

Probability Density Estimation, Smoothed Mean Estimators

Mark M. Fredrickson (mfredric@umich.edu)

Computational Methods in Statistics and Data Science (Stats 406)

Probability Density Estimation

Setting

Suppose we have IID data with density f :

$$X_i \sim F, \quad F(x) = \int_{-\infty}^x f(t) dt$$

Goal: Estimate f .

Setting

Suppose we have IID data with density f :

$$X_i \sim F, \quad F(x) = \int_{-\infty}^x f(t) dt$$

Goal: Estimate f .

We've seen the ECDF:

$$\hat{F}_n(x) = \frac{1}{n} \sum_{i=1}^n I(X_i \leq x)$$

Setting

Suppose we have IID data with density f :

$$X_i \sim F, \quad F(x) = \int_{-\infty}^x f(t) dt$$

Goal: Estimate f .

We've seen the ECDF:

$$\hat{F}_n(x) = \frac{1}{n} \sum_{i=1}^n I(X_i \leq x)$$

The **empirical density function** is then a discrete probability mass function

$$\hat{f}_n(x) = \frac{1}{n} \sum_{i=1}^n I(X_i = x)$$

Smoothing

If we think X is a continuous random variable, the empirical density function seems unsatisfactory.

Smoothing

If we think X is a continuous random variable, the empirical density function seems unsatisfactory.

We will try to **smooth** the density function in some way so that $\hat{f}_n(x) \neq 0$ for x not observed in the sample.

Smoothing

If we think X is a continuous random variable, the empirical density function seems unsatisfactory.

We will try to **smooth** the density function in some way so that $\hat{f}_n(x) \neq 0$ for x not observed in the sample.

Key idea: if there are many observations X_i close to x , this implies $f(x)$ high (and vice-versa).

Smoothing

If we think X is a continuous random variable, the empirical density function seems unsatisfactory.

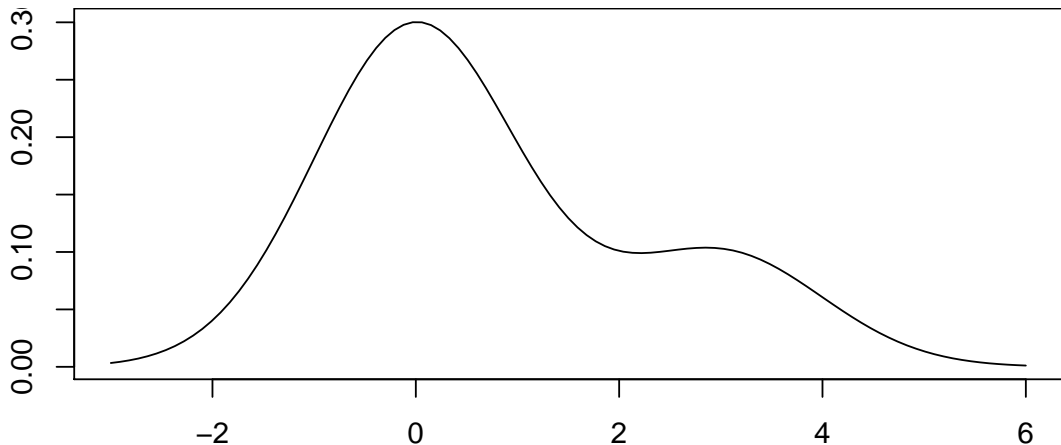
We will try to **smooth** the density function in some way so that $\hat{f}_n(x) \neq 0$ for x not observed in the sample.

Key idea: if there are many observations X_i close to x , this implies $f(x)$ high (and vice-versa).

We will start with the **univariate case**. Later we'll consider **bivariate extensions**. After that, we'll see smoothing for **conditional distributions**.

Simulated Data: Mixture of $N(0,1)$ and $N(3,1)$

```
> x <- rnorm(1000, mean = 3 * rbinom(100, size = 1, 0.25))
```



Histograms

A **histogram estimator** creates bins k bins

$$[t_j, t_{j+1}), \quad j = 1, \dots, k$$

and counts then number of observations X_i that fall in each bin:

$$V_j = \sum_{i=1}^n I(X_i \in [t_j, t_{j+1}))$$

Histograms

A **histogram estimator** creates bins k bins

$$[t_j, t_{j+1}), \quad j = 1, \dots, k$$

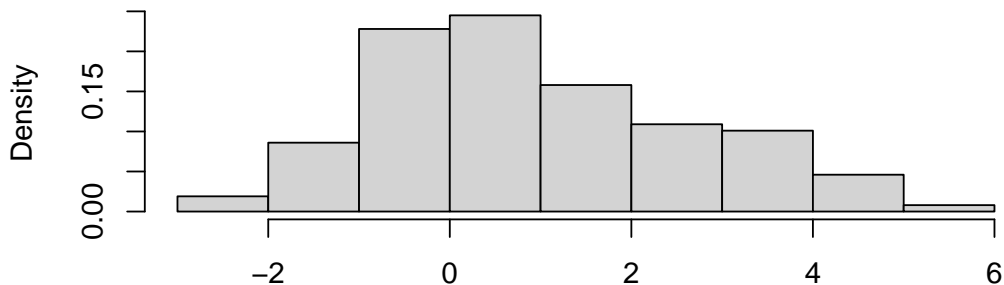
and counts then number of observations X_i that fall in each bin:

$$V_j = \sum_{i=1}^n I(X_i \in [t_j, t_{j+1}))$$

Then an estimator of the density at point x is:

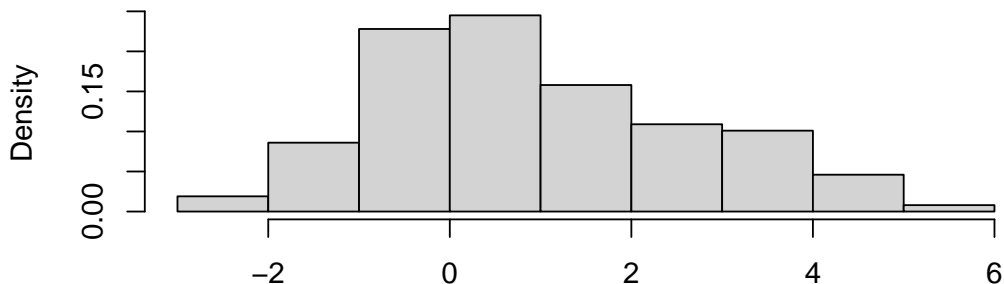
$$\hat{f}(x) = \frac{1}{n} \sum_{j=1}^k \frac{V_j}{t_{j+1} - t_j} I(x \in [t_j, t_{j+1}))$$

Histogram, further notes



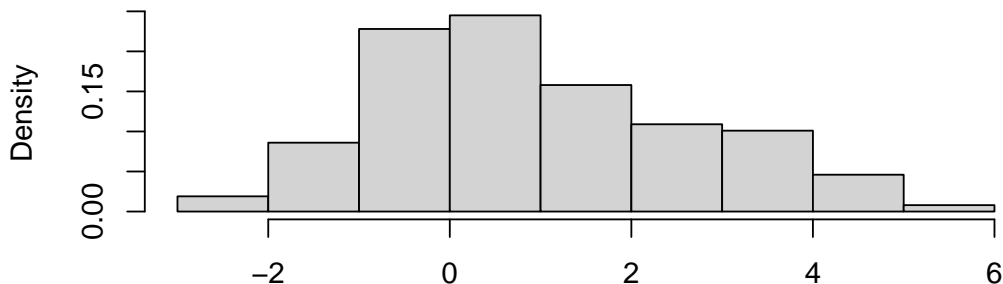
- $\hat{f}(x)$ is **piece-wise constant** (i.e., the same for all x in the same bin)

