Week 03: Monte Carlo Estimation

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Computational Methods in Statistics and Data Science (Stats 406)

Monte Carlo Estimation

Estimation Review

As with hypothesis testing, we want to **infer** something about a **population** based on a **sample**:

- Specific parameters in the distribution function.
- Moments of the population (mean, variance, skew, etc).
- Probabilities or quantiles: $P(X > c) = \theta$ or $P(X \le \theta) = c$

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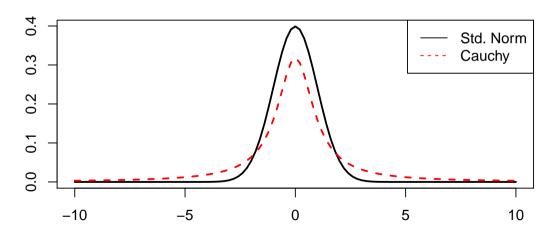
To make our guesses, we'll use an estimator (another term for a statistic):

$$\hat{\theta} = \hat{\theta}(X_1, \ldots, X_n)$$

Understanding the distribution of $\hat{\theta}$ allows us to describe uncertainty and compare different estimators.

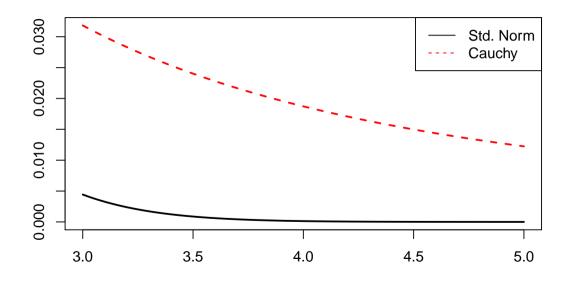
"Light" and "heavy" tails

The Cauchy distribution is known to have "heavy tails" (i.e., puts more mass away from the center).



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Zooming in on the tails



The PDF of the Cauchy is given by:

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Interesting fact: The Cauchy distribution does not have a mean: $E(X) = \infty!$

Suppose $X_i \stackrel{\text{iid}}{\sim} \text{Cauchy}(\theta)$ for i = 1, ..., n. How do we estimate θ ?

As θ is the median, the sample median is a natural choice.

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Which of these estimators is "better?" What does it mean for an estimator to be better?

Let's investigate the **operating characteristics** of estimators: bias, variance, and mean squared error.

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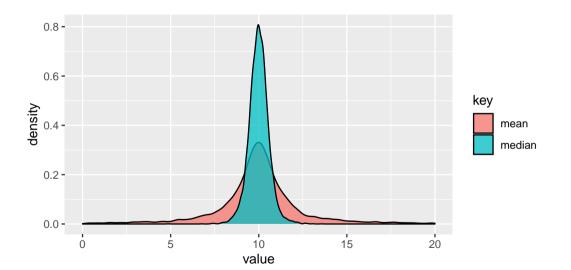
Since this distribution comes from sampling *n* values, we call this the sampling distribution. We will estimate the sampling distribution using Monte Carlo techniques.

```
> n <- 10
> true_theta <- 10
> samples <- rerun(10000, rcauchy(10, location = true_theta))</pre>
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```
> n <- 10
> true_theta <- 10
> samples <- rerun(10000, rcauchy(10, location = true_theta))
> median_sampling_dist <- map_dbl(samples, median)
> mean_sampling_dist <- map_dbl(samples, mean)</pre>
```



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We call $E(\hat{\theta}) - \theta$ the bias of the estimator. An estimator is unbiased if $E(\hat{\theta}) = \theta$.

