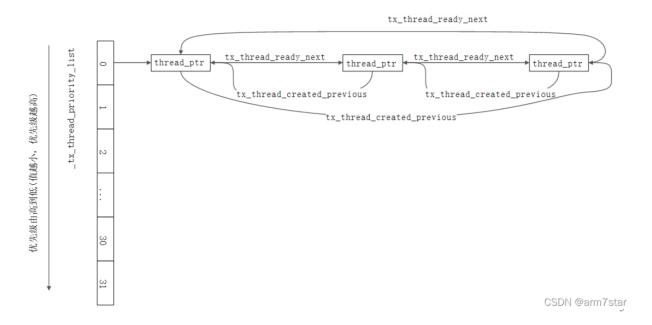
(163条消息) ThreadX内核源码分析 - 优先级及抢占阈值抢 占(arm) arm7star的博客-CSDN博客 threadx 优先级位图

blog.csdn.net/arm7star/article/details/123001013

1、就绪线程链表_tx_thread_priority_list

优先级越高值越低,同优先级线程按先进先出加入就绪线程链表,正在执行的线程始终在 就绪线程链表的表头(线程调度时不会从就绪线程链表删除)。



2、抢占阈值threshold

线程的抢占阈值大于线程的优先级时,表示线程启用了抢占,也就是该线程可以抢占同优 先级线程以及优先级比该线程抢占阈值低的线程; 内核保证抢占阈值不会小于线程优先 级,否则抢占阈值是错误的,因此只要抢占阈值不等与线程优先级就表示抢占阈值高于线 程优先级;

没有启用抢占的线程按优先级及时间片调度,抢占阈值只对启用了抢占的线程正在执行时 以及恢复执行时起作用:

• 启用抢占的线程正在执行时,如果时间片用尽或者有高优先级线程就绪,那么下一个 可能需要调度的线程的优先级必须高于当前正在执行的线程的抢占阈值,被抢占时需 要在 tx thread preempted maps标记被抢占的线程(对应优先级位设置为1即可), 否则正在执行的线程抢占高优先级线程及同优先级线程继续执行;这里也就是抢占阈 值对正在执行的线程有作用,不会判断被唤醒线程的抢占阈值是否高于正在执行线程 的优先级及抢占阈值;

• 高优先级线程退出,高优先级就绪线程链表变为空(如果同优先级线程有就绪线程,那么同优先级就绪线程的优先级仍然高于被抢占的启用了抢占阈值线程的抢占阈值),需要调度下一个高优先级就绪线程链表线程时,下一个高优先级的优先级可能高于当前退出线程的优先级也可能低于当前退出线程的优先级(正在执行线程启用了抢占,有高优先级线程在等待执行,或者没有高优先级线程就绪),不管哪种情况,被抢占的启用了抢占的线程的抢占阈值都可能高于下一个需要调度的线程的优先级,如果有被抢占的启用了抢占的线程的抢占阈值高于下一个高优先级就绪线程,那么优先恢复启用了抢占被抢占出去的线程;这也就是为什么启用了抢占的线程被抢占的时候要在_tx_thread_preempted_maps里面标记了,也就是抢占阈值在被抢占线程在恢复执行时起作用的原因。

也可以以另外一种方式理解,可能更容易理解,线程被执行时,该线程的优先级就等于线程的抢占阈值threshold,该线程并没有加到threshold对应就绪线程链表,该线程被抢占出去的时候,下次并不能在threshold对应优先级链表找到,因此需要通过_tx_thread_preempted_maps找到threshold对应优先级线程,可以理解_tx_thread_preempted_maps就是一个临时的就绪线程链表,内核有两个就绪线程链表,调度线程时需要检查两个就绪线程链表而已。

3、抢占位图_tx_thread_preempted_maps

启用抢占的线程一定意义上是以threshold优先级在执行,被抢占时,threshold对应优先级链表找不到被抢占的线程,借助_tx_thread_preempted_maps来找到threshold优先级的线程;

启用抢占的正在执行的线程被抢占时,_tx_thread_preempted_maps对应优先级位设置为 1,通过优先级找到线程的控制块,通过控制块找到线程的threshold,threshold也就是该 线程执行时的动态优先级,有高优先级退出时,要检查threshold是否可以抢占其他就绪线 程。

需要特别理解的是,_tx_thread_preempted_maps高优先级线程的优先级一定高于低优先级抢占阈值,把_tx_thread_preempted_maps当作就绪线程链表,那么可以理解_tx_thread_preempted_maps是按优先级排序的;启用抢占的高优先级线程被抢占的前提是高优先级线程需要执行,而执行的前提是,高优先级线程的优先级不能被_tx_thread_preempted_maps里面的线程的抢占阈值抢占,也就是高优先级线程的优先级高于_tx_thread_preempted_maps里面线程的抢占阈值,自然而然_tx_thread_preempted_maps高优先级线程的抢占阈值也高于_tx_thread_preempted_maps低优先级线程的抢占阈值。

4、优先级抢占

之前介绍时间片的时候介绍过启用抢占的线程时间片用尽时不会调度同优先级的下一个就 绪线程,在此略过;内核只有在线程唤醒时,才可能导致当前执行线程的优先级不是最高 的情况,因此,抢占只可能发生在线程唤醒时。

主要实现代码在_tx_thread_system_resume函数里面,_tx_thread_system_resume主要过程是:

• 去激活线程的定时器(这些定时器主要也是用来唤醒线程的,线程已经唤醒就不需要这些定时器了)

- 线程状态检查,多线程对同一个线程进行唤醒操作或者线程本来就不是挂起状态,对线程进行唤醒并不能真正唤醒线程
- 对唤醒线程检查是否可以抢占正在执行的线程,可以抢占的话,如果被抢占的线程已经启用了抢占,那么还得标记一下被抢占的线程,设置下一个执行的线程,返回系统,系统调度下一个需要执行的线程,否则加到就绪线程链表即可

tx_thread_system_resume代码实现如下:

```
1. 081 VOID _tx_thread_system_resume(TX_THREAD *thread_ptr)
2. 082 #ifndef TX_NOT_INTERRUPTABLE
3. 083 {
4. 084
5. 085 TX_INTERRUPT_SAVE_AREA
6. 086
7. 087 UINT
              priority;
8. 088 ULONG
                     priority_bit;
9. 089 TX_THREAD
                      *head_ptr;
10. 090 TX_THREAD
                      *tail_ptr;
11. 091 TX THREAD *execute ptr;
12. 092 TX_THREAD
                     *current_thread;
13. 093 ULONG
                     combined_flags;
14. 094
15. 095 #ifdef TX_ENABLE_EVENT_TRACE
16. 096 TX_TRACE_BUFFER_ENTRY
                                 *entry_ptr;
17. 097 ULONG
                                  time_stamp = ((ULONG) 0);
18. 098 #endif
19. 099
20. 100 #if TX_MAX_PRIORITIES > 32
21. 101 UINT
               map_index;
22. 102 #endif
23. 103
24. 104
25. 105 #ifdef TX_ENABLE_STACK_CHECKING
26. 106
27. 107 /* Check this thread's stack. */
       TX_THREAD_STACK_CHECK(thread_ptr)
28. 108
29. 109 #endif
30. 110
31. 111
        /* Lockout interrupts while the thread is being resumed. */
```

```
33. 113
34. 114 #ifndef TX NO TIMER
35. 115
36. 116
         /* Deactivate the timeout timer if necessary. */
37. 117
         if (thread ptr -> tx thread timer.tx timer internal list head != TX NULL) //
   tx timer internal list head指向超时链表表头,激活的定时器应该都会挂载到
   _tx_timer_list对应的超时定时器链表里面,如果tx_timer_internal_list_head为空,则说明
   定时器不在链表里面,也就是没有激活,否则定时器已经激活;ThreadX内核主要用这个定时器
   来唤醒线程, sleep/timeout等作用, 既然这里唤醒线程, 那么对应的定时器就不需要了, if分
   支就是去激活定时器,从超时定时器链表删除
38. 118
39. 119
40. 120
             /* Deactivate the thread's timeout timer. */
41. 121
             _tx_timer_system_deactivate(&(thread_ptr -> tx_thread_timer));        // 去激活
   线程超时定时器(与else分支比较, tx timer system deactivate没有清除
   tx timer internal remaining ticks; Nucleus Plus内核在发送信号给阻塞线程的时候,并不
   会停止线程的定时器,信号处理比较紧急,Nucleus Plus内核会暂时唤醒线程来处理信号,等信
   号处理完成后,线程仍然需要回到阻塞状态,等待定时器超时唤醒线程,因此Nucleus Plus内核
   的阻塞超时定时器并不会因为信号唤醒线程而停止)
42. 122
         }
43. 123
         else
44, 124
         {
45, 125
46. 126
             /* Clear the remaining time to ensure timer doesn't get activated. */
             thread_ptr -> tx_thread_timer.tx_timer_internal_remaining_ticks =
47. 127
   ((ULONG) 0); // tx timer internal remaining ticks设置为0,确保不会获取到定时器激活状
   态(没有超时时间挂起线程的定时器的tx timer internal remaining ticks为
   TX_WAIT_FOREVER, 该线程是不会激活定时器的, 不会挂载到超时定时器链表)
48. 128
49. 129 #endif
50. 130
51. 131 #ifdef TX ENABLE EVENT TRACE
52. 132
         /* If trace is enabled, save the current event pointer. */
53. 133
54. 134
         entry_ptr = _tx_trace_buffer_current_ptr;
55. 135 #endif
```