Histogram, further notes



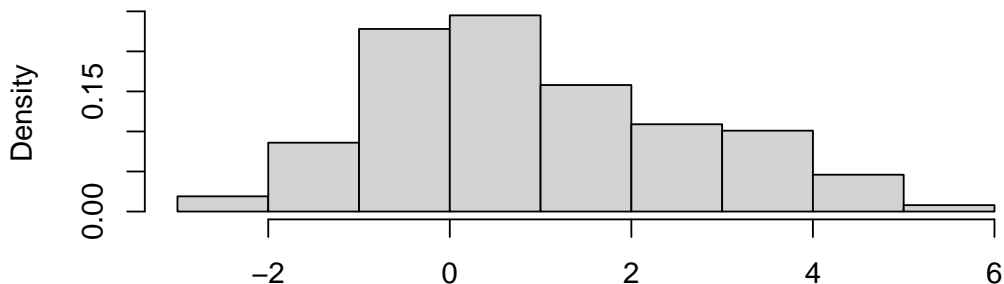
- $\hat{f}(x)$ is **piece-wise constant** (i.e., the same for all x in the same bin)
- We usually make all bins have the same width $h = t_{j+1} - t_j$

Histogram, further notes



- $\hat{f}(x)$ is **piece-wise constant** (i.e., the same for all x in the same bin)
- We usually make all bins have the same width $h = t_{j+1} - t_j$
- There is a tradeoff between smoothness (large h) and precision (small h).

Histogram, further notes



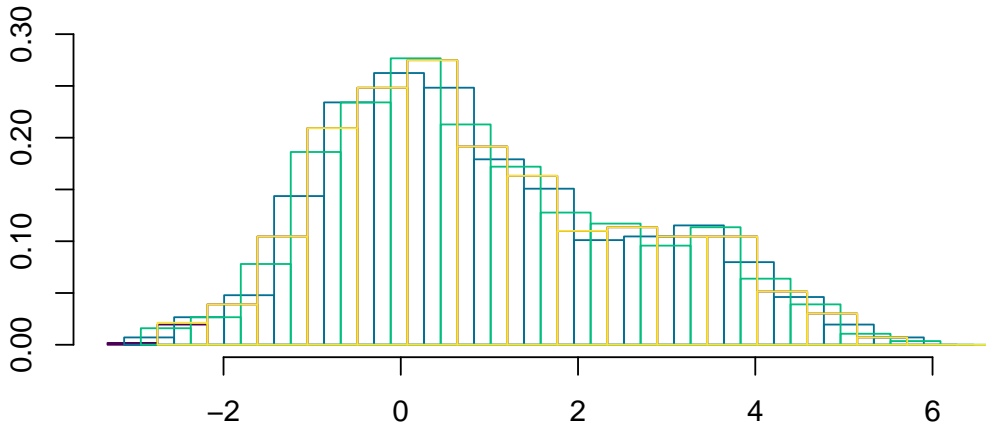
- $\hat{f}(x)$ is **piece-wise constant** (i.e., the same for all x in the same bin)
- We usually make all bins have the same width $h = t_{j+1} - t_j$
- There is a tradeoff between smoothness (large h) and precision (small h).
- There are several options for setting the bin width and locations (see Rizzo, chapter 10).

Multiple Histograms

If all bins have width h , there is only one “parameter” for the histogram: **where the bins are centered**.

Multiple Histograms

If all bins have width h , there is only one “parameter” for the histogram: **where the bins are centered**.



Average Shifted Histogram

Rather than estimate f with a single histogram, we can **average over m histograms**:

$$f_{\text{ASH}}(x) = \frac{1}{m} \sum_{j=1}^m \hat{f}_j(x)$$

where \hat{f}_j is a histogram with bin size h start at $t^{(j)} = t_0 + h/m$.

Average Shifted Histogram

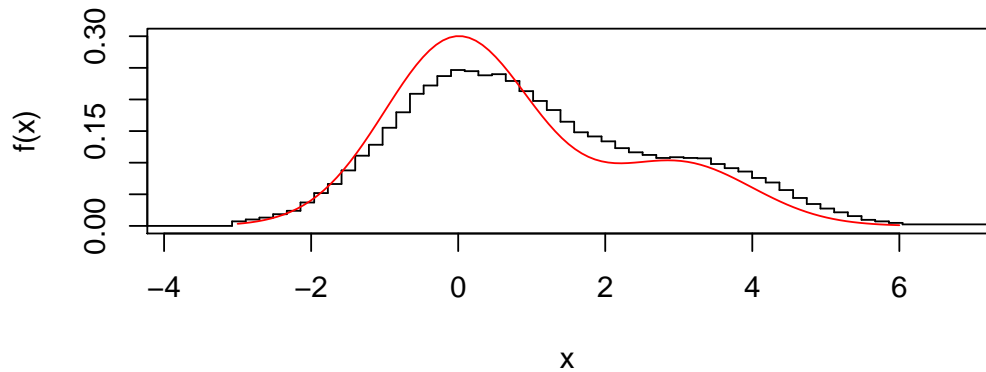
Rather than estimate f with a single histogram, we can **average over m histograms**:

$$f_{\text{ASH}}(x) = \frac{1}{m} \sum_{j=1}^m \hat{f}_j(x)$$

where \hat{f}_j is a histogram with bin size h start at $t^{(j)} = t_0 + h/m$.

```
> library(ash)
```

```
> ash_x <- ash1(bin1(x), 5, kopt = c(0,0))
```



Taking $m \rightarrow \infty$

As we **increase** m (number of histograms in ASH) the approximation will get **more smooth**. What happens when $m \rightarrow \infty$?

Taking $m \rightarrow \infty$

As we **increase** m (number of histograms in ASH) the approximation will get **more smooth**. What happens when $m \rightarrow \infty$?

Suppose all of the data is within $[-1, 1]$ and we want to estimate $f(0)$.

Taking $m \rightarrow \infty$

As we **increase** m (number of histograms in ASH) the approximation will get **more smooth**. What happens when $m \rightarrow \infty$?

Suppose all of the data is within $[-1, 1]$ and we want to estimate $f(0)$.

We will use histograms with **bin width one** and we will **discard any bins that exceed $[-1, 1]$** . As we slide the histograms across, what proportion line up one point?

Taking $m \rightarrow \infty$

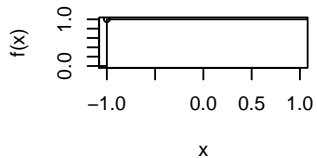
As we **increase** m (number of histograms in ASH) the approximation will get **more smooth**. What happens when $m \rightarrow \infty$?

Suppose all of the data is within $[-1, 1]$ and we want to estimate $f(0)$.

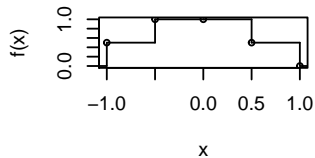
We will use histograms with **bin width one** and we will **discard any bins that exceed $[-1, 1]$** . As we slide the histograms across, what proportion line up one point?

Another way of saying this is, if we keep averaging at a single point as $m \rightarrow \infty$, what proportion of neighbors within $+1/-1$ are included?

