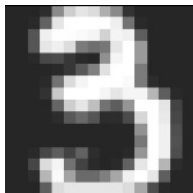
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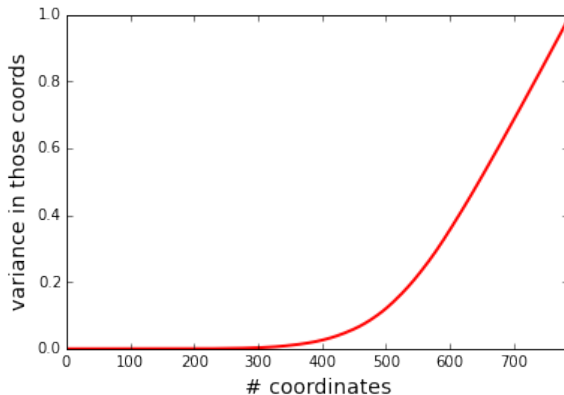
Those with lowest variance...

Eliminating low variance coordinates

Example: MNIST. What fraction of the total variance is contained in the 100 (or 200, or 300) coordinates with lowest variance?

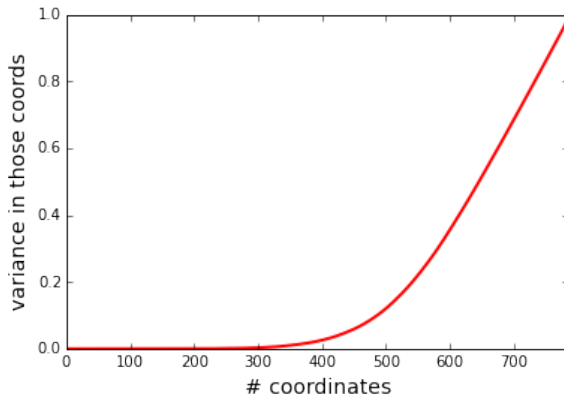
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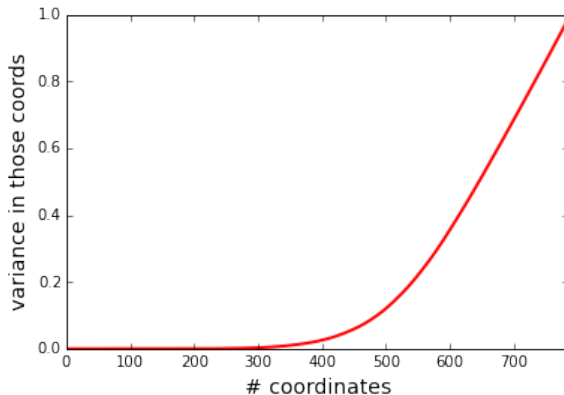
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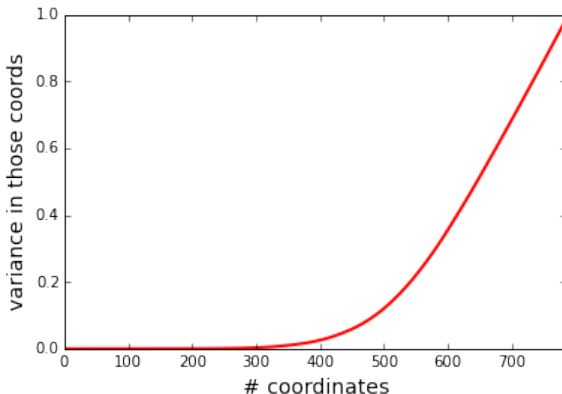


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Can we eliminate more?

Yes! By using features that are **combinations** of pixels instead of single pixels.

Covariance (a quick review)

Suppose X has mean μ_X and Y has mean μ_Y .

- Covariance

$$\text{cov}(X, Y) = \mathbb{E}[(X - \mu_X)(Y - \mu_Y)] = \mathbb{E}[XY] - \mu_X\mu_Y$$

Maximized when $X = Y$, in which case it is $\text{var}(X)$.

In general, it is at most $\text{std}(X)\text{std}(Y)$.

Covariance: example 1

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-1	-1	1/3
-1	1	1/6
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$$\mu_X =$$

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In this case, X, Y are independent. Independent variables always have zero covariance.

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In this case, X and Y are negatively correlated.

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approximate a digit from class j as the class average plus k corrections:

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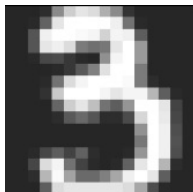


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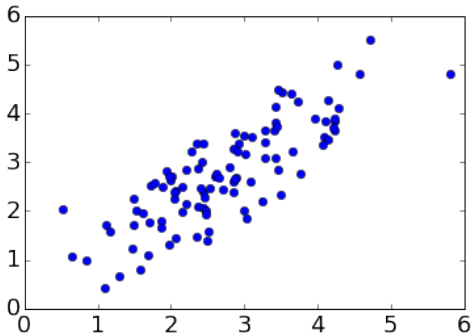
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- $\mu_j \in \mathbb{R}^{784}$ class mean vector
- $\vec{v}_{j,1}, \dots, \vec{v}_{j,k}$ are the **principal directions**.

