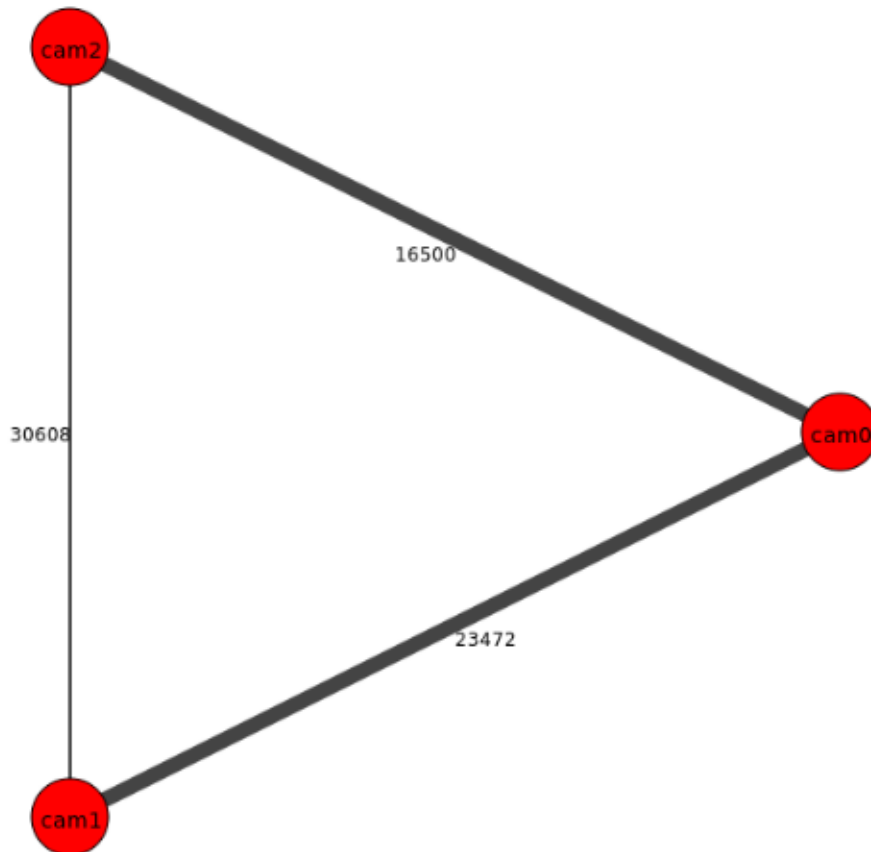
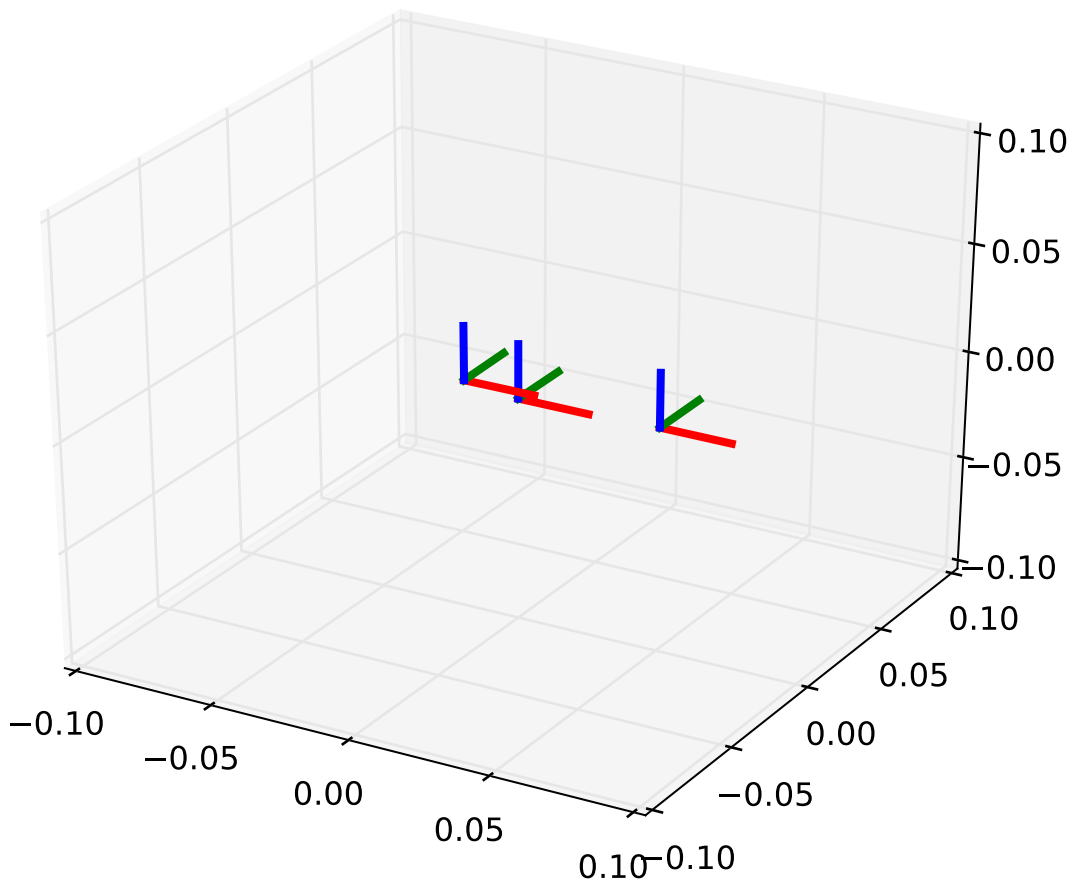