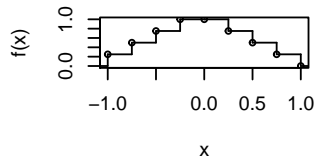
m = 1



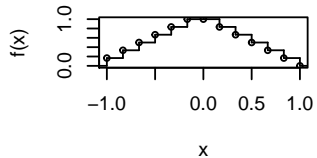
m = 3



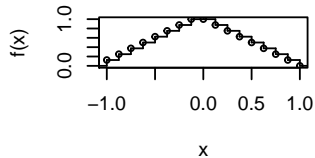
m = 5



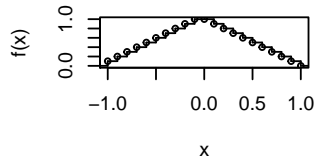
m = 7



m = 9



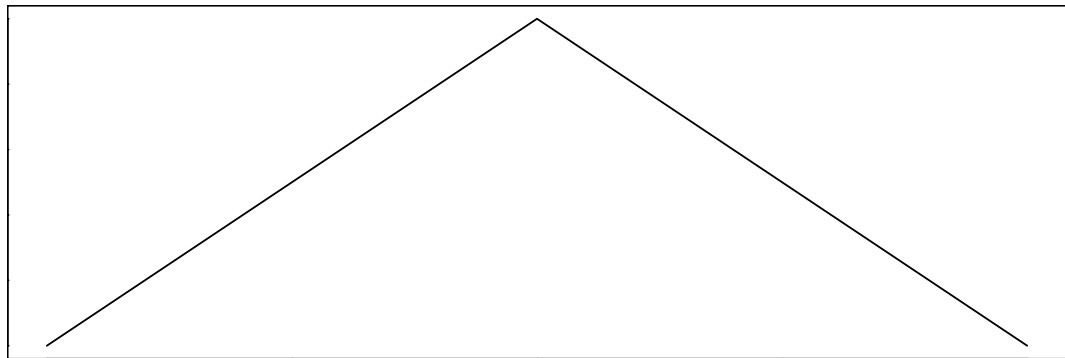
m = 11



Triangular Distribution

As $m \rightarrow \infty$, the ASH becomes

$$\hat{f}(x) = \frac{1}{nh} \sum_{i=1}^n I(X_i \in [x - h, x + h]) \left(1 - \frac{|x - X_i|}{h}\right)$$



Density objects in R

R has a built in function to perform **density estimation**:

```
> fx <- density(x, kernel = "triangular")
```

Density objects in R

R has a built in function to perform **density estimation**:

```
> fx <- density(x, kernel = "triangular")
```

The object is list of two vectors: x values from the sample and $\hat{f}(x)$ estimates

```
> fx$x[1:5]
```

```
[1] -3.905 -3.884 -3.863 -3.842 -3.820
```

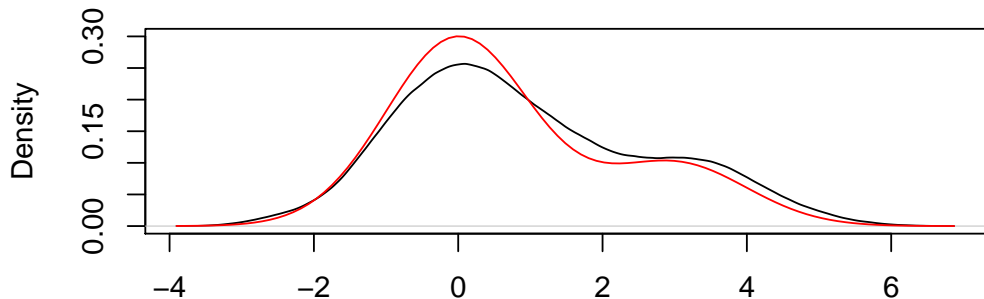
```
> fx$y[1:5]
```

```
[1] 9.544e-19 2.537e-18 8.760e-18 1.487e-17 1.626e-17
```

Plotting in Base R

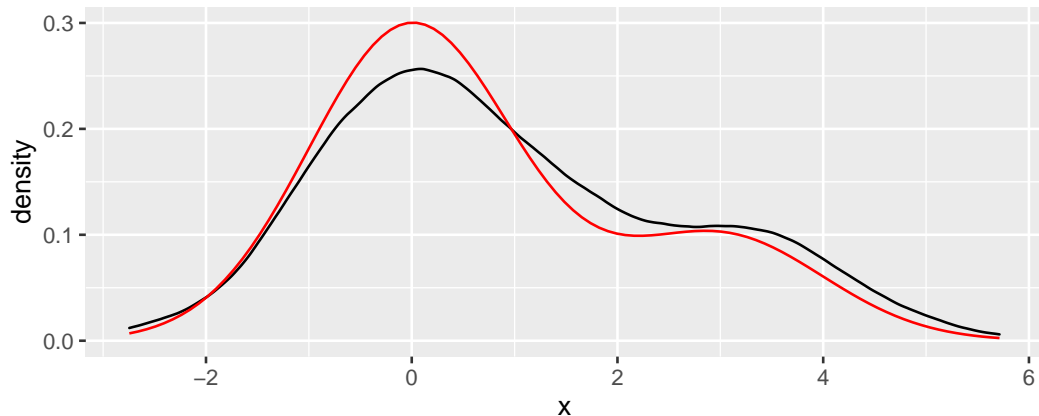
```
> plot(fx, ylim = c(0, 0.3))  
> truef <- function(x) { 0.75 * dnorm(x) + 0.25 * dnorm(x, mean = 3) }  
> curve(truef(x), add = TRUE, col = "red")
```

density.default(x = x, kernel = "triangular")



Plotting in ggplot

```
> ggplot(data.frame(x), aes(x = x)) + geom_density(kernel = 'triangular') +  
+   stat_function(fun = truef, col = 'red')
```



Kernel Density Estimators

In general, we can write:

$$\hat{f}_{K,h}(x) = \frac{1}{nh} \sum_{i=1}^n K\left(\frac{x - X_i}{h}\right)$$

where

- h is the “bandwidth” of the estimator
- $K(t)$ is a probability density symmetric about 0 (the “kernel”)

Kernel Density Estimators

In general, we can write:

$$\hat{f}_{K,h}(x) = \frac{1}{nh} \sum_{i=1}^n K\left(\frac{x - X_i}{h}\right)$$

where

- h is the “bandwidth” of the estimator
- $K(t)$ is a probability density symmetric about 0 (the “kernel”)

Optimal bandwidth depends on the true f . Heuristics discussed in Rizzo.

Some common kernels (with support)

- Gaussian $K(t) = (1/\sqrt{2\pi}) \exp(-t^2/2)$ ($t \in (-\infty, \infty)$)

Some common kernels (with support)

- Gaussian $K(t) = (1/\sqrt{2\pi}) \exp(-t^2/2)$ ($t \in (-\infty, \infty)$)
- Epanenchnikov: $K(t) = \frac{3}{4}(1 - t^2)$ ($t \in [-1, 1]$)

Some common kernels (with support)

- Gaussian $K(t) = (1/\sqrt{2\pi}) \exp(-t^2/2)$ ($t \in (-\infty, \infty)$)
- Epanenchnikov: $K(t) = \frac{3}{4}(1 - t^2)$ ($t \in [-1, 1]$)
- Rectangular: $K(t) = 1/2$ ($t \in [-1, 1]$)

Some common kernels (with support)

- Gaussian $K(t) = (1/\sqrt{2\pi}) \exp(-t^2/2)$ ($t \in (-\infty, \infty)$)
- Epanenchnikov: $K(t) = \frac{3}{4}(1 - t^2)$ ($t \in [-1, 1]$)
- Rectangular: $K(t) = 1/2$ ($t \in [-1, 1]$)
- Triangular: $K(t) = 1 - |t|$ ($t \in [-1, 1]$)

Some common kernels (with support)

