# Xinge ZHU

Email: zhuxinge123@gmail.com Phone: +86-13636674996 WeChat: zxg930301

Homepage Google Scholar

# PROFESSIONAL SUMMARY

- Extensive research experience on deep learning, 3D vision, and robotics
- Strong experience in leading research teams, making product-level solutions and collaborating with industrial partners
- Outstanding record of publication, with over 40 papers published on top conferences and journals (TPAMI, IJCV, CVPR, ICCV, etc) and 3000+ citations

#### **EDUCATION**

#### Ph.D

Sep. 2018 - July. 2021

- MMLab, the Chinese University of Hong Kong
- Supervisor: Dahua Lin

#### Research Assistant

Sep. 2015 - Jan. 2017

■ Institute of Computing Technology, Chinese Academy of Sciences

#### B.Eng

July. 2011 - July. 2015

■ Shandong University

# WORK

## TopMinds 天才少年, Tech LEAD

Aug. 2021 - present

#### **EXPERIENCE**

# ★ HUAWEI Advanced Driving Solution (ADS)

- Lead a team with more than 20 people working on cutting-edge and product-level multi-modality 3D perception for autonomous vehicles. Mass production on AITO M5 M7 and AVATR E11.
- Outstanding Individual of Car Business Unit

#### Research Consultant

Apr. 2020 - June. 2021

#### **★** INCEPTIO

- Work on point-cloud segmentation and detection, and achieve multiple champions of global challenges.
- Work closely with Prof. Ruigang Yang

#### Researcher

Feb. 2017 - July. 2018

## ★ SenseTime

- Work on domain adaptation and zero-shot learning
- Work closely with Dr. Jianping Shi

#### **AWARDS**

	Best paper award on the ICCV 3DODI workshop,	202	22.10
•	The 2nd places in Waymo Camera-only 3D Detection,	202	22.08
•	"TrafficPredict: Trajectory Prediction For Heterogeneous Traffic-Age tained Most Influential AAAI Papers of AAAI 2019. Rank 13.		ob-
•	The ${f 1st}$ place in NuScenes Camera-based 3D Detection,	202	20.12
•	The 2nd places in NuScenes LiDAR Semantic Segmentation,	202	20.12
•	The ${\bf 1st}$ place in Semantic KITTI Semantic & Panoptic Segmentation,	202	20.11
•	Gold Medal, Lyft 3D Detection challenge,	201	19.07
•	Gold Medal (Runner-up), NuScenes 3D Detection challenge,	201	19.03
■ Best paper candidate of PCM (Pacific-Rim Conference on Multimedia), 2017			
•	Top100, Baidu A-Star Programming Contest		2013
•	Golden Medal (Runner-up), Shandong Provincial Programming Conte	$\operatorname{st}$	2013
-	Silver Medal, The ACM/ICPC Asia Regional Contest Tonghua Site		2012

# ACADEMIC SERVICES

# I reviewed papers for the following journals:

- IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI)
- International Journal of Computer Vision (IJCV)
- IEEE Transactions on Multimedia (TMM)
- Springer Journal of Multimedia Tools and Applications (MTA)

#### I served on the TPC Member and reviewer of the following conferences:

- IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)
- International Conference on Learning Representations (ICLR)
- The AAAI Conference on Artificial Intelligence (AAAI)
- Conference on Neural Information Processing Systems (NeurIPS)
- European Conference on Computer Vision (ECCV)

#### PUBLICATIONS #: Corresponding Author; \*: Co-first Author

- Xinge Zhu, Hui Zhou, Tai Wang, Fangzhou Hong, Yuexin Ma, Wei Li, Hongsheng Li, Dahua Lin Cylindrical and Asymmetrical 3D Convolution Networks for LiDAR Segmentation, CVPR (Oral). 2021, rank 1st in LiDAR Semantic Segmentation of SemanticKITTI
- Xinge Zhu, Yuexin Ma, Tai Wang, Yan Xu, Jianping Shi, Dahua Lin. SSN: Shape Signature Networks for Multi-class Object Detection from Point Clouds. ECCV. 2020.

