

# 3D Magnetohydrodynamic Code

Variables :  $\vec{b}$ ,  $\vec{u}$ ,  $\theta$

$$\vec{b} = \nabla \times (g \hat{r}) + \nabla \times \nabla \times (h \hat{r})$$

$$\vec{u} = \nabla \times (e \hat{r}) + \nabla \times \nabla \times (f \hat{r})$$

Expand as

$$g = g_c(r) P_l^m(\cos\theta) \cos(m\phi) + g_s(r) P_l^m(\cos\theta) \sin(m\phi)$$

$$h = h_c(r) \quad " \quad " \quad + h_s(r) \quad " \quad "$$

$$e = e_c(r) \quad " \quad " \quad + e_s(r) \quad " \quad "$$

$$f = f_c(r) \quad " \quad " \quad + f_s(r) \quad " \quad "$$

$$\theta = \theta_c(r) \quad " \quad " \quad + \theta_s(r) \quad " \quad "$$

(2)

Consider, for example,  $g_c(r) P_l^m(\cos\theta) \cos(m\phi)$ .

$m$  runs from 0 to MB.

$l$  then runs from  $m$  to LB. ( $LB \geq MB$ )

(but for  $m=0$   $l$  starts at 1)

Also expand  $g_c(r) = \sum_{k=1}^{KB2} T_{k-1}(x)$ . ( $KB2 = KB + 2$ )  
 $\quad \quad \quad \uparrow$   
 $\quad \quad \quad GC(k, l, m)$

So, dimension  $GC(KB2, LB, 0:MB)$ ,

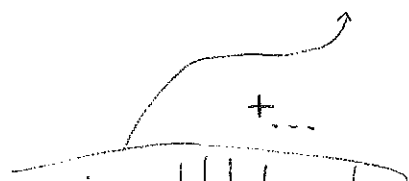
and similarly for GS, HC, HS.

Note, though, that this is wasteful in  $l$ ,  
 but with "triangular" truncation this  
 can't be avoided.

With these spectral coefficients so defined,

$$g = \sum_{m=0}^{MB} \sum_{l=m}^{LB} \sum_{k=1}^{KB2} GC(k, l, m) T_{k-1}(x) P_l^m(\cos\theta) \cos(m\phi)$$

↑  
start at  
1 for  $m=0$



$\sin(m\phi)$

↑

# Induction Equation

$$\frac{\partial}{\partial t} \vec{b} - \nabla^2 \vec{b} = \nabla \times (\vec{u} \times \vec{b})$$

With  $\vec{b}$  expanded in terms of  $g$  and  $h$ , and  $g$  and  $h$  expanded in terms of spherical harmonics as above, the induction equation becomes:

$$\sum_{l,m} \frac{l(l+1)}{r^2} \left[ \frac{\partial h_{lm}}{\partial t} - \frac{\partial^2}{\partial r^2} h_{lm} + \frac{l(l+1)}{r^2} h_{lm} \right] P_l^m e^{im\phi} = \hat{r} \cdot \nabla \times (\vec{u} \times \vec{b})$$

call these spectral coeffs DHC and DHS  
↓

$$- \sum_{l,m} \frac{l(l+1)}{r^2} \left[ \frac{\partial g_{lm}}{\partial t} - \frac{\partial^2}{\partial r^2} g_{lm} + \frac{l(l+1)}{r^2} g_{lm} \right] P_l^m e^{im\phi} = \hat{r} \cdot \nabla \times \nabla \times (\vec{u} \times \vec{b})$$

(DGC and DGS)  
↓

So, given the spectral coefficients for  $\vec{u}$  and  $\vec{b}$ , we compute the nonlinear term  $\vec{u} \times \vec{b}$  at a set of collocation points, then convert back to spectral space and do the curls, to obtain finally the spectral coefficients of the right-hand sides.