- Gaussian $K(t) = (1/\sqrt{2\pi}) \exp(-t^2/2)$ ($t \in (-\infty, \infty)$)
- Epanenchnikov: $K(t) = \frac{3}{4}(1 - t^2)$ ($t \in [-1, 1]$)
- Rectangular: $K(t) = 1/2$ ($t \in [-1, 1]$)
- Triangular: $K(t) = 1 - |t|$ ($t \in [-1, 1]$)
- Biweight: $K(t) = (15/16)(1 - t^2)^2$ ($t \in [-1, 1]$)

Some common kernels (with support)

- Gaussian $K(t) = (1/\sqrt{2\pi}) \exp(-t^2/2)$ ($t \in (-\infty, \infty)$)
- Epanenchnikov: $K(t) = \frac{3}{4}(1 - t^2)$ ($t \in [-1, 1]$)
- Rectangular: $K(t) = 1/2$ ($t \in [-1, 1]$)
- Triangular: $K(t) = 1 - |t|$ ($t \in [-1, 1]$)
- Biweight: $K(t) = (15/16)(1 - t^2)^2$ ($t \in [-1, 1]$)
- Cosine: $K(t) = (\pi/4) \cos(t\pi/2)$ ($t \in (-\infty, \infty)$)

Some common kernels (with support)

- Gaussian $K(t) = (1/\sqrt{2\pi}) \exp(-t^2/2)$ ($t \in (-\infty, \infty)$)
- Epanenchnikov: $K(t) = \frac{3}{4}(1 - t^2)$ ($t \in [-1, 1]$)
- Rectangular: $K(t) = 1/2$ ($t \in [-1, 1]$)
- Triangular: $K(t) = 1 - |t|$ ($t \in [-1, 1]$)
- Biweight: $K(t) = (15/16)(1 - t^2)^2$ ($t \in [-1, 1]$)
- Cosine: $K(t) = (\pi/4) \cos(t\pi/2)$ ($t \in (-\infty, \infty)$)

Some common kernels (with support)

- Gaussian $K(t) = (1/\sqrt{2\pi}) \exp(-t^2/2)$ ($t \in (-\infty, \infty)$)
- Epanenchnikov: $K(t) = \frac{3}{4}(1 - t^2)$ ($t \in [-1, 1]$)
- Rectangular: $K(t) = 1/2$ ($t \in [-1, 1]$)
- Triangular: $K(t) = 1 - |t|$ ($t \in [-1, 1]$)
- Biweight: $K(t) = (15/16)(1 - t^2)^2$ ($t \in [-1, 1]$)
- Cosine: $K(t) = (\pi/4) \cos(t\pi/2)$ ($t \in (-\infty, \infty)$)

Properties of the kernel usually transfer to \hat{f} . E.g., if K is smooth, then $f_{K,h}$ is also smooth.

Multivariate Density Smoothing

Suppose we have $X = (X_1, \dots, X_d)$ from a **multivariate density**. We can create multivariate kernels two ways:

- Use multivariate kernels (e.g., the multivariate standard Normal distribution):

$$\hat{f}(x_1, \dots, x_d) = \frac{1}{nh_1 h_2 \dots h_d} \sum_{i=1}^n K\left(\frac{x_1 - X_{i1}}{h_1}, \frac{x_2 - X_{i2}}{h_2}, \dots, \frac{x_d - X_{id}}{h_d}\right)$$

Multivariate Density Smoothing

Suppose we have $X = (X_1, \dots, X_d)$ from a **multivariate density**. We can create multivariate kernels two ways:

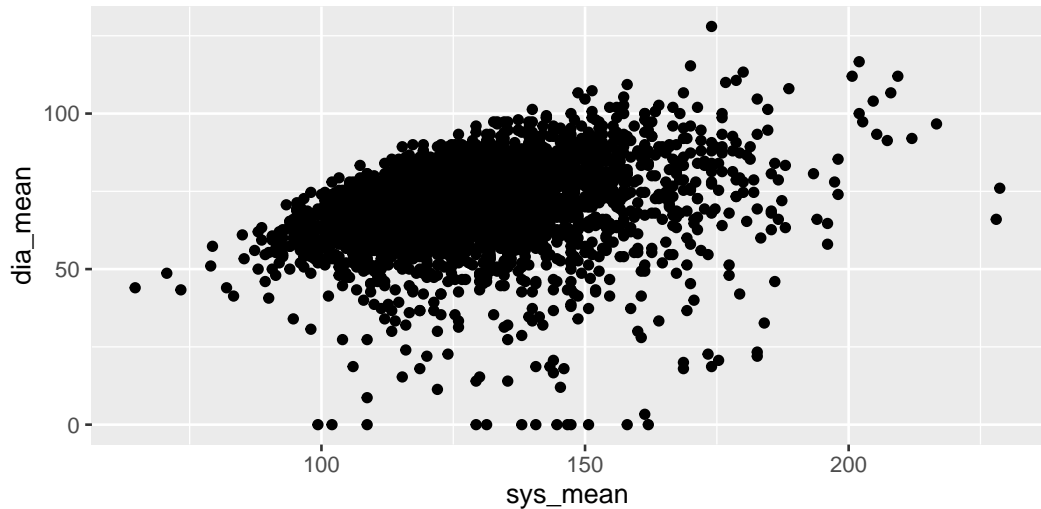
- Use multivariate kernels (e.g., the multivariate standard Normal distribution):

$$\hat{f}(x_1, \dots, x_d) = \frac{1}{nh_1 h_2 \dots h_d} \sum_{i=1}^n K\left(\frac{x_1 - X_{i1}}{h_1}, \frac{x_2 - X_{i2}}{h_2}, \dots, \frac{x_d - X_{id}}{h_d}\right)$$

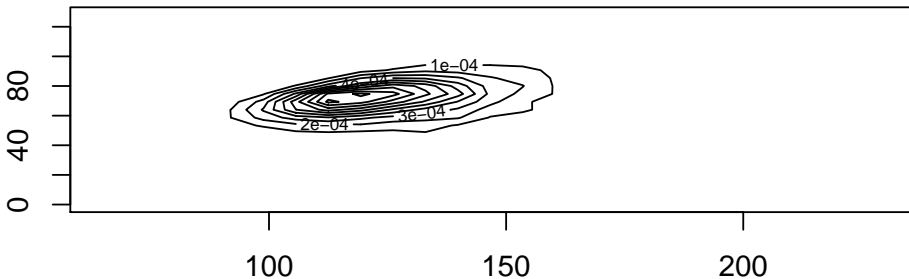
- Create a kernel from the product of unidimensional kernels (“independent joint distribution”)

$$\hat{f}(x_1, \dots, x_d) = \frac{1}{nh_1 h_2 \dots h_d} \sum_{i=1}^n \prod_{j=1}^d K\left(\frac{x_j - X_{ij}}{h_j}\right)$$

```
> ggplot(nhanes, aes(x = sys_mean, y = dia_mean)) + geom_point()
```



```
> library(MASS)
> contour(kde2d(nhanes$sys_mean, nhanes$dia_mean))
```



Mixture distributions

Recall our definition of a **mixture distribution**

$$F(x) = \sum_{i=1}^n w_i F_i(x)$$

where

- Each F_i is a **valid CDF**.
- All the w_i **sum to 1**.

Mixture distributions

Recall our definition of a **mixture distribution**

$$F(x) = \sum_{i=1}^n w_i F_i(x)$$

where

- Each F_i is a **valid CDF**.
- All the w_i **sum to 1**.

