Lecture 13: CPU Scheduling

(Threads, Dispatching, and Scheduling Policies)

Xin Liu

xliu15@fsu.edu

COP 4610 Operating Systems

Outline

- Threads
- Dispatcher
- Amdahl's Law
- CPU Scheduling

Why *Concurrency*?

Allows multiple applications to run at the same time

Analogy: juggling



- What is an applications?
 - A Program that runs on the OS.

History Phase I: Hardware Expensive, Humans Cheap

- Hardware: mainframes
- OS: human operators
 - Handle one job (a unit of processing) at a time
 - Computer time wasted while operators walk around the machine room



IBM System/360

OS Design Goal

- Efficient use of the hardware
 - Batch system: collects a batch of jobs before processing them and printing out results
 - Job collection, job processing, and printing out results can occur concurrently
 - *Multiprogramming*: multiple programs can run concurrently
 - Example: I/O-bound jobs and CPU-bound jobs

History Phase II: Hardware Cheap, Humans Expensive

- Hardware: terminals
- OS design goal: more efficient use of human resources
 - Timesharing systems: each user can afford to own terminals to interact with machines
 - The operating system could support multiple users simultaneously, each with their own terminal
 - Each user had an efficient and responsive experience, without the need for dedicated machines for each person



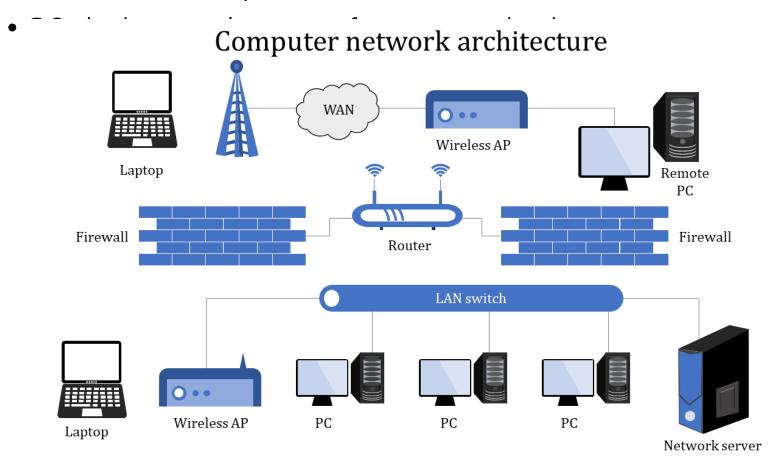
History Phase III: Hardware Very Cheap, Humans Very Expensive

- Hardware: personal computers
- OS design goal: allowing a user to perform many tasks at the same time
 - Multitasking. a single user can run multiple programs on the same machine at the same time
 - Multiprocessing. the ability to use multiple processors on the same machine



History Phase IV: Distributed Systems

Hardware: computers with networks



Why *Concurrency*?

- Allows multiple applications to run at the same time
 - Analogy: juggling
- Program is a state machine.
- What is the red ball?
 - A State.



Benefits of Concurrency

- Better performance
 - One application uses only the processor
 - One application uses only the disk drive
 - Completion time is shorter when running both concurrently than consecutively

Drawbacks of Concurrency

- Applications need to be protected from one another
- Additional coordination mechanisms among applications
- Overhead to switch among applications
- Potential performance degradation when running too many applications

Thread

- A sequential execution stream
 - The smallest CPU scheduling unit
 - Can be programmed as if it owns the entire CPU
 - Implication: an infinite loop within a thread won't halt the system
 - Illusion of multiple CPUs on a single-CPU machine

Thread Benefits

- Simplified programming model per thread
- Example: Microsoft Word
 - One thread for grammar check; one thread for spelling check; one thread for formatting; and so on...
 - Can be programmed independently
 - Simplifies the development of large applications

Address Space

- Contains all states necessary to run a program
 - Code, data, stack
 - Program counter
 - Register values
 - Resources required by the program
 - Status of the running program
- A mechanism to protect one app from crashing another app

Process

- An address space + at least one thread of execution
 - Address space offers protection among processes
 - Threads offer concurrency
- A fundamental unit of computation

Process =? Program

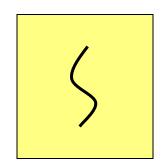
- Program: a collection of statements in C or any programming languages
- Process: a running instance of the program, with additional states and system resources
- Two processes can run the same program
 - The code segment of two processes are the same program
- A program can create multiple processes
 - Example: gcc, chrome

Real-life Analogy?

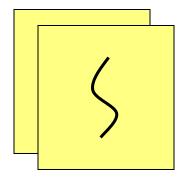
- Program: a recipe
- Process: everything needed to cook
 - e.g., kitchen
- Two chefs can cook the same recipe in different kitchens
- One complex recipe can involve several chefs

Some Definitions

• *Uniprogramming*: running one process at a time

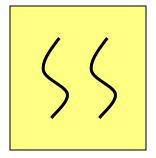


• Multiprogramming: running multiple processes on a machine



Some Definitions

- *Multithreading*: having multiple threads per address space (threads share the same address space)
- *Multiprocessing*: running programs on a machine with multiple processors
- *Multitasking*: a single user can run multiple processes



Classifications of OSes

	Single address space	Multiple address
		spaces
Single thread	MS DOS, Macintosh	Traditional UNIX
Multiple threads	Embedded systems	Windows, iOS

Threads & Thread Control Block

- A thread owns a thread control block
 - Execution states of the thread
 - The status of the thread
 - Running or sleeping
 - Scheduling information of the thread
 - e.g., priority

Threads & Dispatching Loop

- •Threads are run from a *dispatching loop*
 - Can be thought as a per-CPU thread
 - •1 OOP
 - Run thread
 - Save states
- •Choose a new thread to run —— Scheduling
 •Load states from a different thread



Simple? Not quite...