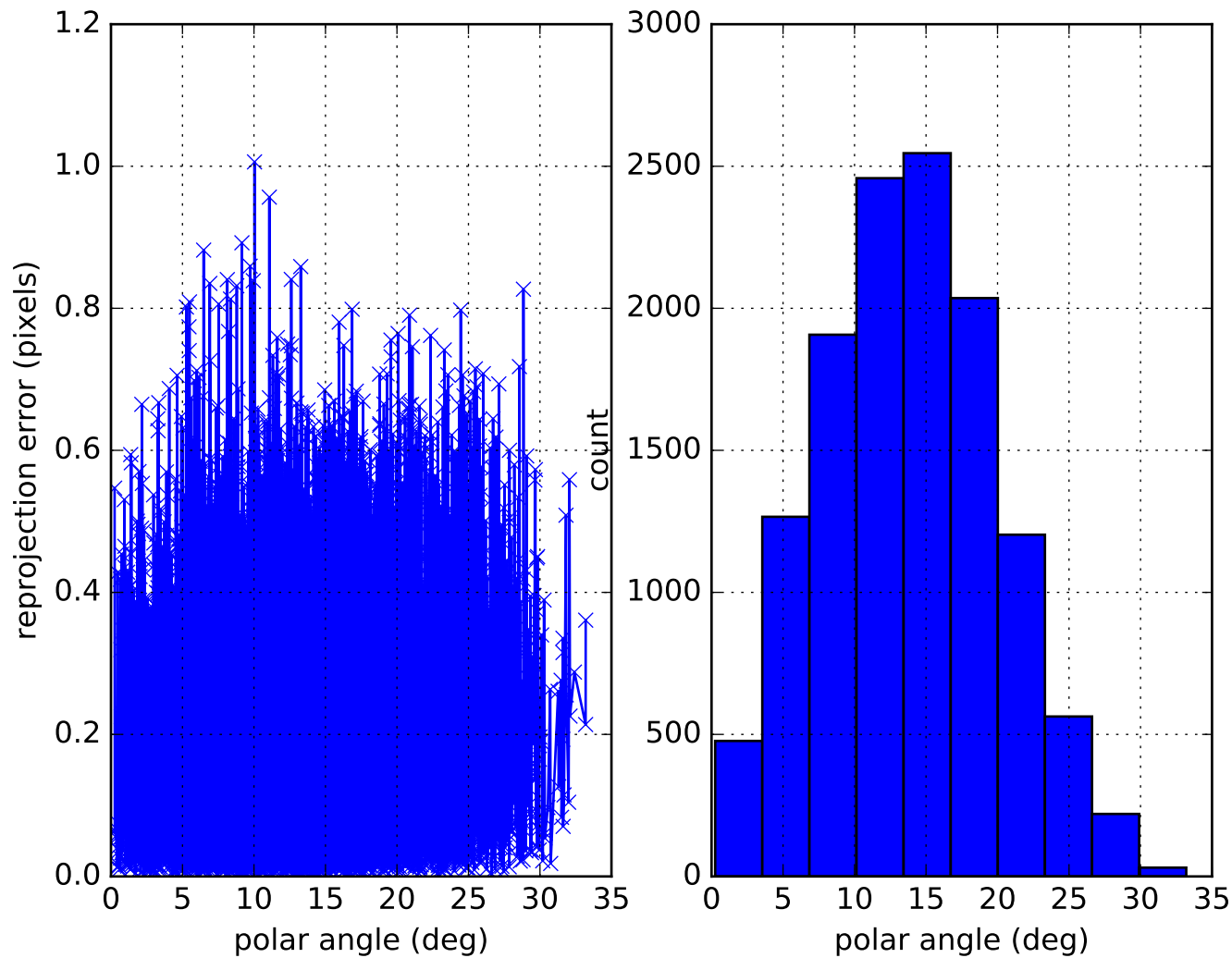
Inter-camera observations graph (edge weight=#mutual obs.)



