#### **Prediction and Crossvalidation**

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Computational Methods in Statistics and Data Science (Stats 406)

### **Cross Validation**

#### **Prediction**

Suppose we have a sample of the form

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Goal: predict  $\hat{Y}$  at certain X

- X may be cheap/easy to sample, but Y is expensive/difficult
- Wish to get understanding of Y where we have not observed X

In many cases we will **condition on X** = x and **model**  $Y \mid x = x$  using some function f(x).

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#### **Examples**

- Using the mean or medians of the sample Y values (no predictors).
- Linear regression:  $f(x_1, x_2,...) = \hat{\beta}_0 + \hat{\beta}_1 x_1 + \hat{\beta}_2 x_2 + ...$
- Machine learning technique (support vector machines, deep learners, random forests)

#### **Predictions and Loss Functions**

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We'll come back to loss functions, but for now a concrete example is **squared error** loss:

$$I(f(\mathbf{x}^*), y \mid \mathbf{x}^*) = (y - f(\mathbf{x}^*))^2$$

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#### **Sources of Randomness**

Notice, *f* implicitly depends on the original sample:

$$f(\mathbf{x}^*) = f(\mathbf{x}^*, Y_1, \mathbf{X}_1, \dots, Y_n, \mathbf{X}_n)$$

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so  $I^*$  is a random quantity.

Additionally, if we are thinking about a new observation  $Y^* = Y \mid \mathbf{x}^*$ , then

$$I(f(\mathbf{x}^*), Y^*)$$

has two sources of randomness (the original sample and  $Y^*$ ).

### **Operating Characteristics**

As you might expect, we want to understand **operating characteristics** of loss functions. We could look at many things, but we'll focus on **expected loss**:

$$\mathsf{E}(I(f(\mathbf{x}^*), Y^*))$$

where the expectation is taken over the joint distribution of the original sample and a new observation (equiv.: by IID assumption, a sample of size n + 1).

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Notice: when using squared error loss this is similar but different than MSE:

$$\mathsf{E}\left((\hat{\theta}-\theta)^2\right)$$

because  $\theta$  is fixed.

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- Split the sample into training and test sets. Fit in one, predict in the other.

Want to note one way **not to compute**: use the sample:

$$\frac{1}{n}\sum_{i=1}^{n}I(f(\mathbf{x}_{i}),Y_{i})$$

Since f and Y are not independent we risk under estimating prediction error (overfitting).

### **Overfitting Example**

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We'll see some examples later in the semester of smoothing estimators  $\hat{\mu}(\mathbf{x})$  that are unbiased for the conditional mean:

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Consider the case of using squared error loss and a new observation  $Y^*$ . What is our (true) expected loss?

$$\mathsf{E}\left((\mathsf{Y}^* - \hat{\mu}(\mathbf{x}^*))^2\right) = \mathsf{E}\left(\mathsf{Y}^{*2}\right) - 2\mathsf{E}\left(\mathsf{Y}^*\hat{\mu}(\mathbf{x}^*)\right) + \mathsf{E}\left(\hat{\mu}(\mathbf{x}^*)^2\right)$$

$$\begin{split} \mathsf{E}\left((Y^* - \hat{\mu}(\mathbf{x}^*))^2\right) &= \mathsf{E}\left(Y^{*2}\right) - 2\mathsf{E}\left(Y^*\hat{\mu}(\mathbf{x}^*)\right) + \mathsf{E}\left(\hat{\mu}(\mathbf{x}^*)^2\right) \\ &= \mathsf{E}\left(Y^{*2}\right) - \mathsf{E}\left(Y^*\right)^2 + \mathsf{E}\left(Y^*\right)^2 + \\ &\quad \mathsf{E}\left(\hat{\mu}(\mathbf{x}^*)^2\right) - \mathsf{E}\left(\hat{\mu}(\mathbf{x}^*)\right)^2 + \mathsf{E}\left(\hat{\mu}(\mathbf{x}^*)\right)^2 - 2\mathsf{E}\left(Y^*\hat{\mu}(\mathbf{x}^*)\right) \end{split}$$

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What if we didn't have a new  $Y^*$  and just used the sample average squared error?

$$\frac{1}{n}\sum_{i=1}^n\left[\hat{\mu}(\mathbf{x}_i)-Y_i\right]^2$$

This is generally **not unbiased** for the true prediction error because the  $\hat{\mu}$  and  $Y_i$  are not independent and

$$\mathsf{E}(\hat{\mu}(\mathbf{x}_i)Y_i) \neq \mathsf{E}(\hat{\mu}(\mathbf{x}_i))\mathsf{E}(Y_i)$$

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Solution: find another sample that is independent of the original to make our prediction error estimate.

#### Leave-one-out prediction

Recall, the jackknife estimates bias by repeatedly dropping one observation.

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Idea: we could **predict** each  $X_j$  with  $T_j$  and **average over all** n. We call this "leave-one-out" (LOO) prediction.