- How does the dispatcher regain control after a thread starts running?
- What states should a thread save?
- How does the dispatcher choose the next thread?

How does the dispatcher regain control?

- Two ways:
 - 1. Internal events ("Sleeping Beauty")
 - O Yield—a thread gives up CPU voluntarily
 - A thread is waiting for I/O
 - A thread is waiting for some other thread
 - 2. External events
 - O Interrupts—a complete disk request
 - O Timer—it's like an alarm clock

What states should a thread save?

- Anything that the next thread may trash before a context switch
 - Program counter
 - Registers
 - Changes in execution stack

How does the dispatcher choose the next thread?

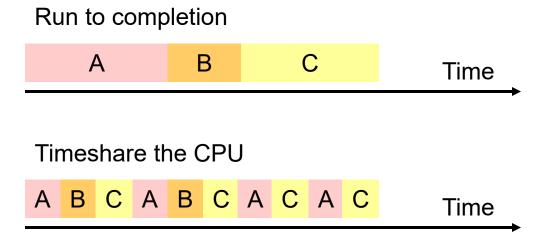
- The dispatcher keeps a list of threads that are ready to run
- If no threads are ready
 - Dispatcher just loops
- If one thread is ready
 - Easy

How does the dispatcher choose the next thread?

- If more than one thread are ready
 - We choose the next thread based on the scheduling policies
 - Examples
 - FIFO (first in, first out)
 - LIFO (last in, first out)
 - Priority-based policies

How does the dispatcher choose the next thread?

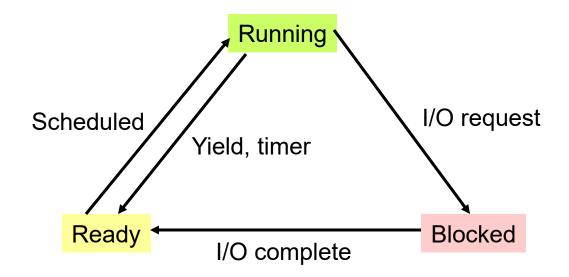
- Additional control by the dispatcher on how to share the CPU
 - Suppose we have three threads



Per-thread States

- Each thread can be in one of the three states
 - *1. Running*: has the CPU
 - Blocked: waiting for I/O or another thread
 - 3. Ready to run: on the ready list, waiting for the CPU

Per-thread State Diagram



For Multi-core Machines

- Each core has a dispatcher loop
 - Decide which thread will execute next
- One core has a global dispatcher loop
 - Decide which core to execute a thread

Parallelism vs. Concurrency

- Parallel computations
 - Computations can happen at the same time on separate cores
- Concurrent computations
 - One unit of computation does not depend on another unit of computation
 - Can be done in parallel on multiple cores
 - Can time share a single core (not parallel)

Real-life Example

- Two hands are playing piano in parallel (not concurrently)
 - Notes from left and right hands are dependent on each other
- Two separate groups singing 'row row row your boat' concurrently (and in parallel)

Amdahl's Law

- Identifies potential performance gains from adding cores
 - P = % of program that can be executed in parallel
 - N = number of cores

•speedup
$$\leq \frac{1}{(1-P)+\frac{P}{N}}$$

Amdahl's Law

- Example
 - P = 75% of program that can be executed in parallel
 - N = 2 cores

•speedup
$$\leq \frac{1}{(1-0.75) + \frac{0.75}{2}} = 1.6$$

CPU Scheduler

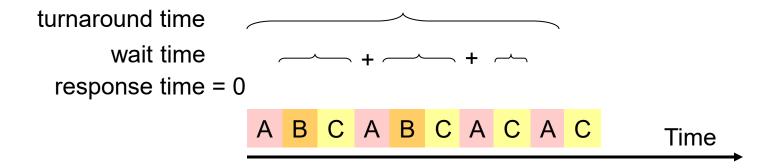
- A CPU scheduler is responsible for
 - Removal of running process from the CPU
 - Selection of the next running process
 - Based on a particular strategy

- Maximize
 - *CPU utilization*: keep the CPU as busy as possible
 - *Throughput*: the number of processes completed per unit time

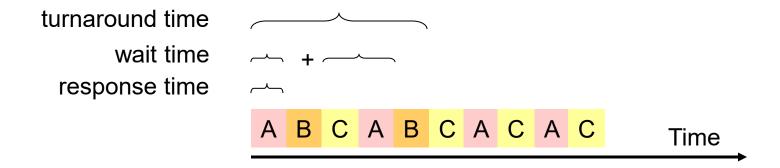
Minimize

- Response time: the time of submission to the time the first response is produced
- Wait time: total time spent waiting in the ready queue
- Turnaround time: the time of submission to the time of completion