Solve equations of the general type  $\frac{\partial y}{\partial t} - D^2 y = F(y)$  (4)  
 by a modified 2<sup>nd</sup> order Runge-Kutta method:

Given  $y_n$ ,

$$D^2 = \frac{\partial^2}{\partial r^2} - \frac{l(l+1)}{r^2}$$

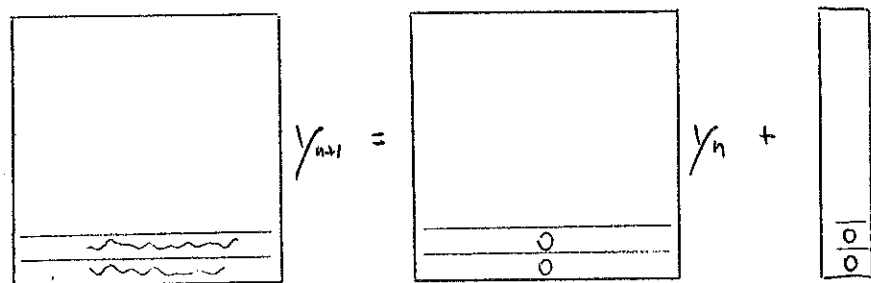
①  $F_n = F(y_n)$

②  $(\tilde{y}_{n+1} - y_n)/\Delta t - D^2(\tilde{y}_{n+1} + y_n)/2 = F_n$

$$(I_1 - \frac{1}{2}\Delta t D^2) \tilde{y}_{n+1} = (I_2 + \frac{1}{2}\Delta t D^2) y_n + \Delta t \cdot F_n$$

③  $\tilde{F}_{n+1} = F(\tilde{y}_{n+1})$

④  $(I_1 - \frac{1}{2}\Delta t D^2) y_{n+1} = (I_2 + \frac{1}{2}\Delta t D^2) y_n + \frac{1}{2}\Delta t (F_n + \tilde{F}_{n+1})$



last two rows impose b.c.'s by setting some appropriate linear combination of the spectral coefficients equal to zero

The first KB rows are given by

$$\frac{l(l+1)}{r_i^2} \left[ T_{j-1}(x_i) - \frac{1}{2}\Delta t \left( \frac{d^2}{dr^2} T_{j-1}(x_i) - \frac{l(l+1)}{r_i^2} T_{j-1}(x_i) \right) \right]$$

where the rows  $i$  denote the appropriate collocation points, and the columns  $j$  the expansion functions.



(6)

$$b_r = l(l+1) \frac{1}{r^2} h_c \cdot P_l^m \cdot \cos(m\phi)$$

$$+ l(l+1) \frac{1}{r^2} h_s \cdot P_l^m \cdot \sin(m\phi)$$


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$$b_\theta = \frac{1}{r} h'_c \cdot \frac{d}{d\theta} P_l^m \cdot \cos(m\phi) - \frac{1}{r} g_c \cdot \frac{1}{s} P_l^m \cdot m \sin(m\phi)$$

$$+ \frac{1}{r} h'_s \cdot \frac{d}{d\theta} P_l^m \cdot \sin(m\phi) + \frac{1}{r} g_s \cdot \frac{1}{s} P_l^m \cdot m \cos(m\phi)$$


---

$$b_\phi = -\frac{1}{r} h'_c \cdot \frac{1}{s} P_l^m \cdot m \sin(m\phi) - \frac{1}{r} g_c \cdot \frac{d}{d\theta} P_l^m \cdot \cos(m\phi)$$

$$+ \frac{1}{r} h'_s \cdot \frac{1}{s} P_l^m \cdot m \cos(m\phi) - \frac{1}{r} g_s \cdot \frac{d}{d\theta} P_l^m \cdot \sin(m\phi)$$


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$$u_r = l(l+1) \frac{1}{r^2} F_c \cdot P_l^m \cdot \cos(m\phi)$$

$$+ l(l+1) \frac{1}{r^2} F_s \cdot P_l^m \cdot \sin(m\phi)$$


---

$$u_\theta = \frac{1}{r} F'_c \cdot \frac{d}{d\theta} P_l^m \cdot \cos(m\phi) - \frac{1}{r} e_c \cdot \frac{1}{s} P_l^m \cdot m \sin(m\phi)$$

$$+ \frac{1}{r} F'_s \cdot \frac{d}{d\theta} P_l^m \cdot \sin(m\phi) + \frac{1}{r} e_s \cdot \frac{1}{s} P_l^m \cdot m \cos(m\phi)$$


---

$$u_\phi = -\frac{1}{r} F'_c \cdot \frac{1}{s} P_l^m \cdot m \sin(m\phi) - \frac{1}{r} e_c \cdot \frac{d}{d\theta} P_l^m \cdot \cos(m\phi)$$

Given the spectral coefficients for  $g$  and  $h$ ,  
compute  $\vec{b}$  at a set of collocation points:

$$b_r = \sum_{k,l,m} HC(k,l,m) \cdot \left( \frac{1}{r^2} T_{k-1}(x) \right) \cdot \left( l(l+1) P_l^m(\cos\theta) \right) \cdot \cos(m\phi) \\ + \dots \sin(m\phi)$$