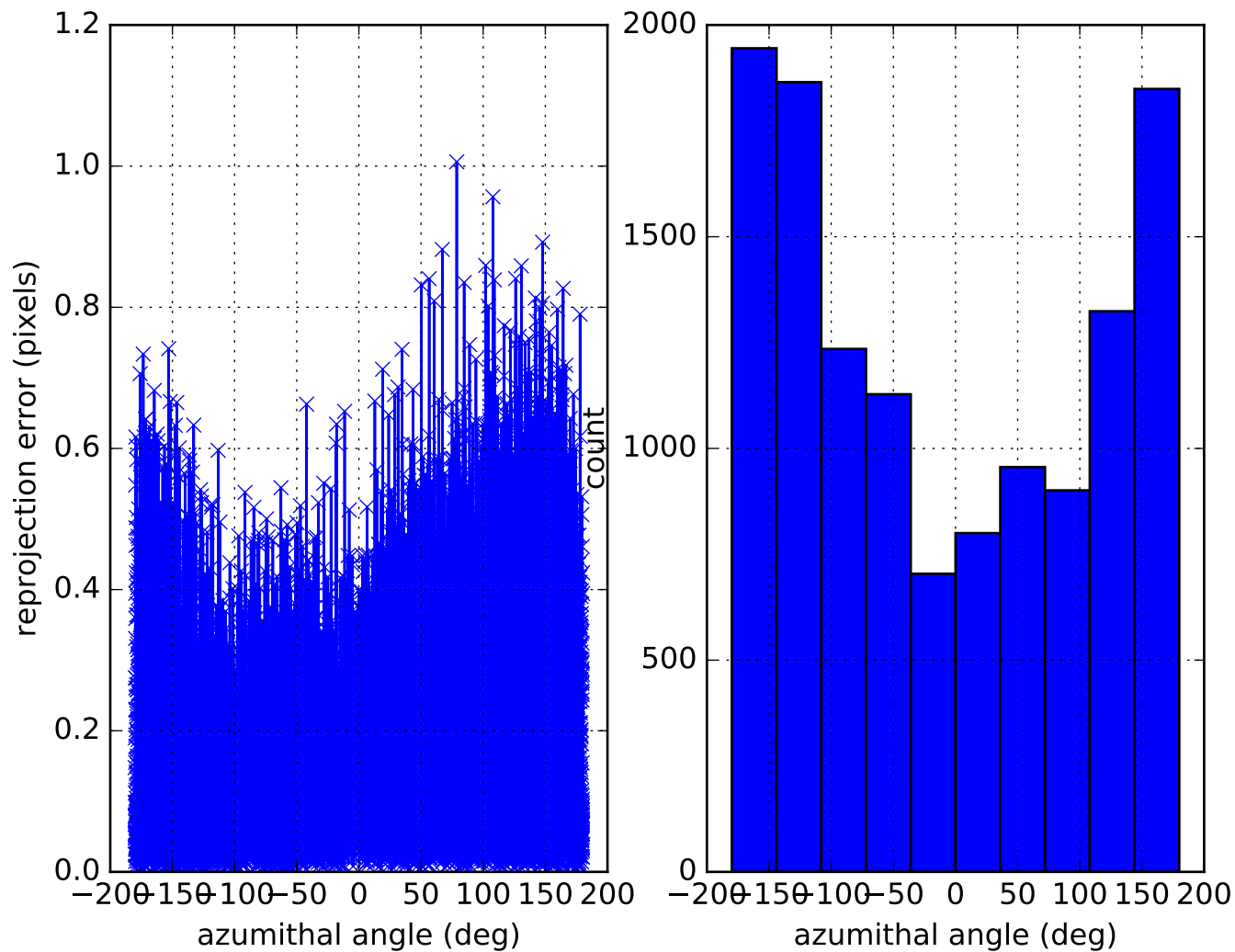
camera system



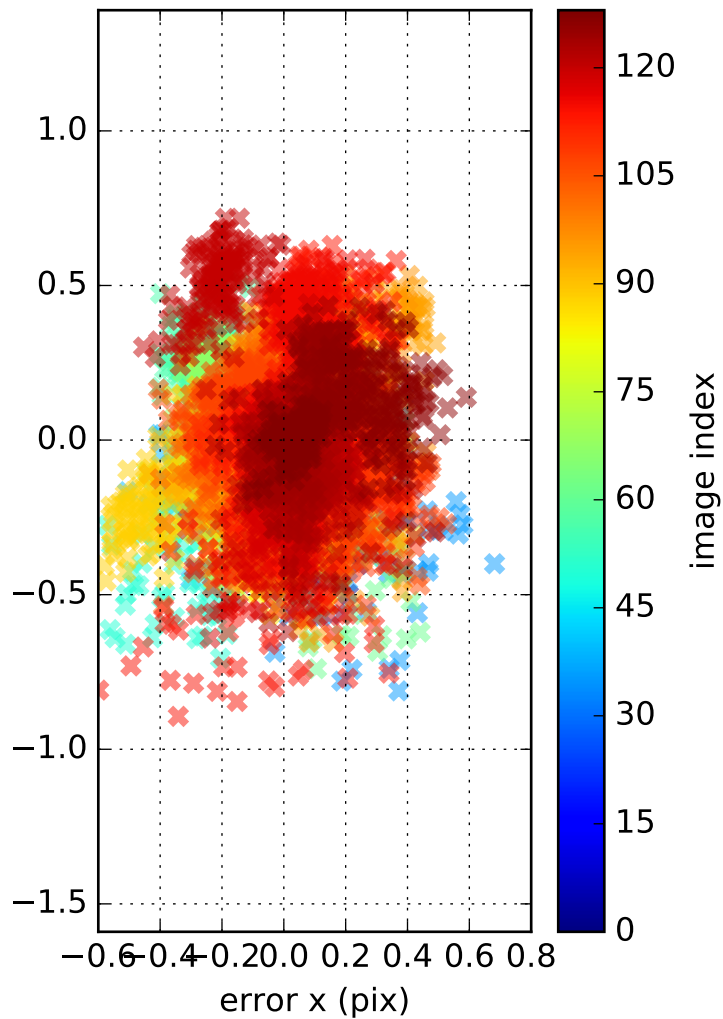
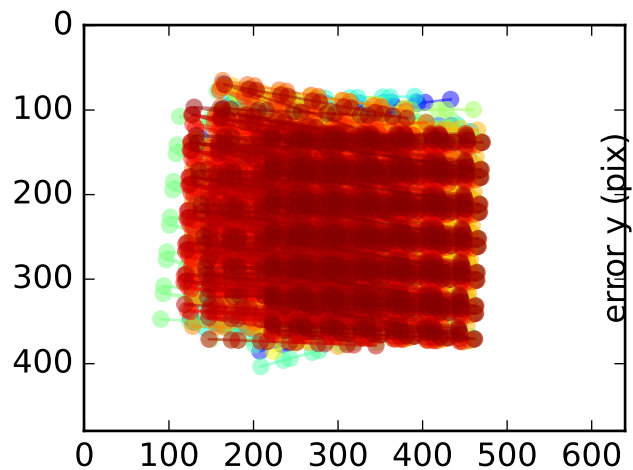
cam0: polar error