#### **Example: Student academic test scores**



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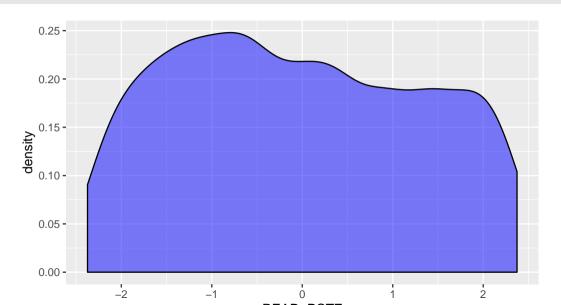
# Differences between Hispanic and non-Hispanic families in social capital and child development: First-year findings from an experimental study

Adam Gamoran a,\*, Ruth N. López Turleyb, Alyn Turnera, Rachel Fisha

<sup>a</sup> University of Wisconsin-Madison, , United States
<sup>b</sup> Rice University, , United States

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# Reading test scores



## Question: what would have less prediction error, the mean or mode?

Suppose we want to predict the reading score of a student not in the original study. What would have smaller error:

• The sample mean of the students in the study?

```
> mean(reading, na.rm = TRUE)
[1] -0.04814175
```

• The sample mode of a smoothed density?

```
> d <- density(reading)
> d$x[which.max(d$y)]
[1] -0.790038
```

## Using the mean

Observe that if we drop  $X_j$  from the mean, we get:

$$ar{X}_j = rac{1}{n-1} \sum_{i 
eq j} X_i = rac{1}{n-1} \left( \left[ \sum_{i=1}^n X_i 
ight] - X_j 
ight)$$

- > n <- length(reading)</pre>
- > barxj <-1 / (n 1) \* (sum(reading) reading)

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- > n <- length(reading)</pre>
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We will estimate our squared error with the average of  $(\bar{X}_j - X_j)^2$ .

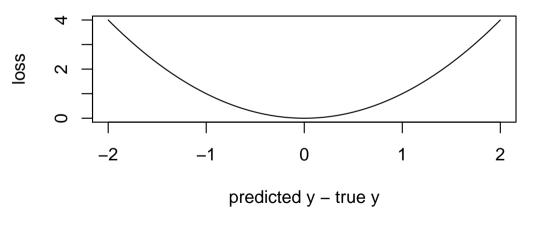
- > err\_mean <- barxj reading
- > (err2\_mean <- mean(err\_mean^2))</pre>
- [1] 1.800303

## Using the mode

```
> modej <- sapply(1:n, function(i) {</pre>
      d <- density(reading[-i])</pre>
      dx[which.max(dv)]
+ })
> err_mode <- modej - reading</pre>
> (err2_mode <- mean(err_mode^2))</pre>
[1] 2.349879
Which is larger than the predicted error using the mean:
> err2_mean / err2_mode
[1] 0.7661257
```

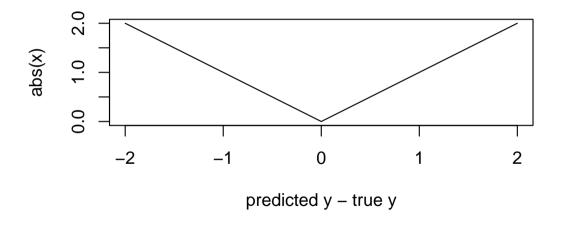
### More on loss functions

We have been using squared loss

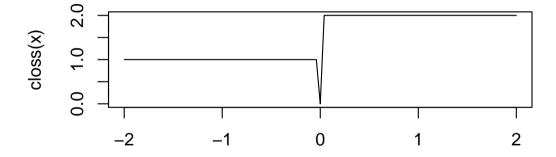


but we could consider other loss functions.

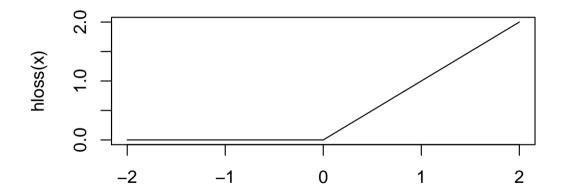
**Absolute loss:**  $|Y^* - f(\mathbf{x}^*)|$ 



Constant loss:  $a \times I(\hat{Y} > Y^*) + b \times I(\hat{Y} < Y^*)$ 



**Hinge loss:**  $max(0, \hat{Y} - Y^*)$ 



### **Different Loss, Different Conclusion**

```
> mean(err_mean^2) / mean(err_mode^2) # squared error
[1] 0.7661257
> mean(abs(err mean)) / mean(abs(err mode)) # absolute error
[1] 0.9217158
> mean(closs(err mean)) / mean(closs(err mode)) # constant loss
[1] 1.121518
> mean(hloss(err_mean)) / mean(hloss(err_mode)) # hinge loss
[1] 2.268704
```

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Best way: write down how costly mistakes are and deduce proper loss function.

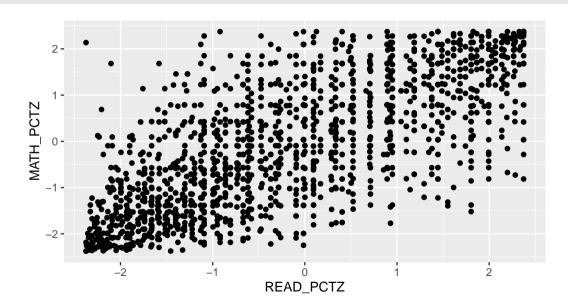
## Picking a loss function

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Best way: write down how costly mistakes are and deduce proper loss function.