56. 136

TX DISABLE

```
57. 137
          /* Log the thread status change. */
          TX_TRACE_IN_LINE_INSERT(TX_TRACE_THREAD_RESUME, thread_ptr, thread_ptr ->
58. 138
   tx_thread_state, TX_POINTER_TO_ULONG_CONVERT(&execute_ptr),
   TX POINTER TO ULONG CONVERT( tx thread execute ptr), TX TRACE INTERNAL EVENTS)
59. 139
60. 140 #ifdef TX ENABLE EVENT TRACE
61, 141
62. 142
          /* Save the time stamp for later comparison to verify that
63. 143
             the event hasn't been overwritten by the time we have
64. 144
             computed the next thread to execute. */
65. 145
          if (entry_ptr != TX_NULL)
66. 146
          {
67. 147
68. 148
              /* Save time stamp. */
69. 149
              time stamp = entry ptr -> tx trace buffer entry time stamp;
70. 150
          }
71. 151 #endif
72. 152
73. 153
         /* Decrease the preempt disabled count. */
74. 154
          _tx_thread_preempt_disable--; // 禁止抢占计数器_tx_thread_preempt_disable减
   1( tx thread system resume进入前,已经禁止抢占了,但是中断还是开着的,如果不禁止抢
   占,那么唤醒过程就可能被抢占,唤醒过程就不能及时处理;这里虽然允许抢占了,但是中断还
   是关着的)
75. 155
76. 156
           /* Determine if the thread is in the process of suspending. If so, the
   thread
77. 157
             control block is already on the linked list so nothing needs to be done.
   */
78. 158
           if (thread_ptr -> tx_thread_suspending == TX_FALSE) // 唤醒非挂起过程中的线
   程(挂起中的线程被没有被真正挂起,还在就绪线程链表里面;真正被挂起的线程已经不在就绪
   线程链表里面,需要重新加入就绪线程链表)
79. 159
          {
80. 160
81. 161
              /* Thread is not in the process of suspending. Now check to make sure
   the thread
82. 162
                 has not already been resumed. */
```

```
(一般调用唤醒函数前都会对禁止抢占计数器加1,然后打开中断,虽然唤醒期间不会被抢占,但
    是不能保证中断服务程序不会唤醒线程,例如驱动中断服务程序的信号量就会唤醒等待信号量的
    线程)
84. 164
              {
85. 165
                  /* No, now check to see if the delayed suspension flag is set. */
86, 166
                  if (thread ptr -> tx thread delayed suspend == TX FALSE) // 非延迟挂
87. 167
    起状态(挂起一个非就绪/非挂起的线程,会设置tx thread delayed suspend,
    tx thread delayed suspend也就是有个挂起操作由于线程处于等待信号量或者其他状态而没能
    立即被挂起,需要等线程唤醒后再挂起,也就是当前函数 tx thread system resume后面会使线
    程进入挂起状态)
88. 168
                  {
89. 169
90.170
                     /* Resume the thread! */
91. 171
92. 172
                     /* Make this thread ready. */
93. 173
94. 174
                     /* Change the state to ready. */
95. 175
                     thread ptr -> tx thread state = TX READY; // 线程状态变为就绪状
    态
96. 176
97. 177
                     /* Pickup priority of thread. */
98. 178
                     priority = thread_ptr -> tx_thread_priority;
99. 179
100. 180
                     /* Thread state change. */
101. 181
                     TX_THREAD_STATE_CHANGE(thread_ptr, TX_READY)
102. 182
103. 183
                     /* Log the thread status change. */
104. 184
                     TX_EL_THREAD_STATUS_CHANGE_INSERT(thread_ptr, TX_READY)
105. 185
106. 186 #ifdef TX_THREAD_ENABLE_PERFORMANCE_INFO
107. 187
108. 188
                     /* Increment the total number of thread resumptions. */
109. 189
                     _tx_thread_performance_resume_count++;
110. 190
```

if (thread_ptr -> tx_thread_state != TX_READY) // 检查线程是否已经被唤醒

```
111. 191
                      /* Increment this thread's resume count. */
112. 192
                      thread_ptr -> tx_thread_performance_resume_count++;
113. 193 #endif
114. 194
115. 195
                     /* Determine if there are other threads at this priority that
    are
116, 196
                        ready. */
117. 197
                      head_ptr = _tx_thread_priority_list[priority]; // 线程所在就绪
    线程链表
118. 198
                      if (head ptr == TX NULL) // 被唤醒线程的就绪线程链表没有其他就绪
    线程,那么就要一个先优先级的线程就绪,可能存在墙正在;如果过该优先级有其他其他就绪线
    程,被唤醒线程加到就绪线程链表末尾即可(内核调度的要么是当前优先级的第一个就绪线程或
    者更高优先级线程,当前被唤醒的线程怎么也不可能抢占线程被唤醒前的就绪线程)
119. 199
                      {
120. 200
121. 201
                        /* First thread at this priority ready. Add to the front of
   the list. */
122. 202
                         _tx_thread_priority_list[priority] =
                                                              thread ptr; // 该
    优先级的就绪线程链表(就只有当前被唤醒线程)
123. 203
                         thread ptr -> tx thread ready next =
                                                          thread ptr;
124. 204
                         thread ptr -> tx thread ready previous = thread ptr;
125. 205
126. 206 #if TX MAX PRIORITIES > 32
127. 207
128. 208
                         /* Calculate the index into the bit map array. */
129. 209
                         map_index = priority/((UINT) 32);
130. 210
131. 211
                         /* Set the active bit to remember that the priority map has
    something set. */
132. 212
                         TX_DIV32_BIT_SET(priority, priority_bit)
133, 213
                         _tx_thread_priority_map_active =
    _tx_thread_priority_map_active | priority_bit;
134. 214 #endif
135. 215
136. 216
                         /* Or in the thread's priority bit. */
137. 217
                         TX_MOD32_BIT_SET(priority, priority_bit)
```

```
_tx_thread_priority_maps[MAP_INDEX] | priority_bit; // _tx_thread_priority_maps中,
    priority优先级对应的bit位设置为1,表示该优先级有就绪线程
139. 219
140. 220
                        /* Determine if this newly ready thread is the highest
    priority. */
                        if (priority < _tx_thread_highest_priority) // 被唤醒线程的
141. 221
    优先级高于被唤醒前的就绪线程的最高优先级
142. 222
                        {
143, 223
144. 224
                           /* A new highest priority thread is present. */
145. 225
146, 226
                           /* Update the highest priority variable. */
147, 227
                           _tx_thread_highest_priority = priority; // 更新就绪线程
    的最高优先级
148, 228
149, 229
                           /* Pickup the execute pointer. Since it is going to be
    referenced multiple
150, 230
                              times, it is placed in a local variable. */
151. 231
                            execute_ptr = _tx_thread_execute_ptr; // 获取
    tx thread execute ptr( tx thread execute ptr不一定是当前正在执行的线程,
    _tx_thread_execute_ptr只是调度程序选出来的下一个应该要执行的线程,优先级高或者抢占阈
    值高,但是因为禁止抢占等原因, tx thread execute ptr并不能立即执行或者还没来得及执
    行)
152. 232
153. 233
                           /* Determine if no thread is currently executing. */
154. 234
                            if (execute_ptr == TX_NULL) // _tx_thread_execute_ptr为0
    的话,表示之前没有就绪线程(当前唤醒操作可能是在中断服务程序里面执行),那么当前线程就
    是下一个需要调度的线程
155. 235
                            {
156. 236
157, 237
                               /* Simply setup the execute pointer. */
158, 238
                               _tx_thread_execute_ptr = thread_ptr; // 设置被唤醒
    的线程为执行线程
159. 239
                           }
160. 240
                           else // 虽然被唤醒线程优先级高,但是被唤醒前调度器正要执
    行_tx_thread_execute_ptr线程,由于抢占阈值,被唤醒线程还得检查_tx_thread_execute_ptr
    是否启用了抢占,如果_tx_thread_execute_ptr启用了抢占,如果_tx_thread_execute_ptr抢占
```