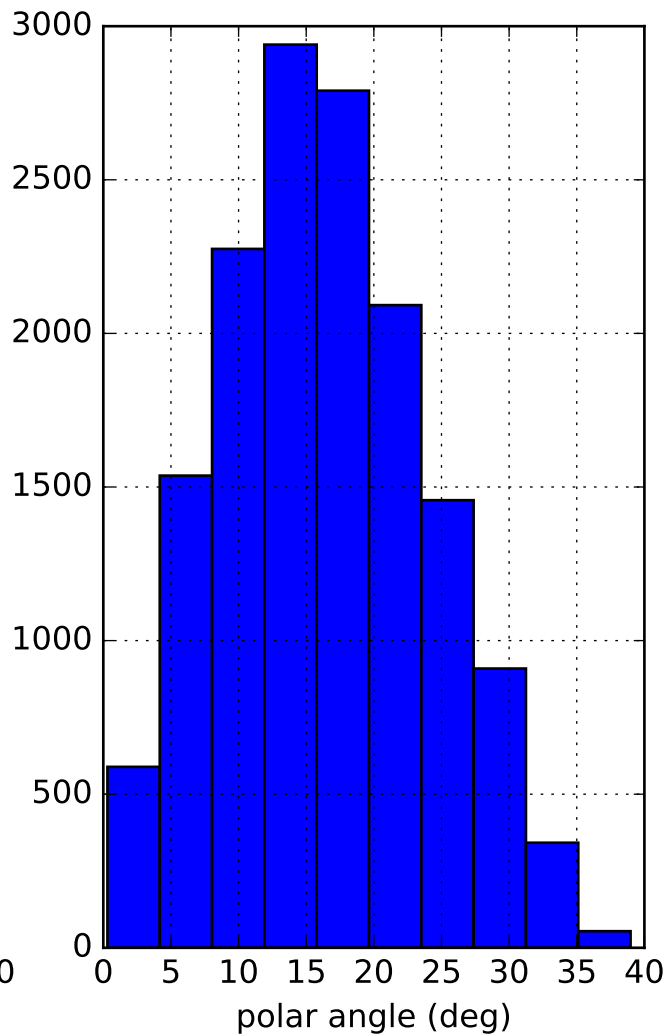
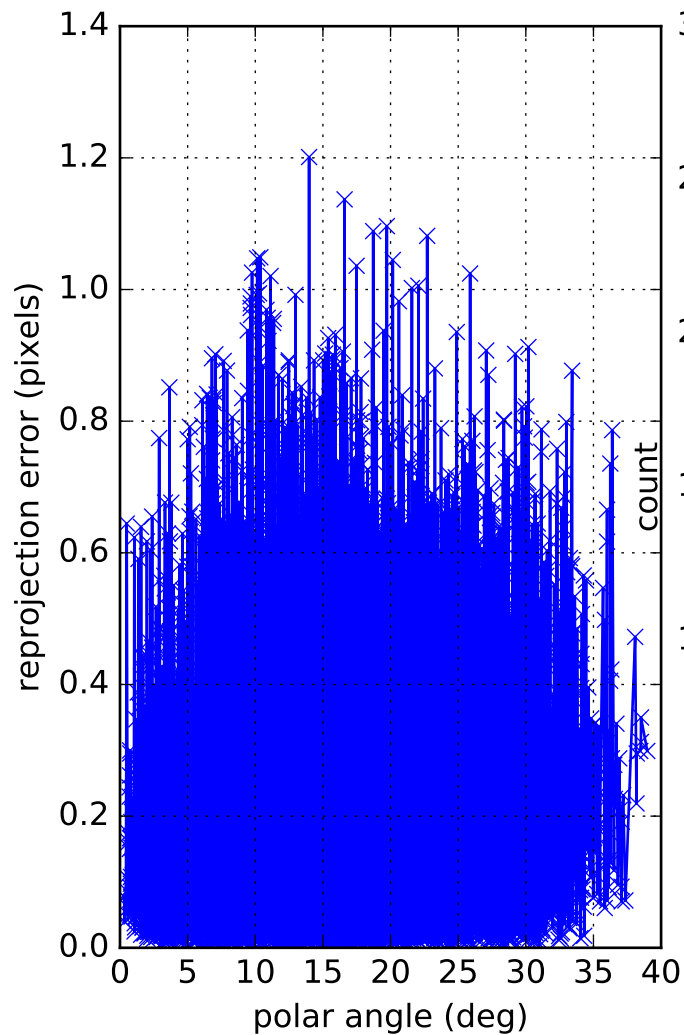
cam0: azimuthal error