At the collocation points  $(x_{ik}, ik = 1, KN; \theta_{il}, il = 1, LN; \phi_{im}, im = 1, 2 \cdot MN)$  precompute the arrays

$$\left. \begin{aligned} TT1(k, ik) &= \frac{1}{r^2} T_{k-1}(x) \\ TT2(k, ik) &= \frac{1}{r} \frac{d}{dr} T_{k-1}(x) \\ TT3(k, ik) &= \frac{1}{r} T_{k-1}(x) \end{aligned} \right\} \begin{aligned} &\text{at } x = x_{ik}, \\ &\text{the } KN \text{ zeros of } T_{KN} \end{aligned}$$

$$\left. \begin{aligned} PP1(l, m, il) &= l(l+1) P_l^m \\ PP2(l, m, il) &= \frac{d}{d\theta} P_l^m \\ PP3(l, m, il) &= \frac{1}{\sin\theta} P_l^m \end{aligned} \right\} \begin{aligned} &\text{at } \theta = \theta_{il}, \\ &\text{the } LN \text{ zeros of } P_{LN}^0 \end{aligned}$$

$$\left. \begin{aligned} CS(m, im) &= \cos(m\phi) \\ SN(m, im) &= \sin(m\phi) \end{aligned} \right\} \text{at } \phi = \phi_{im}$$

Once these arrays have been precomputed,

$$b_r(x_{ik}, \theta_{il}, \phi_{im})$$

$$= \sum_{klm} HC(k, l, m) \cdot TT1(k, ik) \cdot PP1(l, m, il) \cdot CS(m, im)$$

$$+ \sum_{klm} HS(k, l, m) \cdot TT1(k, ik) \cdot PP1(l, m, il) \cdot SN(m, im)$$

and similarly for  $b_\theta$  and  $b_\phi$ .

Define work arrays

$$WHC1(ik, l, m) = \sum_k HC(k, l, m) \cdot TT1(k, ik)$$

$$WHS1(ik, l, m) = \dots$$

then

$$b_r = \sum_{lm} WHC1(ik, l, m) \cdot PP1(l, m, il) \cdot CS(m, im)$$

$$+ \sum_{lm} WHS1(ik, l, m) \cdot \dots$$

Define more work arrays

$$WHC11(ik, il, m) = \sum_l WHC1(ik, l, m) \cdot PP1(l, m, il)$$



then

$$b_r = \sum_m WHC11(ik, il, m) \cdot CS(m, im) \\ + WHS11(ik, il, m) \cdot SN(m, im)$$

Actually, the do loops can be rearranged so that these work arrays only need to be subscripted

$WHC1(l, m)$  ...

$WHS11(m)$  ...

so save some memory by doing that.

Given  $\vec{b}$  and  $\vec{u}$  at the collocation points, compute  $\vec{u} \times \vec{b}$ , and separate out the different azimuthal modes again (easy using slow Fourier transform).

So, for each azimuthal mode  $m$ , we have the three components of  $\vec{u} \times \vec{b}$  at the collocation points  $ik, il$ . Then compute  $\hat{r} \cdot \nabla \times (\vec{u} \times \vec{b})$  and  $\hat{r} \cdot \nabla \times \nabla \times (\vec{u} \times \vec{b})$  as follows:

Given  $\vec{F} = \vec{u} \times \vec{b}$  at the collocation points, it will have a spectral expansion of the form

$$F1C(ik, il, m) = \sum_{k,l} F1C^*(k, l, m) \cdot T_{k-1}(x_{ik}) \cdot P_l^m(\cos \theta_{il})$$

$$F1S(ik, il, m) = \dots$$

$$F2C(ik, il, m) = \sum_{k,l} F2C^*(k, l, m) \cdot T_{k-1}(x_{ik}) \cdot \frac{1}{\sin \theta_{il}} P_l^m(\cos \theta_{il})$$

...

$$F3C(ik, il, m) = \sum_{k,l} F3C^*(k, l, m) \cdot T_{k-1}(x_{ik}) \cdot \frac{1}{\sin \theta_{il}} P_l^m(\cos \theta_{il})$$

....