Estimated bias of the two estimators:

- > mean(median_sampling_dist) true_theta
- [1] 0.001323
- > mean(mean_sampling_dist) true_theta
- [1] 11.77

More sampling distribution details

> summary(median_sampling_dist)

```
Min. 1st Qu. Median Mean 3rd Qu. Max. 4.87 9.66 10.00 10.00 10.33 13.57
```

> summary(mean_sampling_dist)

```
Min. 1st Qu. Median Mean 3rd Qu. Max. -9051 9 10 22 11 119723
```

Comparing variance

We also asked how often we could reject false null hypotheses (power).

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The equivalent for estimation is the variance of the sampling distribution.

- > var(median_sampling_dist)
- [1] 0.3292
- > var(mean_sampling_dist)
- [1] 1449215

A better estimator

The order statistics of a sample are the sorted values:

$$X_{(1)} \leq X_{(2)} \leq \cdots \leq X_{(n)}$$

I.e., $X_{(1)}$ is the sample minimum; $X_{(n)}$ is the sample maximum.

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I.e., $X_{(1)}$ is the sample minimum; $X_{(n)}$ is the sample maximum.

Another estimator takes the average of some middle portion of the order statistics, we call this a "trimmed mean".

```
> trimmed_mean <- function(x, k) {
+  n <- length(x)
+  orderstats <- sort(x)
+  mean(orderstats[k:(n - k)])
+ }</pre>
```

How should we pick k?

```
> ks <- 1:4
> map(ks, function(k) {
+ ts <- map_dbl(samples, ~ trimmed_mean(.x, k = k))
+ t_bias <- mean(ts) - true_theta
+ t var <- var(ts)
+ c(t_bias, t_var)
+ }) %>% bind cols
# A tibble: 2 x 4
       V1 V2 V3 V4
    <dbl> <dbl> <dbl> <dbl> <
   -4.22 -0.418 -0.251 -0.202
2 11534. 1.27 0.460 0.358
```

Bigger sample size n

```
> n <- 500
> k <- round(0.38 * n / 2)
> samples_500 <- data.frame(replicate(1000, rcauchy(n, true_theta)))
> median_500 <- map_dbl(samples_500, median)
> trimmed_500 <- map_dbl(samples_500, trimmed_mean, k = k)</pre>
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Bigger sample size n

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> n <- 500
> k < - round(0.38 * n / 2)
> samples_500 <- data.frame(replicate(1000, rcauchy(n, true_theta)))</pre>
> median_500 <- map_dbl(samples_500, median)</pre>
> trimmed_500 <- map_dbl(samples_500, trimmed_mean, k = k)</pre>
> c(mean(median_500), var(median_500))
[1] 9.995974 0.005108
> c(mean(trimmed_500), var(trimmed_500))
[1] 9.990400 0.006029
```

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For unbiased estimators, then we simply prefer those with low variance.

Estimating MSE

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> mean((median_500 - true_theta)^2)
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[1] 0.006115
```

Since both were nearly unbiased, this is basically equal to variance.

Confidence Intervals for MSE

It is useful to give statements of how precise our estimates of the MSE are:

```
> t.test((median_500 - true_theta)^2)$conf.int
[1] 0.004648 0.005590
attr(, "conf.level")
[1] 0.95
> t.test((trimmed_500 - true_theta)^2)$conf.int
[1] 0.005594 0.006636
attr(,"conf.level")
[1] 0.95
```

Example: estimating upper bound of uniform distribution

Consider a distribution with an **unknown upper bound** θ given by:

$$f(x) = I(x \in [0, \theta]) \frac{1}{\theta}$$

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Suppose we have a sample of 20 IID draws from f. How can we estimate θ ?

- Method of moments estimation: find θ as a function of the moments of the distribution.
- Maximum likelihood estimation: find the θ that maximizes the joint density (likelihood function).

In general, for any uniform distribution on [a, b], the mean is given by (b - a)/2 (the midpoint of the range).

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$$\theta = 2\mathsf{E}(X) \Rightarrow \tilde{\theta} = 2\bar{X}$$

Maximum likelihood

For IID data, the likelihood in this case will be

$$L(\theta) = \prod_{i=1}^{n} I(x_i \in [0, \theta]) \frac{1}{\theta} = \frac{1}{\theta^n} \prod_{i=1}^{n} I(x_i \in [0, \theta])$$

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Notice:

- $\prod_{i=1}^n I(x_i \in [0, \theta]) = 0$ if any $x_i > \theta$.
- $1/\theta^n$ is decreasing in θ .

These two facts imply, the MLE is the sample maximum: $\hat{\theta} = \max_i X_i$.

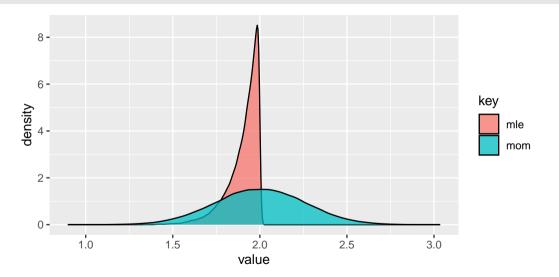
Sampling distribution for $n = 20, \theta = 2$

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```
> k <- 100000
> n <- 20
> theta <- 2
> samples <- rerun(k, runif(n, min = 0, max = theta))
> mle_sampling_dist <- map_dbl(samples, max)
> mom_sampling_dist <- map_dbl(samples, ~ 2 * mean(.x))</pre>
```

Sampling Distributions



Operating characteristics

```
Bias:
```

```
> t.test(mle_sampling_dist - theta)$conf.int[1:2] # 1:2 silence attr
[1] -0.09571 -0.09458
> t.test(mom_sampling_dist - theta)$conf.int[1:2]
[1] -0.001261  0.001942
```

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[1] 0.06617 0.06733

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MSE:
> t.test((mle_sampling_dist - theta)^2)$conf.int[1:2] # 1:2 silence attr
[1] 0.01718 0.01762
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- We can evaluate for bias and variance of estimators, and combine these with mean squared error.
- As with generating **null distributions**, we pick a distribution for the X_i , and the **estimate the distribution of** $\hat{\theta}$ (sampling distribution).
- Usually we wish to compare estimators or change aspects of the problem to see how the performance changes (ample size, parameter values).

Confidence Intervals

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A similar concept in estimation is to construct a **confidence interval** for θ (target of inference).

Capturing Uncertainty: Confidence Intervals

A $(1 - \alpha) \times 100\%$ confidence interval (CI) is a pair of random variables A and B such that

$$Pr(A \le \theta, B \ge \theta) > 1 - \alpha$$
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Confidence intervals are sometimes called **interval estimators** because A and B are typically functions of the data, X_1, \ldots, X_n :

$$A = A(X_1, \ldots, X_n)$$
 $B = B(X_1, \ldots, X_n)$

Confidence interval construction

The notation $A(X_1, ..., X_n)$, $B(X_1, ..., X_n)$ has a natural connection to **test statistics** and highlights one way of construction confidence intervals: **find the set of null hypotheses not rejected at the** α -**level**.

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$$A = \inf\{\theta_0 : T(X_1, \dots, X_n) \notin \mathcal{R}(\theta_0, \alpha)\}$$

$$B = \sup\{\theta_0 : T(X_1, \dots, X_n) \notin \mathcal{R}(\theta_0, \alpha)\}$$

where $\mathcal{R}(\theta_0, \alpha)$ is the rejection region for T when $H_0: \theta = \theta_0$ versus $H_1: \theta \neq \theta_0$.

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This is called the "test inversion" method of CI construction.

Connections to hypothesis tests

Many of the concepts from hypothesis tests have direct analogs to CIs (no matter how they are constructed):

• Type I error: The confidence coefficient/coverage is $Pr(\theta \in [A, B])$, which is greater than $1 - \alpha$.