优先级高于被唤醒线程优先级,那么正在执行的_tx_thread_execute_ptr抢占被唤醒的高优先级

_tx_thread_priority_maps[MAP_INDEX] =

138. 218

线程...

```
161. 241
162. 242
163. 243
                                /* Another thread has been scheduled for execution.
    */
164. 244
165. 245
                                /* Check to see if this is a higher priority thread
    and determine if preemption is allowed. */
166. 246
                                if (priority < execute_ptr ->
    tx_thread_preempt_threshold) // 正在执行的线程不能抢占被唤醒的线程
167, 247
                                {
168, 248
169. 249 #ifndef TX DISABLE PREEMPTION THRESHOLD
170. 250
171. 251
                                    /* Determine if the preempted thread had
    preemption-threshold set. */
172. 252
                                    if (execute_ptr -> tx_thread_preempt_threshold
    != execute_ptr -> tx_thread_priority) // 如果正在执行的线程启用了抢占, 启用了抢占的
    线程正在执行时,被抢占而换出cpu的话,那么需要标记一下,如果有高优先级线程退出的话,
    尽量尽快恢复被抢占的低优先级线程(ThreadX内核抢占阈值并不是在任何时候都有用,而是线程
    正在执行时以及恢复执行时才有用,线程创建及唤醒时,都是添加到就绪线程链表末尾,并不会
    用抢占阈值去抢占高优先级线程)
173. 253
                                    {
174. 254
175. 255 #if TX_MAX_PRIORITIES > 32
176. 256
177. 257
                                       /* Calculate the index into the bit map
    array. */
178. 258
                                       map_index = (execute_ptr ->
    tx thread priority)/((UINT) 32);
179. 259
180. 260
                                       /* Set the active bit to remember that the
    preempt map has something set. */
181. 261
                                       TX_DIV32_BIT_SET(execute_ptr ->
    tx_thread_priority, priority_bit)
182. 262
                                        _tx_thread_preempted_map_active =
    _tx_thread_preempted_map_active | priority_bit;
183. 263 #endif
184. 264
```

```
by a thread above the thread's threshold.
186. 266
                                      TX_MOD32_BIT_SET(execute_ptr ->
    tx thread_priority, priority_bit)
187. 267
                                      _tx_thread_preempted_maps[MAP_INDEX] =
    tx thread preempted maps[MAP INDEX] | priority bit; // 设置启用了抢占的被抢占的线程
    的优先级在 tx thread preempted map active的对应bit位(被抢占出去的正在执行的线程还在
    就绪线程链表的表头,找到该优先级的就绪线程链表即可找到被抢占的线程;
    _tx_thread_preempted_map_active后续是从高优先级到低优先级来检查是否可以抢占最高优先
    级线程的,如果某个高优先级线程退出了,那么会检查 tx thread preempted map active标记
    的被抢占切换出去的线程的抢占阈值是否可以抢占下一个高优先级的线程; 为什么要从高优先级
    开始检查呢,因为 tx thread preempted map active标记的高优先级线程的抢占阈值一定高于
    tx thread preempted map active标记的低优先级线程的抢占阈值,
    _tx_thread_preempted_map_active高优先级线程要被标记的前提是该线程要在执行时被高优先
    级线程抢占, 而高优先级线程要执行的前提是不能被 tx thread preempted map active标记的
    低优先级线程抢占)
188. 268
                                   }
189. 269 #endif
190. 270
191. 271 #ifdef TX THREAD ENABLE PERFORMANCE INFO
192. 272
193, 273
                                   /* Determine if the caller is an interrupt or
    from a thread. */
194. 274
                                   if (TX THREAD GET SYSTEM STATE() == ((ULONG) 0))
195, 275
                                   {
196. 276
197, 277
                                      /* Caller is a thread, so this is a
    solicited preemption. */
198. 278
    _tx_thread_performance_solicited_preemption_count++;
199. 279
                                      /* Increment the thread's solicited
200. 280
    preemption counter. */
201. 281
                                      execute ptr ->
    tx thread performance solicited preemption count++;
202. 282
                                   }
203. 283
                                   else
204. 284
                                   {
205. 285
206. 286
                                      if (TX_THREAD_GET_SYSTEM_STATE() <</pre>
    TX_INITIALIZE_IN_PROGRESS)
```

/* Remember that this thread was preempted

```
207. 287
208. 288
209. 289
                                               /* Caller is an interrupt, so this is an
    interrupt preemption. */
210. 290
    tx thread performance interrupt preemption count++;
211, 291
212, 292
                                               /* Increment the thread's interrupt
    preemption counter. */
213, 293
                                               execute ptr ->
    tx thread performance interrupt preemption count++;
214. 294
                                            }
215, 295
                                        }
216. 296
217. 297
                                        /* Remember the thread that preempted this
    thread. */
218. 298
                                        execute_ptr ->
    tx_thread_performance_last_preempting_thread = thread_ptr;
219. 299
220. 300 #endif
221. 301
222. 302
                                       /* Yes, modify the execute thread pointer. */
223. 303
                                        _tx_thread_execute_ptr = thread_ptr; // 被唤醒
    线程的优先级最高,并且正在执行的线程不能抢占被唤醒的线程,设置被唤醒线程为执行线程
224. 304
225. 305 #ifndef TX_MISRA_ENABLE
226. 306
                                        /* If MISRA is not-enabled, insert a preemption
    and return in-line for performance. */
228. 308
229. 309 #ifdef TX THREAD ENABLE PERFORMANCE INFO
230. 310
231. 311
                                        /* Is the execute pointer different? */
232. 312
                                        if
    (_tx_thread_performance_execute_log[_tx_thread_performance__execute_log_index] !=
    _tx_thread_execute_ptr)
233. 313
                                        {
```

```
234. 314
235. 315
                                             /* Move to next entry. */
236. 316
                                             _tx_thread_performance__execute_log_index++;
237. 317
238. 318
                                             /* Check for wrap condition. */
239. 319
                                             if
     (_tx_thread_performance__execute_log_index >= TX_THREAD_EXECUTE_LOG_SIZE)
240. 320
                                              {
241. 321
242. 322
                                                 /* Set the index to the beginning. */
243. 323
    tx thread performance execute log index = ((UINT) 0);
244. 324
                                              }
245. 325
246. 326
                                             /* Log the new execute pointer. */
247. 327
    _tx_thread_performance_execute_log[_tx_thread_performance__execute_log_index] =
    tx thread execute ptr;
248. 328
                                         }
249. 329 #endif
250. 330
251. 331 #ifdef TX ENABLE EVENT TRACE
252. 332
253. 333
                                         /* Check that the event time stamp is unchanged.
     A different
254. 334
                                            timestamp means that a later event wrote over
     the thread
255. 335
                                             resume event. In that case, do nothing here.
     */
256. 336
                                         if (entry_ptr != TX_NULL)
257. 337
                                         {
258. 338
259. 339
                                             /* Is the timestamp the same? */
260. 340
                                             if (time_stamp == entry_ptr ->
     tx_trace_buffer_entry_time_stamp)
261. 341
                                              {
```

```
263. 343
                                               /* Timestamp is the same, set the "next
    thread pointer" to NULL. This can
264. 344
                                                  be used by the trace analysis tool to
    show idle system conditions. */
265. 345
                                               entry ptr ->
    tx trace buffer entry information field 4 =
    TX POINTER TO ULONG CONVERT( tx thread execute ptr);
266. 346
                                           }
267. 347
                                       }
268. 348 #endif
269. 349
270. 350
                                       /* Restore interrupts. */
271. 351
                                       TX RESTORE // 开中断
272. 352
273. 353 #ifdef TX ENABLE STACK CHECKING
274. 354
275. 355
                                       /* Pickup the next execute pointer. */
                                       thread_ptr = _tx_thread_execute_ptr;
276. 356
277. 357
278. 358
                                       /* Check this thread's stack. */
279. 359
                                       TX THREAD STACK CHECK(thread ptr)
280. 360 #endif
281. 361
                                       /* Now determine if preemption should take
    place. This is only possible if the current thread pointer is
                                          not the same as the execute thread pointer
    AND the system state and preempt disable flags are clear. */
284. 364
                                       TX_THREAD_SYSTEM_RETURN_CHECK(combined_flags) //
    检查_tx_thread_preempt_disable是否禁止抢占以及是否在系统初始化阶段(禁止抢占或者还在
    系统初始化阶段,还得继续执行当前线程,不能进行线程切换)
285. 365
                                       if (combined_flags == ((ULONG) 0))
286. 366
                                       {
287. 367
288. 368 #ifdef TX_THREAD_ENABLE_PERFORMANCE_INFO
```

```
290. 370
                                        /* There is another thread ready to run and
    will be scheduled upon return. */
291. 371
    _tx_thread_performance_non_idle_return count++;
292. 372 #endif
293. 373
294, 374
                                        /* Preemption is needed - return to the
    system! */
295. 375
                                         _tx_thread_system_return(); // 非系统初始化
    阶段也没有禁止抢占,返回系统执行调度程序,调度被唤醒线程_tx_thread_execute_ptr
296. 376
                                     }
297. 377
298. 378
                                     /* Return in-line when MISRA is not enabled. */
299. 379
                                     return;
300. 380 #endif
301. 381
                                 }
302. 382
                              }
303. 383
                          }
304. 384
                      }
                      else // 被唤醒线程优先级所在就绪线程链表不为空,将被唤醒线程加入
305. 385
    就绪线程链表即可(从下面代码可以看到线程加入的就绪线程链表末尾,也就是就绪线程链表是
    先进先出的,并不会因为抢占阈值而改变顺序)
306.386
                      {
307. 387
308.388
                          /* No, there are other threads at this priority already
    ready. */
309. 389
310. 390
                          /* Just add this thread to the priority list. */
311. 391
                          tail_ptr =
                                                                 head_ptr ->
    tx_thread_ready_previous;
312. 392
                          tail_ptr -> tx_thread_ready_next =
                                                                 thread_ptr;
313. 393
                          head_ptr -> tx_thread_ready_previous =
                                                                 thread_ptr;
314. 394
                          thread_ptr -> tx_thread_ready_previous =
                                                                 tail_ptr;
315. 395
                          thread_ptr -> tx_thread_ready_next =
                                                                 head_ptr;
316. 396
                      }
```