If each CDF has a **PDF/PMF** f_j , then

$$f(x) = \frac{d}{dx} \sum_{j=1}^m w_j F_j(x) = \sum_{j=1}^m w_j f_j(x)$$

Location-scale mixtures

Suppose we have a **mixture** where the F_j come from a single **location-scale family**:

$$F_j(x) = G\left(\frac{x - \mu_j}{\sigma}\right)$$

Location-scale mixtures

Suppose we have a **mixture** where the F_j come from a single **location-scale family**:

$$F_j(x) = G\left(\frac{x - \mu_j}{\sigma}\right)$$

A slight extension to a result from the last homework gives us the density:

$$f_j(x) = \frac{g\left(\frac{x - \mu_j}{\sigma}\right)}{\sigma}$$

Location-scale mixtures

Suppose we have a **mixture** where the F_j come from a single **location-scale family**:

$$F_j(x) = G\left(\frac{x - \mu_j}{\sigma}\right)$$

A slight extension to a result from the last homework gives us the density:

$$f_j(x) = \frac{g\left(\frac{x - \mu_j}{\sigma}\right)}{\sigma}$$

The mixture density is then

$$f(x) = \sum_{i=1}^n w_i \frac{g\left(\frac{x - \mu_j}{\sigma}\right)}{\sigma}$$

Density estimation as a mixture

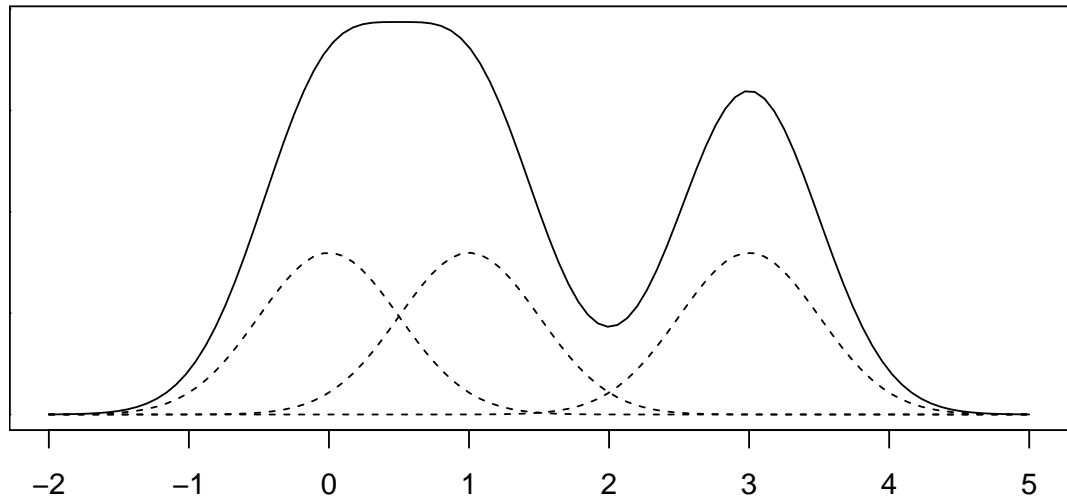
Now we can see that **kernel density estimator** is fitting a **mixture distribution**:

$$\hat{f}_{K,h}(x) = \sum_{i=1}^n \frac{1}{n} \frac{K\left(\frac{x-X_i}{h}\right)}{h}$$

where

- K is the **location-scale density**,
- X_i is the **mean** μ_j
- h is the **scale/sd** σ .
- All **weights are 1/n**.

Gaussian kernel, $h = 1/2$, $X = (0, 1, 3)$



Density estimation summary

- Goal: estimate a density function from a sample

Density estimation summary

- Goal: estimate a density function from a sample
- Technique: for any point x , average using close by observations

Density estimation summary

- Goal: estimate a density function from a sample
- Technique: for any point x , average using close by observations
- Need to pick a kernel and a bandwidth. Can be done with cross validation and a loss function.

Density estimation summary

- Goal: estimate a density function from a sample
- Technique: for any point x , average using close by observations
- Need to pick a kernel and a bandwidth. Can be done with cross validation and a loss function.
- Uses:

Density estimation summary

- Goal: estimate a density function from a sample
- Technique: for any point x , average using close by observations
- Need to pick a kernel and a bandwidth. Can be done with cross validation and a loss function.
- Uses:
 - Display

Density estimation summary

- Goal: estimate a density function from a sample
- Technique: for any point x , average using close by observations
- Need to pick a kernel and a bandwidth. Can be done with cross validation and a loss function.
- Uses:
 - Display
 - Smoothed bootstrapping

Density estimation summary

- Goal: estimate a density function from a sample
- Technique: for any point x , average using close by observations
- Need to pick a kernel and a bandwidth. Can be done with cross validation and a loss function.
- Uses:
 - Display
 - Smoothed bootstrapping
 - Using densities as outcomes in regressions

Smoothed Means

Suppose we have bivariate data (Y_i, x_i) .

Scenario

Suppose we have bivariate data (Y_i, x_i) .

We will consider the Y_i to be random in some way, but the x_i values may be fixed.

Suppose we have bivariate data (Y_i, x_i) .

We will consider the Y_i to be random in some way, but the x_i values may be fixed.

We've seen examples of this in the HW, previous examples, etc.

Suppose we have bivariate data (Y_i, x_i) .

We will consider the Y_i to be random in some way, but the x_i values may be fixed.

We've seen examples of this in the HW, previous examples, etc.

Goal: Understand the relationship between x_i and Y_i (perhaps for prediction, data reduction, inference).

Mean functions

We've seen models of the form:

$$Y = \mu(x) + \epsilon$$

where we assume $E(\epsilon) = 0$.

Mean functions

We've seen models of the form:

$$Y = \mu(x) + \epsilon$$

where we assume $E(\epsilon) = 0$.

For example,

$$Y = \beta_0 + \beta_1 x + \epsilon$$

Mean functions

We've seen models of the form:

$$Y = \mu(x) + \epsilon$$

where we assume $E(\epsilon) = 0$.

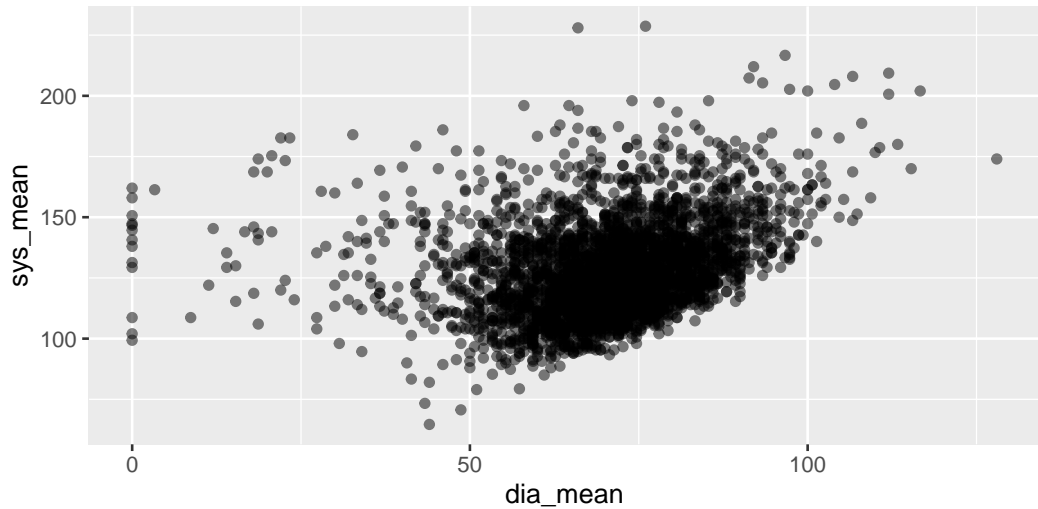
For example,

$$Y = \beta_0 + \beta_1 x + \epsilon$$

Notice because $E(\epsilon) = 0$, we have

$$E(Y|x) = \mu(x)$$

Can we use smoothing to estimate a good mean function?