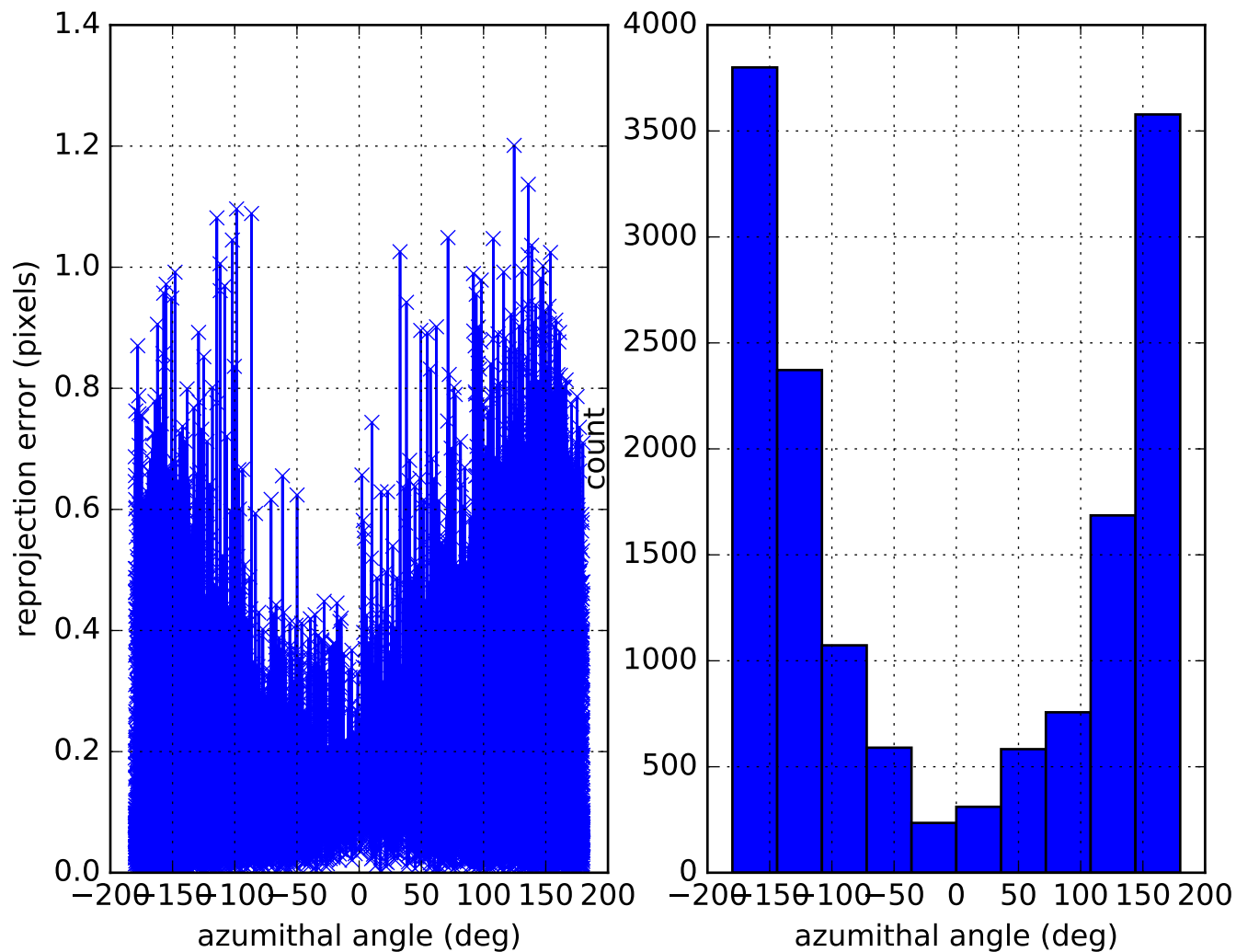
cam0: reprojection errors



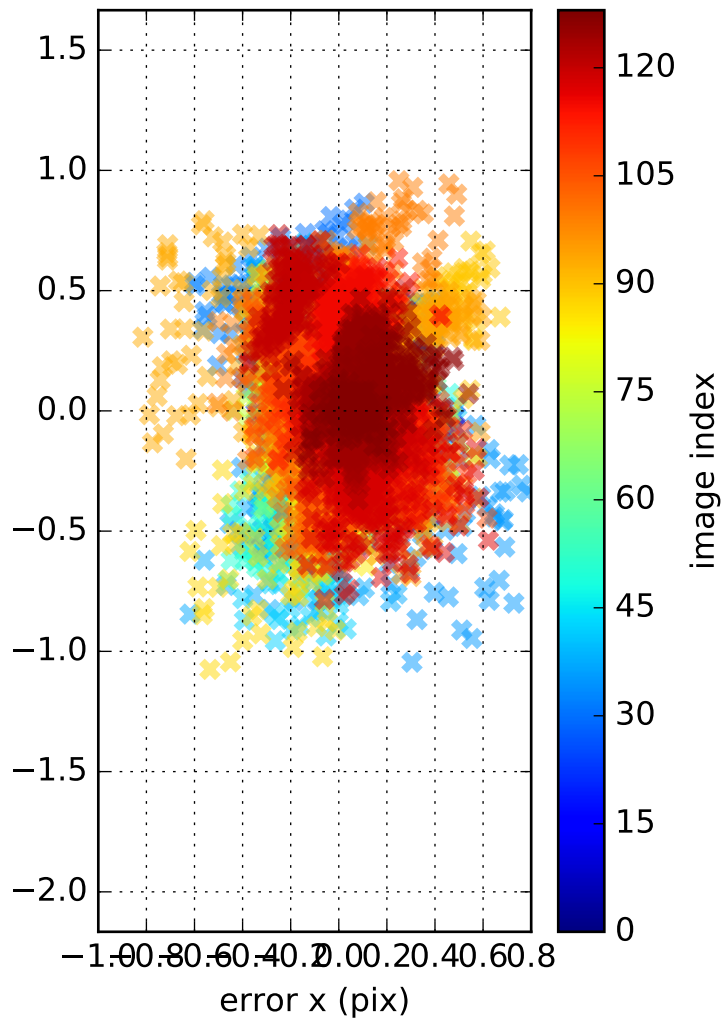
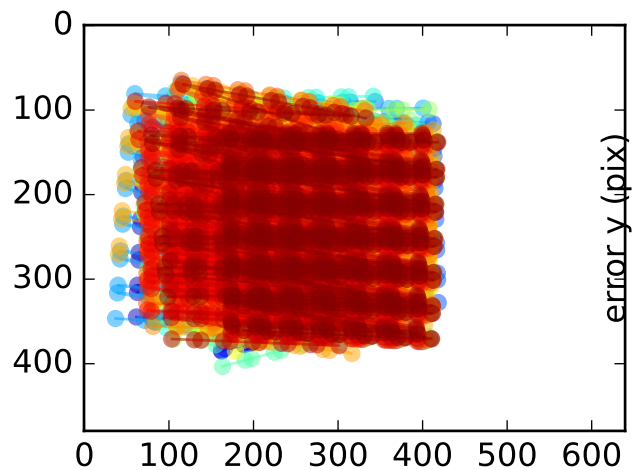