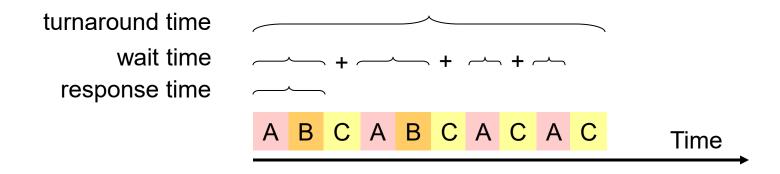
- Suppose we have processes A, B, and C, submitted at time 0
- We want to know the response time, wait time, and turnaround time of process A



- Suppose we have processes A, B, and C, submitted at time 0
- We want to know the response time, wait time, and turnaround time of process B



- Suppose we have processes A, B, and C, submitted at time 0
- We want to know the response time, wait time, and turnaround time of process C



- Suppose we have processes A and B submitted at time 0; process C, time 1
- We want to know the response time, wait time, and turnaround time of process C

turnaround time
wait time
response time

A B C A B C A C Time

- Achieve fairness
 - What is fair?
 - Guaranteed to have at least 1/n share
 - How do two people divide a cake in a fair way?
- There are tensions among these goals

Assumptions

- Each user runs one process
- Each process is single threaded
- Processes are independent
- They are not realistic assumptions; they serve to simplify analyses

Scheduling Policies

- FIFO (first in, first out)
- Round robin
- SJF (shortest job first)
- Multilevel feedback queues
- Lottery scheduling

FIFC

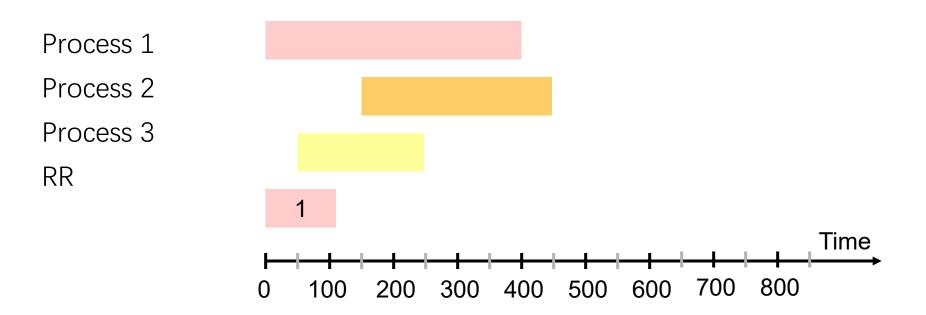
- FIFO: assigns the CPU based on the order of requests
 - Nonpreemptive: A process keeps running on a CPU until it is blocked or terminated
 - Also known as FCFS (first come, first serve)
 - + Simple
 - Short jobs can get stuck behind long jobs

Round Robin

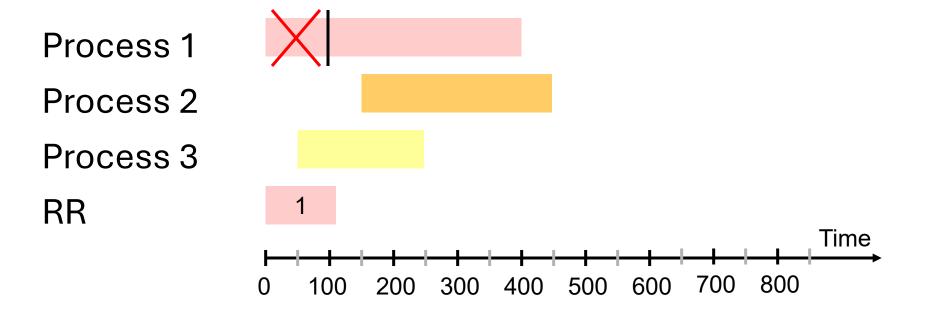
- Round Robin (RR) periodically releases the CPU from longrunning jobs
 - Based on timer interrupts so short jobs can get a fair share of CPU time
 - Preemptive: a process can be forced to leave its running state and replaced by another running process
 - *Time slice*: interval between timer interrupts

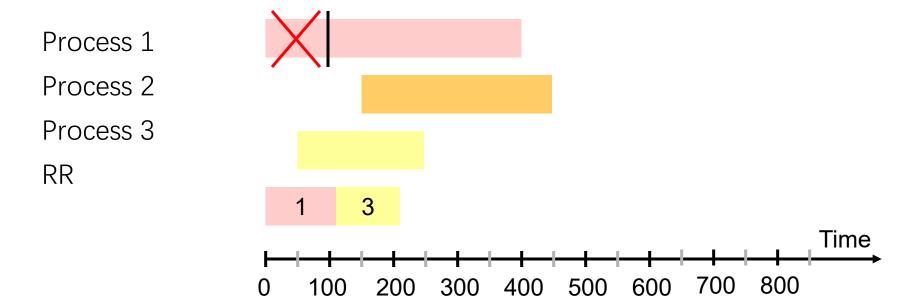
More on Round Robin

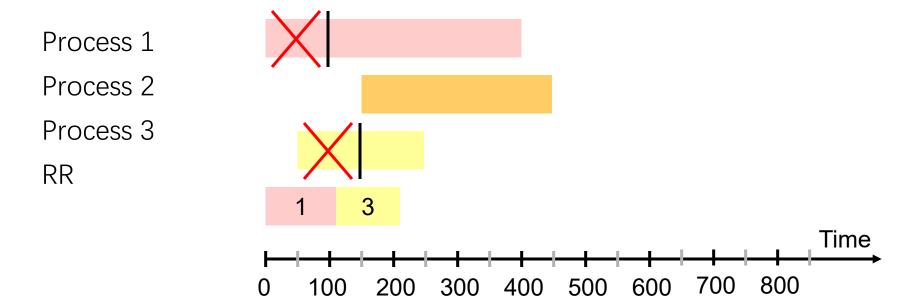
- If time slice is too long
 - Scheduling degrades to FIFO
- If time slice is too short
 - Throughput suffers
 - Context switching cost dominates