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 In other words, the probability of [A, B] excluding θ is no more than α.
- Power: No matter what θ is, we want [A, B] to cover it. Short intervals will exclude more false null hypotheses, so we want E(B - A) (expected length) to be small.

Connections to "estimator $\pm c$ "

For $X_i \sim N(\mu, \sigma^2)$, independent with σ^2 known, let's test

$$H_0: \mu = \mu_0$$
 versus $H_1: \mu \neq \mu_0$

at the α level using \bar{X} as the statistic.

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 versus $H_1: \mu \neq \mu_0$

at the α level using \bar{X} as the statistic.

We accept the null if

$$-\Phi(1-\alpha/2) \leq \frac{\bar{X}-\mu_0}{\sigma/\sqrt{n}} \leq \Phi(1-\alpha/2)$$

Solving for μ_0

Solving for μ_0 gives us

$$\bar{X} - \Phi(1 - \alpha/2)(\sigma/\sqrt{n}) \le \mu_0 \le \bar{X} + \Phi(1 - \alpha/2)(\sigma/\sqrt{n})$$

or

$$\mu_0 \in \bar{X} \pm \Phi(1 - \alpha/2)(\sigma/\sqrt{n})$$

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or

$$\mu_0 \in \bar{X} \pm \Phi(1 - \alpha/2)(\sigma/\sqrt{n})$$

The "plus-minus" type intervals show up for **shift parameters** that change the center of the sampling distribution but not the variance or other properties.

Example: Coverage and Expected Length $X_i \sim N(\mu, \sigma^2)$

Suppose we believe we know σ^2 and

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we want to use \bar{X} to estimate μ .

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We will use two facts (without proof):

$$rac{ar{\mathcal{X}}-\mu}{\sigma/\sqrt{n}}\sim \mathcal{N}(0,1)$$

$$rac{ar{X}-\mu}{\hat{s}/\sqrt{n}}\sim t(n-1),\quad \hat{s}=\sqrt{rac{\sum_{i=1}^n(X_i-ar{X})^2}{n-1}}$$

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This leads to two kinds of $(1 - \alpha) \times 100\%$ confidence intervals:

$$ar{X} \pm z_{lpha/2}(\sigma/\sqrt{n}), \quad ar{X} \pm t_{lpha/2}(n-1)(\hat{s}/\sqrt{n})$$

Simulation to assess coverage and average width

```
> alpha <- 0.05
> k <- 10000
> n <- 20
> mu <- 2 # unknown truth
> sigma2 <- 10 ; sigma <- sqrt(sigma2) # known variance</pre>
```

Simulation to assess coverage and average width

> alpha <- 0.05 > k <- 10000 > n <- 20

Estimating coverage

```
Coverage is P(A \le \theta \le B):

> map_dbl(cis_norm, ~ .x[1] <= mu && mu <= .x[2]) %>% mean

[1] 0.9516

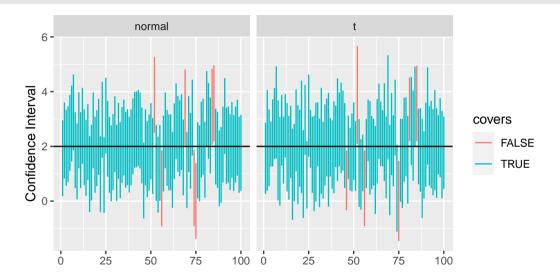
> map_dbl(cis_t, ~ .x[1] <= mu && mu <= .x[2]) %>% mean

[1] 0.9512
```

Estimating expected width

```
> map_dbl(cis_norm, ~ .x[2] - .x[1]) %>% mean
[1] 2.772
> map_dbl(cis_t, ~ .x[2] - .x[1]) %>% mean
[1] 2.918
```

Visual interpretation



Binomial proportion CI

We've already seen that if we are estimating

$$\theta = P(X \le t)$$

using

$$\hat{\theta} = \frac{1}{n} \sum_{i=1}^{n} I(X_i \le t)$$

the variables $Y_i = I(X_i \le t)$ are Bernoulli with $P(Y_i = 1) = \theta$.