}

```
319. 399
                 /* Else, delayed suspend flag was set. */
320. 400
                 else // 延迟挂起标志位被设置, 执行未执行完的挂起操作即可(例如线程等
    待互斥锁进入阻塞状态,别的线程调用挂起操作试图挂起等待互斥锁的线程,那么就会将阻塞的
    线程设置为等待挂起状态,阻塞的线程等到互斥锁后被唤醒,这里的else分支就会继续被挂起,
    不会真正唤醒线程,只是状态从阻塞变为挂起状态而已)
321, 401
                 {
322. 402
323. 403
                     /* Clear the delayed suspend flag and change the state. */
324, 404
                     thread ptr -> tx thread delayed suspend = TX FALSE;
325. 405
                     thread_ptr -> tx_thread_state =
                                                         TX SUSPENDED;
326. 406
                 }
327. 407
              }
328. 408
          }
329. 409
           else // tx thread suspending被设置,线程挂起前还没调用
    tx thread system suspend的时候会设置tx thread suspending,说明有其他挂起操作还在进
    行中(tx thread suspending操作过程线程还没从就绪链表删除,另外线程结束时也调用挂起操
    作)
330. 410
          {
331. 411
332. 412
             /* A resumption occurred in the middle of a previous thread suspension.
    */
333. 413
334. 414
             /* Make sure the type of suspension under way is not a terminate or
335. 415
                thread completion. In either of these cases, do not void the
336. 416
                interrupted suspension processing. */
337. 417
              if (thread_ptr -> tx_thread_state != TX_COMPLETED) // 检查线程是否处于
    TX COMPLETED状态,线程是否已经结束,如果线程结束了,那么不需要唤醒线程
338. 418
              {
339. 419
                 /* Make sure the thread isn't terminated. */
340. 420
                 if (thread_ptr -> tx_thread_state != TX_TERMINATED) // 检查线程是否
    被终止,线程终止了也不需要唤醒线程
342. 422
                 {
343. 423
344. 424
                     /* No, now check to see if the delayed suspension flag is set.
```

*/

```
345. 425
                        if (thread_ptr -> tx_thread_delayed_suspend == TX_FALSE)
346. 426
                        {
347. 427
348. 428
                            /* Clear the suspending flag. */
                            thread_ptr -> tx_thread_suspending = TX_FALSE;
349. 429
350. 430
351. 431
                            /* Restore the state to ready. */
352. 432
                            thread_ptr -> tx_thread_state =
                                                                TX READY;
353. 433
354. 434
                            /* Thread state change. */
355. 435
                            TX_THREAD_STATE_CHANGE(thread_ptr, TX_READY) // 唤醒线程(挂
    起中的线程没有从就绪链表删除,无需重新加入就绪链表)
356. 436
357. 437
                           /* Log the thread status change. */
                            TX_EL_THREAD_STATUS_CHANGE_INSERT(thread_ptr, TX_READY)
358. 438
359. 439
                        }
360. 440
                        else // tx_thread_suspending
361. 441
                        {
362. 442
363. 443
                            /* Clear the delayed suspend flag and change the state. */
364. 444
                            thread_ptr -> tx_thread_delayed_suspend = TX_FALSE;
365. 445
                            thread_ptr -> tx_thread_state = TX_SUSPENDED;
366. 446
                        }
367. 447
368. 448 #ifdef TX_THREAD_ENABLE_PERFORMANCE_INFO
369. 449
370. 450
                       /* Increment the total number of thread resumptions. */
                        _tx_thread_performance_resume_count++;
371. 451
372. 452
373. 453
                        /* Increment this thread's resume count. */
374. 454
                        thread_ptr -> tx_thread_performance_resume_count++;
375. 455 #endif
```

```
376. 456
                     }
377. 457
                 }
378. 458
             }
379. 459
380. 460 #ifdef TX THREAD ENABLE PERFORMANCE INFO
381. 461
382. 462
             /* Is the execute pointer different? */
383. 463
     (_tx_thread_performance_execute_log[_tx_thread_performance__execute_log_index] !=
     _tx_thread_execute_ptr)
384. 464
             {
385. 465
386. 466
                 /* Move to next entry. */
387. 467
                 _tx_thread_performance__execute_log_index++;
388. 468
389. 469
                 /* Check for wrap condition. */
390. 470
                 if (_tx_thread_performance__execute_log_index >=
     TX THREAD EXECUTE LOG SIZE)
391. 471
                 {
392. 472
393. 473
                     /* Set the index to the beginning. */
                     _tx_thread_performance__execute_log_index = ((UINT) 0);
394. 474
395. 475
                 }
396. 476
397. 477
                 /* Log the new execute pointer. */
398. 478
     _tx_thread_performance_execute_log[_tx_thread_performance__execute_log_index] =
     _tx_thread_execute_ptr;
399. 479
             }
400. 480 #endif
401. 481
402. 482 #ifdef TX_ENABLE_EVENT_TRACE
403. 483
404. 484
             /* Check that the event time stamp is unchanged. A different
```

```
405. 485
               timestamp means that a later event wrote over the thread
406. 486
                resume event. In that case, do nothing here. */
407. 487
            if (entry_ptr != TX_NULL)
408. 488
            {
409. 489
                /* Is the timestamp the same? */
410. 490
411. 491
                 if (time_stamp == entry_ptr -> tx_trace_buffer_entry_time_stamp)
412. 492
                {
413. 493
414. 494
                     /* Timestamp is the same, set the "next thread pointer" to NULL.
     This can
415. 495
                        be used by the trace analysis tool to show idle system
     conditions. */
416. 496 #ifdef TX MISRA ENABLE
417, 497
                     entry_ptr -> tx_trace_buffer_entry_info_4 =
     TX_POINTER_TO_ULONG_CONVERT(_tx_thread_execute_ptr);
418. 498 #else
419. 499
                     entry ptr -> tx trace buffer entry information field 4 =
     TX_POINTER_TO_ULONG_CONVERT(_tx_thread_execute_ptr);
420. 500 #endif
421. 501
               }
422. 502
            }
423. 503 #endif
424. 504
425. 505
           /* Pickup thread pointer. */
426. 506
            TX_THREAD_GET_CURRENT(current_thread)
427. 507
428. 508
            /* Restore interrupts. */
429. 509
            TX_RESTORE
430. 510
431. 511
           /* Determine if a preemption condition is present. */
432. 512
            if (current_thread != _tx_thread_execute_ptr)
433. 513
             {
434. 514
```

```
435. 515 #ifdef TX_ENABLE_STACK_CHECKING
436. 516
437. 517
               /* Pickup the next execute pointer. */
               thread_ptr = _tx_thread_execute_ptr;
438. 518
439. 519
               /* Check this thread's stack. */
440. 520
441. 521
          TX THREAD STACK CHECK(thread ptr)
442. 522 #endif
443. 523
                /* Now determine if preemption should take place. This is only possible
    if the current thread pointer is
                  not the same as the execute thread pointer AND the system state and
    preempt disable flags are clear. */
446. 526
               TX_THREAD_SYSTEM_RETURN_CHECK(combined_flags)
447. 527
          if (combined flags == ((ULONG) 0))
448. 528
              {
449. 529
450. 530 #ifdef TX THREAD ENABLE PERFORMANCE INFO
451. 531
452. 532
                  /* There is another thread ready to run and will be scheduled upon
    return. */
453. 533
                   _tx_thread_performance_non_idle_return_count++;
454. 534 #endif
455. 535
456. 536
                   /* Preemption is needed - return to the system! */
457. 537
                    _tx_thread_system_return();
458. 538 }
459. 539 }
460. 540 }
```