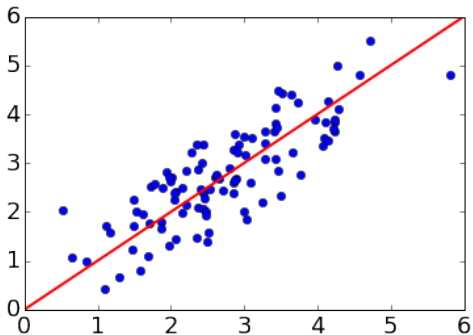
The effect of correlation

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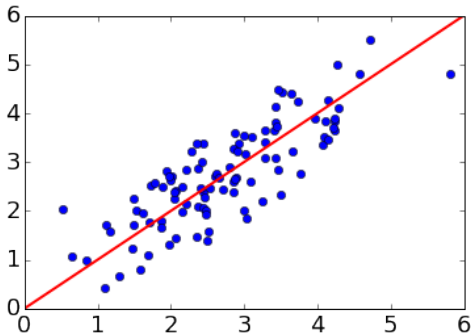
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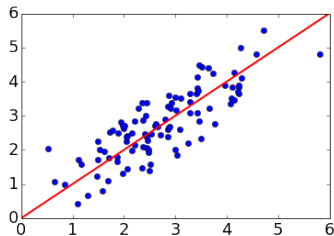
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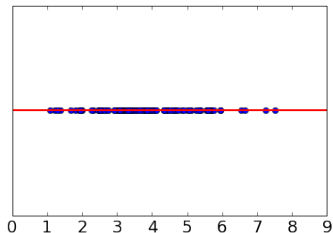


This is the **direction of maximum variance**.

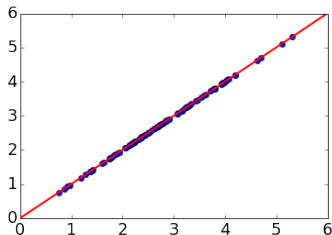
Two types of projection



Projection onto \mathbb{R} :

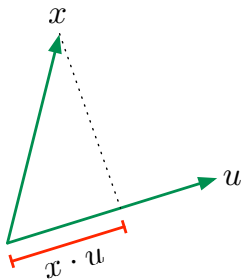


Projection onto a 1-d line in \mathbb{R}^2 :



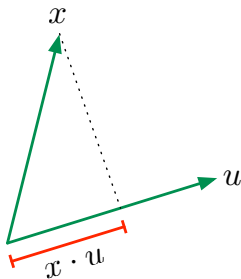
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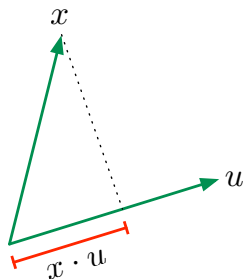


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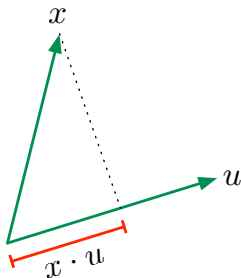
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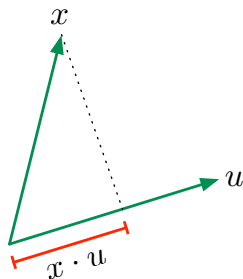
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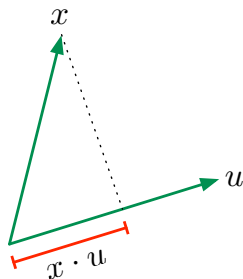
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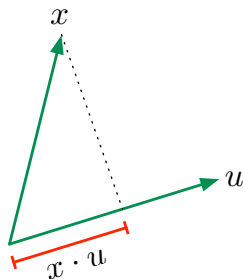
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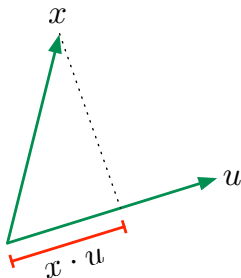
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A notation that allows a simple representation of multiple projections

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A vector $\vec{v} \in \mathbb{R}^d$ can be represented, in matrix notation, as

- A column vector:

$$v = \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_d \end{pmatrix}$$

- A row vector:

$$v^T = (v_1 \quad v_2 \quad \cdots \quad v_d)$$

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While a **column** vector followed by a **row** vector represents an **outer** product which is a matrix:

$$\begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix} (u_1 \quad u_2 \quad \cdots \quad u_m) = \begin{pmatrix} u_1 v_1 & u_2 v_1 & \cdots & u_m v_1 \\ \vdots & \ddots & \ddots & \vdots \\ u_1 v_n & u_2 v_n & \cdots & u_m v_n \end{pmatrix}$$