More commonly, we use loss functions that are common to a discipline or industry. (Similar to picking  $\alpha=0.05$  or  $\alpha=0.001$ )

# **Predicting Math from Reading Scores**



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where Y is an outcome, X is a predictor, and R is a residual term.

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We often use ordinary least squares (OLS) to fit our model, which minimizes the within sample squared error:

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If the **residual terms are Normal**, then OLS minimizes prediction error, but what if errors aren't Normal?

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For this example, we'll generalize this idea by leaving out half of the sample and predicting on the other half.

We could just use a single split into a training set and a testing set.

We will repeat this process many times, cross validation.

# **Basic model fitting**

## **Cross validating**

```
> k < -1000
> n <- dim(read_math)[1]</pre>
> half <- round(n/2)
> err_lm <- replicate(k, {</pre>
+
      rand.order <- sample.int(n)</pre>
      train.idx <- rand.order[1:half]
      test.idx <- rand.order[(half + 1):n]
+
+
      mod <- lm(math ~ read, read math[train.idx, ])</pre>
+
      preds <- predict(mod, newdata = read_math[test.idx, ])</pre>
      read_math$math[test.idx] - preds
+
+ })
```

#### Alternative to OLS

Let's compare the error we get from prediction using OLS to that we would get if pick  $\beta_0$  and  $\beta_1$  to minimize absolute error (median regression):

$$\min_{\beta} \sum_{i=1}^{n} |y_i - (\beta_0 + \beta_1 x_i)|$$

#### Alternative to OLS

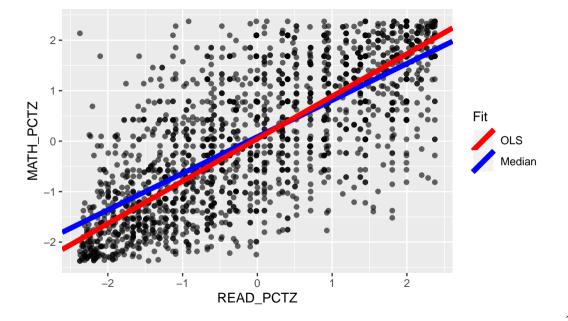
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The quantreg package provides a routine to find  $\beta_0$  and  $\beta_1$ :

- > library(quantreg)
- > mod\_rq <- rq(math ~ read, data = read\_math)</pre>
- > coef(mod\_rq)

```
(Intercept) read
0.04719007 0.84076874
```



```
> err_abs <- replicate(k, {</pre>
      rand.order <- sample.int(n)</pre>
+
      train.idx <- rand.order[1:half]
+
      test.idx <- rand.order[(half + 1):n]
+
      mod <- rq(math ~ read, data = read_math[train.idx, ]) # only different
+
      preds <- predict(mod, newdata = read_math[test.idx, ])</pre>
+
      read_math$math[test.idx] - preds
+
+ })
```

# Comparing OLS and median regression

```
> mean(err_lm^2) / mean(err_abs^2)
[1] 0.9712884
```

# Comparing OLS and median regression

```
> mean(err_lm^2) / mean(err_abs^2)
[1] 0.9712884
> mean(abs(err_lm)) / mean(abs(err_abs))
[1] 1.019969
```

## Other Cross Validation Uses: Picking a model

We've used cross validation for **estimating prediction error**. Other uses include selecting a model to fit:

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2$$
 vs.  $Y = \beta_3 + \beta_4 x_1$ 

The first model will always have smaller in-sample prediction error, but can overfit if  $x_2$  actually is not important.

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Also, using the same data set to pick a model as **perform inference** can lead to biased estimates, improper coverage rates, etc. **Post-selection inference** is a hot topic today, and many techniques boil down to cross-validation.

Many statistical methods have **tuning parameters**. For example the **LASSO shrinkage estimator**:

$$\min_{\beta} \sum_{i=1}^{n} (y_i - (\sum_{j=0}^{p} \beta_j x_{ji}))^2 + \lambda \sum_{j=1}^{n} |\beta_j|$$

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This is traded off the squared error using the tuning parameter  $\lambda$ . CV can be used to pick  $\lambda$ .

We'll see examples later, for example picking a "bandwidth" for density estimation.

## Summary

- Prediction guesses an unobserved  $Y^*$  based on observed  $\mathbf{x}^*$  based on a prediction function  $f(\mathbf{x}^*)$  which is created using a sample  $(Y_i, \mathbf{X}_i)$ .
- The quality of the prediction is given by loss function  $I(Y^*, f(x^*))$
- There are two sources of randomness, the original sample and the  $Y^*$ .
- Key operating characteristic: expected loss
- Loss functions encode costs of making mistakes in predictions.
- Estimating expected loss can be achieved using independent training and test sets
- Many training/test splits are called crossvalidation.