



DEPARTMENT OF INFORMATICS ENGINEERING

DEPARTMENT OF COMPUTER SCIENCE

# Functional and Logic Programming

Bachelor in Informatics and Computing Engineering 2021/2022 - 1st Semester

# Prolog

Database Modification, Graphs and Search

# Agenda

- Database Modification
  - Memoization
- Cycles
- Graphs and Search
  - Puzzles and Games

#### **Database Modification**

- Prolog allows clauses to be dynamically added or removed from a program
  - This provides great flexibility
  - · However, modifying the program is costly, as it requires re-indexing
- In order to add or remove clauses from a predicate, it first needs to be declared dynamic

```
:-dynamic male/1, female/1, parent/2.
```

See section 4.12 of the SICStus Manual for more information

# Adding Clauses

- assert/1 adds a new clause to the program; there are two additional variations of this predicate:
  - assertal 1 the new clause is added before all existing predicate clauses (if any)
  - assertz/1 the new clause is added after all existing predicate clauses (if any)

```
ask_and_add_to_kb:-
    write('Insert Parent-Child to add'),nl,
    read(P-C),
    assert(parent(P, C)).
```

When adding a rule, an additional pair of parentheses is required

# Removing Clauses

- retract/1 removes a clause from the program (the first that matches the given clause)
- retractall/1 retracts all clauses matching the specified head
- abolish/1 removes all clauses and properties of the specified predicate

```
retractall(parent(homer, _)).
abolish(parent/2).
```

```
replace_definition:-
    retract(( ancestor(X,Y):-parent(X,Y) )),
    asserta(( ancestor(X,Y):-father(X,Y) )),
    asserta(( ancestor(X,Y):-mother(X,Y) )).
```

# **Predicate Listing**

- *listing/0* lists all clauses from the currently loaded program
- *listing/1* lists all clauses from a given predicate
- These predicates list the code in the current output stream
  - Note that variable naming and code formatting are not preserved

```
a(X, Y) := b(X), !, b(Y).
a(3, 4).
b(2).
               | ?- listing.
b(3).
               a(A, B) :-
                       b(A), !,
                       b(B).
               a(3, 4).
               b(2).
               b(3).
               yes
               | ?- listing(a/2).
               a(A, B) :-
                       b(A), !,
                       b(B).
               a(3, 4).
               yes
```

# Accessing Clauses

clause(+Head, ?Body)
 allows access to the
 clauses of a given
 predicate in the
 knowledge base

```
a(X, Y):- b(X), !, b(Y).
a(3, 4).
b(2).
b(3).
```

```
| ?- clause( a(X,Y), Body ),
     retract((a(X,Y):-Body)),
    a(A, B),
    asserta((a(X,Y):-Body)).
A = 3
B = 4 ?
yes
| ?- listing(a/2).
a(A, B) :-
       b(A), !,
       b(B).
a(3, 4).
yes
| ?- clause( a(X,Y), Body ), retract(( a(X,Y):-Body )).
Body = (b(X),!,b(Y)) ?
yes
| ?- listing(a/2).
a(3, 4).
yes
```

#### **Database Modification**

- Assert and retract should be used sparingly (ideally only for things that do not change often)
  - They are slow operations
  - It can make programs harder to understand / debug

 The effect of database modification predicates is not undone in backtracking (just like input/output)

#### Memoization

 Modifying the database can be used to save partial results, resulting in a dynamic programming approach

Could we use *assertz* instead?

#### **Database Modification**

 We can also use this approach as an alternative to finding all answers to a query

```
get_all_children(Parent, _Children):-
    assert( children(Parent, []) ),
    fail.

get_all_children(Parent, _Children):-
    parent(Parent, Child),
    retract( children(Parent, Current) ),
    assert( children(Parent, [Child|Current]) ),
    fail.

get_all_children(Parent, Children):-
    retract( children(Parent, Children) ).
```

Why is this approach inefficient?

# Failure Driven Loops

- The example above is a failure driven loop
  - The fail forces Prolog to backtrack until all solutions are found

```
failure_driven_loop:-
    find_solution(X),
    do_something_with_solution(X),
    fail.
failure_driven_loop. %ensure predicate succeeds
```

- Efficient in terms of memory use
- Usually only used in situations when only side effects are important (results are not kept)

# Failure Driven Loops

- Failure driven loops are an alternative to recursive ones
  - Compare the following two approaches to implement a predicate print\_n(N, C), which prints a character C to the console N times

Which approach is more efficient?