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$$(x \cdot u_1, x \cdot u_2, \dots, x \cdot u_k) = \underbrace{\begin{pmatrix} \longleftrightarrow u_1 \longrightarrow \\ \longleftrightarrow u_2 \longrightarrow \\ \vdots \\ \longleftrightarrow u_k \longrightarrow \end{pmatrix}}_{\text{call this } U^T} \begin{pmatrix} \updownarrow \\ x \\ \updownarrow \end{pmatrix}$$

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As a p -dimensional vector, the projection is

$$(x \cdot u_1)u_1 + (x \cdot u_2)u_2 + \dots + (x \cdot u_k)u_k = UU^T x.$$

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Then write $U^T = \begin{pmatrix} \overleftarrow{\hspace{1.5cm}} u_1 \overrightarrow{\hspace{1.5cm}} \\ \overleftarrow{\hspace{1.5cm}} u_2 \overrightarrow{\hspace{1.5cm}} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$

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Take vectors $u_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$, $u_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$ (notice: orthonormal)

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But we'll generally project along non-coordinate directions.

The best single direction

Suppose we need to map our data $x \in \mathbb{R}^P$ into just **one** dimension:

$$x \mapsto u \cdot x \quad \text{for some unit direction } u \in \mathbb{R}^P$$

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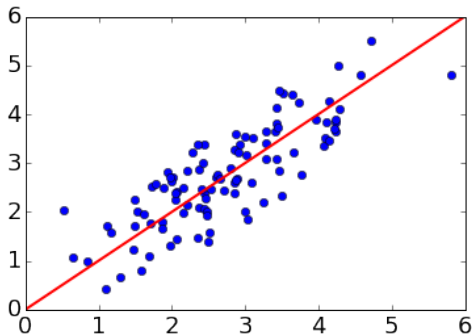
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Another theorem: $u^T \Sigma u$ is maximized by setting u to the first **eigenvector** of Σ . The maximum value is the corresponding **eigenvalue**.

Best single direction: example



This direction is the **first eigenvector** of the 2×2 covariance matrix of the data.

The best k -dimensional projection

Let Σ be the $p \times p$ covariance matrix of X . Its **eigendecomposition** can be computed in $O(p^3)$ time and consists of:

- real **eigenvalues** $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_p$
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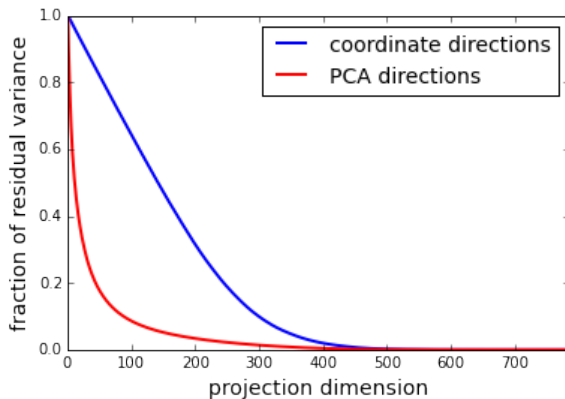
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Projecting the data in this way is **principal component analysis (PCA)**.

Example: MNIST

Contrast coordinate projections with PCA:



MNIST: image reconstruction



Reconstruct this original image from its PCA projection to k dimensions.

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A: Image x is reconstructed as $UU^T x$, where U is a $p \times k$ matrix whose columns are the top k eigenvectors of Σ .

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$$\underbrace{\begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 10 \end{pmatrix}}_M \underbrace{\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}}_x = \underbrace{\begin{pmatrix} 2x_1 \\ -x_2 \\ 10x_3 \end{pmatrix}}_{Mx}$$

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- 5 What about more general matrices that are symmetric but not necessarily diagonal? They also just scale coordinates separately, but in a **different coordinate system**.

Eigenvalue and eigenvector: definition

Let M be a $p \times p$ matrix.

We say $u \in \mathbb{R}^p$ is an **eigenvector** if M maps u onto the same direction, that is,

$$Mu = \lambda u$$

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Notice that these eigenvectors form an orthonormal basis.