(Except for  $m=0$ , for which  $F2$  and  $F3$  are like  $\sin \theta_{il} \cdot P_l^m(\cos \theta_{il})$ )

Recalling that we have already done the Fourier transform in  $m$ , what we have are precisely the left-hand sides. We can therefore recover the spectral coefficients from

$$F1C_{klm}^* = T_{k,ik}^{-1} \cdot F1C_{ik,il,m} \cdot P_{il,l,m}^{-1}$$

$$F2C_{klm}^* = T_{k,ik}^{-1} \cdot F2C_{ik,il,m} \cdot S_{il} P_{il,l,m}^{-1}$$

$$F3C_{klm}^* = T_{k,ik}^{-1} \cdot F3C_{ik,il,m} \cdot S_{il} P_{il,l,m}^{-1}$$

where the real-to-spectral conversion matrices

$$T_{k,ik}^{-1} \equiv \text{inverse of } T_{ik,k} \equiv T_{k-1}(X_{ik})$$

$$P_{il,l,m}^{-1} \equiv \text{inverse of } P_{l,il,m} \equiv P_l^m(\cos \theta_{il})$$

are precomputed and stored.

invert separate  
for each  $m$ ,  
of course

in this routine must

So, labelling  $T_{k,ik}^{-1} = TINV$ ,  $P_{i,l,m}^{-1} = PINV1$

and  $P_{i,l,m}^{-1} = PINV2$ , for each  $m$  we have

$F_{1C}^* = TINV \cdot F1C \cdot PINV1$ ,  $F1S^* = \dots$

$F2C^* = TINV \cdot F2C \cdot PINV2$ ,  $F2S^* = \dots$

$F3C^* = TINV \cdot F3C \cdot PINV2$ ,  $F3S^* = \dots$

Given these spectral coefficients for  $\vec{F}$ , at the collocation points  $\vec{G} = \nabla \times \vec{F}$  will be given by

$G1C(ik, il, m)$

$$= \sum_{k,l} F3C^*(k, l, m) \cdot \frac{1}{r} T_{k-1}(x) \cdot \frac{1}{s} \frac{d}{d\theta} P_l^m \cdot \cos(m\phi) \\ - F2S^*(k, l, m) \cdot \frac{1}{r} T_{k-1}(x) \cdot \frac{m}{s^2} P_l^m \cdot \cos(m\phi)$$

$G1S(ik, il, m)$

$$= \sum_{k,l} F3S^*(k, l, m) \cdot \frac{1}{r} T_{k-1}(x) \cdot \frac{1}{s} \frac{d}{d\theta} P_l^m \cdot \sin(m\phi) \\ + F2C^*(k, l, m) \cdot \frac{1}{r} T_{k-1}(x) \cdot \frac{m}{s^2} P_l^m \cdot \sin(m\phi)$$

$G2C(ik, il, m)$ 

$$= \sum_{k,l} F1S^*(k, l, m) \cdot \frac{1}{r} T_{k-1}(x) \cdot \frac{m}{s} P_l^m \cdot \cos(m\phi) \\ - F3C^*(k, l, m) \cdot \frac{1}{r} \frac{d}{dr}(r T_{k-1}(x)) \cdot \frac{1}{s} P_l^m \cdot \cos(m\phi)$$

 $G2S(ik, il, m)$ 

$$= \sum_{k,l} F1C^*(k, l, m) \cdot \frac{1}{r} T_{k-1}(x) \cdot \frac{m}{s} P_l^m \cdot \sin(m\phi) \\ - F3S^*(k, l, m) \cdot \frac{1}{r} \frac{d}{dr}(r T_{k-1}(x)) \cdot \frac{1}{s} P_l^m \cdot \sin(m\phi)$$

 $G3C(ik, il, m)$ 

$$= \sum_{k,l} F2C^*(k, l, m) \cdot \frac{1}{r} \frac{d}{dr}(r T_{k-1}(x)) \cdot \frac{1}{s} P_l^m \cdot \cos(m\phi) \\ - F1C^*(k, l, m) \cdot \frac{1}{r} T_{k-1}(x) \cdot \frac{d}{d\theta} P_l^m \cdot \cos(m\phi)$$

 $G3S(ik, il, m)$ 

$$= \sum_{k,l} F2S^*(k, l, m) \cdot \frac{1}{r} \frac{d}{dr}(r T_{k-1}(x)) \cdot \frac{1}{s} P_l^m \cdot \sin(m\phi) \\ - F1S^*(k, l, m) \cdot \frac{1}{r} T_{k-1}(x) \cdot \frac{d}{d\theta} P_l^m \cdot \sin(m\phi)$$