- Xinge Zhu, Hui Zhou, Tai Wang, Fangzhou Hong, Wei Li, Yuexin Ma, Hongsheng Li, Ruigang Yang, Dahua Lin. Cylindrical and Asymmetrical 3D Convolution Networks for LiDAR-based Perception. IEEE Transactions on Pattern Analysis and Machine Intelligence. 2021
- Ma, Yuexin\* and Xinge Zhu\* and Cheng, Xinjing and Yang, Ruigang and Liu, Jiming and Manocha, Dinesh AutoTrajectory: Label-free Trajectory Extraction and Prediction from Videos using Dynamic Points, ECCV. 2020.
- Xinge Zhu, Jiangmiao Pang, Ceyuan Yang, Jianping Shi, Dahua Lin. Adapting object detectors via selective cross-domain alignment. CVPR. 2019.
- Ruoqi Sun\*, Xinge Zhu\*, Chongruo Wu, Chen Huang, Jianping Shi, Lizhuang Ma. Not all areas are equal: Transfer learning for semantic segmentation via hierarchical region selection. CVPR (Oral). 2019.
- Yuexin Ma\*, Xinge Zhu\*, Sibo Zhang, Ruigang Yang, Wenping Wang, Dinesh Manocha. TrafficPredict: Trajectory prediction for heterogeneous traffic-agents. AAAI (Oral). 2019.
- 8. **Xinge Zhu**, Zhichao Yin, Jianping Shi, Hongsheng Li, Dahua Lin. Generative Adversarial Frontal View to Bird View Synthesis. **3DV (Oral)**. 2018.
- Xinge Zhu, Hui Zhou, Ceyuan Yang, Jianping Shi, Dahua Lin. Penalizing Top Performers: Conservative Loss for Semantic Segmentation Adaptation. ECCV. 2018.
- Xinge Zhu, Liang Li, Weigang Zhang, Tianrong Rao, Min Xu, Qingming Huang, Dong Xu. Dependency Exploitation: A Unified CNN-RNN Approach for Visual Emotion Recognition. IJCAI. 2017
- Huitong Yang, Xuyang Bai, Xinge Zhu<sup>#</sup>, Yuexin Ma. One Training for Multiple Deployments: Polar-based Adaptive BEV Perception for Autonomous Driving. ICRA. 2023
- Mingkun Wang, Xinge Zhu, Changqian Yu, Wei Li, Yuexin Ma, Ruochun Jin, Xiaoguang Ren, Dongchun Ren, Mingxu Wang, Wenjing Yang. Ganet: Goal area network for motion forecasting. ICRA. 2023
- Xidong Peng, Xinge Zhu, Yuexin Ma. CL3D: Unsupervised Domain Adaptation for Cross-LiDAR 3D Detection. AAAI. 2023.
- Runnan Chen, Xinge Zhu, Nenglun Chen, Wei Li, Yuexin Ma, Ruigang Yang, Wenping Wang. Bridging Language and Geometric Primitives for Zero-shot Point Cloud Segmentation. ACMMM. 2023
- Ming Nie, Yujing Xue, Chunwei Wang, Chaoqiang Ye, Hang Xu, Xinge Zhu, Qingqiu Huang, Michael Bi Mi, Xinchao Wang, Li Zhang. PARTNER: Level up the Polar Representation for LiDAR 3D Object Detection. ICCV. 2023
- Yiteng Xu, Peishan Cong, Yichen Yao, Runnan Chen, Yuenan Hou, Xinge Zhu, Xuming He, Jingyi Yu, Yuexin Ma. Human-centric Scene Understanding for 3D Large-scale Scenarios. ICCV. 2023
- Yuhang Lu, Qi Jiang, Runnan Chen, Yuenan Hou, Xinge Zhu, Yuexin Ma. See More and Know More: Zero-shot Point Cloud Segmentation via Multi-modal Visual Data. ICCV. 2023

