

# CSC380: Principles of Data Science

Midterm review

Xinchen Yu

- What you can bring?
  - Cheat sheet: letter size, double-sided
  - Scientific calculator

$$\frac{\sqrt{2}}{3}$$
 is ok

- Time: Oct 12, Thursday, 3:30-4:45pm
- Location: C E Chavez Bldg, Rm 111 (same as lecture room)

### General tips on midterm preparation

- Prioritize reviewing basic concepts & ideas
- Understand the motivations and links between concepts
- "Memorization with understanding"
- Try to solve these on your own, then discuss with classmates
  - examples in the slides
  - practice problems
  - HW questions (esp. if you did not get them right the first time)

- What will not included in the midterm?
  - Code related questions
  - Data analysis and visualization
  - Pure proof questions
    - may need you to provide justifications

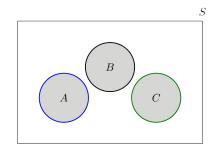
#### Office hours

- Office hours only for midterm:
  - Hui Ni: Oct 6, this Friday 2:00-3:30pm, GS 856
  - Saiful: Oct 9, next Monday 12:30-2:00pm, GS 934
  - Xinchen: Oct 10, next Tuesday 12:30-2:30pm, GS 854
  - Shahriar: Oct 11, next Wednesday 10:00-11:30am, zoom

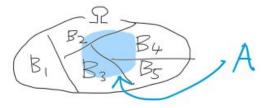
- Basic definitions: outcome space, events
- Probability P: maps events to [0, 1] values
  - Three axioms
  - Axiom 3: additivity
- Special case of P: each outcomes is equally likely

$$P(E) = \frac{|E|}{|\Omega|} \begin{tabular}{|c|c|c|c|} \hline Number of elements in event set \\ \hline |\Omega| \begin{tabular}{|c|c|c|c|c|} \hline Number of possible outcomes (36) \\ \hline \end{tabular}$$

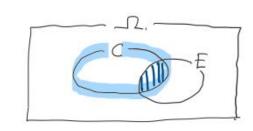
distributive law, inclusion-exclusion rule; law of total probability







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$$P(E \cap C) = P(E|C)P(C) = P(C|E)P(E)$$



- Conditional probability
  - Chain rule, chain rule + law of total probability, bayes rule
  - Important application: medical diagnosis
  - Approach: write down the joint probability table

Independence of events:

$$P(A,B) = P(A)P(B)$$

Conditional / joint / marginal probability

• Discrete random variable *X* (e.g., sum of two dice)



- Representation of its distribution: probability mass function (PMF)
  - $\circ$  Tabular representation of joint distribution of 2 RVs (X,Y)
- RVs: law of total probability, conditional probability, chain rule, bayes rule, independence, conditional independence
- Useful discrete distributions
  - Uniform
  - Bernoulli
  - Binominal

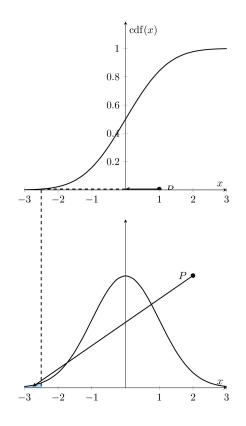
- Continuous random variable X: P(X = x) = 0 for any x
- Probability density function (PDF)

$$P(a < X \le b) = \int_a^b p(x) dx$$
  $p(x) = \frac{dF(x)}{dx}$ 

Cumulative distribution function (CDF)

$$P(a < X \le b) = F(b) - F(a)$$

- Useful continuous distributions
  - Uniform
  - Gaussian (important properties)

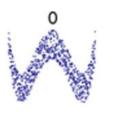


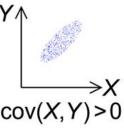
- Moments of random variables: expectation, variance, covariance
- Calculate mean (expectation) and variance of RVs
  - Linearity of expectation: E[X + cY] = E[X] + cE[Y] for constant c
  - $E[X^2]$
  - $\circ$   $\mathsf{E}[XY]$ 
    - If independent: E[X]E[Y]
    - If not independent:  $E[XY] = \sum xy \cdot p(x, y)$ (x,y)
  - $\circ$  E[X | Y = y]
  - Var[cX]
  - $\circ$  Var[X + c] = Var[X] (not in slides, prove?)
  - Var[X+Y] when independent

 $\mathbf{Var}[X] = \mathbf{E}[(X - \mathbf{E}[X])]$ 

- Expectation and variance of useful distributions
  - Bernoulli
  - Gaussian

• Measures *linear relationship* between X, Y $Cov(X, Y) = 0 \Rightarrow X \perp Y$ 

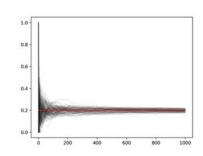


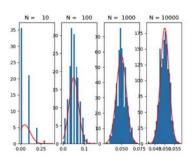


• Pearson correlation: 
$$\rho = \frac{\operatorname{Cov}(X,Y)}{\sigma_X \sigma_Y}$$
, where  $\sigma_X = \sqrt{\operatorname{Var}(X)}$ 

- Important property: Var(X + Y) = Var(X) + Var(Y) + 2Cov(X, Y)
  - What if X, Y are independent?