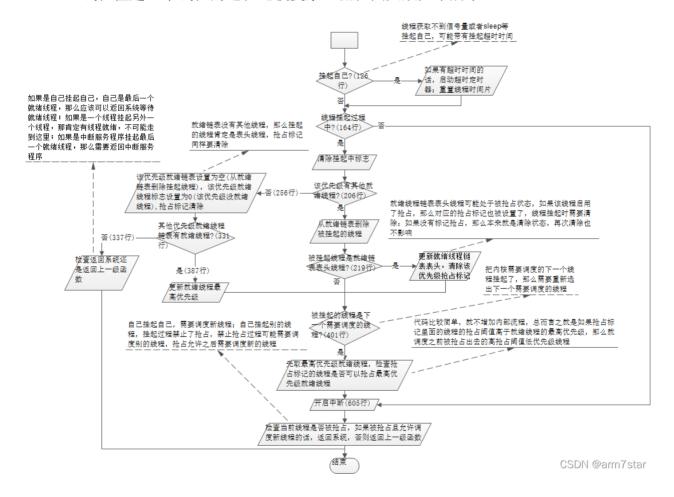
5.1、线程挂起过程恢复其他线程流程

阻塞/挂起线程恢复执行是在_tx_thread_system_resume里面实现的,前面已经介绍过了,这里只介绍就绪线程恢复执行:

就绪线程不能执行那么肯定有高优先级线程在执行或者同优先级线程还没执行完(时间片没有用尽,还没轮到自己执行),时间片用尽前面介绍过,后面介绍线程退出时恢复线程的过程;

线程退出时,正常情况选择下一个高优先级线程执行即可,但是ThreadX启用了抢占,多了一个检查抢占的过程,就绪线程的优先级还需要跟之前被抢占线程的抢占阈值比较,以便能够恢复被抢占的启用了抢占的线程,启用了抢占的被抢占的动态优先级等于抢占阈值,按优先级并不能找到,因此要在_tx_thread_preempted_maps里面找有没有高优先级(抢占阈值高)的线程就绪:

ThreadX线程挂起一个线程的过程比较复杂,流程图大致如下所示:



5.2、线程挂起时恢复其他线程代码

线程挂起代码如下:

```
1. 083 VOID _tx_thread_system_suspend(TX_THREAD *thread_ptr)
2. 084 #ifndef TX_NOT_INTERRUPTABLE
3. 085 {
4. 086
5. 087 TX_INTERRUPT_SAVE_AREA
6. 088
7. 089 UINT
             priority;
8. 090 UINT
                     base priority;
9. 091 ULONG
                     priority_map;
10. 092 ULONG
              priority_bit;
11. 093 ULONG
                 combined_flags;
12. 094 TX_THREAD
                      *ready_next;
13. 095 TX_THREAD
                     *ready_previous;
14. 096 TX THREAD *current thread;
15. 097
16. 098 #if TX_MAX_PRIORITIES > 32
17. 099 UINT
                     map index;
18. 100 #endif
19. 101
20. 102 #ifndef TX_NO_TIMER
21. 103 ULONG
                timeout;
22. 104 #endif
23. 105
24. 106 #ifdef TX_ENABLE_EVENT_TRACE
25. 107 TX_TRACE_BUFFER_ENTRY *entry_ptr;
26. 108 ULONG
                                  time_stamp = ((ULONG) 0);
27. 109 #endif
28. 110
29. 111 /* Pickup thread pointer. */
30. 112
         TX_THREAD_GET_CURRENT(current_thread)
31. 113
```

```
32. 114 #ifdef TX_ENABLE_STACK_CHECKING
33. 115
34. 116
          /* Check this thread's stack. */
35. 117
           TX_THREAD_STACK_CHECK(thread_ptr)
36. 118 #endif
37, 119
38. 120
           /* Lockout interrupts while the thread is being suspended. */
39. 121
           TX DISABLE
40. 122
41. 123 #ifndef TX NO TIMER
42. 124
43. 125
          /* Is the current thread suspending? */
44. 126
           if (thread_ptr == current_thread) // 挂起自己线程(可能是调用sleep或者等待信
   号量等导致的阻塞,可能需要超时唤醒)
45. 127
          {
46. 128
47. 129
              /* Pickup the wait option. */
48, 130
              timeout = thread ptr ->
   tx_thread_timer.tx_timer_internal_remaining_ticks; // 获取超时时间, sleep或者等待信
   号量前会设置好tx_timer_internal_remaining_ticks
49. 131
50. 132
              /* Determine if an activation is needed. */
51. 133
              if (timeout != TX_NO_WAIT) // TX_NO_WAIT表示不等待,不用启动定时器
52, 134
              {
53. 135
54. 136
                  /* Make sure the suspension is not a wait-forever. */
                  if (timeout != TX WAIT FOREVER) // TX WAIT FOREVER表示没有超时时间,
55. 137
   信号量等只有等到了才返回
56. 138
57. 139
58. 140
                      /* Activate the thread timer with the timeout value setup in the
   caller. */
59. 141
                      _tx_timer_system_activate(&(thread_ptr -> tx_thread_timer)); //
   激活超时定时器(挂载到超时定时器链表等)
60. 142
                  }
```

```
61. 143
               }
62. 144
63. 145
              /* Yes, reset time slice for current thread. */
64. 146
               _tx_timer_time_slice = thread_ptr -> tx_thread_new_time_slice; // 重置
   当前线程的时间片(后面保存线程上下文的时候会把_tx_timer_time_slice保存到线程里面,下
   次唤醒后以新的时间片调度)
65, 147
          }
66. 148 #endif
67. 149
68. 150
           /* Decrease the preempt disabled count. */
69. 151
           _tx_thread_preempt_disable--;
70. 152
71. 153 #ifdef TX THREAD ENABLE PERFORMANCE INFO
72. 154
73. 155
           /* Increment the thread's suspend count. */
74. 156
           thread ptr -> tx thread performance suspend count++;
75. 157
76. 158
           /* Increment the total number of thread suspensions. */
           _tx_thread_performance_suspend_count++;
77. 159
78. 160 #endif
79. 161
80. 162
          /* Check to make sure the thread suspending flag is still set. If not, it
81. 163
              has already been resumed. */
           if (thread_ptr -> tx_thread_suspending == TX_TRUE) // 挂起过程没被其他线程或
82. 164
   者中断服务程序唤醒
83. 165
           {
84. 166
85. 167
              /* Thread state change. */
86. 168
              TX THREAD STATE CHANGE(thread ptr, thread ptr -> tx thread state)
87. 169
88. 170
               /* Log the thread status change. */
89. 171
               TX_EL_THREAD_STATUS_CHANGE_INSERT(thread_ptr, thread_ptr ->
   tx_thread_state)
90. 172
```

```
91. 173 #ifdef TX_ENABLE_EVENT_TRACE
92. 174
93. 175
                /* If trace is enabled, save the current event pointer. */
94. 176
                entry_ptr = _tx_trace_buffer_current_ptr;
95. 177 #endif
96, 178
97. 179
                /* Log the thread status change. */
98. 180
                TX TRACE IN LINE INSERT(TX TRACE THREAD SUSPEND, thread ptr, thread ptr
     -> tx thread state, TX POINTER TO ULONG CONVERT(&priority),
    TX POINTER TO ULONG CONVERT( tx thread execute ptr), TX TRACE INTERNAL EVENTS)
99. 181
100. 182 #ifdef TX ENABLE EVENT TRACE
101. 183
102. 184
               /* Save the time stamp for later comparison to verify that
103. 185
                   the event hasn't been overwritten by the time we have
104. 186
                   computed the next thread to execute. */
105. 187
                if (entry_ptr != TX_NULL)
106. 188
                {
107. 189
108. 190
                    /* Save time stamp. */
109. 191
                    time_stamp = entry_ptr -> tx_trace_buffer_entry_time_stamp;
110. 192
                }
111. 193 #endif
112. 194
113. 195
               /* Actually suspend this thread. But first, clear the suspending flag.
     */
                thread_ptr -> tx_thread_suspending = TX_FALSE; // tx_thread_suspending
114. 196
     设置为TX_FALSE,这里已经关闭了中断,这个过程不会再被中断
115. 197
116. 198
                /* Pickup priority of thread. */
                priority = thread_ptr -> tx_thread_priority; // 被挂起线程的优先级
117. 199
118. 200
119. 201
                /* Pickup the next ready thread pointer. */
120. 202
                ready_next =
                                  thread_ptr -> tx_thread_ready_next;
```

```
121. 203
122. 204
              /* Determine if there are other threads at this priority that are
123. 205
                 ready. */
               if (ready_next != thread_ptr) // 被挂起线程的就绪线程链表有其他线程
124. 206
125. 207
               {
126. 208
127. 209
                   /* Yes, there are other threads at this priority ready. */
128. 210
                  /* Pickup the previous ready thread pointer. */
129. 211
130. 212
                  ready previous = thread ptr -> tx thread ready previous;
131. 213
132, 214
                   /* Just remove this thread from the priority list. */ // 接下来几行
    代码将挂起线程从就绪线程链表删除
133. 215
                   ready_next -> tx_thread_ready_previous = ready_previous;
134. 216
                  ready_previous -> tx_thread_ready_next = ready_next;
135. 217
136. 218
                  /* Determine if this is the head of the priority list. */
                   if (_tx_thread_priority_list[priority] == thread_ptr) // 检查被挂起
137, 219
    线程是不是就绪线程链表的表头线程(是的话,需要更新就绪线程链表表头)
138. 220
                   {
139. 221
140. 222
                      /* Update the head pointer of this priority list. */
141. 223
                      tx thread priority list[priority] = ready next; // 更新就绪线
    程链表表头
142. 224
143. 225 #ifndef TX DISABLE PREEMPTION THRESHOLD
144. 226
145. 227 #if TX_MAX_PRIORITIES > 32
146. 228
147. 229
                      /* Calculate the index into the bit map array. */
148. 230
                      map_index = priority/((UINT) 32);
149. 231 #endif
150. 232
```

```
/* Check for a thread preempted that had preemption threshold
    set. */
                       if (_tx_thread_preempted_maps[MAP_INDEX] != ((ULONG) 0)) // 前面
152. 234
    有介绍,线程被执行的时候,线程仍在就绪线程链表表头,如果 tx thread preempted maps被
    标记的话,需要清除该标记,因为现在的就绪线程链表的表头线程还没执行,不存在被抢占情况
153. 235
                       {
154, 236
155. 237
                          /* Ensure that this thread's priority is clear in the
    preempt map. */
156, 238
                          TX MOD32 BIT SET(priority, priority bit)
157. 239
                           tx thread preempted maps[MAP INDEX] =
    _tx_thread_preempted_maps[MAP_INDEX] & (~(priority_bit)); // 清除抢占标记
158, 240
159. 241 #if TX MAX PRIORITIES > 32
160. 242
161, 243
                          /* Determine if there are any other bits set in this preempt
    map.
162. 244
                          if ( tx thread preempted maps[MAP INDEX] == ((ULONG) 0))
163. 245
                           {
164. 246
165. 247
                              /* No, clear the active bit to signify this preempt map
    has nothing set. */
166. 248
                              TX_DIV32_BIT_SET(priority, priority_bit)
167. 249
                              _tx_thread_preempted_map_active =
    _tx_thread_preempted_map_active & (~(priority_bit));
168. 250
                           }
169. 251 #endif
170. 252
                       }
171. 253 #endif
172. 254
                   }
173. 255
               }
               else // 被挂起线程的下一个就绪线程指向自己(就绪线程链表里面没有其他线程
174. 256
    了)
175. 257
               {
176. 258
177. 259
                   /* This is the only thread at this priority ready to run. Set the
```