# Failure Driven Loops

• Another example: consulting a program

```
consult(File):-
      see (File),
      loop,
      seen.
loop:-
      repeat,
      read(Clause),
      process (Clause), !.
process(end of file):- !.
process(Clause):-
      assert (Clause),
      fail.
```

DEI / FEUP

#### Generic Game Program

• A generic game program can be coded with a recursive loop

```
play game:-
      initial state (GameState-Player),
      display game (GameState-Player),
      game cycle(GameState-Player).
game cycle(GameState-Player):-
      game over (GameState, Winner), !,
      congratulate (Winner).
game cycle(GameState-Player):-
      choose move (GameState, Player, Move),
      move (GameState, Move, NewGameState),
      next player (Player, NextPlayer),
      display game (GameState-NextPlayer), !,
      game cycle (NewGameState-NextPlayer).
```

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#### Generic Game Program

```
choose move (GameState, human, Move):-
      % interaction to select move
choose move (GameState, computer-Level, Move):-
      valid moves (GameState, Moves),
      choose move (Level, GameState, Moves, Move).
valid moves(GameState, Moves):-
      findall (Move, move (GameState, Move, NewState), Moves).
choose move(1, GameState, Moves, Move):-
      random select (Move, Moves, Rest).
choose move (2, GameState, Moves, Move):-
      setof(Value-Mv, NewState^( member(Mv, Moves),
              move (GameState, Mv, NewState),
              evaluate board (NewState, Value) ), [ V-Move| ]).
% evaluate board assumes lower value is better
```

# Graphs and Search

- Graphs can be represented as the connections between nodes
  - set of facts representing [directed] edges

```
connected(porto, lisbon).
connected(lisbon, madrid).
connected(lisbon, paris).
connected(lisbon, porto).
connected(madrid, paris).
connected(madrid, lisbon).
connected(paris, madrid).
connected(paris, lisbon).
```

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# Depth-First Search

 Searching for a possible connection between nodes is made easy by Prolog's standard depth-first search mechanism

```
connected(porto, lisbon).
connected(lisbon, madrid).
connected(lisbon, paris).
connected(lisbon, porto).
connected(madrid, paris).
connected(madrid, lisbon).
connected(paris, madrid).
connected(paris, lisbon).
```

When does this approach fail?

# Depth-First Search

Adapted solution with an accumulator to avoid loops

```
connected(porto, lisbon).
connected(lisbon, madrid).
connected(lisbon, paris).
connected(lisbon, porto).
connected(madrid, paris).
connected(madrid, lisbon).
connected(paris, madrid).
connected(paris, lisbon).
```

```
connects_dfs(S, F):-
        connects_dfs(S, F, [S]).

connects_dfs(F, F, _Path).
connects_dfs(S, F, T):-
        connected(S, N),
        not( member(N, T) ),
        connects_dfs(N, F, [N|T]).
```

What would we have to change to *return* the connecting path (route)?

#### Breadth-First Search

• We can also easily create a BFS solution using findall

```
connected(porto, lisbon).
connected(lisbon, madrid).
connected(lisbon, paris).
connected(lisbon, porto).
connected(madrid, paris).
connected(madrid, lisbon).
connected(paris, madrid).
connected(paris, lisbon).
```

```
connects_bfs(S, F):-
    connects_bfs([S], F, [S]).

connects_bfs([F|_], F, _V).
connects_bfs([S|R], F, V):-
    findall(N,
        (connected(S, N),
            not(member(N, V)),
            not(member(N, [S|R]))), L),
    append(R, L, NR),
    connects_bfs(NR, F, [S|V]).
```

What would we have to change to return the connecting path (route)?

#### Games and Puzzles

- Prolog (and search) can easily be used to search for a solution to one-person games or puzzles
- States represented as the nodes of the graph
  - Initial state is the starting node
  - Winning conditions define the final nodes
- Movements represented as the transitions between nodes
  - States don't need to be represented in extension transitions can specify new states based on the previous one and the move made