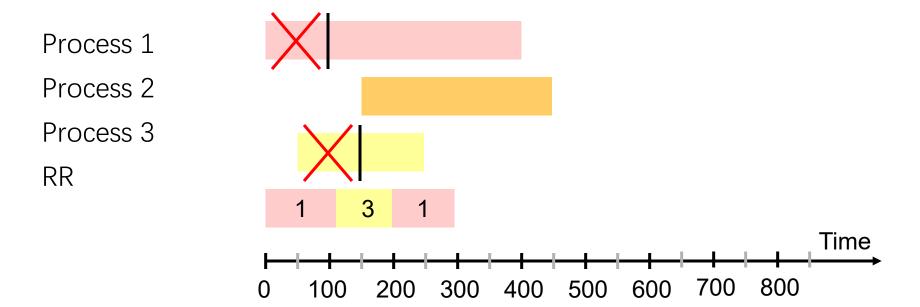


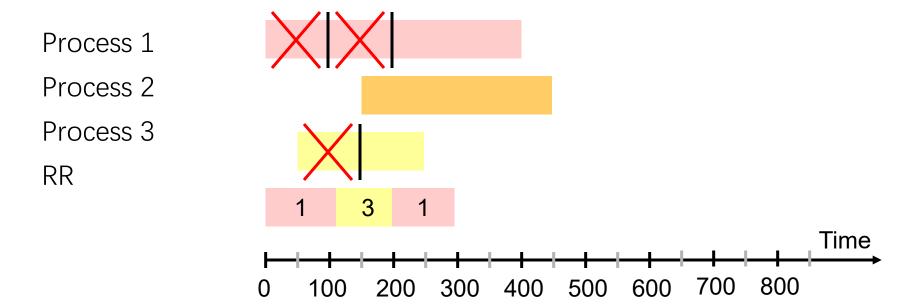
Important

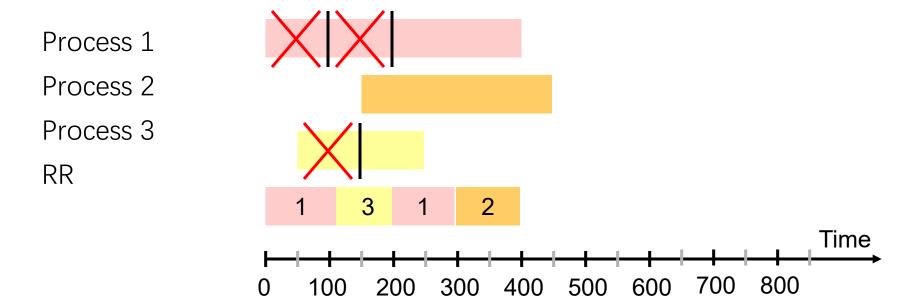








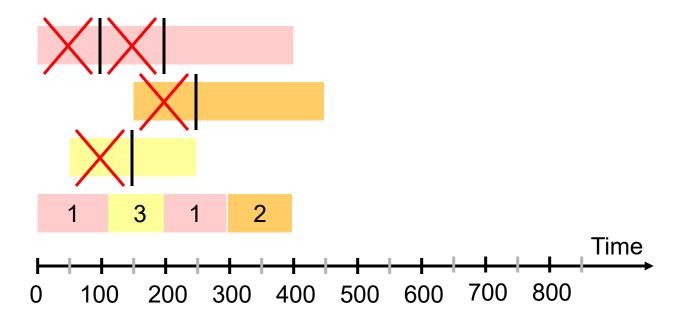




Process 1

Process 2

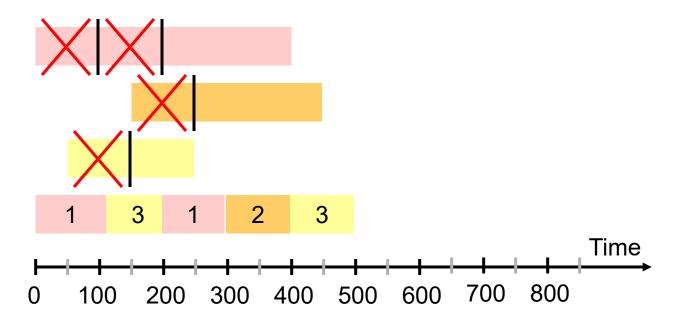
Process 3



Process 1

Process 2

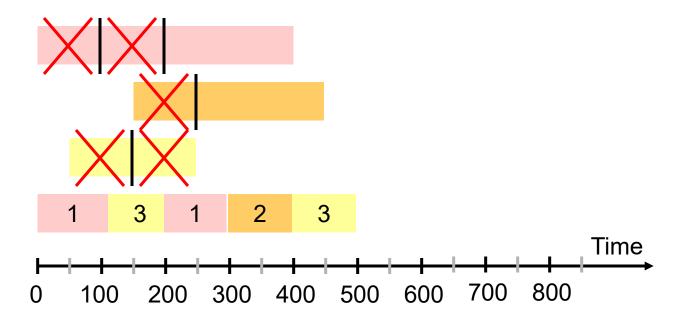
Process 3



Process 1

Process 2

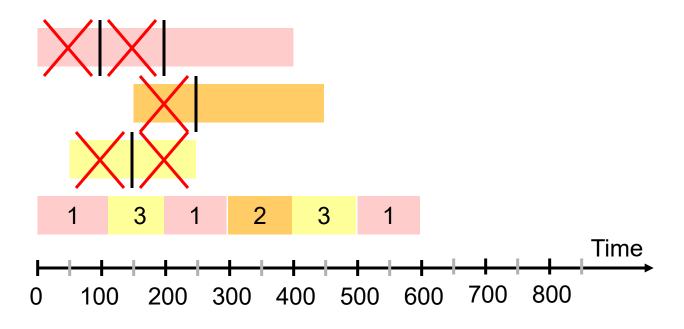
Process 3



Process 1

Process 2

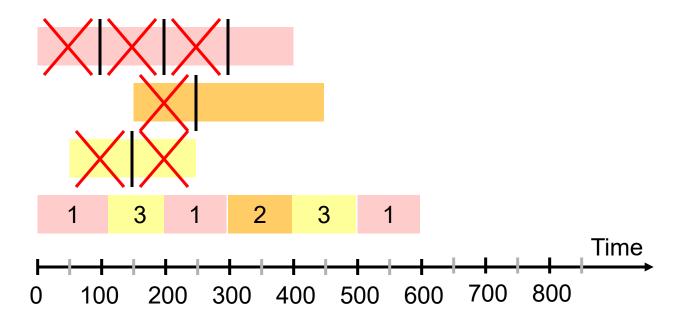
Process 3



Process 1

Process 2

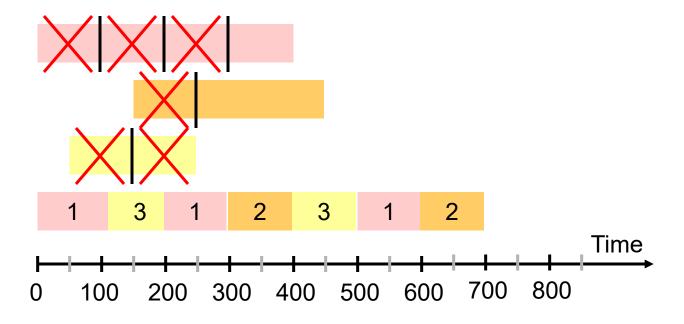