head

```
178. 260
                       pointer to NULL. */
                    _tx_thread_priority_list[priority] = TX_NULL; // 将被挂起线程的就
179. 261
    绪线程链表清空即可
180. 262
181. 263 #if TX MAX PRIORITIES > 32
182. 264
183. 265
                   /* Calculate the index into the bit map array. */
184. 266
                  map_index = priority/((UINT) 32);
185. 267 #endif
186. 268
187. 269
                  /* Clear this priority bit in the ready priority bit map. */
188. 270
                    TX MOD32 BIT SET(priority, priority bit)
189. 271
                    _tx_thread_priority_maps[MAP_INDEX] =
    _tx_thread_priority_maps[MAP_INDEX] & (~(priority_bit)); // 该优先级已经没有其他就绪
    线程了,清除对应的位
190. 272
191. 273 #if TX MAX PRIORITIES > 32
192. 274
193. 275
                   /* Determine if there are any other bits set in this priority map.
    */
194. 276
                    if ( tx thread priority maps[MAP INDEX] == ((ULONG) 0))
195. 277
                    {
196. 278
197. 279
                       /* No, clear the active bit to signify this priority map has
    nothing set. */
198. 280
                        TX_DIV32_BIT_SET(priority, priority_bit)
199. 281
                        _tx_thread_priority_map_active = _tx_thread_priority_map_active
    & (~(priority bit));
200. 282
                    }
201. 283 #endif
202. 284
203. 285 #ifndef TX_DISABLE_PREEMPTION_THRESHOLD
204. 286
205. 287
                   /* Check for a thread preempted that had preemption-threshold set.
```

