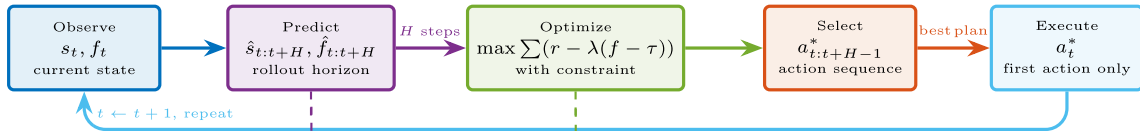


Objective at time t :

$$\max_{a_{t:t+H-1}} \sum_{h=0}^{H-1} \left[r_{t+h|t} - \lambda_t \cdot \max(0, f_{t+h|t} - \tau) \right]$$



Planned trajectory

