

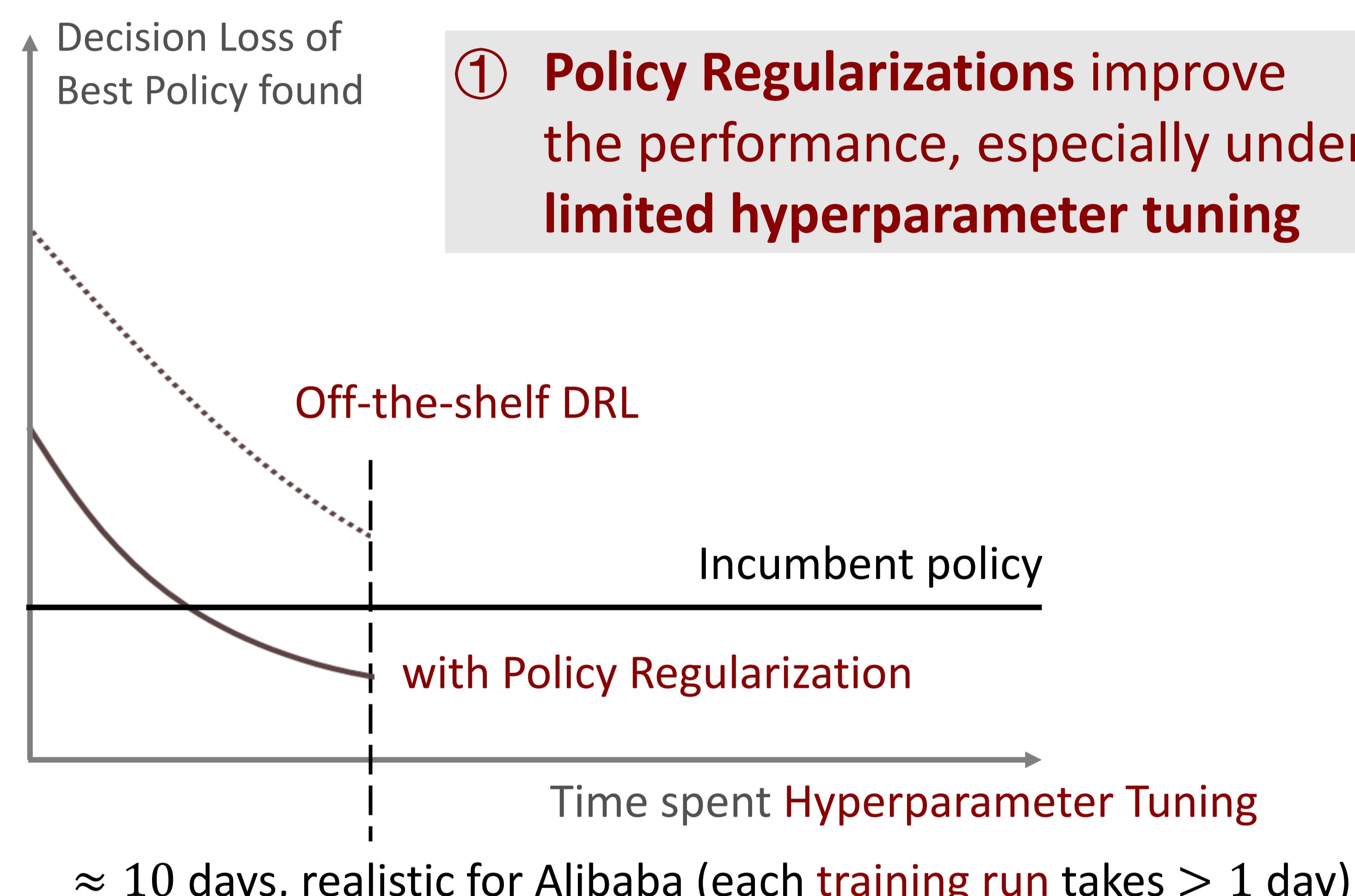
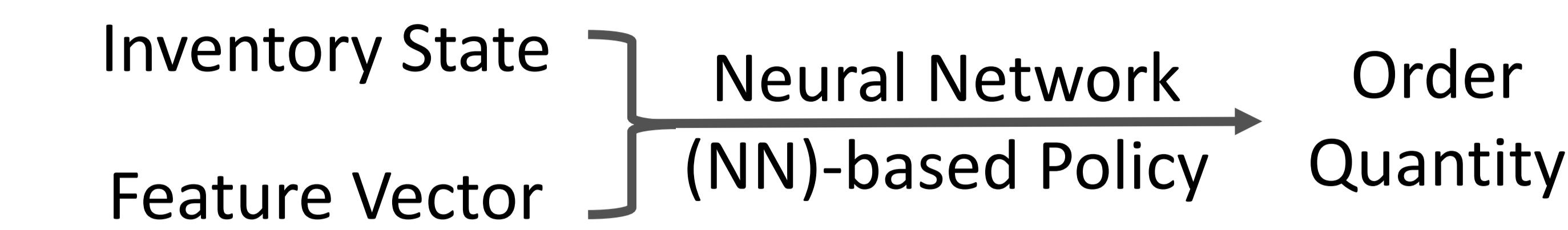
# DeepStock: Reinforcement Learning with Policy Regularizations for Inventory Management