*/

```
if (_tx_thread_preempted_maps[MAP_INDEX] != ((ULONG) 0)) //
206. 288
    _tx_thread_preempted_maps抢占标志位有被设置(不一定有标记被挂起的线程)
207. 289
                    {
208. 290
209. 291
                        /* Ensure that this thread's priority is clear in the preempt
         */
    map.
210, 292
                        TX_MOD32_BIT_SET(priority, priority_bit)
211, 293
                        _tx_thread_preempted_maps[MAP_INDEX] =
    _tx_thread_preempted_maps[MAP_INDEX] & (~(priority_bit)); // 清除被挂起线程优先级的
    抢占标记(被挂起线程有没有标记都要清除;有的话,线程已经挂起,没必要再调度)
212. 294
213. 295 #if TX_MAX_PRIORITIES > 32
214, 296
215. 297
                       /* Determine if there are any other bits set in this preempt
    map.
216. 298
                       if (_tx_thread_preempted_maps[MAP_INDEX] == ((ULONG) 0))
217. 299
                        {
218. 300
219. 301
                            /* No, clear the active bit to signify this preempted map
    has nothing set. */
220. 302
                           TX_DIV32_BIT_SET(priority, priority_bit)
221. 303
                           _tx_thread_preempted_map_active =
    _tx_thread_preempted_map_active & (~(priority_bit));
222. 304
                        }
223. 305 #endif
224. 306
                    }
225. 307 #endif
226. 308
227. 309 #if TX_MAX_PRIORITIES > 32
228. 310
229. 311
                    /* Calculate the index to find the next highest priority thread
    ready for execution. */
230. 312
                    priority_map = _tx_thread_priority_map_active;
231. 313
232. 314
                    /* Determine if there is anything.
233. 315
                   if (priority_map != ((ULONG) 0))
```

```
234. 316
235. 317
236. 318
                       /* Calculate the lowest bit set in the priority map. */
237. 319
                       TX_LOWEST_SET_BIT_CALCULATE(priority_map, map_index)
238. 320
                   }
239. 321
240. 322
                   /* Calculate the base priority as well. */
241. 323
                   base priority = map index * ((UINT) 32);
242. 324 #else
243. 325
244. 326
                   /* Setup the base priority to zero. */
245. 327
                   base_priority = ((UINT) 0);
246. 328 #endif
247. 329
248. 330
                    /* Setup working variable for the priority map. */
249. 331
                                    _tx_thread_priority_maps[MAP_INDEX]; // 检查是否有
                    priority_map =
    就绪线程(tx thread priority maps对应的位为1表示对应优先有就绪线程)
250. 332
251. 333
                   /* Make a quick check for no other threads ready for execution. */
252. 334
                   if (priority map == ((ULONG) 0)) // 没有就绪线程
253. 335
                    {
254. 336
255. 337
                       /* Nothing else is ready. Set highest priority and execute
    thread
256. 338
                          accordingly. */
257. 339
                        _tx_thread_highest_priority = ((UINT) TX_MAX_PRIORITIES); //最
    高就绪线程优先级TX_MAX_PRIORITIES
258. 340
                                                     TX_NULL; // 需要调度的线程
                       _tx_thread_execute_ptr =
    _tx_thread_execute_ptr设置为空,没有线程需要调度
259. 341
260. 342 #ifndef TX_MISRA_ENABLE
261. 343
262. 344 #ifdef TX_ENABLE_EVENT_TRACE
263. 345
```

```
264. 346
                        /* Check that the event time stamp is unchanged. A different
265. 347
                           timestamp means that a later event wrote over the thread
266. 348
                           suspend event. In that case, do nothing here. */
267. 349
                        if (entry_ptr != TX_NULL)
268. 350
                        {
269. 351
270. 352
                            /* Is the timestamp the same? */
271. 353
                            if (time stamp == entry ptr ->
    tx trace buffer entry time stamp)
272. 354
                            {
273. 355
274. 356
                                /* Timestamp is the same, set the "next thread pointer"
    to the new value of the
275. 357
                                   next thread to execute. This can be used by the trace
     analysis tool to keep
276. 358
                                   track of next thread execution. */
277. 359
                                entry_ptr -> tx_trace_buffer_entry_information_field_4 =
    0;
278. 360
                            }
279. 361
                        }
280. 362 #endif
281. 363
282. 364
                        /* Restore interrupts. */
283. 365
                        TX RESTORE
284. 366
                        /* Determine if preemption should take place. This is only
285. 367
    possible if the current thread pointer is
286. 368
                           not the same as the execute thread pointer AND the system
     state and preempt disable flags are clear. */
287. 369
                        TX THREAD SYSTEM RETURN CHECK(combined flags) //
     _tx_thread_preempt_disable等
288. 370
                        if (combined_flags == ((ULONG) 0)) // 检查是否禁止抢占是否在内核
     初始化过程,不是的话返回系统(没有就绪线程的话需要返回系统等待就绪线程)
289. 371
                        {
290. 372
291. 373 #ifdef TX THREAD ENABLE PERFORMANCE INFO
```

```
292. 374
293. 375
                          /* Yes, increment the return to idle return count. */
294. 376
                          _tx_thread_performance_idle_return_count++;
295. 377 #endif
296. 378
                         /* Preemption is needed - return to the system! */
297. 379
298. 380
                          tx thread system return(); // 返回系统等待就绪线程
299. 381
                      }
300. 382
301. 383
                      /* Return to caller. */
302. 384
                      return;
303. 385 #endif
304. 386
                  }
                  else // 有就绪线程
305. 387
306. 388
                   {
307. 389
308. 390
                      /* Other threads at different priority levels are ready to run.
    */
309.391
310. 392
                      /* Calculate the lowest bit set in the priority map. */
311. 393
                      TX_LOWEST_SET_BIT_CALCULATE(priority_map, priority_bit)
312. 394
313. 395
                      /* Setup the next highest priority variable. */
                      _tx_thread_highest_priority = base_priority + ((UINT)
314. 396
    priority_bit); // 更新就绪线程最高优先级(被挂起线程优先级所在就绪线程链表没有其他线
    程)
315. 397
                   }
316. 398
               }
317. 399
318. 400
              /* Determine if the suspending thread is the thread designated to
    execute. */
319. 401
              if (thread_ptr == _tx_thread_execute_ptr) // 挂起正在执行的线程(没有其他
    就绪线程的情况,前面已经处理过了,这里应该就是有其他就绪线程的情况,需要调度别的就绪
    线程; 挂起不在执行的线程不会导致线程调度)
320. 402
               {
```

```
322. 404
                   /* Pickup the highest priority thread to execute. */
323. 405
                    _tx_thread_execute_ptr =
    _tx_thread_priority_list[_tx_thread_highest_priority]; // _tx_thread_execute_ptr指向
    最高优先级就绪线程
324. 406
325. 407 #ifndef TX DISABLE PREEMPTION THRESHOLD
326. 408
327. 409
                   /* Determine if a previous thread with preemption-threshold was
    preempted. */
328. 410 #if TX_MAX_PRIORITIES > 32
329. 411
                   if ( tx thread preempted map active != ((ULONG) 0))
330. 412 #else
                   if (_tx_thread_preempted_maps[MAP_INDEX] != ((ULONG) 0)) // 检查是否
331. 413
    有启用抢占的线程被抢占
332. 414 #endif
333. 415
334. 416
335. 417
                       /* Yes, there was a thread preempted when it was using
    preemption-threshold. */
336. 418
337. 419
                       /* Disable preemption. */
                       _tx_thread_preempt_disable++; // 禁止抢占(后面开中断让中断得到及
338. 420
    时处理,禁止抢占避免当前过程被其他线程中断)
339. 421
340. 422
                       /* Restore interrupts. */
341. 423
                       TX RESTORE
342. 424
343. 425
                       /* Interrupts are enabled briefly here to keep the interrupt
344. 426
                          lockout time deterministic. */
345. 427
346. 428
                       /* Disable interrupts again. */
347. 429
                       TX DISABLE
348. 430
349. 431
                       /* Decrement the preemption disable variable. */
```

```
350. 432
                       _tx_thread_preempt_disable--;
351. 433
352. 434
                       /* Calculate the thread with preemption threshold set that
353. 435
                          was interrupted by a thread above the preemption level. */
354. 436
355. 437 #if TX MAX PRIORITIES > 32
356. 438
357. 439
                       /* Calculate the index to find the next highest priority thread
    ready for execution. */
358. 440
                       priority_map = _tx_thread_preempted_map_active;
359. 441
360. 442
                       /* Calculate the lowest bit set in the priority map. */
361. 443
                       TX LOWEST SET BIT CALCULATE(priority map, map index)
362. 444
363. 445
                       /* Calculate the base priority as well. */
364. 446
                       base_priority = map_index * ((UINT) 32);
365. 447 #else
366, 448
367. 449
                       /* Setup the base priority to zero. */
368. 450
                       base priority = ((UINT) 0);
369. 451 #endif
370. 452
371. 453
                       /* Setup temporary preempted map. */
372. 454
                       priority_map = _tx_thread_preempted_maps[MAP_INDEX];
373. 455
374. 456
                       /* Calculate the lowest bit set in the priority map. */
                       TX_LOWEST_SET_BIT_CALCULATE(priority_map, priority_bit) // 获取
    最高优先级的抢占线程的标记位(前面讲过了,_tx_thread_preempted_maps里面的高优先级线程
    的优先级高于低优先级线程的抢占阈值,要调度的话也只可能是 tx thread preempted maps里
    面高优先级线程)
376. 458
377. 459
                       /* Setup the highest priority preempted thread. */
378. 460
                       priority = base_priority + ((UINT) priority_bit); // 获取
    _tx_thread_preempted_maps标记的最高优先级线程的优先级
```

```
/* Determine if the next highest priority thread is above the
380. 462
    highest priority threshold value. */
381. 463
                       if (_tx_thread_highest_priority >=
    (_tx_thread_priority_list[priority] -> tx_thread_preempt_threshold)) // 最高优先级就
    绪线程的优先级不高于 tx thread preempted maps被抢占线程的抢占阈值,
    tx thread preempted maps里面的高优先级线程抢占下一个就绪的最高优先级线程
382. 464
                       {
383. 465
384, 466
                           /* Thread not allowed to execute until earlier preempted
    thread finishes or lowers its
385. 467
                              preemption-threshold. */
386, 468
                           tx thread execute ptr =
    tx thread priority list[priority]; // 获取 tx thread preempted maps标记的被抢占的线
    程(被抢占的线程还在就绪线程链表 tx thread priority list的表头)
387. 469
388. 470
                           /* Clear the corresponding bit in the preempted map, since
    the preemption has been restored. */
389. 471
                           TX_MOD32_BIT_SET(priority, priority_bit)
390, 472
                           tx thread preempted maps[MAP INDEX] =
    _tx_thread_preempted_maps[MAP_INDEX] & (~(priority_bit)); // 清除
    _tx_thread_preempted_maps里面的抢占标记
391, 473
392. 474 #if TX MAX PRIORITIES > 32
393. 475
394. 476
                           /* Determine if there are any other bits set in this preempt
          */
    map.
                           if (_tx_thread_preempted_maps[MAP_INDEX] == ((ULONG) 0))
395. 477
396, 478
                           {
397. 479
398. 480
                               /* No, clear the active bit to signify this preempt map
    has nothing set. */
399. 481
                               TX_DIV32_BIT_SET(priority, priority_bit)
400.482
                               _tx_thread_preempted_map_active =
    _tx_thread_preempted_map_active & (~(priority_bit));
401. 483
                           }
402. 484 #endif
```

