STAT547 Homework 4

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Problem 1

The NW estimator has the form: $\hat{\mu}(x_0) = \frac{\sum_{i=1}^n K_h(X_i - x_0)Y_i}{\sum_{i=1}^n K_h(X_i - x_0)}$, therefore:

$$\operatorname{Bias}(\hat{\mu}(x_0)|\mathbf{X}_n) = \frac{\sum_{i=1}^n K_h(X_i - x_0)\mu(X_i)}{\sum_{i=1}^n K_h(X_i - x_0)} - \mu(x_0); \qquad \operatorname{Var}(\hat{\mu}(x_0)|\mathbf{X}_n) = \frac{\sum_{i=1}^n K_h^2(X_i - x_0)\sigma^2}{(\sum_{i=1}^n K_h(X_i - x_0))^2}$$

Define $S_n = \sum_{i=1}^n K_h(X_i - x_0), T_n = \sum_{i=1}^n K_h^2(X_i - x_0), \mu_{j,c} = \int_{-c}^1 u^j K(u) du, \nu_{j,c} = \int_{-c}^1 u^j K^2(u) du$, then

$$\mathrm{E}(S_n) = \frac{n}{h} \int_0^1 K(\frac{x-x_0}{h}) f(x) dx \stackrel{x_0 = ch}{=} \frac{n}{h} \int_0^{hc+h} K(\frac{x}{h} - c) f(x) dx \stackrel{u = \frac{x}{h} - c}{=} n \int_{-c}^1 K(u) f(hu + x_0) du = n \{ f(x_0) \mu_{0,c} + o(1) \},$$

$$\operatorname{Var}(S_n) \leq \operatorname{E}(\sum_{i=1}^n K_h^2(X_i - x_0)) = \frac{n}{h^2} \int_0^1 K^2(\frac{x - x_0}{h}) f(x) dx = \frac{n}{h} \int_{-c}^1 K^2(u) f(hu + x_0) du = \frac{n}{h} \{f(x_0) \nu_{0,c} + o(1)\},$$

Therefore $\frac{S_n}{n} = f(x_0)\mu_{0,c} + o_p(1)$. Similarly, we can show that $\frac{T_n}{nh^{-1}} = f(x_0)\nu_{0,c} + o_p(1)$.

Thus:

$$\operatorname{Var}(\hat{\mu}(x_0)|\mathbf{X}_n) = \frac{\sum_{i=1}^n K_h^2(X_i - x_0)\sigma^2}{(\sum_{i=1}^n K_h(X_i - x_0))^2} = \frac{\sigma^2 n h^{-1} \{f(x_0)\nu_{0,c} + o_p(1)\}}{n^2 \{f(x_0)\mu_{0,c} + o_p(1)\}^2} = \frac{\sigma^2 \nu_{0,c}}{f(x_0)\mu_{0,c}^2} \frac{1}{nh} + o_p(\frac{1}{nh}),$$

For bias, first note that:

$$\operatorname{Bias}(\hat{\mu}(x_0)|\mathbf{X}_n) = \frac{\sum_{i=1}^n K_h(X_i - x_0)(\mu(X_i) - \mu(x_0))}{\sum_{i=1}^n K_h(X_i - x_0)} = \frac{\sum_{i=1}^n K_h(X_i - x_0)(\mu'(x_0)h\frac{X_i - x_0}{h} + o_p(h))}{\sum_{i=1}^n K_h(X_i - x_0)}$$

$$E\left(\sum_{i=1}^{n} K_{h}(X_{i} - x_{0})(\mu'(x_{0})h \frac{X_{i} - x_{0}}{h} + o_{p}(h))\right) = \mu'(x_{0})f(x_{0})\mu_{1,c}nh + o(nh)$$

$$\operatorname{Var}\left(\sum_{i=1}^{n} K_{h}(X_{i} - x_{0})(\mu'(x_{0})h \frac{X_{i} - x_{0}}{h} + o_{p}(h))\right) \leq nh(\mu'(x_{0}))^{2} f(x_{0})\nu_{2,c} + o(nh)$$

Therefore:

$$\sum_{i=1}^{n} K_{h}(X_{i} - x_{0})(\mu'(x_{0})h \frac{X_{i} - x_{0}}{h} + o_{p}(h)) = \mu'(x_{0})f(x_{0})\mu_{1,c}nh + o_{p}(nh)$$

Therefore:

$$\operatorname{Bias}(\hat{\mu}(x_0)|\mathbf{X}_n) = \frac{\mu'(x_0)f(x_0)\mu_{1,c}nh + o_p(nh)}{n(f(x_0)\mu_{0,c} + o_p(1))} = \mu'(x_0)\frac{\mu_{1,c}}{\mu_{0,c}}h + o_p(h)$$