Kernel Smoothing

As with density estimation, we want to let **near by values of Y_i** influence our estimate of $E(Y|x)$.

Kernel Smoothing

As with density estimation, we want to let **near by values of Y_i** influence our estimate of $E(Y|x)$.

The Nardaraya-Watson estimator using a kernel function K :

$$\hat{\mu}(x) = \frac{\sum_{i=1}^n K\left(\frac{x_i - x}{h}\right) Y_i}{\sum_{i=1}^n K\left(\frac{x_i - x}{h}\right)}$$

From density estimation to smoothed means

Consider the estimators for the **joint distribution of (Y, X)** and the **marginal distribution of X** :

$$\hat{f}(x, y) = \frac{1}{nh^2} \sum_{i=1}^n K\left(\frac{X_i - x}{h}\right) K\left(\frac{Y_i - y}{h}\right)$$

$$\hat{f}(x) = \frac{1}{nh} \sum_{i=1}^n K\left(\frac{X_i - x}{h}\right)$$

From density estimation to smoothed means

Consider the estimators for the **joint distribution of (Y, X)** and the **marginal distribution of X** :

$$\hat{f}(x, y) = \frac{1}{nh^2} \sum_{i=1}^n K\left(\frac{X_i - x}{h}\right) K\left(\frac{Y_i - y}{h}\right)$$
$$\hat{f}(x) = \frac{1}{nh} \sum_{i=1}^n K\left(\frac{X_i - x}{h}\right)$$

By the relationship that $f(y | x) = f(x, y)/f(x)$, we can plugin in our estimators to get

$$\hat{f}(y | x) = \frac{\frac{1}{h} \sum_{i=1}^n K\left(\frac{X_i - x}{h}\right) K\left(\frac{Y_i - y}{h}\right)}{\sum_{i=1}^n K\left(\frac{X_i - x}{h}\right)}$$

Estimating $E(Y | x)$

We want to estimate $E(Y | x) = \int y f(y | x) dy$, so let's plug in our estimate $\hat{f}(y | x)$:

$$\begin{aligned}\int y \hat{f}(y | x) dy &= \int y \frac{\frac{1}{h} \sum_{i=1}^n K\left(\frac{X_i - x}{h}\right) K\left(\frac{Y_i - y}{h}\right)}{\sum_{i=1}^n K\left(\frac{X_i - x}{h}\right)} dy \\ &= \frac{\frac{1}{h} \sum_{i=1}^n K\left(\frac{X_i - x}{h}\right) \int y K\left(\frac{Y_i - y}{h}\right) dy}{\sum_{i=1}^n K\left(\frac{X_i - x}{h}\right)}\end{aligned}$$

Estimating $E(Y | x)$

We want to estimate $E(Y | x) = \int y f(y | x) dy$, so let's plug in our estimate $\hat{f}(y | x)$:

$$\begin{aligned}\int y \hat{f}(y | x) dy &= \int y \frac{\frac{1}{h} \sum_{i=1}^n K\left(\frac{X_i - x}{h}\right) K\left(\frac{Y_i - y}{h}\right)}{\sum_{i=1}^n K\left(\frac{X_i - x}{h}\right)} dy \\ &= \frac{\frac{1}{h} \sum_{i=1}^n K\left(\frac{X_i - x}{h}\right) \int y K\left(\frac{Y_i - y}{h}\right) dy}{\sum_{i=1}^n K\left(\frac{X_i - x}{h}\right)}\end{aligned}$$

We're done if we can show

$$\frac{1}{h} \int y K\left(\frac{Y_i - y}{h}\right) dy = Y_i$$

Final step

Recall that K is a density function for some random variable V , symmetric about 0. Let's do a little change of variables.

$$v = \frac{y - Y_i}{h} \Rightarrow y = Y_i + hv, dy = h dv$$

Final step

Recall that K is a density function for some random variable V , symmetric about 0. Let's do a little change of variables.

$$v = \frac{y - Y_i}{h} \Rightarrow y = Y_i + hv, dy = h dv$$

$$\frac{1}{h} \int (Y_i + hv) K(-v) h dv$$

Final step

Recall that K is a density function for some random variable V , symmetric about 0. Let's do a little change of variables.

$$v = \frac{y - Y_i}{h} \Rightarrow y = Y_i + hv, dy = h dv$$

$$\frac{1}{h} \int (Y_i + hv) K(-v) h dv = \int (Y_i + hv) K(v) dv$$

Final step

Recall that K is a density function for some random variable V , symmetric about 0. Let's do a little change of variables.

$$v = \frac{y - Y_i}{h} \Rightarrow y = Y_i + hv, dy = h dv$$

$$\frac{1}{h} \int (Y_i + hv) K(-v) h dv = \int (Y_i + hv) K(v) dv = Y_i + hE(V) =$$

Final step

Recall that K is a density function for some random variable V , symmetric about 0. Let's do a little change of variables.

$$v = \frac{y - Y_i}{h} \Rightarrow y = Y_i + hv, dy = h dv$$

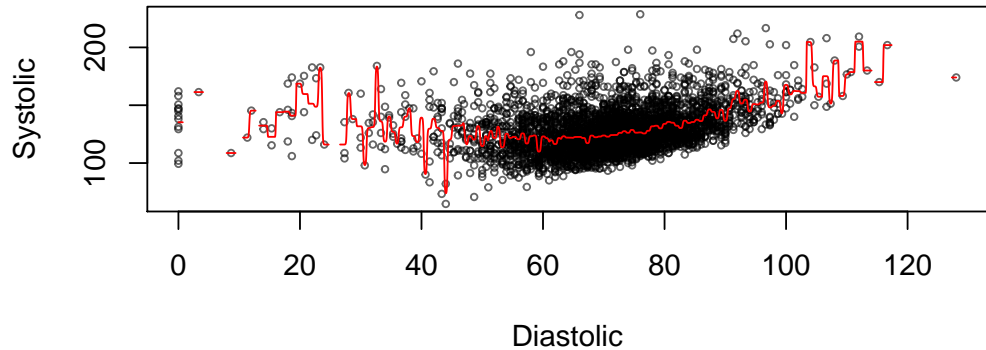
$$\frac{1}{h} \int (Y_i + hv) K(-v) h dv = \int (Y_i + hv) K(v) dv = Y_i + hE(V) = Y_i$$

Narrow bandwidth

```
> ## default bandwidth is 0.5
> bp_smooth <- ksmooth(nhanes$dia_mean,
+                       nhanes$sys_mean,
+                       kernel = "normal")
> str(bp_smooth)
```