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## Deep Reinforcement Learning (DRL) for Inventory

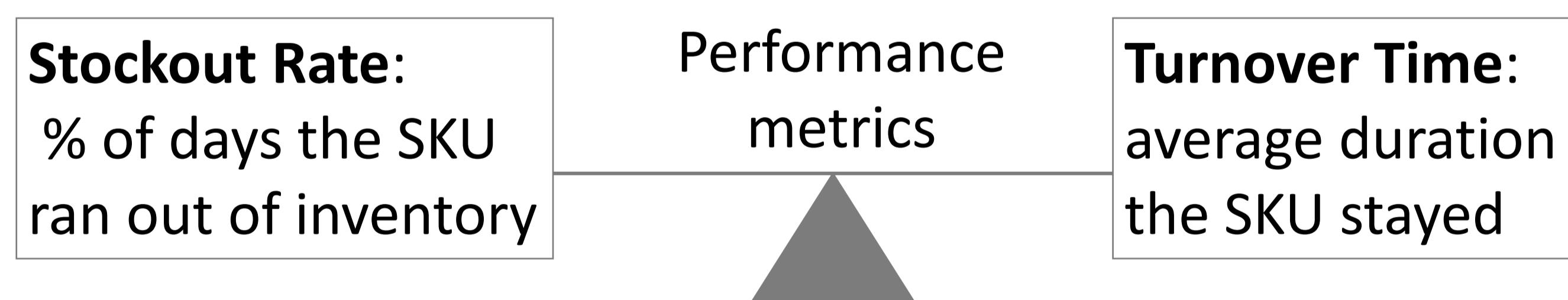


### Policy Regularizations

- “**BASE**”: NN outputs **Basestock level**  
Order quantity =  $\max\{\text{basestock level} - \text{on-hand inventory position}, 0\}$
- “**COEFF**”: NN outputs **Coefficient vector**  
Order quantity =  $\text{coefficient vector}^T \text{selected features}$   
e.g., selected features = recent/forecasted demands
- “**BOTH**”:  $\max\{\text{coefficient vector}^T \text{selected features} - \text{on-hand inventory position}, 0\}$

### Alibaba’s Setting

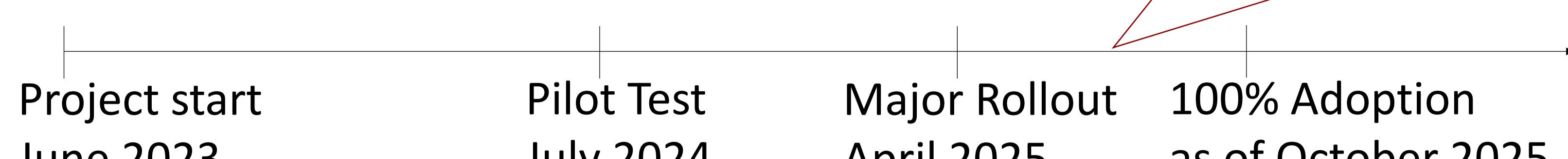
- Tmall: 100,000+ SKU’s B2C across ≈20 warehouses



- Metrics: take weighted average across all SKU-warehouse inventories

- ② One unified policy to manage all 1,000,000+ inventories at Alibaba Tmall

Compared to July-August 2024:  
no change in Stockout Rate  
-20% in Turnover Time (Tmall global)



Difference-in Differences:  
-0.83 % in Stockout Rate  
-9.53 days in Turnover Time

no change in Stockout Rate  
-1 day in Turnover Time (Tmall global)  
-2 days in Turnover Time (Tmall)

### Offline Comparison in Alibaba’s setting

- Train/Validate on 55,000 SKU-warehouse combinations
- Test on chronologically-later days through simulation