Problem 2

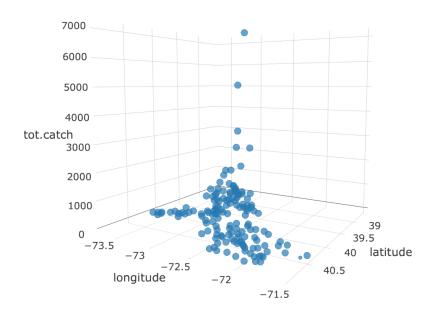


Figure 1: 3D Scatter Plot — Raw Data

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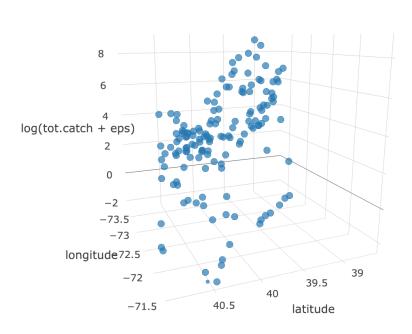


Figure 2: 3D Scatter Plot — Log Data

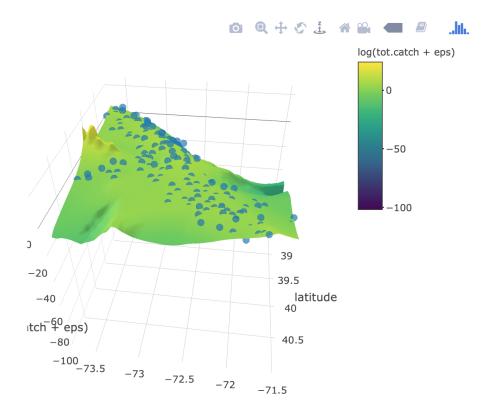


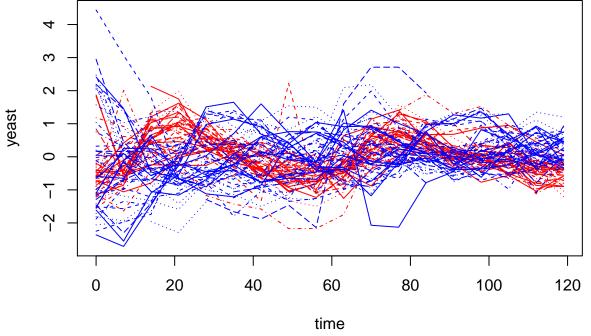
Figure 3: Local Linear Bivariate Fit — Log Data

```
library (SemiPar)
library(locfit)
## locfit 1.5-9.1
                     2013-03-22
library(plotly)
## Loading required package: ggplot2
## Attaching package: 'plotly'
## The following object is masked from 'package:ggplot2':
##
##
       last_plot
## The following object is masked from 'package:stats':
##
##
       filter
## The following object is masked from 'package:graphics':
##
##
       layout
data(scallop)
## plot raw data
p0 <- plot_ly() %>%
```

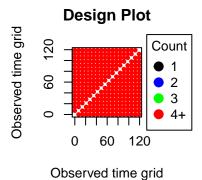
```
add_trace(
  data = scallop,
  x = -latitude,
  y = ~longitude,
  z = ~tot.catch,
  type = "scatter3d",
  mode = "markers",
  size = 3
  )
## plot log data
eps <- 0.1
p <- plot_ly() %>%
  add_trace(
  data = scallop,
  x = -latitude,
  y = ~longitude,
  z = \sim \log(\text{tot.catch} + \text{eps}),
  type = "scatter3d",
  mode = "markers",
  size = 3
## locpol fit using gcv
m < -50
## gcv
nnCandidate \leftarrow seq(0.1, 1, 0.1)
gcvScores <- sapply(</pre>
  nnCandidate,
  function(nn) {
    gcv( log(tot.catch + eps) ~ lp(latitude, longitude, deg=1, nn=nn),
         scallop, ev=lfgrid(mg=m))['gcv']
nnGCV <- nnCandidate[which.min(gcvScores)]</pre>
## fit
res <- locfit( log(tot.catch + eps) ~ lp(latitude, longitude, deg=1, nn = nnGCV),</pre>
                scallop, ev=lfgrid(mg=m))
xGrid <- seq(min(scallop$latitude), max(scallop$latitude), length.out=m)</pre>
yGrid <- seq(min(scallop$longitude), max(scallop$longitude), length.out=m)
z <- matrix(predict(res), m, m, byrow = TRUE)</pre>
p1 <- p %>%
  add_trace(
```

