Lecture 17: Device Driver

(Principles of Device Drivers, Device Driver Design, GPU & CUDA)

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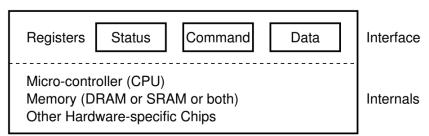
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Review of I/O Devices

From the OS' perspective, an I/O device is essentially

A Set of Registers and Protocols

- Regardless of what is connected behind them
 - Examples: serial port, keyboard, printer



A hardware-level abstraction for devices

Connecting Devices to the Computer:

- **Bus:** The sole external interface of the computer, connecting all devices.
 - The bus itself can be viewed as a device.

Managing the Bus:

- Interrupt Controller:
 - Coordinates device interrupts to manage CPU attention.
 - Avoids busy-waiting
- **DMA:** Acts as a co-processor, assisting in data transfer for I/O devices.

Expanding Co-Processing:

- **GPU:** Another specialized co-processor.
- Enables heterogeneous computing alongside the CPU.

Driver: A software-level abstraction for devices

- Each type of device has its own protocol and set of registers.
- Even for the same type of device, different models may have different registers and protocols.
- Directly exposing devices to the OS greatly increases the likelihood of errors.

Solution: Device Abstraction

To address this, we abstract all devices to communicate with the CPU in a unified manner as much as possible.

Outline

Today's Key Question:

How does the OS enable applications to access these devices?

- What is a device driver?
- How do we abstract the device?

Main Topics for Today:

- Principles of Device Drivers
- Linux Device Driver Design
- GPU and CUDA
- Disk (to be covered in File Management)



Principles of Device Drivers

Main Functions of I/O Devices

Input and Output

- "Readable (read) and writable (write) byte sequences (streams or arrays)"
- Most common devices fit this model:
 - Character Device:
 - Terminal/Serial Port Byte Stream
 - Printer Byte Stream (e.g., PostScript files)
 - Block Device:
 - Hard Disk Byte Array (Block Access)
 - GPU: Neither a Character Device Nor a Block Device
 - Byte Stream (Control) + Byte Array (Display)

How to Abstract I/O Devices

Since I/O devices are designed for input and output, we can abstract them using basic operations:

- Devices as Objects (Files) Supporting Various Operations
 - System call read Reads data from a specified location on the device
 - System call write Writes data to a specified location on the device
 - System call ioctl Reads/Sets the status of the device
 - RTFM:man 2 ioctl

What is a Device Driver?

Translates system calls (read/write/ioctl/...) into interactions with device registers

- Essentially a piece of kernel code
- Human \rightarrow Shell \rightarrow System Calls \rightarrow Driver \rightarrow Devices
 - Our computer continuously performs abstraction and translation
- May block (e.g., waiting on a semaphore P operation, awakened by V operation in interrupt)

Examples of Objects in /dev/

```
$ cd /dev && ls
```

- Note: A driver is simply code:
 - It may not have a real device behind it.
 - It can simulate devices entirely through code.
- Examples:
 - /dev/random, /dev/urandom Random number generators
 - Try: head -c 512 /dev/urandom | xxd
 - May use hardware device for true random numbers, or software for pseudo-random numbers
 - /dev/null "Null" device
 - Try: yes > /dev/null (Fake write success)
 - Try: cat /dev/null (No data to read)
 - Observe using strace
 - /dev/zero "Zero" device
 - Try: cat /dev/zero | head -c 512 | xxd

The Challenges of Device Drivers

I/O devices appear as a "black box"

- Prone to Errors!
- Any code mistake simply causes it to "not work"
- Device drivers: often the lowest quality code in Linux kernel

The Complexity of Device Drivers

- The computer industry includes countless devices, each with unique registers and protocols.
- Often, only the device's programmers understand them, and even they may not fully.
- Since Vista, Microsoft, and now Linux, have been moving drivers to user space to prevent system crashes from driver errors.

Limitations of Byte Stream Abstraction

Devices involve not only data but also control

- Especially for additional functions and configurations of devices
- All extra features rely on ioctl
 - Arguments, returns, and semantics of ioctl() vary according to the device driver in question
 - Complex "hidden specifications"

Examples

- Printer settings: print quality, paper feed, duplex, card stock, cleaning, auto binding, ...
 - A printer worth tens of thousands is not that simple!
- Keyboard lighting effects, repeat rate, macro programming, ...
- Disk health, cache control, ...

Device Complexity: More Than Just Byte Streams

Functions beyond the "Byte Stream"

- Devices are far more complex than simple input/output streams.
- Many features require specific configurations, often handled through ioctl calls.
- This complexity is just the tip of the iceberg.