Compared to DDPG BOTH; best results found after searching 10 hyperparameter configurations:

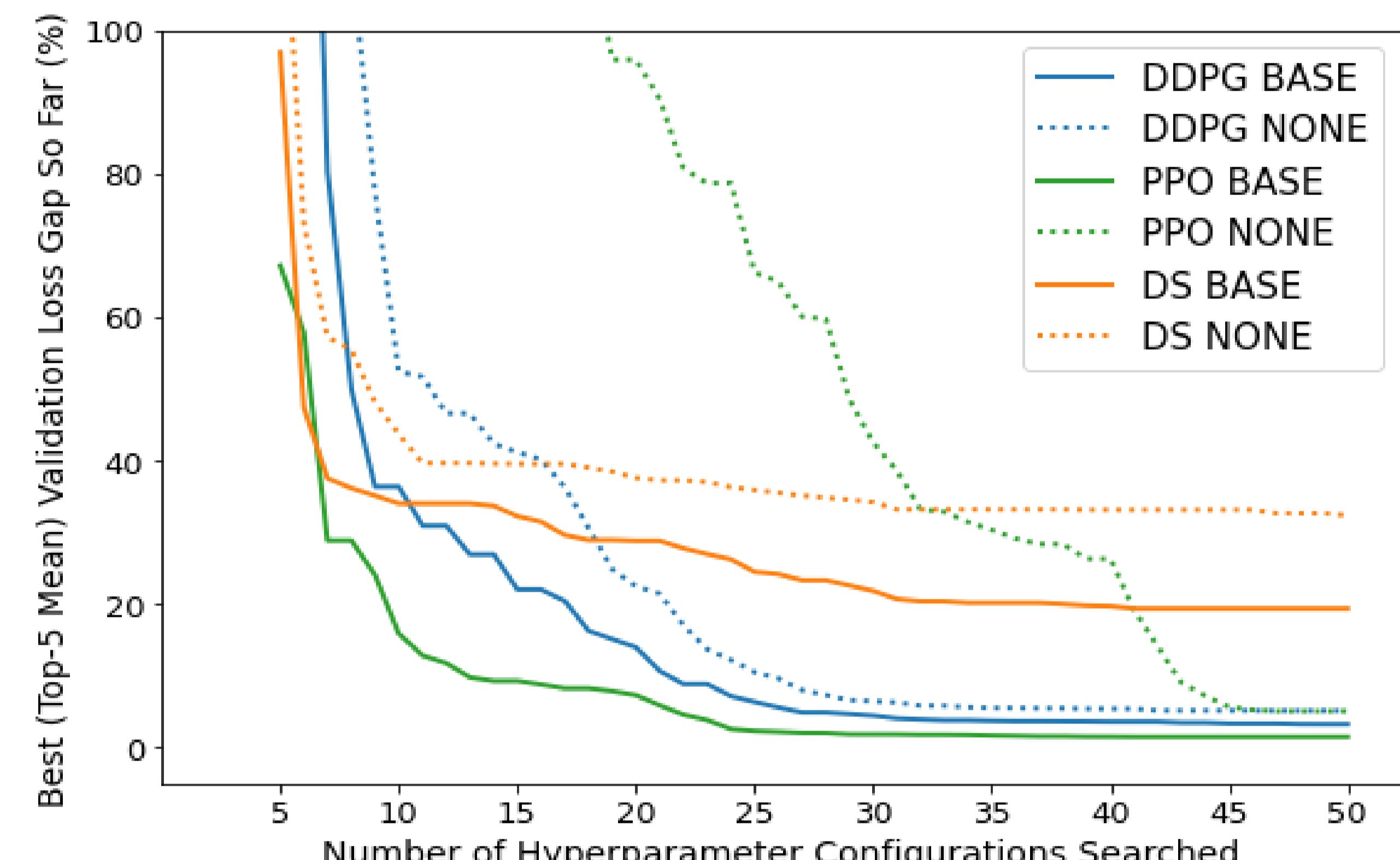
Deep Deterministic Policy Gradient (DDPG)				
Policy Regularization	NONE	BASE	COEFF	BOTH
Stockout Rate (%)	+10.10	+6.03	+4.41	-
Turnover Time (days)	+6.13	+6.46	-0.41	-

Differentiable Simulator (DS)				
Policy Regularization	NONE	BASE	COEFF	BOTH
Stockout Rate (%)	+2.10	+2.18	+1.74	+1.91
Turnover Time (days)	-1.25	-2.81	+3.80	+0.23