cam1: polar error



cam1: azimuthal error

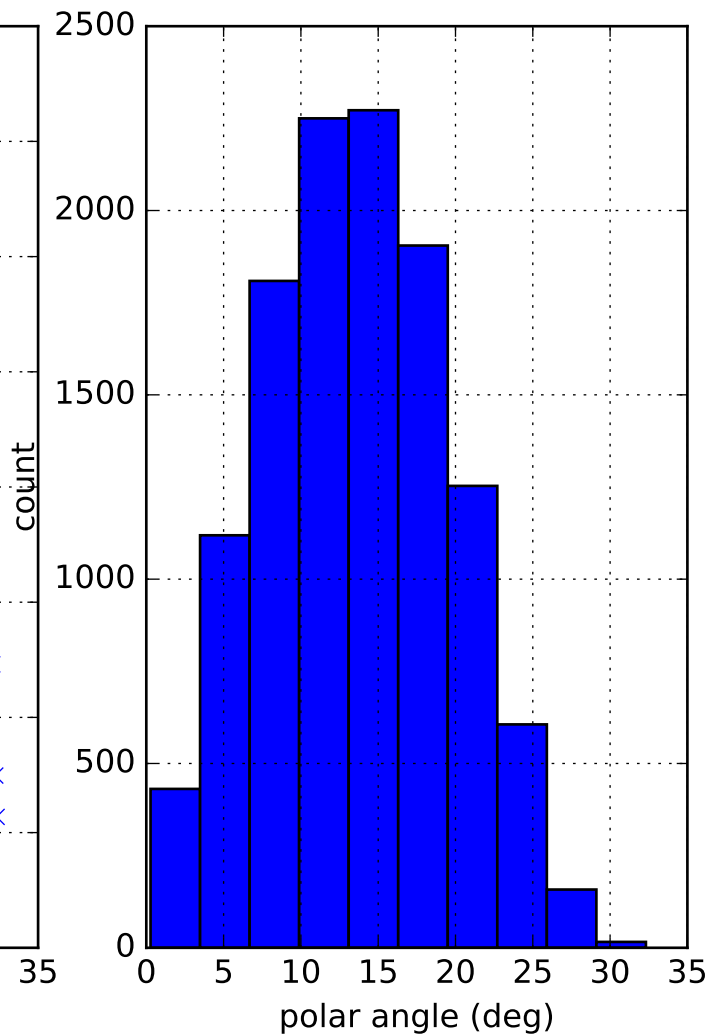
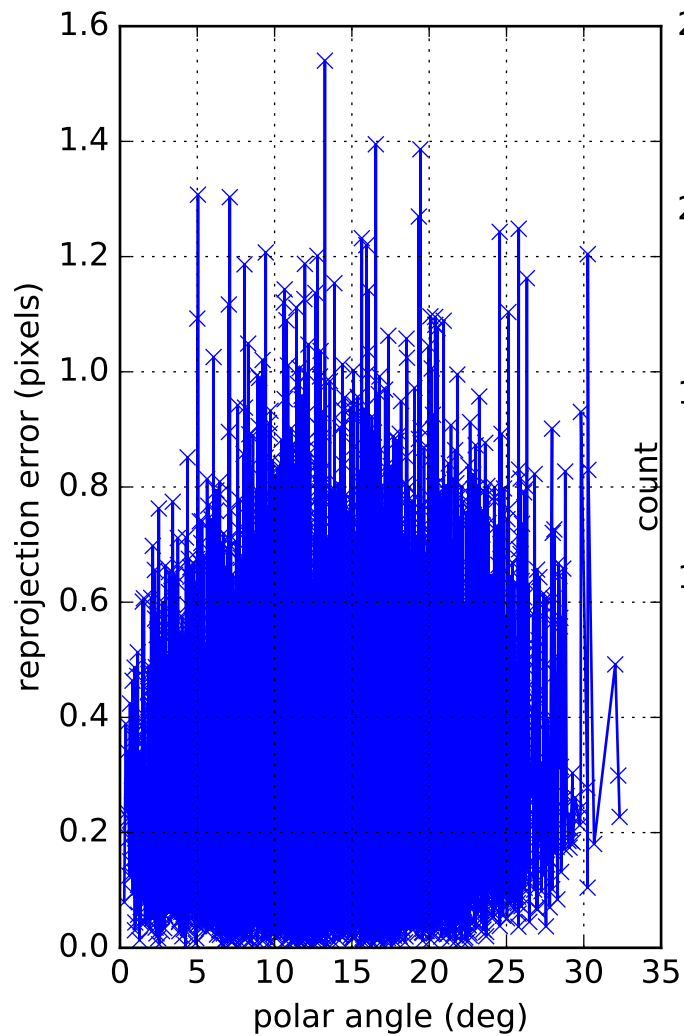