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Theorem. Let M be any real symmetric $p \times p$ matrix. Then M has

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Example: consider the matrix

$$M = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}$$

It has eigenvectors

$$u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad u_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

and corresponding eigenvalues $\lambda_1 = 4$ and $\lambda_2 = 2$. (Check)

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Thus $Mx = U\Lambda U^T x$, which can be interpreted as follows:

- U^T rewrites x in the $\{u_i\}$ coordinate system
- Λ is a simple coordinate scaling in that basis
- U then sends the scaled vector back into the usual coordinate basis

Spectral decomposition: example

Apply spectral decomposition to the matrix M we saw earlier:

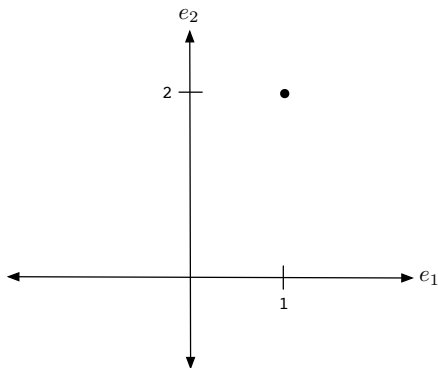
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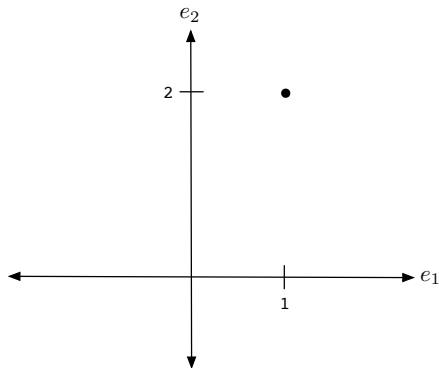


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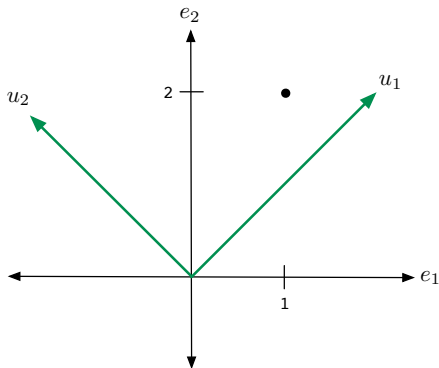


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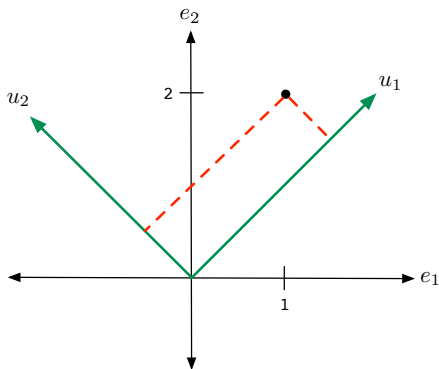


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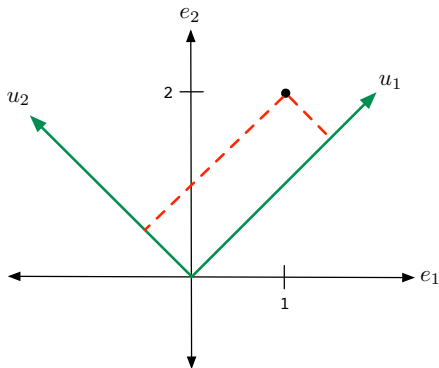


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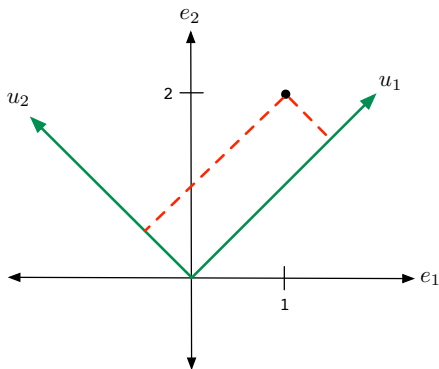


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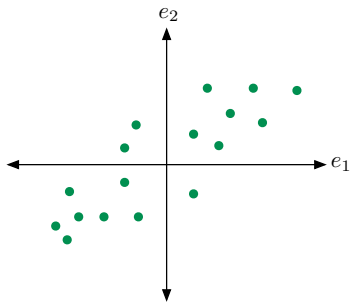
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Principal component analysis: recap