Define the matrices

$$\left. \begin{aligned} T1_{ik,k} &= \frac{1}{r} T_{k-1}(x) \\ T2_{ik,k} &= \frac{1}{r} \frac{d}{dr} (r T_{k-1}(x)) \end{aligned} \right\} \text{ at } x = x_{ik}$$

$$\left. \begin{aligned} \text{For } m=0 \rightarrow P1_{i,i,m} &= \frac{1}{s} \frac{d}{d\theta} P_1^m \\ P2_{i,i,m} &= \frac{m}{s^2} P_1^m \\ P3_{i,i,m} &= \frac{d}{d\theta} P_1^m \end{aligned} \right\} \text{ at } \theta = \theta_{ii}$$

then for each  $m$

$$G1C = T1 \cdot F3C^* \cdot P1 - T1 \cdot F2S^* \cdot P2$$

$$G1S = T1 \cdot F3S^* \cdot P1 + T1 \cdot F2C^* \cdot P2$$

$$G2C = T1 \cdot F1S^* \cdot \left(\frac{m}{s} P_1^m\right) - T2 \cdot F3C^* \cdot \left(\frac{1}{s} P_1^m\right)$$

$$G2S = -T1 \cdot F1C^* \cdot \left(\frac{m}{s} P_1^m\right) - T2 \cdot F3S^* \cdot \left(\frac{1}{s} P_1^m\right)$$

$$G3C = T2 \cdot F2C^* \cdot \left(\frac{1}{s} P_1^m\right) - T1 \cdot F1C^* \cdot P3$$

$$G3S = T2 \cdot F2S^* \cdot \left(\frac{1}{s} P_1^m\right) - T1 \cdot F1S^* \cdot P3$$

Finally, remembering that we know the  $F^*$ 's in terms of the  $F$ 's, and in exactly the same way the  $G^*$ 's in terms of the  $G$ 's, we have,

$$G1C^* = TINV \cdot [T1 \cdot (TINV \cdot F3C \cdot PINV2) \cdot P1] \cdot PINV1 \\ - TINV \cdot [T1 \cdot (TINV \cdot F2S \cdot PINV2) \cdot P2] \cdot PINV1$$

$$G1S^* = \dots$$

$$G2C^* = TINV \cdot T1 \cdot (TINV \cdot F1S \cdot PINV1) \cdot m \\ - TINV \cdot T2 \cdot (TINV \cdot F3C \cdot PINV2)$$

$$G2S^* = \dots$$

$$G3C^* = TINV \cdot T2 \cdot (TINV \cdot F2C \cdot PINV2) \\ - TINV \cdot [T1 \cdot (TINV \cdot F1C \cdot PINV1) \cdot P3] \cdot PINV2$$

$$G3S^* = \dots$$

So, define the matrices

$$TT1 = TINV \cdot T1 \cdot TINV$$

$$TT2 = TINV \cdot T2 \cdot TINV$$

$$PP1 = PINV2 \cdot P1 \cdot PINV1$$

$$PP2 = PINV2 \cdot P2 \cdot PINV1$$

$$PP3 = PINV1 \cdot P3 \cdot PINV2$$

then

$$G1C^* = TT1 \cdot F3C \cdot PP1 - TT1 \cdot F2S \cdot PP2$$

$$G1S^* = TT1 \cdot F3S \cdot PP1 + TT1 \cdot F2C \cdot PP2$$

$$G2C^* = TT1 \cdot F1S \cdot mPINV1 - TT2 \cdot F3C \cdot PINV2$$

$$G2S^* = -TT1 \cdot F1C \cdot mPINV1 - TT2 \cdot F3S \cdot PINV2$$

$$G3C^* = TT2 \cdot F2C \cdot PINV2 - TT1 \cdot F1C \cdot PP3$$

$$G3S^* = TT2 \cdot F2S \cdot PINV2 - TT1 \cdot F1S \cdot PP3$$



Now,  $G1C^*$  and  $G1S^*$  are half of what we want, namely the spectral coefficients of  $\hat{r} \cdot \nabla \times \vec{F}$ . To obtain the spectral coefficients of  $\hat{r} \cdot \nabla \times \nabla \times \vec{F}$ , just take one more curl,