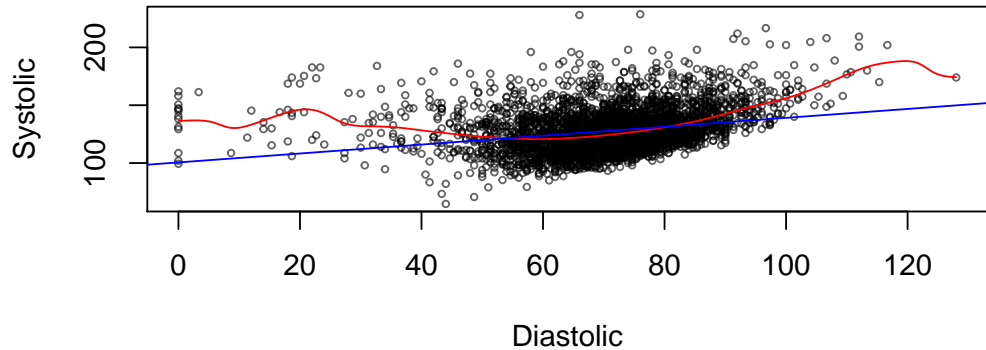
List of 2

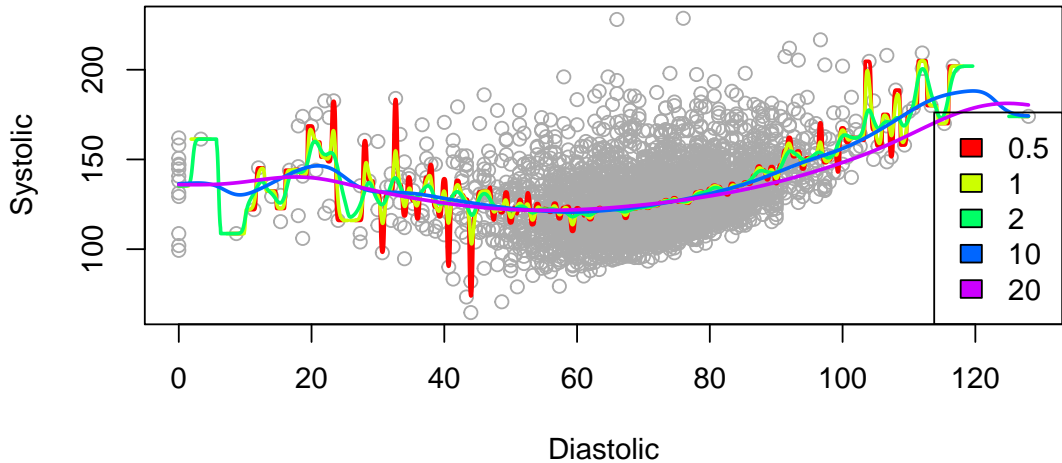
```
$ x: num [1:3567] 0 0.0359 0.0718 0.1077 0.1436 ...
$ y: num [1:3567] 135 135 135 135 135 ...
```

Better bandwidth

```
> bp_smooth_2 <- ksmooth(nhanes$dia_mean,  
+                          nhanes$sys_mean,  
+                          kernel = "normal", bandwidth = 10)  
> bp_linea <- lm(sys_mean ~ dia_mean, data = nhanes)
```





Picking a bandwidth using CV

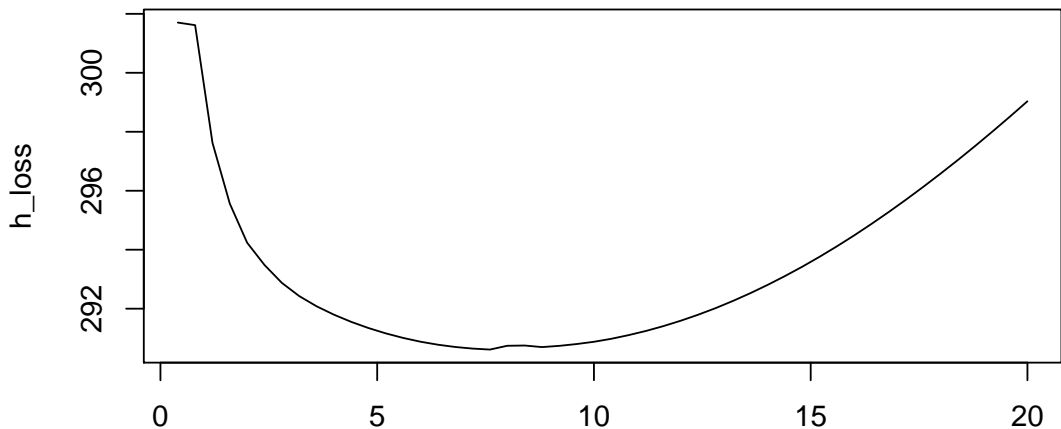
Recall that **cross validation** splits the data into (many) training and test sets and estimates **prediction loss** (costs paid for estimating new values).

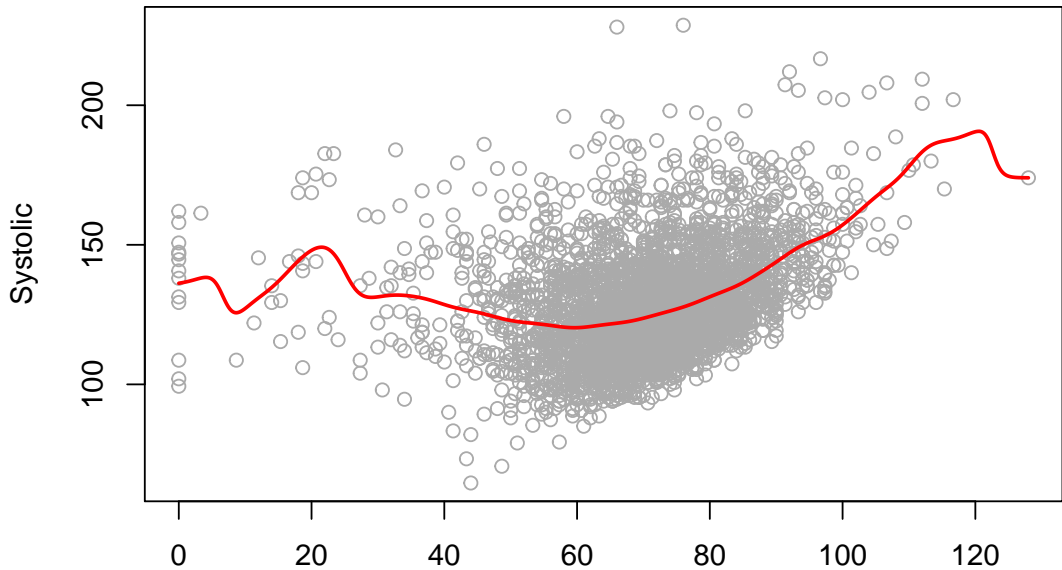
Let's pick bandwidth using **leave one out cross validation** with **squared error loss**.

```
> loss_one <- function(i, h) {  
+   yhat_i <- ksmooth(bandwidth = h, kernel = "normal",  
+                     x = nhanes$dia_mean[-i],  
+                     y = nhanes$sys_mean[-i],  
+                     x.points = nhanes$dia_mean[i])  
+   (yhat_i$y - nhanes$sys_mean[i])^2 ## loss  
+ }  
> loss_LOOCV <- function(h) { mean(sapply(1:nrow(nhanes), loss_one, h = h)) }
```

```
> hs <- seq(0.4, 20, length.out = 50)
> h_loss <- sapply(hs, loss_LOOCV)
> (best <- hs[which.min(h_loss)])

[1] 7.6
```





Comparing smoothed mean functions

Question: Is the mean function for aspirin takers the same as the mean function for non-aspirin takers?

Comparing smoothed mean functions

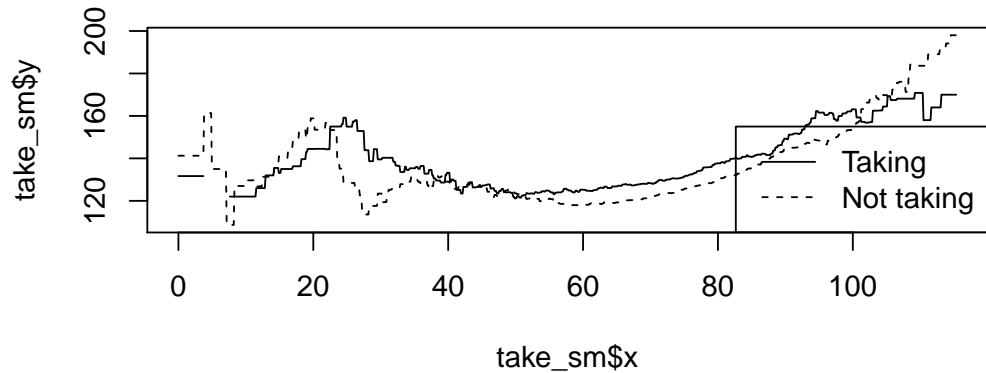
Question: Is the mean function for aspirin takers the same as the mean function for non-aspirin takers?