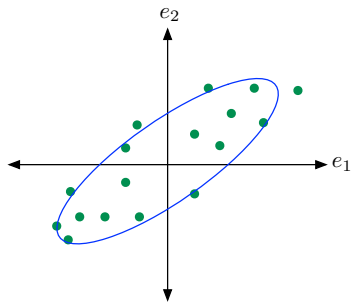
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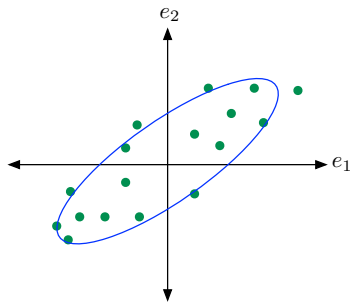
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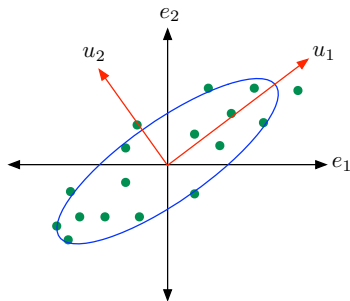
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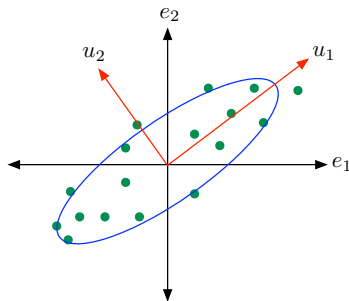
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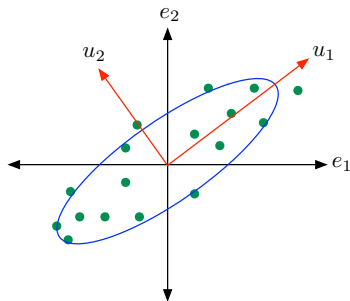
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What is the covariance of the projected data?

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- Allport and Odbert (1936): sat down with the English dictionary and extracted all terms that could be used to distinguish one person's behavior from another's. Roughly 18000 words, of which 4500 could be described as personality traits.

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- Allport and Odbert (1936): sat down with the English dictionary and extracted all terms that could be used to distinguish one person's behavior from another's. Roughly 18000 words, of which 4500 could be described as personality traits.
- Step: group these words into (approximate) synonyms. This is done by manual clustering. e.g. Norman (1967):

Spirit	Jolly, merry, witty, lively, peppy
Talkativeness	Talkative, articulate, verbose, gossipy
Sociability	Companionable, social, outgoing
Spontaneity	Impulsive, carefree, playful, zany
Boisterousness	Mischievous, rowdy, loud, prankish
Adventure	Brave, venturesome, fearless, reckless
Energy	Active, assertive, dominant, energetic
Conceit	Boastful, conceited, egotistical
Vanity	Affected, vain, chic, dapper, jaunty
Indiscretion	Nosey, snoopy, indiscreet, meddlesome
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- Data collection: Ask a variety of subjects to what extent each of these words describes them.

Personality assessment: the data

Matrix of data (1 = strongly disagree, 5 = strongly agree)

	shy	merry	tense	boastful	forgiving	quiet
Person 1	4	1	1	2	5	5
Person 2	1	4	4	5	2	1
Person 3	2	4	5	4	2	2
		:				

How to extract important directions?

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- Other ideas: factor analysis, independent component analysis, ...

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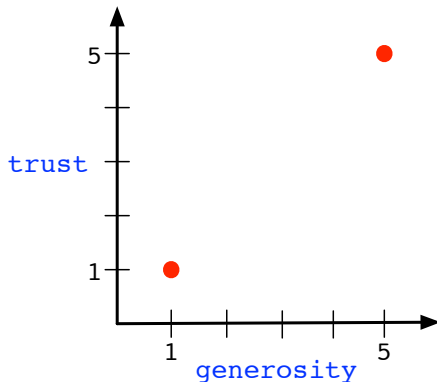
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Many of these yield similar results

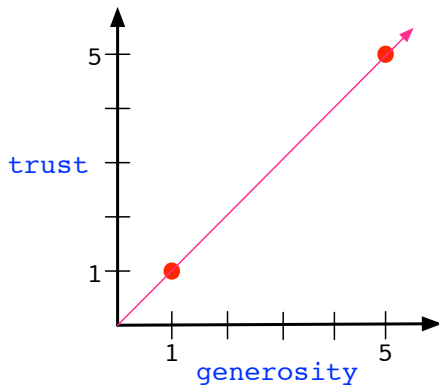
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Example: suppose two traits (generosity, trust) are highly correlated, to the point where each person either answers “1” to both or “5” to both.



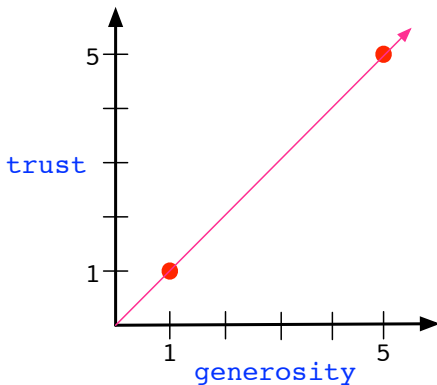
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This single PCA dimension entirely accounts for the two traits.