Process 3



Process 1

Process 2

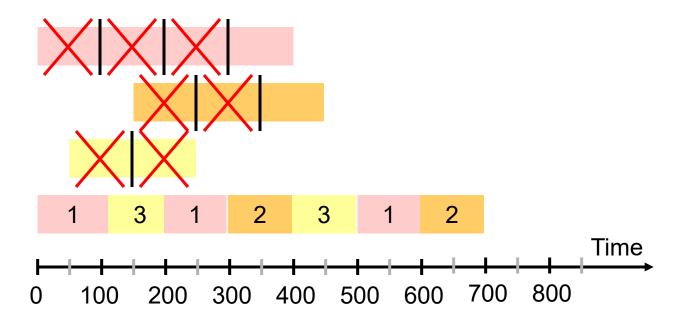
Process 3



Process 1

Process 2

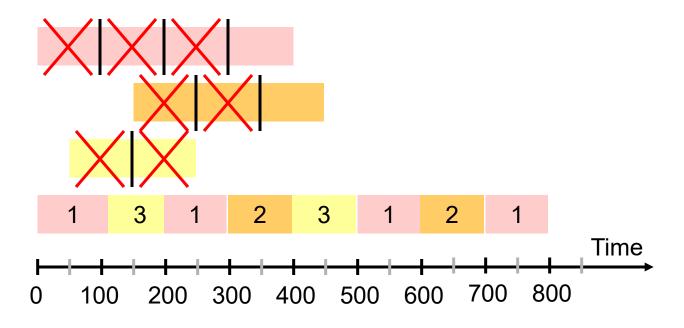
Process 3



Process 1

Process 2

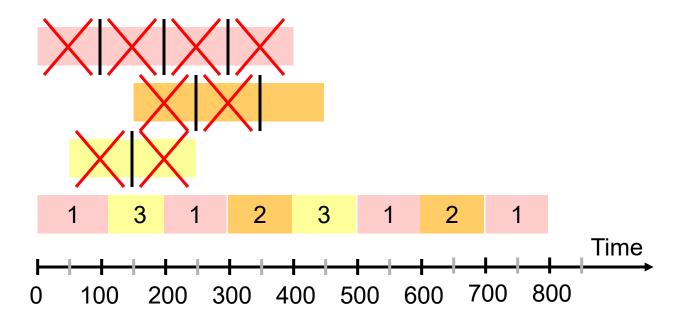
Process 3



Process 1

Process 2

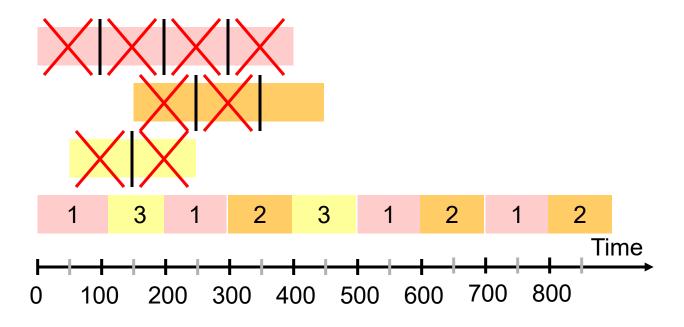
Process 3



Process 1

Process 2

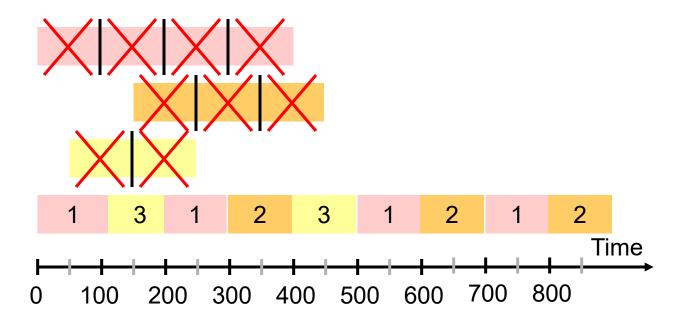
Process 3

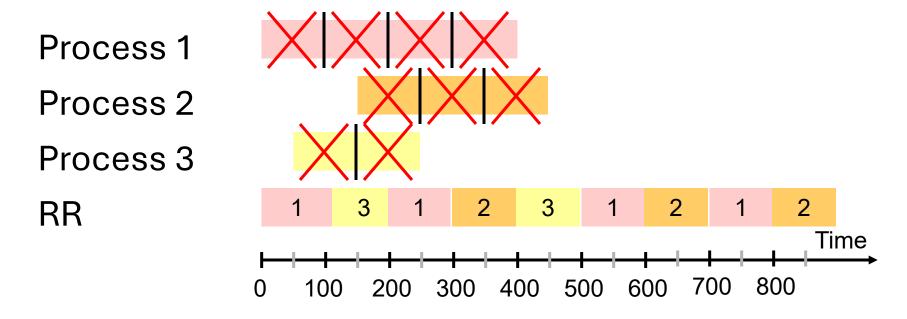


Process 1

Process 2

Process 3

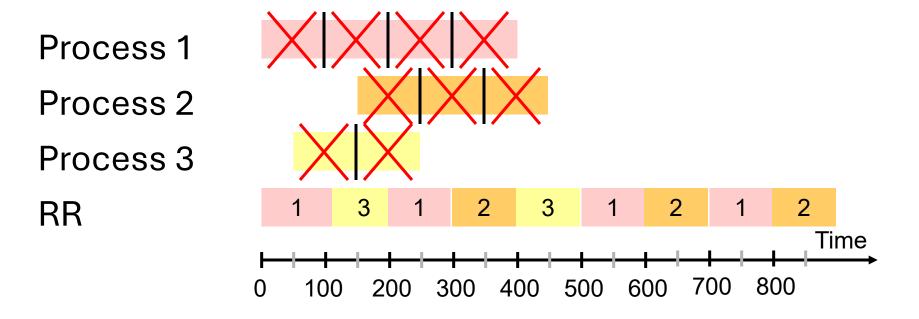




Response time for process 1: 0