- Lingdong Kong, Youquan Liu, Runnan Chen, Yuexin Ma, Xinge Zhu, Yikang Li, Yuenan Hou, Yu Qiao, Ziwei Liu. Rethinking range view representation for lidar segmentation. ICCV. 2023
- Xiangze Jia, Hui Zhou, Xinge Zhu, Yandong Guo, Ji Zhang, Yuexin Ma. Contrast-Motion: Self-supervised Scene Motion Learning for Large-Scale LiDAR Point Clouds. IJCAI. 2023
- Zhaoyang Xia, Youquan Liu, Xin Li, Xinge Zhu, Yuexin Ma, Yikang Li, Yuenan Hou,
  Yu Qiao. SCPNet: Semantic Scene Completion on Point Cloud. CVPR (Highlight).
  2023
- Runnan Chen, Youquan Liu, Lingdong Kong, Xinge Zhu, Yuexin Ma, Yikang Li, Yuenan Hou, Yu Qiao, Wenping Wang. CLIP2Scene: Towards Label-efficient 3D Scene Understanding by CLIP. CVPR. 2023
- Peishan Cong, Xinge Zhu, Feng Qiao, Yiming Ren, Xidong Peng, Yuenan Hou, Lan Xu, Ruigang Yang, Dinesh Manocha, Yuexin Ma. STCrowd: A Multimodal Dataset for Pedestrian Perception in Crowded Scenes. CVPR. 2022
- Xuyang Bai, Zeyu Hu, Xinge Zhu, Qingqiu Huang, Yilun Chen, Hongbo Fu, Chiew-Lan Tai. TransFusion: Robust LiDAR-Camera Fusion for 3D Object Detection with Transformers. CVPR. 2022
- Yuenan Hou, Xinge Zhu, Yuexin Ma, Chen Change Loy, Yikang Li. Point-to-Voxel Knowledge Distillation for LiDAR Semantic Segmentation. CVPR. 2022
- 25. Xidong Peng, **Xinge Zhu**, Yuexin Ma. SIDE: Center-based Stereo 3D Detector with Structure-awareInstance Depth Estimation. WACV. 2022
- Yiming Ren, Peishan Cong, Xinge Zhu, Yuexin Ma. Self-supervised Point Cloud Completion on Real Traffic Scenes via Scene-concerned Bottom-up Mechanism. ICME. 2022
- Xiao Song, Guorun Yang, Xinge Zhu, Hui Zhou, Yuexin Ma, Zhe Wang, Jianping Shi.
  AdaStereo: An Efficient Domain-Adaptive Stereo Matching Approach. International Journal of Computer Vision. 2022.
- Wanli Chen, Xinge Zhu, Guojin Chen, Bei Yu. Efficient Point Cloud Analysis Using Hilbert Curve. ECCV. 2022
- Tai Wang, Xinge Zhu, Jiangmiao Pang, Dahua Lin. FCOS3D: Fully Convolutional One-Stage Monocular 3D Object Detection. ICCV workshop. 2021. Best paper award on the ICCV 3DODI workshop
- 30. Lin Zhao, Hui Zhou, **Xinge Zhu**, Xiao Song, Hongsheng Li, Wenbing Tao. Lif-seg: Lidar and camera image fusion for 3d lidar semantic segmentation. IEEE Transactions on Multimedia. 2021
- 31. Xiao Song, Guorun Yang, **Xinge Zhu**, Hui Zhou, Zhe Wang, Jianping Shi. AdaStereo: A Simple and Efficient Approach for Adaptive Stereo Matching. CVPR. 2021
- 32. Fangzhou Hong, Hui Zhou, **Xinge Zhu**, Hongsheng Li, Ziwei Liu, LiDAR-based Panoptic Segmentation via Dynamic Shifting Network, CVPR. 2021, **rank 1st in LiDAR Panoptic Segmentation of SemanticKITTI**
- Tai Wang, Xinge Zhu, Dahua Lin. Reconfigurable Voxels: A New Representation for LiDAR-Based Point Clouds. CoRL. 2020.

- Peishan Cong, Xinge Zhu, Yuexin Ma. Input-Output Balanced Framework for Longtailed LiDAR Semantic Segmentation. ICME. 2021
- 35. Yan Xu, Zhaoyang Huang, Kwan-Yee Lin, **Xinge Zhu**, Jianping Shi, Hujun Bao, Guofeng Zhang, Hongsheng Li. SelfVoxeLO: Self-supervised LiDAR Odometry with Voxel-based Deep Neural Networks. CoRL. 2020
- Wanli Chen, Xinge Zhu, Ruoqi Sun, Junjun He, Ruiyu Li, Xiaoyong Shen, Bei Yu.
  Tensor Low-Rank Reconstruction for Semantic Segmentation. ECCV. 2020
- 37. Yan Xu, **Xinge Zhu**, Jianping Shi, Guofeng Zhang, Hujun Bao, Hongsheng Li. Depth Completion from Sparse LiDAR Data with Depth-Normal Constraints. ICCV. 2019.
- 38. Yang Yi, Feng Ni, Yuexin Ma, **Xinge Zhu**, Yuankai Qi, Riming Qiu, Shijie Zhao, Feng Li, Yongtao Wang. High Performance Gesture Recognition via Effective and Efficient Temporal Modeling. IJCAI. 2019
- 39. Ceyuan Yang, Zhe Wang, **Xinge Zhu**, Chen Huang, Jianping Shi, Dahua Lin. Pose Guided Human Video Generation. ECCV. 2018
- 40. Yuexin Ma, **Xinge Zhu**, Yujing Sun, Bingzheng Yan. Image tagging by joint deep visual-semantic propagation. PCM. 2017. Best paper candidate, 5/340