The “Big Five” taxonomy

[illegible]

The “Big Five” taxonomy

Extraversion		Agreeableness		Conscientiousness		Neuroticism		Openness/Intellect	
Low	High	Low	High	Low	High	Low	High	Low	High
-.83 Quiet	.85 Talkative	-.52 Fault-finding	.87 Sympathetic	-.58 Careless	.80 Organized	-.39 Stable*	.73 Tense	-.74 Commonplace	.76 Wide interests
-.80 Reserved	.83 Assertive	-.48 Cold	.85 Kind	-.53 Disorderly	.80 Thorough	-.35 Calm*	.72 Anxious	-.73 Narrow interests	.76 Imaginative
-.75 Shy	.82 Active	-.45 Unfriendly	.85 Appreciative	-.50 Frivolous	.78 Placid	-.21 Contented*	.72 Nervous	-.67 Simple	.72 Intelligent
-.71 Silent	.82 Energetic	-.45 Quarrelsome	.84 Affectionate	-.49 Irresponsible	.78 Efficient	.14 Unemotional*	.71 Moody	-.55 Shallow	.73 Original
-.67 Withdrawn	.82 Outgoing	-.45 Hard-hearted	.84 Soft-hearted	-.40 Slipshod	.73 Responsible		.71 Worrying	-.47 Unintelligent	.68 Insightful
-.66 Retiring	.80 Outspoken	-.38 Unkind	.82 Warm	-.39 Undependable	.72 Reliable		.68 Touchy		.64 Curious
	.79 Dominant	-.33 Cruel	.81 Generous	-.37 Forgetful	.70 Dependable		.64 Fearful		.59 Sophisticated
	.73 Forceful	-.31 Stern*	.78 Trusting		.68 Conscientious		.63 High-strung		.59 Artistic
	.73 Enthusiastic	-.28 Thankless	.77 Helpful		.66 Precise		.63 Self-pitying		.59 Clever
	.68 Show-off	-.24 Stingy*	.77 Forgiving		.66 Practical		.60 Temperamental		.58 Inventive
	.68 Sociable		.74 Pleasant		.65 Deliberate		.59 Unstable		.56 Sharp-witted
	.64 Spunky		.73 Good-natured		.46 Painstaking		.58 Self-punishing		.55 Ingenious
	.64 Adventurous		.73 Friendly		.26 Cautious*		.54 Despondent		.45 Witty*
	.62 Noisy		.72 Cooperative				.51 Emotional		.45 Resourceful*
	.58 Bossy		.67 Gentle						.37 Wise
			.66 Unselfish						.33 Logical*
			.56 Praising						.29 Civilized*
			.51 Sensitive						.22 Foresighted*
									.21 Polished*
									.20 Dignified*

Many applications, such as online match-making.

Singular value decomposition (SVD)

For **symmetric** matrices, such as covariance matrices, we have seen:

- Results about existence of eigenvalues and eigenvectors
- The fact that the eigenvectors form an alternative basis
- The resulting spectral decomposition, which is used in PCA

But what about arbitrary matrices $M \in \mathbb{R}^{p \times q}$?

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But what about arbitrary matrices $M \in \mathbb{R}^{p \times q}$?

Any $p \times q$ matrix (say $p \leq q$) has a **singular value decomposition**:

$$M = \underbrace{\begin{pmatrix} \uparrow & & \uparrow \\ u_1 & \cdots & u_p \\ \downarrow & & \downarrow \end{pmatrix}}_{p \times p \text{ matrix } U} \underbrace{\begin{pmatrix} \sigma_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \sigma_p \end{pmatrix}}_{p \times p \text{ matrix } \Lambda} \underbrace{\begin{pmatrix} \longleftarrow v_1 \longrightarrow \\ \vdots \\ \longleftarrow v_p \longrightarrow \end{pmatrix}}_{p \times q \text{ matrix } V^T}$$

- u_1, \dots, u_p are orthonormal vectors in \mathbb{R}^p
- v_1, \dots, v_p are orthonormal vectors in \mathbb{R}^q
- $\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_p$ are **singular values**

Matrix approximation

We can **factor** any $p \times q$ matrix as $M = UW^T$:

$$\begin{aligned} M &= \begin{pmatrix} \uparrow & & \uparrow \\ u_1 & \cdots & u_p \\ \downarrow & & \downarrow \end{pmatrix} \begin{pmatrix} \sigma_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \sigma_p \end{pmatrix} \begin{pmatrix} \longleftarrow v_1 \longrightarrow \\ \vdots \\ \longleftarrow v_p \longrightarrow \end{pmatrix} \\ &= \underbrace{\begin{pmatrix} \uparrow & & \uparrow \\ u_1 & \cdots & u_p \\ \downarrow & & \downarrow \end{pmatrix}}_{p \times p \text{ matrix } U} \underbrace{\begin{pmatrix} \longleftarrow \sigma_1 v_1 \longrightarrow \\ \vdots \\ \longleftarrow \sigma_p v_p \longrightarrow \end{pmatrix}}_{p \times q \text{ matrix } W^T} \end{aligned}$$