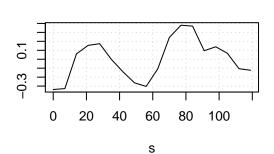
```
x = xGrid,
y = yGrid,
z = z,
type = "surface"
)
```

problem 3



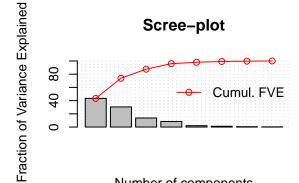
```
data_o <- MakeFPCAInputs(tVec = time, yVec = X)
res_o <- FPCA(data_o$Ly, data_o$Lt)
plot(res_o)</pre>
```



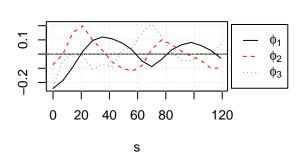


First 3 Eigenfunctions

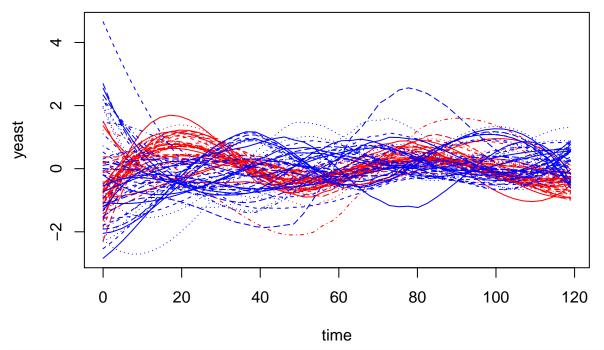
Mean Function



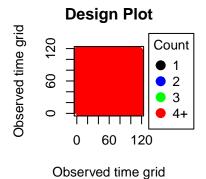
Number of components

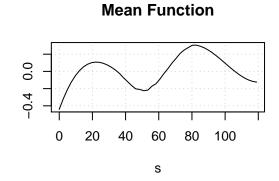


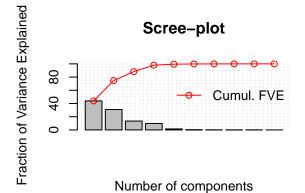
smoothed data $n \leftarrow nrow(X)$ m < -50X_smooth <- matrix(0, ncol = m, nrow = n)</pre> tGrid <- seq(range(time)[1], range(time)[2], length.out = m) for (i in 1:n){ fit <- locfit(X[i,] ~ lp(time, deg=3), ev=lfgrid(mg=m))</pre> X_smooth[i,] <- predict(fit)</pre> } matplot(tGrid, t(X_smooth), type='l', col=c(rep(2,44), rep(4,45)), xlab = "time", ylab = "yeast")

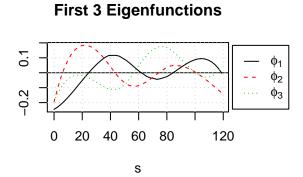


data_s <- MakeFPCAInputs(tVec = tGrid, yVec = X_smooth)
res_s <- FPCA(data_s\$Ly, data_s\$Lt)
plot(res_s)</pre>

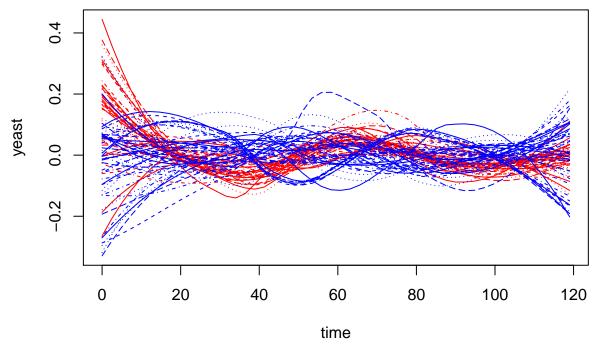




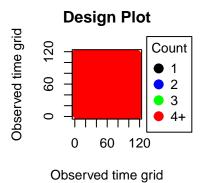


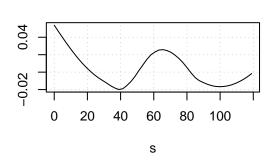


```
## derivative
X_deriv <- matrix(0, ncol = m, nrow = n)
for (i in 1:n){
  fit <- locfit( X_smooth[i,] ~ lp(tGrid, deg=4, nn=0.2), ev=lfgrid(mg=m), deriv=1)</pre>
```

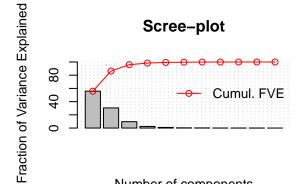


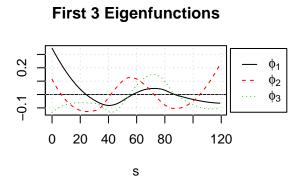
```
data_d <- MakeFPCAInputs(tVec = tGrid, yVec = X_deriv)
res_d <- FPCA(data_d$Ly, data_d$Lt)
plot(res_d)</pre>
```





Mean Function





Number of components