A little setup to make sure we compute the smoothers at the same point:

```
> range_d1 <- range(nhanes$dia_mean[nhanes$taking_aspirin])  
> range_d2 <- range(nhanes$dia_mean[!nhanes$taking_aspirin])  
> bounds <- c(max(range_d1[1], range_d2[1]),  
+             min(range_d1[2], range_d2[2]))
```

Implementing the smoothers

```
> compute_smoother <- function(y, x, z) {  
+   # we'll use the optimal bandwidth from before,  
+   # but this could be computed within groups  
+   ksmooth(x[z], y[z], bandwidth = 7.6,  
+           n.points = 1000, range = bounds)  
+ }  
  
> take_sm <- with(nhanes,  
+                 compute_smoother(sys_mean, dia_mean, taking_aspirin))  
> nott_sm <- with(nhanes,  
+                 compute_smoother(sys_mean, dia_mean, !taking_aspirin))
```

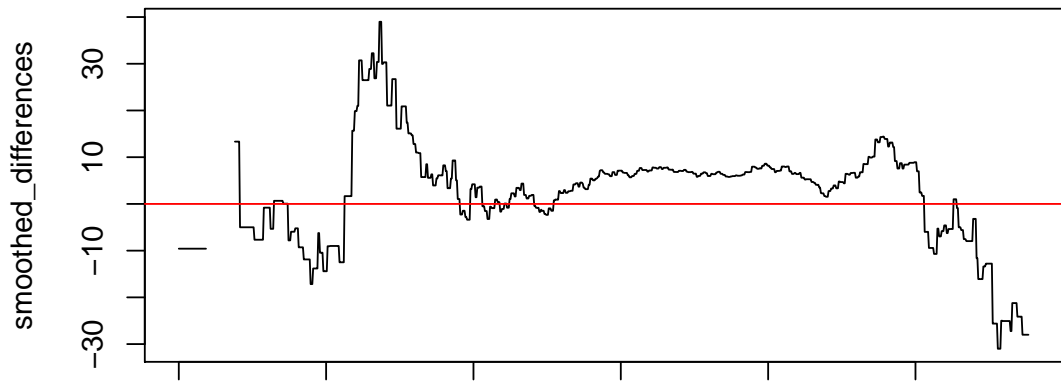


Difference Function

We probably want to know if

$$\mu_1(x) > \mu_0(x) \Rightarrow \mu_1(x) - \mu_0(x) > 0$$

```
> smoothed_differences <- take_sm$y - nott_sm$y
```

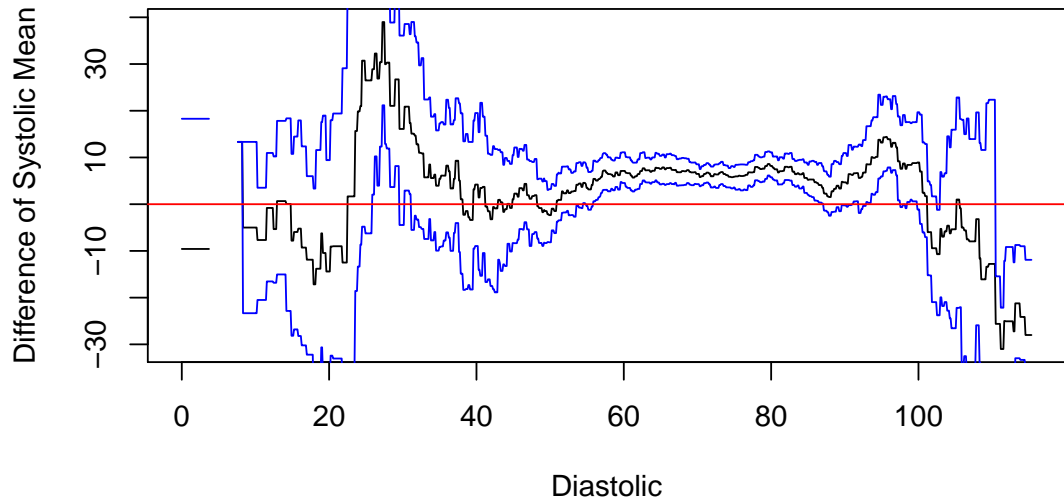


Confidence intervals for differences

```
> mu_diff <- function(data, index) {  
+   xstar <- data[index, ]  
+  
+   s1 <- with(xstar,  
+             compute_smoother(sys_mean, dia_mean, taking_aspirin))  
+  
+   s2 <- with(xstar,  
+             compute_smoother(sys_mean, dia_mean, !taking_aspirin))  
+  
+   return(s1$y - s2$y)  
+ }
```

```
> mu_boot <- boot(nhanes,  
+   mu_diff,  
+   strata = nhanes$taking_aspirin, R = 100)  
> point_ci <- apply(mu_boot$t, 2,  
+   quantile, probs = c(0.025, 0.975), na.rm = TRUE)
```

95% confidence CIs for difference of mean fns



Smoothed Mean Function Summary

- Trying to estimate the function μ in

$$Y = \mu(x) + \epsilon, E(\epsilon = 0) \iff E(Y | x) = \mu(x)$$

Smoothed Mean Function Summary

- Trying to estimate the function μ in

$$Y = \mu(x) + \epsilon, E(\epsilon = 0) \iff E(Y | x) = \mu(x)$$

- Used **smoothed joint and marginal densities** to create a **smoothed conditional density** $\hat{f}(y | x)$.

Smoothed Mean Function Summary

- Trying to estimate the function μ in

$$Y = \mu(x) + \epsilon, E(\epsilon = 0) \iff E(Y | x) = \mu(x)$$

- Used **smoothed joint and marginal densities** to create a **smoothed conditional density** $\hat{f}(y | x)$.
- Used the smooth conditional to estimate $\hat{\mu}(x) = \int y \hat{f}(y | x) dy$ (Nadaraya-Watson)

Smoothed Mean Function Summary

- Trying to estimate the function μ in

$$Y = \mu(x) + \epsilon, E(\epsilon = 0) \iff E(Y | x) = \mu(x)$$

- Used **smoothed joint and marginal densities** to create a **smoothed conditional density** $\hat{f}(y | x)$.
- Used the smooth conditional to estimate $\hat{\mu}(x) = \int y \hat{f}(y | x) dy$ (Nadaraya-Watson)
- Saw that NW is example of **linear smoother** (we'll see more later), bias and variance depend on h and K

Smoothed Mean Function Summary

- Trying to estimate the function μ in

$$Y = \mu(x) + \epsilon, E(\epsilon = 0) \iff E(Y | x) = \mu(x)$$

- Used **smoothed joint and marginal densities** to create a **smoothed conditional density** $\hat{f}(y | x)$.
- Used the smooth conditional to estimate $\hat{\mu}(x) = \int y \hat{f}(y | x) dy$ (Nadaraya-Watson)
- Saw that NW is example of **linear smoother** (we'll see more later), bias and variance depend on h and K
- Added uncertainty using bootstrap (could have assumed constant variance as well)