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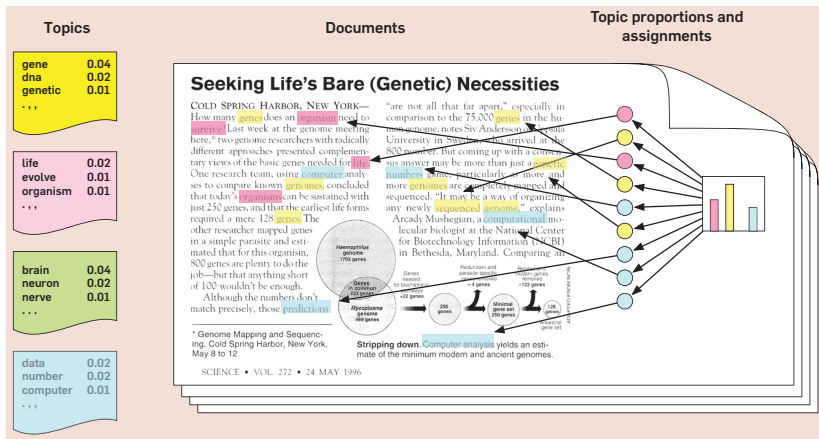
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A concise approximation to M : just take the first k columns of U and the first k rows of W^T , for $k < p$:

$$\hat{M} = \underbrace{\begin{pmatrix} \uparrow & & \uparrow \\ u_1 & \cdots & u_k \\ \downarrow & & \downarrow \end{pmatrix}}_{p \times k} \underbrace{\begin{pmatrix} \longleftarrow \sigma_1 v_1 \longrightarrow \\ \vdots \\ \longleftarrow \sigma_k v_k \longrightarrow \end{pmatrix}}_{k \times q}$$

Example: topic modeling

Blei (2012):



Latent semantic indexing (LSI)

Given a large corpus of n documents:

- Fix a vocabulary, say of V words.
- Bag-of-words representation for documents: each document becomes a vector of length V , with one coordinate per word.
- The corpus is an $n \times V$ matrix, one row per document.

	<i>cat</i>	<i>dog</i>	<i>house</i>	<i>boat</i>	<i>garden</i>	<i>...</i>
Doc 1	4	1	1	0	2	
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Let's find a concise approximation to this matrix M .

Latent semantic indexing, cont'd

Use SVD to get an approximation to M : for small k ,

$$\underbrace{\begin{pmatrix} \leftarrow \text{doc 1} \rightarrow \\ \leftarrow \text{doc 2} \rightarrow \\ \leftarrow \text{doc 3} \rightarrow \\ \vdots \\ \leftarrow \text{doc } n \rightarrow \end{pmatrix}}_{n \times V \text{ matrix } M} \approx \underbrace{\begin{pmatrix} \leftarrow \theta_1 \rightarrow \\ \leftarrow \theta_2 \rightarrow \\ \leftarrow \theta_3 \rightarrow \\ \vdots \\ \leftarrow \theta_n \rightarrow \end{pmatrix}}_{n \times k \text{ matrix } \Theta} \underbrace{\begin{pmatrix} \leftarrow \psi_1 \rightarrow \\ \vdots \\ \leftarrow \psi_k \rightarrow \end{pmatrix}}_{k \times V \text{ matrix } \Psi}$$

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Think of this as a *topic model* with k topics.

- ψ_j is a vector of length V describing topic j : coefficient ψ_{jw} is large if word w appears often in that topic.
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Document i originally represented by i th row of M , a vector in \mathbb{R}^V .
Can instead use $\theta_i \in \mathbb{R}^k$, a more concise “semantic” representation.

The rank of a matrix

Suppose we want to approximate a matrix M by a simpler matrix \hat{M} .
What is a suitable notion of “simple”?

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We can get \hat{M} directly from the singular value decomposition of M .

Low-rank approximation

Recall: Singular value decomposition of $p \times q$ matrix M (with $p \leq q$):

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The **best rank- k approximation** to M , for any $k \leq p$, is then

$$\hat{M} = \underbrace{\begin{pmatrix} \uparrow & & \uparrow \\ u_1 & \cdots & u_k \\ \downarrow & & \downarrow \end{pmatrix}}_{p \times k} \underbrace{\begin{pmatrix} \sigma_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \sigma_k \end{pmatrix}}_{k \times k} \underbrace{\begin{pmatrix} \longleftarrow v_1 \longrightarrow \\ \vdots \\ \longleftarrow v_k \longrightarrow \end{pmatrix}}_{k \times q}$$

Example: Collaborative filtering

Details and images from Koren, Bell, Volinsky (2009).

Recommender systems: matching customers with products.

- Given: data on prior purchases/interests of users
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Prototypical example: Netflix.