The Terminal: A Special Device in UNIX

- The Shell acts as the interface between the user and the OS.
- The terminal is the I/O device behind this interface.
- Terminals support text-based input and output, enabling users to interact with the OS.
- They handle complex features like:
 - Input modes, signal handling, and line editing
 - Terminal settings, which can be configured dynamically
 - RTFM: tty, stty, ...



The Terminal Usage

```
$ echo hello > /dev/pts/l
```

Find out which system call "recognizes" the terminal.

```
#include <stdio.h>
int main() {
   printf("Hello,_World\n");
}
```

Tip: Compare using the following two comandes:

```
$ strace ./a.out
$ strace ./a.out > /dev/null
```

More On Terminal

Terminal as a Line Buffer

- Terminal uses line buffering: output is stored until a newline ('\n') or 'fflush(stdout);' is called.
- Files, on the other hand, use **full buffering**, meaning data is stored until the buffer is full or manually flushed.
- Buffering improves performance by reducing the number of slow system calls.
- If an error occurs before flushing, buffered data may not be displayed.

```
#include <stdio.h>
int main() {
    printf("Hello_World!");
    int *p;
    p = NULL;
    *p = 1;
}
```

```
#include <stdio.h>
int main() {
  printf("Hello_World!\n");
  int *p;
  p = NULL;
  *p = 1;
}
```

```
#include <stdio.h>
int main() {
    printf("Hello_World!");
    fflush(stdout);
    int *p;
    p = NULL;
    *p = 1;
}
```

Understanding Terminal Buffering

Consider the following code:

```
#include <stdio.h>
#include <unistd.h>
#include <sys/wait.h>

int main (int argc, char *argv[]) {
   for (int i = 0; i < 2; i++) {
      fork();
      printf("Hello_World!\n");
   }
   for (int i = 0; i < 2; i++) {
      wait(NULL);
   }
}</pre>
```

- When we run ./a.out, we get 6 "Hello World!"
- When we run ./a.out | cat, we get 8 "Hello World!"

Understanding Fork

- fork() duplicates everything in the process, including the output buffers!
- When we run ./a.out | cat, we get 8 "Hello World!"
 - It's connected to a pipe, not directly to the terminal.
 - The buffer does not flush after each newline; it waits until it's full or the program ends.
 - When fork() is called, the parent process's buffer (which may contain "Hello World!") is duplicated in the child process.
 - Both parent and child processes may flush the same buffered data, leading to duplicated outputs.
 - Result: Buffer duplication causes additional outputs; 8 "Hello World!" are printed.

Principles of Device Driver Design

How can we use a computer to launch a nuclear missile? Code



1. Define the Driver's Purpose

Key Questions to Define:

- What operations will the driver support? (e.g., read, write)
- How will the device interact with the user or system?
- Example: Our nuclear missile code triggers an ASCII art when the password is received.

2. Register Device Number and Class

- Major Number: Specifies the driver type that handles the device.
 - Tells the OS which driver to use for this type of device.
 - Assigned by alloc_chrdev_region and stored in dev_major.
- **Minor Number:** Differentiates instances of the same type of device.
 - Allows the driver to handle multiple devices of the same type.
 - Specified by MKDEV (dev_major, i), creating instances like '/dev/nuke0'
 (Minor 0) and '/dev/nuke1' (Minor 1).

```
ret = alloc chrdev region(&dev, 0, MAX DEV, "nuke");
if (ret < 0) {
 printk (KERN ALERT "nuke: Failed to allocate char device region\n");
 return ret;
dev major = MAJOR(dev);
lx class = class create(THIS MODULE, "nuke");
for (i = 0: i < MAX DEV: i++) {
 cdev init (&devs[i].cdev, &fops);
 devs[i].cdev.owner = THIS MODULE;
 ret = cdev add(&devs[i].cdev, MKDEV(dev major, i), 1);
 if (ret) {
  printk(KERN_ALERT "nuke: Failed_to_add_cdev_for_device_%d\n", i);
  while (--i >= 0) {
    cdev del(&devs[i].cdev);
    device_destroy(lx_class, MKDEV(dev_major, i));
   class_destroy(lx_class);
   unregister chrdev region (MKDEV (dev major, 0), MAX DEV);
   return ret:
```

Device Driver Design

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3. Define File Operations Interface

File Operations:

- Define how users will interact with the device:
 - read: Retrieves data from the device.
 - write: Sends data to the device.
 - open/release: Opens and closes access to the device.

```
static ssize_t lx_read(struct file *, char __user *, size_t, loff_t *);
static ssize_t lx_write(struct file *, const char __user *, size_t, loff_t *);
static struct file_operations fops = {
    .owner = THIS_MODULE,
    .read = lx_read,
    .write = lx_write,
};
```

4. Implement Core Functions

Core Functions Based on file_operations:

- Each function provides specific device behavior:
 - lx_read: Returns "This is dangerous!" when read.
 - **Ix_write:** Checks input for specific pattern to trigger ASCII art.

```
static ssize t lx write(struct file *file, const char user *buf, size t count, loff t *
      offset) {
if (cmp result == 0) {
  printk (KERN INFO "nuke: correct password entered.\n");
   const char *EXPLODE[] =
   int i:
   for (i = 0; i < sizeof(EXPLODE) / sizeof(EXPLODE[0]); i++) {
    printk(KERN INFO "%s\n", EXPLODE[i]);
 } else {
   printk(KERN INFO "nuke: incorrect secret, cannot launch.\n");
 return count:
```

5. Initialization and Cleanup

- module_init: Registers device and sets up file operations.
- module_exit: Unregisters device and cleans up resources.

```
static void __exit lx_exit(void) {
    device_destroy(lx_class, MKDEV(dev_major, 0));
    class_unregister(lx_class);
    class_destroy(lx_class);
    unregister_chrdev_region(MKDEV(dev_major, 0), MINORMASK);
}

module_init(lx_init);
module_exit(lx_exit);
```

Device Driver Design Summary

Key Steps in Device Driver Design:

- Define purpose and main functions.
- Register device (major and minor numbers, class).
- Set up file operations interface (read, write, ioctl).
- Implement core functions for device-specific logic.
- Initialize resources and provide cleanup routines.

Installation and Running

Building the Driver:

Use a Makefile to compile into a '.ko' file:

```
obj-m += nuke.o
KDIR := /lib/modules/$(shell uname -r)/build
all:
    make -C $(KDIR) M=$(PWD) EXTRA_CFLAGS==Wno-error modules
clean:
    make -C $(KDIR) M=$(PWD) clean
```

Install the Driver:

- make
- Load module: sudo insmod nuke.ko
- Check '/dev' for device files ('/dev/nuke0', '/dev/nuke1') using
 ls -l /dev/nuke*
- Set the devices to be readable and writable with textttchmod 666 /dev/nuke0
- Test with echo "COP4610" | sudo tee /dev/nuke0
- Observe logs with dmesg | tail -n 20
- Unload the module with sudo rmmod nuke

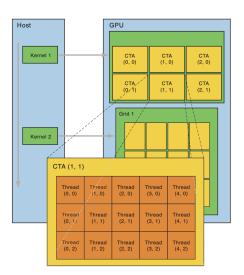
Dutline Principle Device Driver Design CUDA Takeaways 25/30

CUDA: Programming for GPUs

Programming for GPUs

Single Instruction, Multiple Threads

- Many threads execute the same instruction
- Each thread has some thread-local data (e.g., ID)
- Highly optimized design
 - One Program Counter (PC), multiple data elements
 - Successor to VLIW and SIMD architectures



Introduction to CUDA Toolchain

Reference: Parallel Thread Execution ISA Application Guide

- CUDA uses an instruction set architecture (ISA) for parallel thread execution.
- The code is compiled into SASS (machine code).
 - Use cuobjdump --dump-ptx or --dump-sass to view assembly code.

Essential Tools in the CUDA Toolchain

- $\mathbf{gcc} \rightarrow \mathbf{nvcc}$: NVIDIA CUDA Compiler, used to compile CUDA code.
- **binutils** → **cuobjdump**: Disassembler for CUDA binaries.
- $\mathbf{gdb} \rightarrow \mathbf{cuda} \cdot \mathbf{gdb}$: Debugger for CUDA code.
 - Allows debugging directly on the GPU!
- **perf** \rightarrow **nvprof**: Performance profiling tool to analyze GPU code.
- ...

CUDA brings a complete set of tools to the GPU, similar to what we have for CPUs.

GPU Driver Overview

GPU Drivers are Complex

- Complete Toolchain
 - Just-in-time (JIT) compilation
 - Profiler
 - ..
- API Implementation
 - cudaMemcpy, cudaMalloc,...
 - Kernel execution
 - Mostly implemented via ioctl
- Device Compatibility

Note: NVIDIA open-sourced its driver in 2022!

Before that ... Video

Takeaways

- What are device drivers?
 - Translate read/write/ioctl calls into device-understandable protocols
- Device Driver Design Principles