- Statistics: make statements about data generation process based on data seen; reverse engineering
- Point estimation
  - Given iid samples  $X_1, ..., X_n \sim \mathcal{D}_{\theta}$ , estimate  $\theta$  by constructing statistics  $\hat{\theta}_n$
  - Basic estimators: sample mean, sample variance
  - Performance measures: unbiasedness, consistency, MSE (efficiency)
  - Bias-variance decomposition:
    - $MSE(\hat{\theta}) = bias(\hat{\theta})^2 + var(\hat{\theta})$
- Useful probability tools:
  - Law of Large Numbers
  - Central Limit Theorem





Sample mean, sample variance

- Sample variance
  - biased version
  - unbiased version
  - how to determine an estimator is biased or unbiased?
- MSE, Bias, Variance
  - how to calculate expectation and variance if there are more than 1 random variable -- use what we learned in probability lecture 5 & 6

Calculate bias and variance

$$\begin{aligned} \mathrm{MSE}(\hat{\theta}_n) &= \mathbf{E}[(\hat{\theta}_n - \theta)^2] \\ &= \left(\mathbf{E}[\hat{\theta}] - \theta\right)^2 + \mathbf{E}[(\hat{\theta} - \mathbf{E}[\hat{\theta}])^2] \\ &= \mathrm{bias}^2(\hat{\theta}) + \mathrm{Var}(\hat{\theta}) \end{aligned}$$

#### Important properties of Gaussian

• Closed under additivity:

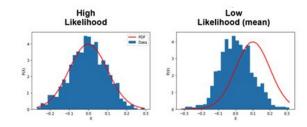
$$X \sim \mathcal{N}(\mu_x, \sigma_x^2)$$
  $Y \sim \mathcal{N}(\mu_y, \sigma_y^2)$   
 $X + Y \sim \mathcal{N}(\mu_x + \mu_y, \sigma_x^2 + \sigma_y^2)$ 

Closed under affine transformation (a and b constant):

$$aX + b \sim \mathcal{N}(a\mu_x + b, a^2\sigma_x^2)$$

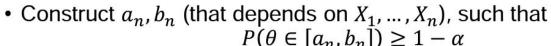
- Maximum likelihood (MLE): a general approach for point estimation
- Given  $X_1, ..., X_n \sim \mathcal{D}_{\theta^*}$ , estimate  $\theta^*$  by finding the maximizer of the likelihood function

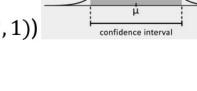
$$\mathcal{L}_n(\theta) = p(x_1, \dots, x_n; \theta) = p(x_1; \theta) \cdot \dots \cdot p(x_n; \theta)$$



- Intuition:  $\mathcal{L}_n(\theta)$  measures the "goodness of fit" of  $\mathcal{D}_{\theta}$  to data  $x_1, ..., x_n$
- $\mathcal{D}_{\theta}$  can be general, e.g. Bernoulli, Gaussian, Poisson (in HW3)

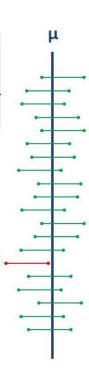
- Confidence interval (interval estimation)
- Definition of confidence intervals:
  - Given data  $X_1, ..., X_n \sim \mathcal{D}_{\theta}$  with unknown  $\theta$  (say,  $\mathcal{D}_{\theta} = \mathcal{N}(\theta, 1)$ )





confidence

• Interpretation: unless we are extremely unlucky (in that we encounter an unrepresentative dataset, which happens with prob.  $\leq \alpha$ ), our confidence interval always contains the underlying parameter



Confidence intervals for population mean:

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· Gaussian(naive):

$$\left[\hat{\mu} - \frac{z_{1-\alpha/2}\hat{\sigma}}{\sqrt{n}}, \hat{\mu} + \frac{z_{1-\alpha/2}\hat{\sigma}}{\sqrt{n}}\right], z_{1-\alpha/2} = 1 - \alpha/2$$
-quantile of  $\mathcal{N}(0,1)$ 

Gaussian(corrected):

$$\left[\hat{\mu} - \frac{t_{1-\alpha/2}\hat{\sigma}}{\sqrt{n}}, \hat{\mu} + \frac{t_{1-\alpha/2}\hat{\sigma}}{\sqrt{n}}\right]$$
,  $t_{1-\alpha/2} = 1 - \alpha/2$ -quantile of  $t$  distribution (degree of freedom=?)

- We expect you to be able to compute them on a small dataset
- Confidence intervals for general population parameters: bootstrap