$$H1C = T1 \cdot G3C^* \cdot P1 - T1 \cdot G2S^* \cdot P2$$

$$H1S = T1 \cdot G3S^* \cdot P1 + T1 \cdot G2C^* \cdot P2$$

so

$$H1C^* = TINV \cdot [T1 \cdot (TT2 \cdot F2C \cdot PINV2) \cdot P1] \cdot PINV1$$

$$- TINV \cdot [T1 \cdot (TT1 \cdot F1C \cdot PP3) \cdot P1] \cdot PINV1$$

$$+ TINV \cdot [T1 \cdot (TT1 \cdot F1C \cdot mPINV1) \cdot P2] \cdot PINV1$$

$$+ TINV \cdot [T1 \cdot (TT2 \cdot F3S \cdot PINV2) \cdot P2] \cdot PINV1$$

$$H1S^* = TINV \cdot [T1 \cdot (TT2 \cdot F2S \cdot PINV2) \cdot P1] \cdot PINV1$$

$$- TINV \cdot [T1 \cdot (TT1 \cdot F1S \cdot PP3) \cdot P1] \cdot PINV1$$

$$+ TINV \cdot [T1 \cdot (TT1 \cdot F1S \cdot mPINV1) \cdot P2] \cdot PINV1$$

$$- TINV \cdot [T1 \cdot (TT2 \cdot F3C \cdot PINV2) \cdot P2] \cdot PINV1$$

So, define the matrices

$$TT3 = TINV \cdot T1 \cdot TT1$$

$$TT4 = TINV \cdot T1 \cdot TT2$$

$$PP4 = (mPINV1 \cdot P2 - PP3 \cdot P1) \cdot PINV1$$

then finally

$$G1C^* = TT1 \cdot F3C \cdot PP1 - TT1 \cdot F2S \cdot PP2$$

$$G1S^* = TT1 \cdot F3S \cdot PP1 + TT1 \cdot F2C \cdot PP2$$


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$$H1C^* = TT4 \cdot F2C \cdot PP1 + TT3 \cdot F1C \cdot PP4$$

$$+ TT4 \cdot F3S \cdot PP2$$


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$$H1S^* = TT4 \cdot F2S \cdot PP1 + TT3 \cdot F1S \cdot PP4$$

$$- TT4 \cdot F3C \cdot PP2$$

completes the evaluation of the curls.

## Momentum Equation

$$\frac{\partial}{\partial t} \vec{u} - E \nabla^2 \vec{u} = -\nabla p - (\vec{u} \cdot \nabla) \vec{u} \\ + \Lambda (\nabla \times \vec{b}) \times \vec{b} + Ra \theta \vec{r}$$

With  $\vec{u}$  expanded in terms of  $e$  and  $F$ ,  
and  $e$  and  $F$  expanded in terms of spherical  
harmonics as above, the momentum equation  
becomes:

$$\frac{l(l+1)}{r^2} \left[ \frac{\partial}{\partial t} - E \frac{\partial^2}{\partial r^2} + E \frac{l(l+1)}{r^2} \right] e P_l^m = \hat{r} \cdot \nabla \times \vec{F}$$

call these spectral  
coeffs DEC and DE

$$\frac{l(l+1)}{r^2} \left[ \frac{\partial}{\partial t} - E \frac{\partial^2}{\partial r^2} + E \frac{l(l+1)}{r^2} \right] \left[ -\frac{\partial^2}{\partial r^2} + \frac{l(l+1)}{r^2} \right] F P_l^m$$

$$= \hat{r} \cdot \nabla \times \nabla \times \vec{F}$$

← OFC and  
OFS

where

$$\vec{F} = -(\vec{u} \cdot \nabla) \vec{u} + \Lambda (\nabla \times \vec{b}) \times \vec{b} + Ra \theta \vec{r}$$

## Temperature Equation

$$\frac{\partial}{\partial t} \theta - q \nabla^2 \theta = -u \cdot \nabla \theta$$

Expand as

$$\theta = \theta_c(r) P_l^m(\cos \theta) \cos(m\phi) + \theta_s(r) P_l^m(\cos \theta) \sin(m\phi)$$

(and remember that here we must include  $l=0$ )

then the temperature equation becomes

$$\left[ \frac{\partial}{\partial t} \theta - q \left( \frac{\partial^2}{\partial r^2} \theta + \frac{2}{r} \frac{\partial}{\partial r} \theta - \frac{l(l+1)}{r^2} \theta \right) \right] P_l^m = -u \cdot \nabla \theta$$

↑  
(DTC and  
OTS)