Response time for process 2: 300 - 150 = 150

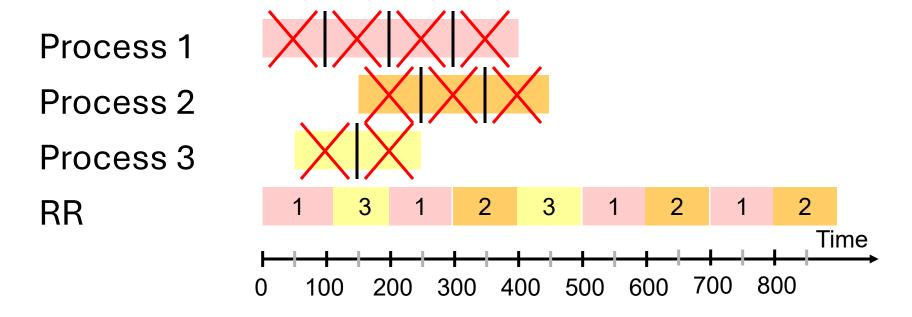
Response time for process 3: 100 - 50 = 50



Wait time for process 1: 0 + (200 - 100) + (500 - 300) + (700 - 600) = 400

Wait time for process 2: (300 - 150) + (600 - 400) + (800 - 700) = 450

Wait time for process 3: (100 - 50) + (400 - 200) = 250



Turnaround time for process 1: 800 - 0 = 800

Turnaround time for process 2: 900 - 150 = 750

Turnaround time for process 3: 500 - 50 = 450

FIFO vs. Round Robin

• With zero-cost context switch, is RR always better than FIFO?