#### Generic Solver

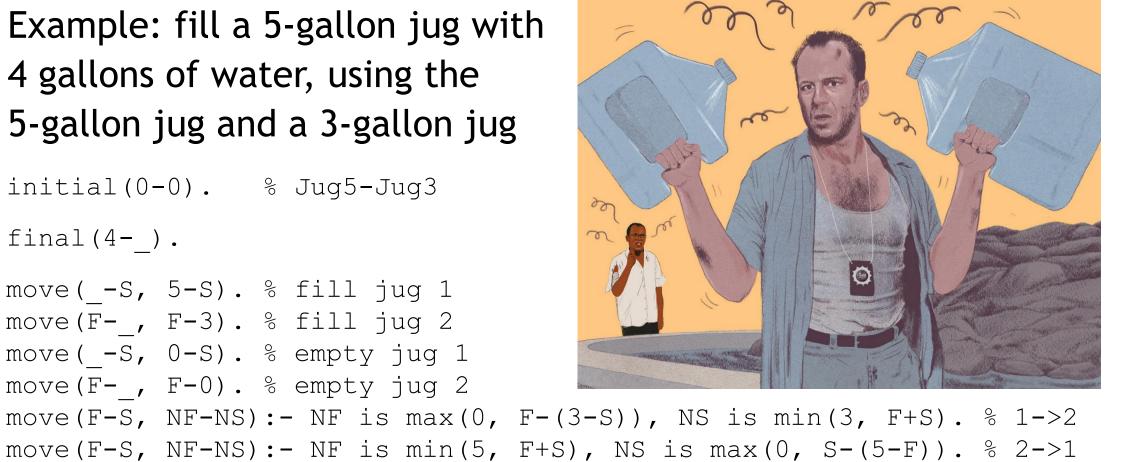
A generic [abstract] solver to one-person games/puzzles

```
initial (Initial State).
final(State): - winning condition(State).
move (OldState, NewState): - valid move (OldState, NewState).
play:- initial(Init),
         play(Init, [Init], States),
         reverse (States, Path), write (Path).
play(Curr, Path, Path):- final(Curr), !.
play(Curr, Path, States):- move(Curr, Next),
                               not ( member (Next, Path) ),
                               play(Next, [Next|Path], States).
```

#### Games and Puzzles

 Example: fill a 5-gallon jug with 4 gallons of water, using the 5-gallon jug and a 3-gallon jug

```
initial (0-0). % Juq5-Juq3
final(4-).
move(-S, 5-S). % fill jug 1
move (F-, F-3). % fill jug 2
move(-S, 0-S). % empty jug 1
move (F-, F-0). % empty jug 2
```



#### **Shortest Path**

- To find the smallest set of plays we just need to find all paths and select the shortest one
  - Easily accomplished using setof

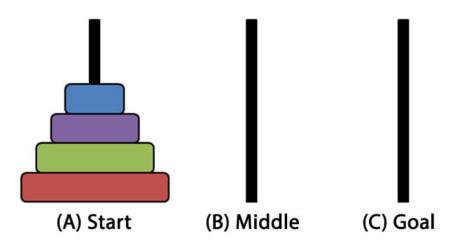
Is DFS the best way of doing this?

What if we wanted the path with the lowest cost?

How could we obtain all paths with shortest length?

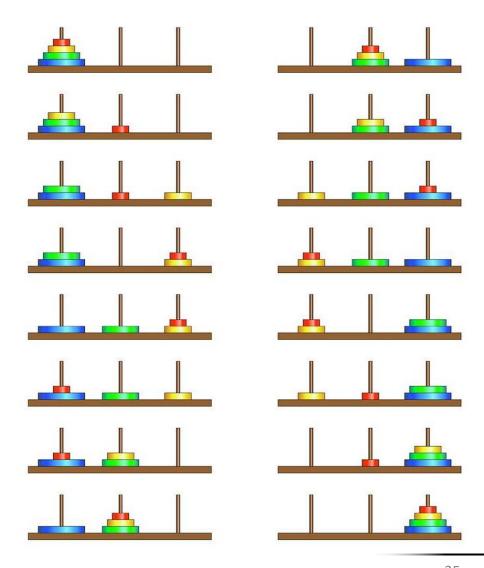
#### Games and Memoization

- Example: Tower of Hanoi
  - Goal: move stack from pole 1 to pole 3
  - Rules:
    - Can only move one disk at a time
    - Disks can only be placed on top of a larger disk

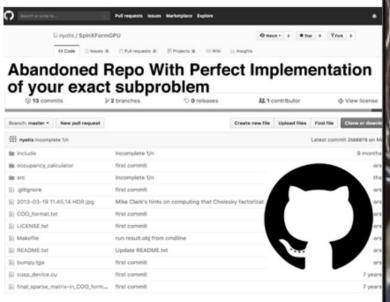


#### Games and Memoization

• To move a stack of size N from pole 1 to pole 3, first move stack of size N-1 to pole 2, move base piece, and then move N-1 stack from pole 2 to pole 3



Q & A



# But it is written in Prolog