cam1: reprojection errors

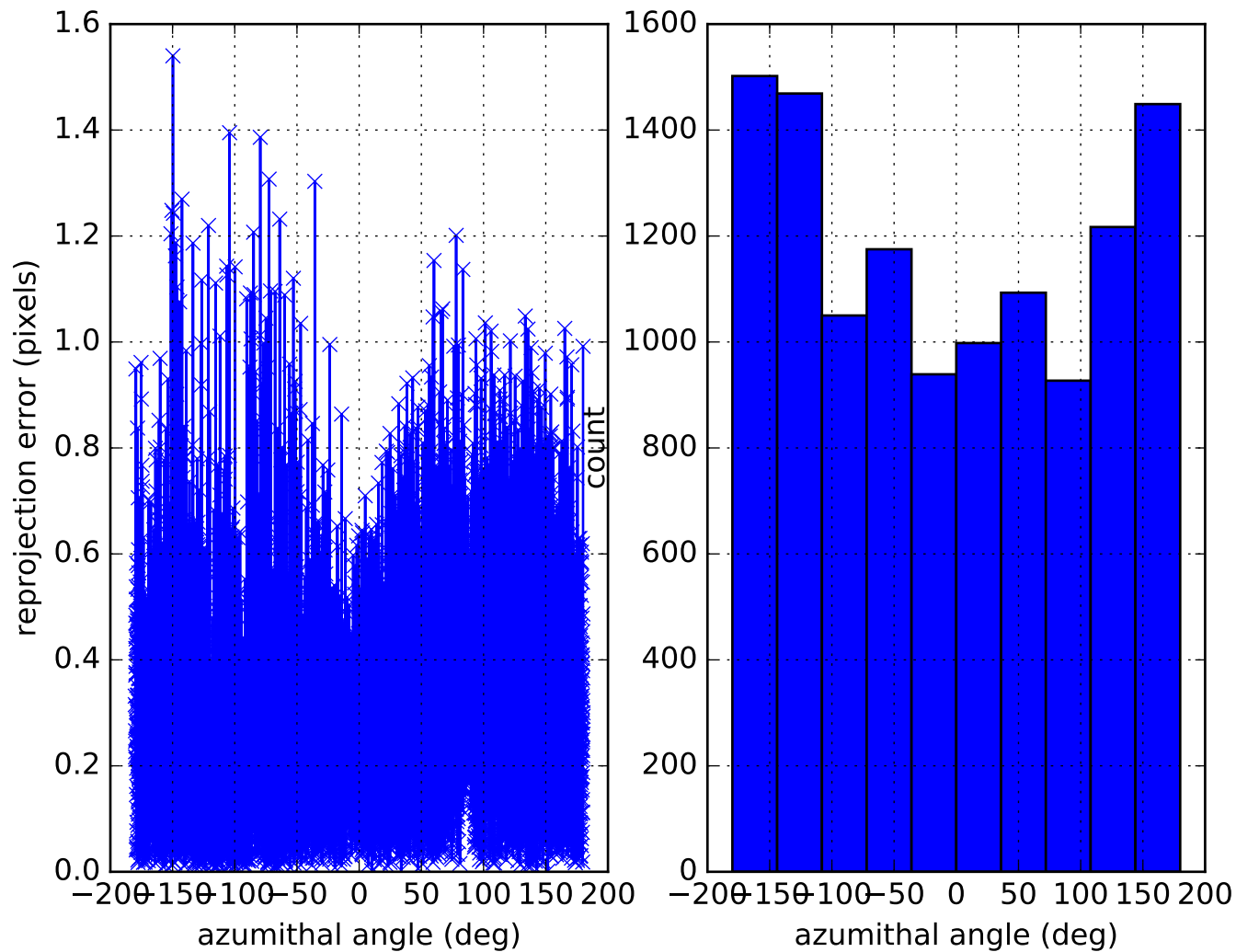




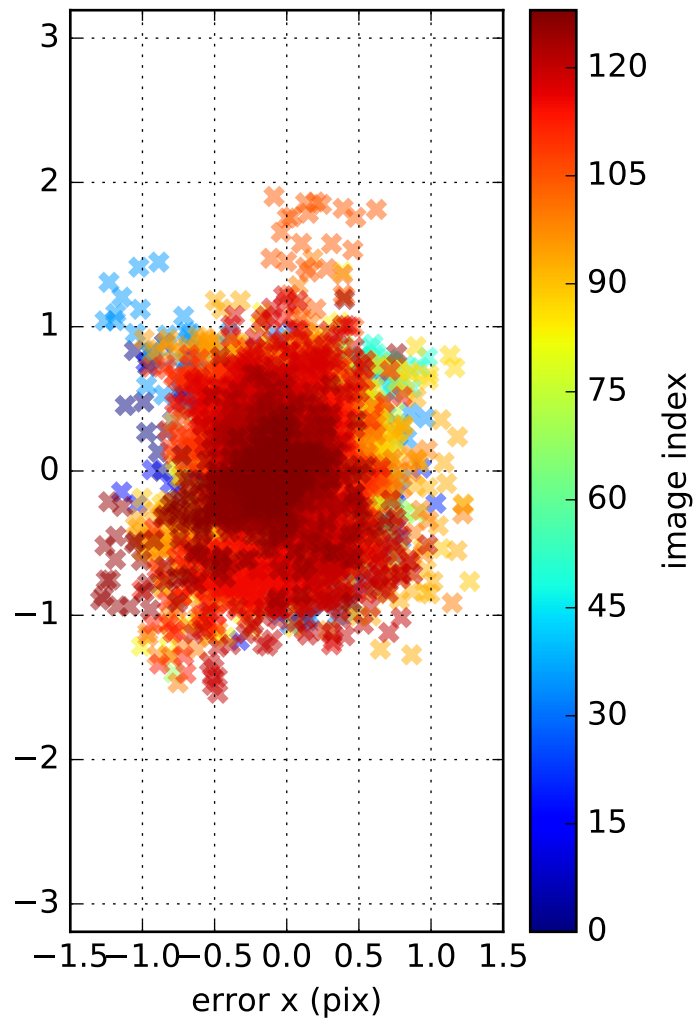
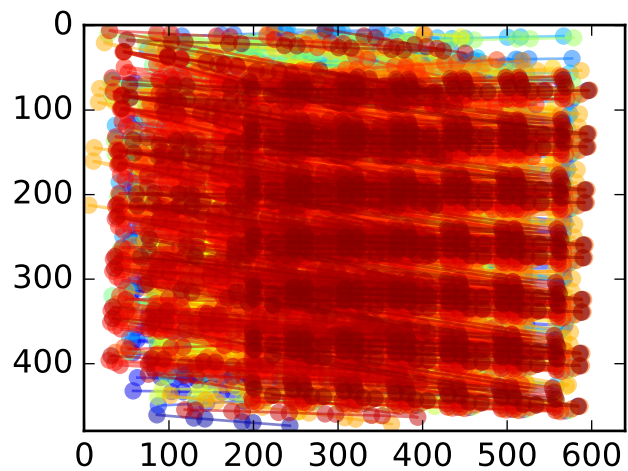
cam2: polar error