FIFO vs. Round Robin

Suppose we have three jobs of equal length

turnaround time of C turnaround time of B turnaround time of A ABCABCABC Time Round Robin turnaround time of C turnaround time of B turnaround time of A Α В Time **FIFO**

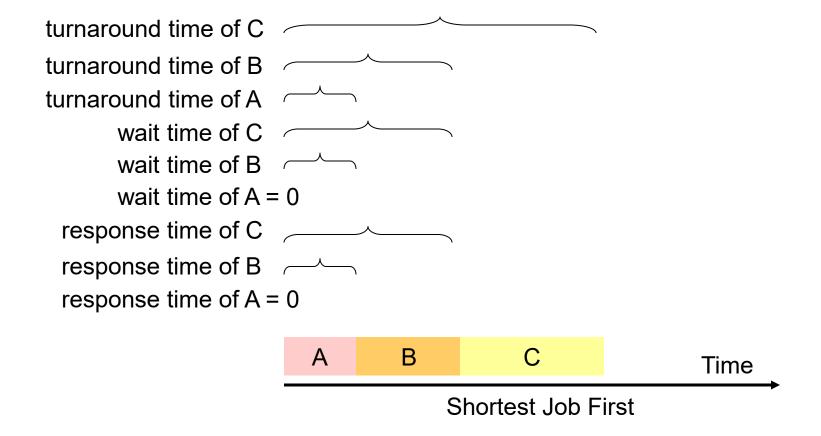
FIFO vs. Round Robin

- Round Robin
 - + Shorter response time
 - + Fair sharing of CPU
 - Not all jobs are preemptive
 - Not good for jobs of the same length

Shortest Job First (SJF)

- SJF runs whatever job puts the least demand on the CPU, also known as STCF (shortest time to completion first)
 - + Provably optimal
 - + Great for short jobs
 - + Small degradation for long jobs
- Real life example: supermarket express checkouts

SJF Illustrated



Shortest Remaining Time First (SRTF)

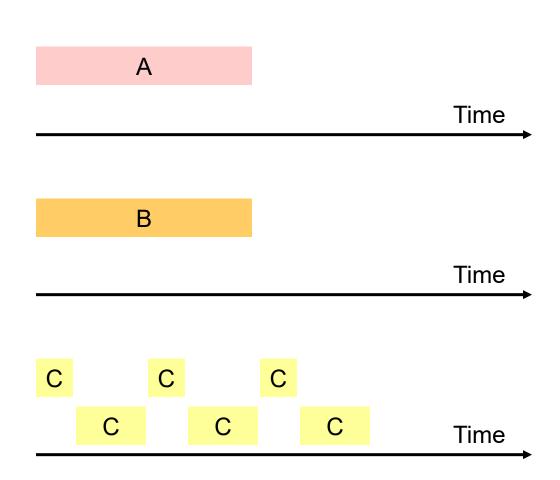
- SRTF: a preemptive version of SJF
 - If a job arrives with a shorter time to completion, SRTF preempts the CPU for the new job
 - Also known as SRTCF (shortest remaining time to completion first)
 - Generally used as the base case for comparisons

SJF and SRTF vs. FIFO and Round Robin

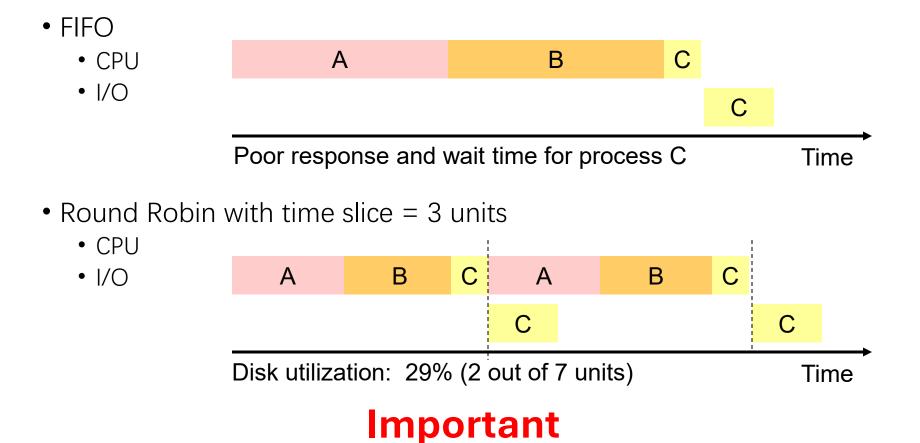
- If all jobs are the same length, SJF → FIFO
 - FIFO is the best you can do
- If jobs have varying length
 - Short jobs do not get stuck behind long jobs under SRTF

A More Complicated Scenario (Arrival Times = 0)

- Process A (6 units of CPU request)
 - 100% CPU
 - 0% I/O
- Process B (6 units of CPU request)
 - 100% CPU
 - 0% I/O
- Process C (infinite loop)
 - 33% CPU
 - 67% I/O

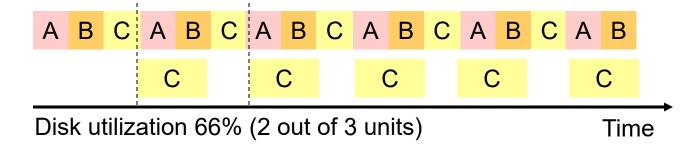


A More Complicated Scenario

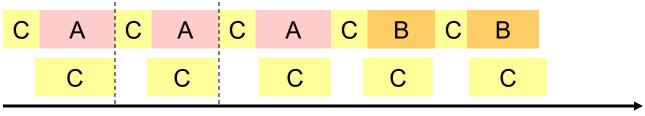


A More Complicated Scenario

- Round Robin with time slice = 1 unit
 - CPU
 - 1/0



- SRTCF
 - CPU
 - 1/0



Time

Disk utilization: 66% (2 out of 3 units)

Drawbacks of Shortest Job First

- *Starvation*: constant arrivals of short jobs can keep long ones from running
- There is no way to know the completion time of jobs (most of the time)
 - Some solutions
 - Ask the user, who may not know any better
 - If a user cheats, the job is killed

Priority Scheduling (Multilevel Queues)

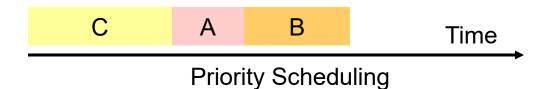
• *Priority scheduling*: The process with the highest priority runs first

Priority 0: CPriority 1:

• Priority 2:

В

Assume that low numbers represent high priority



Priority Scheduling

+ Generalization of SJF

 With SJF, higher priority is inversely proportionally to requested_CPU_time

- Starvation

• To prevent starvation, mechanisms like aging can be used, where the priority of a process increases the longer it waits.