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- Model dependencies between different products, and between different users.
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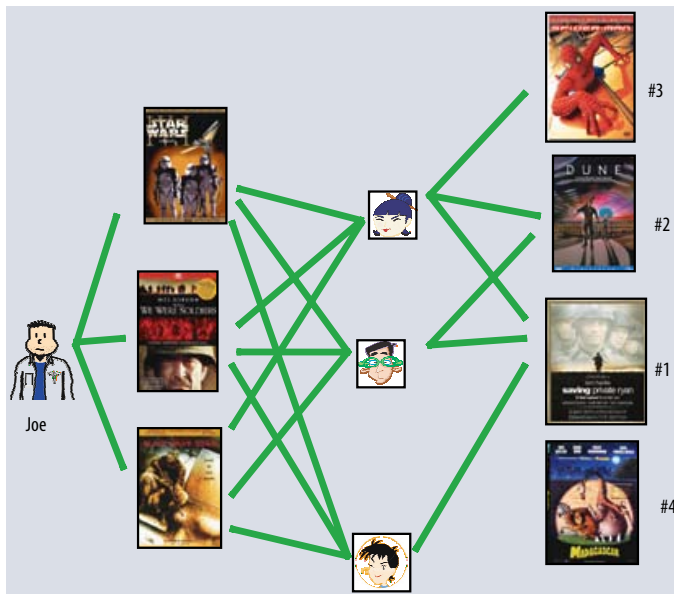
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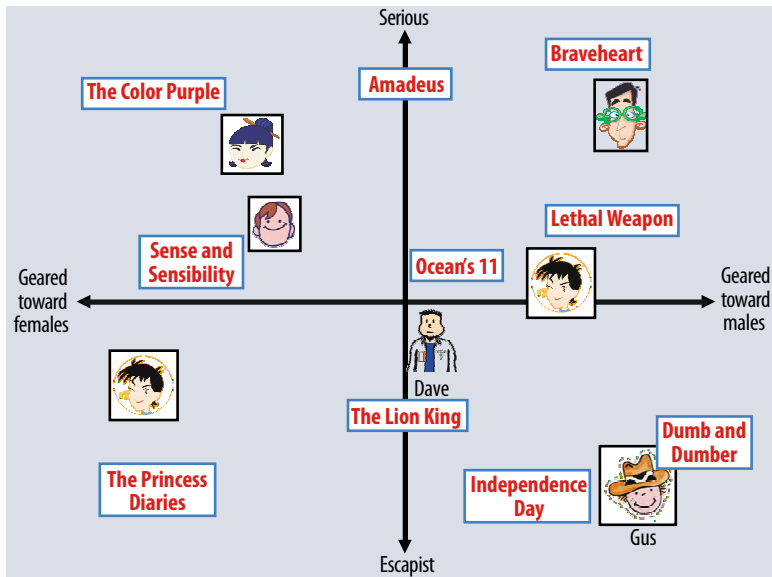
Two strategies for collaborative filtering:

- Neighborhood methods
- Latent factor methods

Neighborhood methods



Latent factor methods



The matrix factorization approach

User ratings are assembled in a large matrix M :

	<i>Star Wars</i>	<i>Matrix</i>	<i>Casablanca</i>	<i>Camelot</i>	<i>Godfather</i>	...
User 1	5	5	2	0	0	
User 2	0	0	3	4	5	
User 3	0	0	5	0	0	
		⋮				

- Not rated = 0, otherwise scores 1-5.
- For n users and p movies, this has size $n \times p$.
- Most of the entries are unavailable, and we'd like to predict these.

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Idea: Find the best low-rank approximation of M , and use it to fill in the missing entries.

User and movie factors

Best rank- k approximation is of the form $M \approx UW^T$:

$$\underbrace{\begin{pmatrix} \leftarrow \text{user 1} \rightarrow \\ \leftarrow \text{user 2} \rightarrow \\ \leftarrow \text{user 3} \rightarrow \\ \vdots \\ \leftarrow \text{user } n \rightarrow \end{pmatrix}}_{n \times p \text{ matrix } M} \approx \underbrace{\begin{pmatrix} \leftarrow u_1 \rightarrow \\ \leftarrow u_2 \rightarrow \\ \leftarrow u_3 \rightarrow \\ \vdots \\ \leftarrow u_n \rightarrow \end{pmatrix}}_{n \times k \text{ matrix } U} \underbrace{\begin{pmatrix} \uparrow w_1 & \uparrow w_2 & \cdots & \uparrow w_p \\ \downarrow & \downarrow & & \downarrow \end{pmatrix}}_{k \times p \text{ matrix } W^T}$$

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This “latent” representation embeds users and movies within the same k -dimensional space:

- Represent i th user by $u_i \in \mathbb{R}^k$
- Represent j th movie by $w_j \in \mathbb{R}^k$

Top two Netflix factors