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Using the central limit theorem, if we have a large sample, then

$$ar{Y} pprox \mathcal{N}\left(heta, rac{ heta(1- heta)}{n}
ight)$$

Binomial proportion continued

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Of course, we don't know θ , but we can stick in an **estimate**:

$$\bar{Y} \pm z_{\alpha/2} \sqrt{rac{ar{Y}(1-ar{Y})}{n}}$$

This is the standard confidence interval for a proportion.

95% CI for P(X > 1), $X \sim Cauchy(0)$

> n <- 10000 > x <- rcauchy(n) > y <- x > 1 > ybar <- mean(y)

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```
> n <- 10000
> x <- rcauchy(n)
> y <- x > 1
> ybar <- mean(y)

> (norm_ci <- ybar + c(-1,1) * qnorm(0.975) * sqrt(ybar * (1 - ybar) / n))
[1] 0.2504 0.2676</pre>
```

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We would accept θ_0 if either

$$a_0 < \sum_{i=1}^n Y_i < b_0$$

Finding a_0 s and b_0 s

We will search over a range of possible θ_0 values:

```
> theta_0 <- seq(0, 1, length.out = 1000)
```

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For each, compute the bounds:

```
> a0 <- qbinom(0.025, size = n, prob = theta_0)
> b0 <- qbinom(0.025, size = n, prob = theta_0,
```

lower.tail = FALSE) - 1

Reject or Accept θ_0

Now see for which θ_0 we would accept:

```
> w <- sum(y)
> range(theta_0[a0 < w & w < b0])
[1] 0.2513 0.2673</pre>
```

Reject or Accept θ_0

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```
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```

Which shows that the Normal approximation is quite good a n = 10000:

Binomial proportions intervals

R provides three methods for computing binomial confidence intervals:

- t.test: Using a standard normal approximation
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Which has proper coverage? Smallest size?

MC Setup

```
> theta <- 0.25
> n <- 20
> k <- 1000
> xs <- rbinom(k, size = n, prob = theta)</pre>
```

```
> tints <- map(xs, function(x) {
+     if (x == 0 || x == n) {
+         return(c(0, 1)) # can't estimate
+     } else {
+         return(t.test(c(rep(1, x), rep(0, n - x)))$conf.int)
+     }
+ })</pre>
```

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+ })
> bints <- map(xs, ~ binom.test(.x, n)$conf.int)
> pints <- map(xs, ~ prop.test(.x, n)$conf.int)</pre>
```

Confidence coefficient

Recall, the **confidence coefficient** is defined as

$$P(A \le \theta, \theta \le B)$$

- > cover <- function(x) { x[1] <= theta && theta <= x[2] }
- > (tcover <- map_dbl(tints, cover) %>% mean)

[1] 0.895

> (bcover <- map_dbl(bints, cover) %>% mean)

[1] 0.961

- > (pcover <- map_dbl(pints, cover) %>% mean)
- [1] 0.981

Expected Width

```
> (twidth <- map_dbl(tints, diff) %>% mean)
[1] 0.4053
> (bwidth <- map_dbl(bints, diff) %>% mean)
[1] 0.3944
> (pwidth <- map_dbl(pints, diff) %>% mean)
[1] 0.3893
```

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- The Pearson-Clopper method is **slightly conservative** (i.e., overcovers), which is reflected by having slightly higher average width.
- The score test inversion method has the smallest intervals, but also has good coverage.
- Important: these conclusions are for n=20 and $\theta=0.25$; other values might have other conclusions (e.g., when $\theta\approx 1$)

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- As with Type I error and power, we can investigate the operating characteristics of confidence intervals.
- Confidence coefficient (actual probability of including θ , analogous to Type I error)
- Expected width (ability to exclude incorrect θ , analogous to power)