- Multilevel feedback queues use multiple queues with different priorities
 - Round robin at each priority level
 - Run highest priority jobs first
 - Once those finish, run next highest priority, etc
 - Jobs start in the highest priority queue
 - If time slice expires, drop the job by one level
 - If time slice does not expire, push the job up by one level

time = 0

Priority 0 (time slice = 1):

A B C

- Priority 1 (time slice = 2):
- Priority 2 (time slice = 4):

Time

Important

time = 1

Priority 0 (time slice = 1):

ВС

- Priority 1 (time slice = 2):
- Priority 2 (time slice = 4):

A Time

time = 2

- Priority 0 (time slice = 1):
- Priority 1 (time slice = 2): A B
- Priority 2 (time slice = 4):

A B Time

time = 3

- Priority 0 (time slice = 1):
- Priority 1 (time slice = 2): A B C
- Priority 2 (time slice = 4):

A B C Time

time = 3

- Priority 0 (time slice = 1):
- Priority 1 (time slice = 2): A B C
- Priority 2 (time slice = 4):

suppose process A is blocked on an I/O

A B C Time

time = 3

- Priority 0 (time slice = 1):
- Priority 1 (time slice = 2):
- Priority 2 (time slice = 4):

suppose process A is blocked on an I/O

A B C Time

time = 5

- Priority 0 (time slice = 1):
- Priority 1 (time slice = 2):
- Priority 2 (time slice = 4):

suppose process A is returned from an I/O

A B C B Time

time = 6

- Priority 0 (time slice = 1):
- Priority 1 (time slice = 2):
- Priority 2 (time slice = 4):

A B C B A Time

time = 8

- Priority 0 (time slice = 1):
- Priority 1 (time slice = 2):
- Priority 2 (time slice = 4):

A B C B A C Time

C

time = 9

- Priority 0 (time slice = 1):
- Priority 1 (time slice = 2):
- Priority 2 (time slice = 4):

A B C B A C C Time

- Approximates SRTF
 - A CPU-bound job drops like a rock
 - I/O-bound jobs stay near the top
 - Still unfair for long running jobs
 - Counter-measure: Aging
 - Increase the priority of long running jobs if they are not serviced for a period of time
 - Tricky to tune aging

Lottery Scheduling

- Lottery scheduling is an adaptive scheduling approach to address the fairness problem
 - Each process owns some tickets
 - On each time slice, a ticket is randomly picked
 - On average, the allocated CPU time is proportional to the number of tickets given to each job

Lottery Scheduling

- To approximate SJF, short jobs get more tickets
- To avoid starvation, each job gets at least one ticket

Lottery Scheduling Example

• short jobs: 10 tickets each

• long jobs: 1 ticket each

# short jobs/# long jobs	% of CPU for each short job	% of CPU for each long job

Important

Pros and Cons of Lottery Scheduling

- + Good for coordinating computers with different computing power
- + Good for controlling the schedules for child processes
- Not as good for real-time systems

Multicore Scheduling

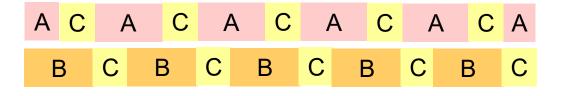
- Single-queue multiprocessor scheduling (SQMS)
 - CPU1
 - CPU2



Expensive to migrate jobs across CPUs

Time

- Another SQMS (Poor CPU affinity)
 - CPU1
 - CPU2



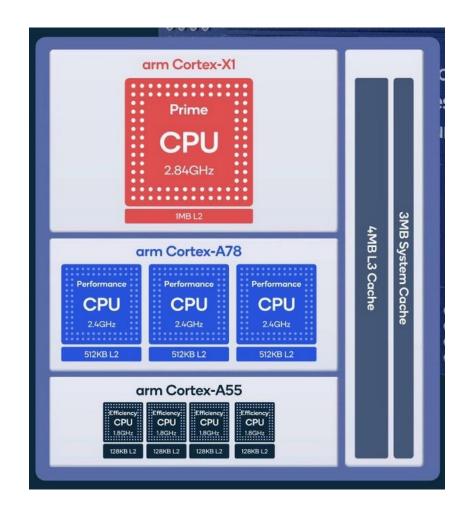
Time

More Schedulers

- Multi-queue scheduling
- O(1) scheduler
- Completely Fair Scheduler (CFS)

Real World

- Big.LITTLE
 - Snapdragon 888
- Others
 - The physical distance between CPUs on the circuit board
 - Power
 - ...



Takeaways

- OS is a state machine.
- Process, Thread, Address Space
- Thread Dispatch Loop
- Amdahl's Law
- CPU Scheduling