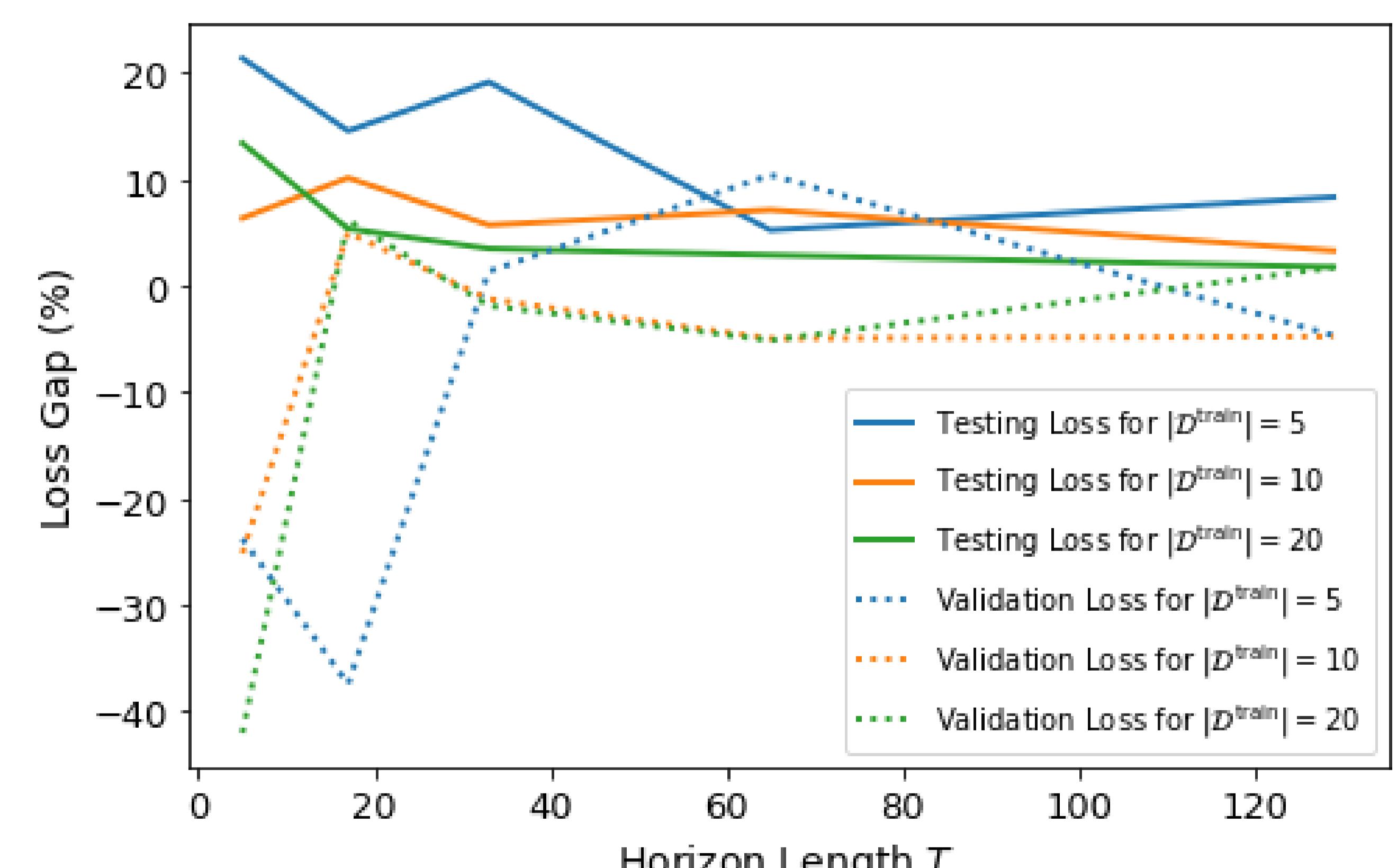
- New DRL method “DS”, not sensitive to hyperparameters [Madeka et al. 22; Alvo et al. 25]

### Synthetic Data

- Independent demands over 29 days
- 1-dimensional feature; train/validate on 20 trajectories



- ③ Reshape the narrative on the best DRL method among DS and traditional DDPG & PPO for inventory



### Why do Policy Regularizations help DRL training?

- Stabilize learning of  $Q$ -function when minimizing the Bellman error

### Why is the final performance of DS worse?

- Not cross-learning over time; overfitting to idiosyncrasies in trajectories