403. 485

}

```
404. 486
                     }
405. 487 #endif
406. 488
407. 489 #ifndef TX_MISRA_ENABLE
408. 490
409. 491 #ifdef TX THREAD ENABLE PERFORMANCE INFO
410. 492
411. 493
                     /* Is the execute pointer different? */
412. 494
     (_tx_thread_performance_execute_log[_tx_thread_performance__execute_log_index] !=
     _tx_thread_execute_ptr)
413. 495
                     {
414. 496
415. 497
                         /* Move to next entry. */
416. 498
                         tx thread performance execute log index++;
417. 499
418. 500
                         /* Check for wrap condition. */
                         if (_tx_thread_performance__execute_log_index >=
419. 501
     TX THREAD EXECUTE LOG SIZE)
420. 502
                         {
421. 503
422. 504
                             /* Set the index to the beginning. */
423. 505
                             _tx_thread_performance__execute_log_index = ((UINT) 0);
424. 506
                         }
425. 507
426. 508
                         /* Log the new execute pointer. */
427. 509
     _tx_thread_performance_execute_log[_tx_thread_performance__execute_log_index] =
     _tx_thread_execute_ptr;
428. 510
                     }
429. 511 #endif
430. 512
431. 513 #ifdef TX_ENABLE_EVENT_TRACE
432. 514
```

```
433. 515
                    /* Check that the event time stamp is unchanged. A different
434. 516
                       timestamp means that a later event wrote over the thread
435. 517
                       suspend event. In that case, do nothing here. */
436. 518
                    if (entry_ptr != TX_NULL)
437. 519
                    {
438. 520
439. 521
                        /* Is the timestamp the same? */
440. 522
                        if (time_stamp == entry_ptr -> tx_trace_buffer_entry_time_stamp)
441. 523
                        {
442. 524
443. 525
                            /* Timestamp is the same, set the "next thread pointer" to
    the new value of the
444. 526
                               next thread to execute. This can be used by the trace
    analysis tool to keep
445. 527
                               track of next thread execution. */
446. 528
                            entry_ptr -> tx_trace_buffer_entry_information_field_4 =
    TX_POINTER_TO_ULONG_CONVERT(_tx_thread_execute_ptr);
447. 529
                        }
448. 530
                    }
449. 531 #endif
450. 532
451. 533
                   /* Restore interrupts. */
452. 534
                    TX_RESTORE
453. 535
454. 536
                    /* Determine if preemption should take place. This is only possible
    if the current thread pointer is
455. 537
                       not the same as the execute thread pointer AND the system state
     and preempt disable flags are clear. */
456. 538
                    TX_THREAD_SYSTEM_RETURN_CHECK(combined_flags)
457. 539
                    if (combined flags == ((ULONG) 0)) // 与之前一样,检查是返回系统调度
    线程还是返回
458. 540
                    {
459. 541
460. 542 #ifdef TX_THREAD_ENABLE_PERFORMANCE_INFO
461. 543
```

```
462. 544
                         /* No, there is another thread ready to run and will be
     scheduled upon return.
463. 545
                         _tx_thread_performance_non_idle_return_count++;
464. 546 #endif
465. 547
466. 548
                         /* Preemption is needed - return to the system! */
467. 549
                         _tx_thread_system_return();
468. 550
                     }
469. 551
470. 552
                     /* Return to caller. */
471. 553
                     return; // 返回
472. 554 #endif
473. 555
                 }
474. 556
475. 557 #ifdef TX_THREAD_ENABLE_PERFORMANCE_INFO
476. 558
477. 559
                /* Is the execute pointer different? */
478, 560
     (_tx_thread_performance_execute_log[_tx_thread_performance__execute_log_index] !=
     _tx_thread_execute_ptr)
479. 561
                 {
480. 562
481. 563
                     /* Move to next entry. */
482. 564
                     _tx_thread_performance__execute_log_index++;
483. 565
484. 566
                     /* Check for wrap condition. */
485. 567
                     if (_tx_thread_performance__execute_log_index >=
     TX_THREAD_EXECUTE_LOG_SIZE)
486. 568
                     {
487. 569
488. 570
                         /* Set the index to the beginning. */
489. 571
                         _tx_thread_performance__execute_log_index = ((UINT) 0);
490. 572
                     }
491. 573
```

```
492. 574
                     /* Log the new execute pointer. */
493. 575
    _tx_thread_performance_execute_log[_tx_thread_performance__execute_log_index] =
     _tx_thread_execute ptr;
494. 576
                 }
495. 577 #endif
496, 578
497. 579 #ifdef TX_ENABLE_EVENT_TRACE
498. 580
499. 581
                  /* Check that the event time stamp is unchanged. A different
500. 582
                     timestamp means that a later event wrote over the thread
501. 583
                     suspend event. In that case, do nothing here. */
502. 584
                  if (entry ptr != TX NULL)
503. 585
                  {
504. 586
505. 587
                     /* Is the timestamp the same? */
506. 588
                     if (time_stamp == entry_ptr -> tx_trace_buffer_entry_time_stamp)
507. 589
                     {
508. 590
509. 591
                         /* Timestamp is the same, set the "next thread pointer" to the
     new value of the
510. 592
                            next thread to execute. This can be used by the trace
     analysis tool to keep
511. 593
                            track of next thread execution. */
512. 594 #ifdef TX MISRA ENABLE
513. 595
                         entry_ptr -> tx_trace_buffer_entry_info_4 =
     TX POINTER TO ULONG CONVERT( tx thread execute ptr);
514. 596 #else
515. 597
                         entry_ptr -> tx_trace_buffer_entry_information_field_4 =
     TX POINTER TO ULONG CONVERT( tx thread execute ptr);
516. 598 #endif
517. 599
                     }
518. 600
                 }
519. 601 #endif
520. 602
             }
```

```
521. 603
522. 604
           /* Restore interrupts. */
523. 605
           TX RESTORE
524. 606
525. 607
            /* Determine if a preemption condition is present. */
            if (current thread != tx thread execute ptr)
526. 608
527. 609
528. 610
529. 611 #ifdef TX ENABLE STACK CHECKING
530. 612
531. 613
                /* Pickup the next execute pointer. */
532. 614
                thread_ptr = _tx_thread_execute_ptr;
533. 615
534. 616
                /* Check this thread's stack. */
                TX_THREAD_STACK_CHECK(thread_ptr)
535. 617
536. 618 #endif
537. 619
                /* Determine if preemption should take place. This is only possible if
538. 620
    the current thread pointer is
539. 621
                   not the same as the execute thread pointer AND the system state and
    preempt disable flags are clear. */
540. 622
                TX_THREAD_SYSTEM_RETURN_CHECK(combined_flags)
541. 623
                if (combined flags == ((ULONG) 0))
542. 624
                {
543. 625
544. 626 #ifdef TX THREAD ENABLE PERFORMANCE INFO
545. 627
546. 628
                    /* Determine if an idle system return is present. */
547. 629
                    if ( tx thread execute ptr == TX NULL)
548. 630
                     {
549. 631
550. 632
                         /* Yes, increment the return to idle return count. */
551. 633
                         _tx_thread_performance_idle_return_count++;
```

```
552. 634
                   }
553. 635
                   else
554. 636
                   {
555. 637
556. 638
                      /* No, there is another thread ready to run and will be
    scheduled upon return. */
557. 639
                       _tx_thread_performance_non_idle_return_count++;
558. 640
                   }
559. 641 #endif
560. 642
561. 643
               /* Preemption is needed - return to the system! */
562. 644
                   _tx_thread_system_return();
563. 645
            }
564. 646
         }
565. 647
566. 648 /* Return to caller. */
567. 649
           return;
568.650 }
```