cam2: azimuthal error

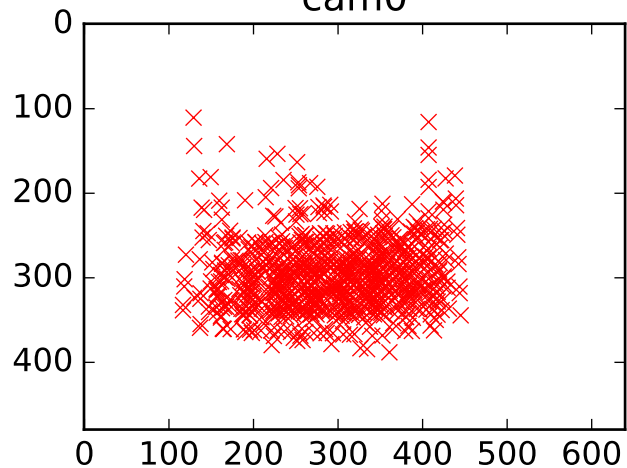


cam2: reprojection errors

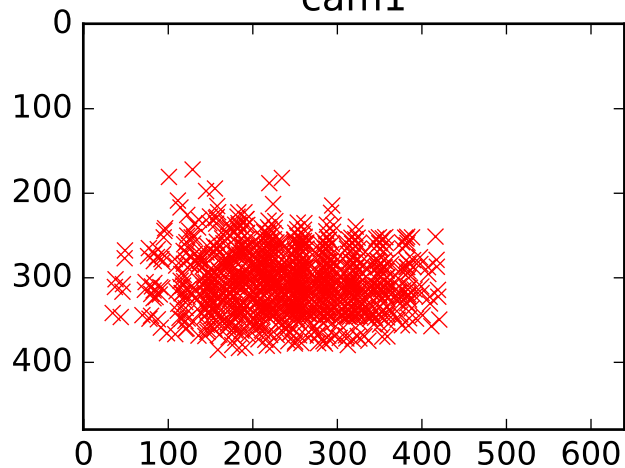


# Location of removed outlier corners

cam0



cam1



cam2

